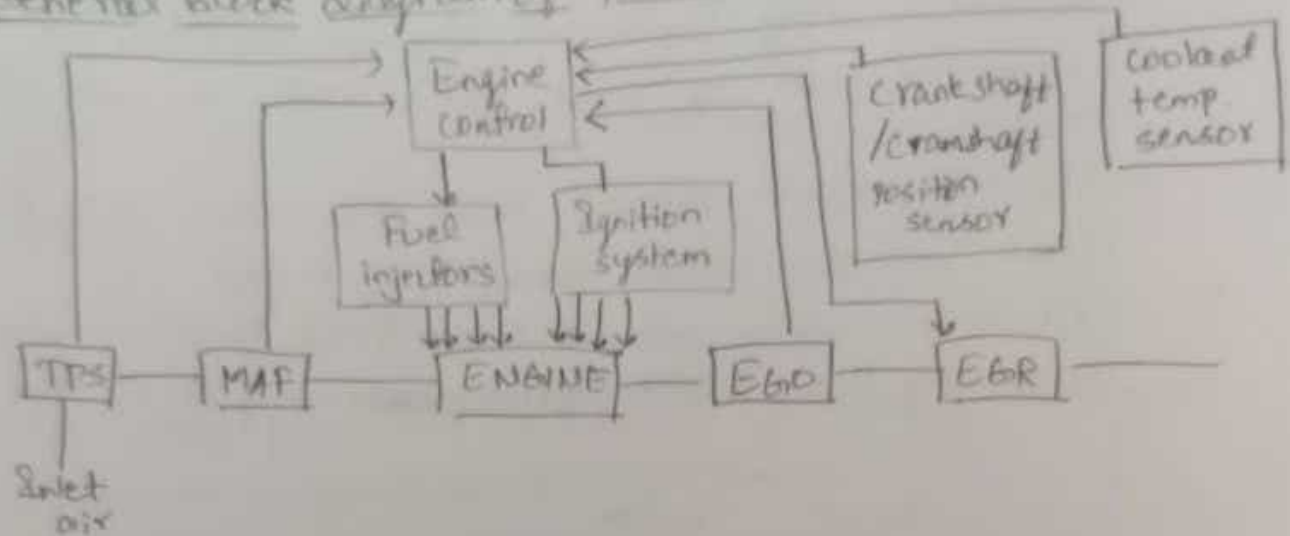


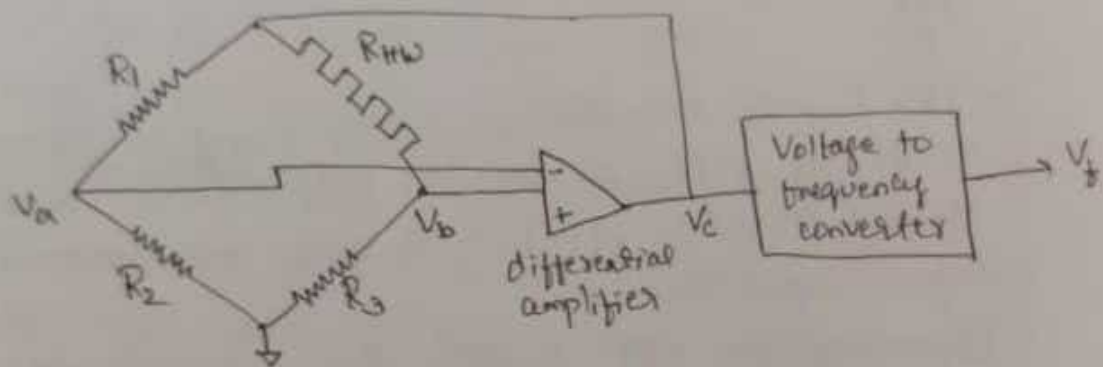
General block diagram of power train



- TPS & MAF are at inlet air manifold. These do, the quality of MAF is directly proportional to air flowing through throttle (TPS). Both will input data or pulse to engine control unit.
- Depending on MAF & TPS, the ECU will decide the amount of fuel injected by fuel injectors in engine cylinders.
- Width of pulse supplied to solenoid & is proportional to injectors open time
- Air & fuel mixture is compressed in engine cylinders with the help of spark advance i.e. ignition system.
- Among other all sensors remaining, cranksaft position sensor is most important. It senses the position of cranksaft/cranksaft in degrees of its rotation inside cylinder. Ideal position for spark ignition is $8-10^\circ$ before TDC.
- The data sent by cranksaft position sensor to ECU, this decides the position of piston before TDC & also ignition timing is produced.
- This ECU will give pulse ignition system i.e., provides current to ignition coils that provides sparks to engine.

MAF sensor:

- An electrically controlled engine requires a measurement of mass flow rate in air (R_m) into engine.
- This requires a sensor that can sense air flow rate into the intake manifold of engine.
- It is normally mounted as part of air cleaner assembly (i.e., intake manifold manifold of the engine).



Wheatstone

Here,

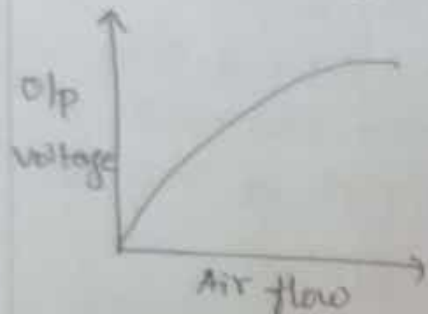
R_{HW} - sensing element

V_a & V_b - output of wheatstone \rightarrow differential amplifiers

output of differential amplifiers $\rightarrow V \rightarrow$ f converter.

- R_{HW} - heated filament resistor.
Value of resistance changes as the filament temperature changes.
- As air flows across the hot filament, heat is carried away from the film by moving air.
- The amount of heat carried away varies in proportional to the mass flow rate of the air.
- The heat lost by the film to the air tends to cause the resistance of the film to vary, which unbalances the

- This voltage is given to voltage to frequency converter.

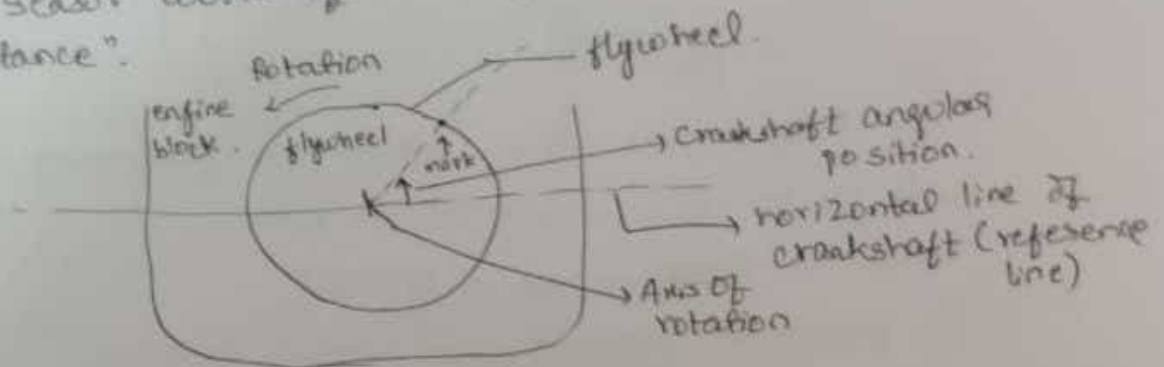


Here the graph is called calibration curve.

- The output from the voltage to frequency converter will go to ECU, which is in pulse
- Here, no linear curve is present.
- In particular zone it gives linear output
- The amount of fuel to be injected is decided by the air flow sensor [MAF] whose output is given in the pulse to the ECU. Finally proper air : fuel ratio should be maintained.

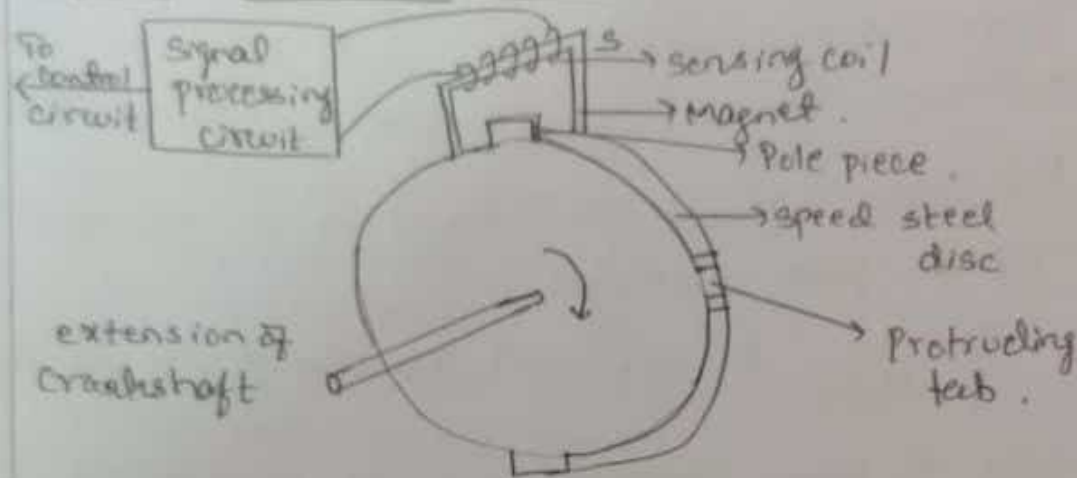
Engine crankshaft angular position sensor:

- In order to determine the spark timing, valve timing etc., the position of piston w.r.t TDC & BDC is necessary. Therefore we need a sensor to sense the same.
- This sensor works on the principle of "magnetic reluctance".



- Flywheel - senses rotation of crankshaft which is integrated in engine block, 1 rotation is 360° of rotation.
- Piston moves from TDC to BDC, then crankshaft completes its half rotation i.e., 180° .
- 360° rotation - from TDC to BDC & again back.
- Considering intake of cylinder where piston is at TDC & if crankshaft rotates at 180° then piston moves from TDC to BDC. Again 180° to 360° is next (compression stroke BDC to TDC).
- In compression stroke, the ignites the spark. Ideal spark ignition is at $8-10^\circ$ before TDC.
- This crankshaft position senses, it will measure the distance of piston from TDC or BDC in degrees of rotation of crankshaft.
- Measurement of degrees is w.r.t horizontal reference line. At 0° - piston at TDC. At 180° - piston at BDC. Again at initial point (360°) - from BDC to TDC.

Magnetic reluctance position sensor (MRP)



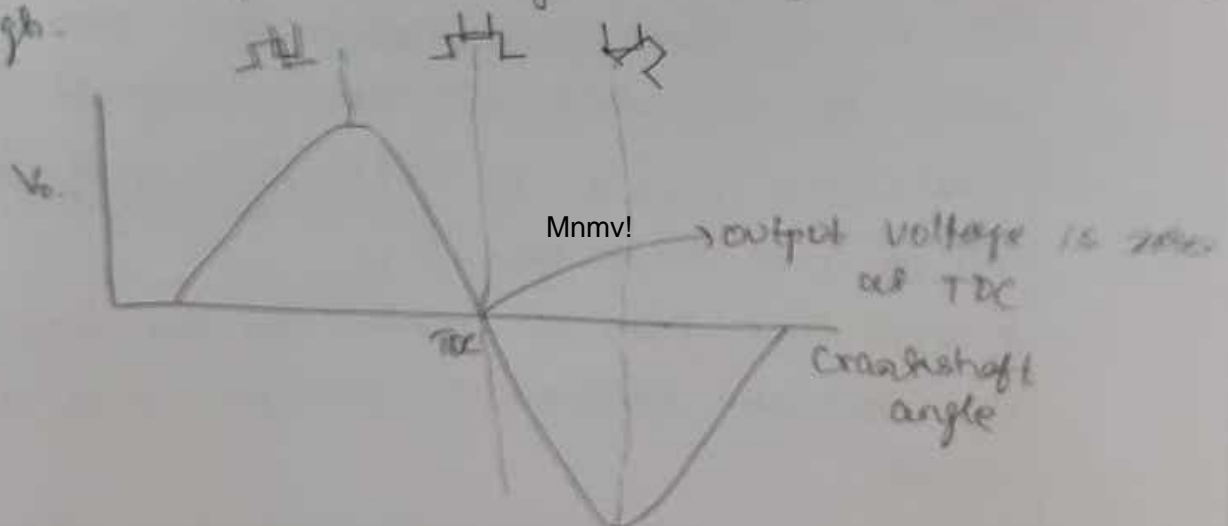
- One engine sensor configuration that measures crankshaft position directly (using magnetic sensor)
- This sensor consists of permanent magnet with a coil of wire wound around it.
- A steel disk that is mounted on the crankshaft has tabs that pass between the pole pieces of this magnet.
- This sensor is of the magnetic reluctance type & is based on the concept of magnetic circuit.
- Reluctance, $R = \frac{l}{\mu_r \mu_0 A}$, Area of cross-section of magnet.
- One noncontacting engine sensor configuration that measures crankshaft position directly (using magnetic phenomena).
- The sensor consists, in general, there are N tabs where N is determined during the design of the engine control system.
- The passage of each tab could correspond for eg, to TDC position of cylinder, although other reference positions are possible.

Changes in reluctance

- Before tab approaches, air is present as dielectric medium. μ_r - relative permeability ($\mu_r = 1$ for air).
- tab comes between the circuit & it changes the magnetic path disturbs.

$$R = \frac{l}{\mu_r \mu_0} \quad \therefore \mu_r \text{ won't remain } 1, \text{ it changes}$$

Here R drops drastically as μ_r of steel will be high.



- The rate of change of flux induces a voltage across the coil.
- A peak in voltage indicates tab crossing the pole face as shown.

Lin no p/v
Jai
G!o

Throttle position sensor

- A variable that must be measured for electronic engine control is the throttle plate angular position.
 - This is linked to accelerator pedal mechanically.
 - When the driver depresses the accelerator pedal, this linkage causes the throttle plate angle to increase allowing air to enter the engine.
 - The power generated by engine is directly proportional to air entering the engine.
 - The throttle sensors are essentially potentiometers.
 - Speed can be controlled by this sensor.
 - When the pedal is pressed, the throttle valve which is called butterfly valve will open & it increases air flow thus increasing speed of vehicle.
-
- TPS monitors, how much the valve is open if how much accelerator pedal is depressed by driver.
 - When valve is widely open, more air flows. Thus fuel intake will be more, speed will be more.
 - When valve is closed nearly, less air flows, fuel intake will be less, speed will automatically reduce. It is presented at accelerator pedal. TPS senses the valve open to the ECU of engine.
 - Thus variable speed is achieved.
 - The ECU decides the amount of fuel to be injected to the engine.

Construction of 3 wired Potentiometer

- 1st wire = 5V, 2nd wire - grounded, 3rd wire connected to movable wiper.
- Other end of needle is input of ECU i.e., $V_{(a)}$
- As throttle valve changes its position, needle will also move accordingly.
- The circuit is closed as $V_{(a)}$ is connected to ECU where continuous constant current will be flow through the circuit.
- The amount of current flowing through resistor is different in different parts, the current changes as the position of needle change. Therefore voltage variable which is input of ECU which decides the amount of fuel to be released for the engine.
- Based on construction, TPS are different like Potentiometer or closed throttle position sensor which has switches in it.
- Disadvantage: the potentiometer for automotive applications is its analog output. But for digital engine, the voltage $V_{(a)}$ must be converted to digital format using an analog to digital converter.

Sensor for feedback control: have exhaust gas recirculation (in order to reduce exhaust gas discharged by engine).

- Exhaust gas oxygen sensor - popularly known as lambda sensor.
- The amount of oxygen present in exhaust gas is in turn used to measure the air/fuel ratio.
- As a result, one of the most significant automotive sensor in use today is exhaust gas oxygen (EGO) sensor.
- Also called lambda sensor,

$$\lambda = \frac{\text{air/fuel}}{\text{air/fuel at stoichiometry}}$$

with the help of λ value, we can know how much carburation is happening inside the engine.

- If λ is too fluctuating, then there is no proper carburation taking place.
- Thus λ should be measured, which is done by EGO sensor.
- If $\lambda > 1 \rightarrow$ mixture is lean
- If $\lambda < 1 \rightarrow$ mixture is rich
- If $\lambda = 1 \rightarrow$ ideal.

stoichiometric air/fuel is 14.7:1.

- Actual air/fuel ratio is measured by air-MAF sensor.

- Some part of λ sensor is placed inside the exhaust gas exhaust tube & some is at output of tube.
- Concentration of oxygen in tube is different from what the concentration of oxygen outside the tube.
- The difference in concentration of oxygen, this will create potential gradient at terminals (V_o)
- V_o is the output voltage of the sensor.
- If $\lambda < 1$ (rich mixture) fuel quantity will be more the oxygen in the exhaust gas tube. This means the EGO will give more output i.e., V_o will be more.
- If $\lambda > 1$, fuel is less & air is more, concentration of oxygen is high. V_o will be lower.
- Difference in concentration of oxygen of inside and outside the tube is less, so here V_o will be less, vice versa.

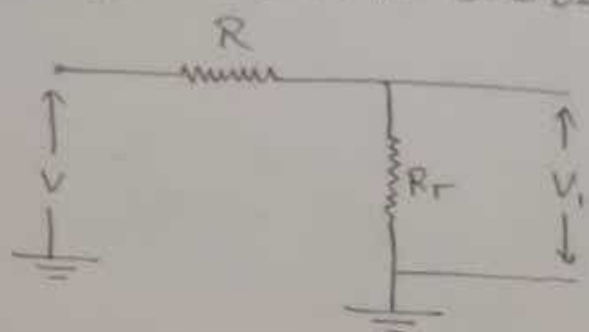
Temperature Sensor:

- Temperature sensor is an important parameter throughout the automotive system.
 - In operation of an electronic fuel control system it is vital to know the temperature of the coolant, the temperature of inlet air & temperature of exhaust gas oxygen sensor.
 - We can illustrate the basic operation of most of the temperature sensors by explaining the operation of types of coolant sensor.
-
- To keep the engine at optimum temperature.
 - Measure the temperature of coolant present in the cooling system.
 - We will get to know amount of heat generated by the engine by knowing coolant temperature.
 - Commonly known as ECT.
 - The ECT resistance of ECT sensors will be converted to voltage signal which is further

by ECU.

- It continuously monitor the temperature of coolant & make sure engine is running at optimum temperature
- $R \propto \frac{1}{T_{\text{emp}}}$, for eg. consider 20° of engine. R will be $2k\Omega$ or $3k\Omega$. When temperature increase like 90° these R will be low like 200Ω to 300Ω

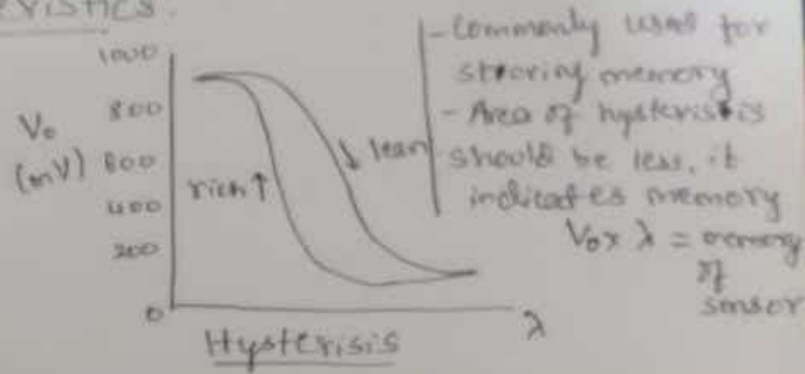
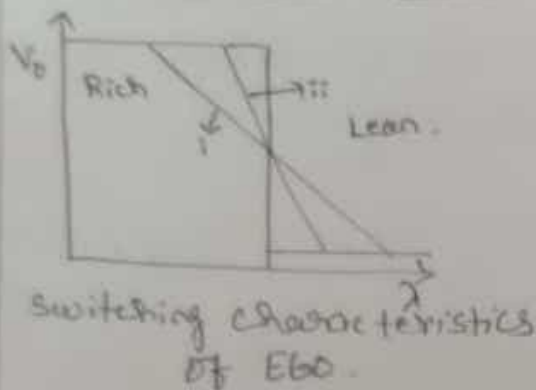
Reference
voltage



Electrical
Circuit of ECT
Sensor.

- Here,
 R_T - coolant temperature sensors resistance value
 R_T - connect to fixed reference voltage through fixed resistance R .
- Sensors discussed before feedback control are open loop ECU sensors.
- Open ECU sensors - with exhaust gas recirculation.
- $V_T = \frac{VR_T}{R + R_T}$
- Here V_T decreases as temperature sensed by R_T increases.

Desirable EGO characteristics:



- ① Abrupt changes in voltage at stoichiometry - if $\lambda > 1$, $V_o = 0.8$ ($V_o > 1$) where $\lambda = 1$, $V_o = 0$, $\lambda < 1$, $V_o = 1.2V$.
Transitions from rich to lean or vice versa will cause V_o change.
 - ② Rapid switching of V_o in response to exhaust to exhaust gas O_2 changes - concentration of O_2 at exhaust gas will be changing fast at every stroke.
 - ③ Large difference in sensor output voltage between rich & lean mixture conditions - V_o should be having large difference at rich & lean. $(V_o)_{rich}$ & $(V_o)_{lean}$ should be differentiable.
 - ④ Stable voltages w.r.t exhaust temperature.
- ∴ In hysteresis graph, $\lambda = 0$ to 0.8 - V_o - constant
- ∴ V_o - more at $\lambda = 0.99$ we need to select it where is more like ideal one to get appropriate value of EGO.
- Choose sensor with lesser memory because less memory can be easily vanished & it is given appropriate output on present. With less hysteresis all desirable EGO characteristics will be satisfied.

Engine Speed sensor:

- ① Wheel speed sensor: required for safety system, works on principle of proximity.

Signal - actual output from sensor

Disc has some protruding tabs which is mounted on wheel, when protruding tab is closed to sensor, then it is said close event

Notch \rightarrow open time.

- The time difference of events (open & close) is directly proportional to the speed of wheel.
- difference is very less, rotation is high amount of rpm
- signal produces pulses, which in turn gives wheel speed
- wheel speed sensor is integral part of ABS.

- ② Vehicle speed sensor: located at transaxle of transmission, kind of wheel speed or derivative.

- Vehicle speed sensor is used by ECU to adjust ignition timing, air/fuel ratio, adjust spark timing or transmission shift times.

- fuel - we need to know rate of spray injection.
- Amount of fuel = rate of spray injection \times time of valve open to injection.

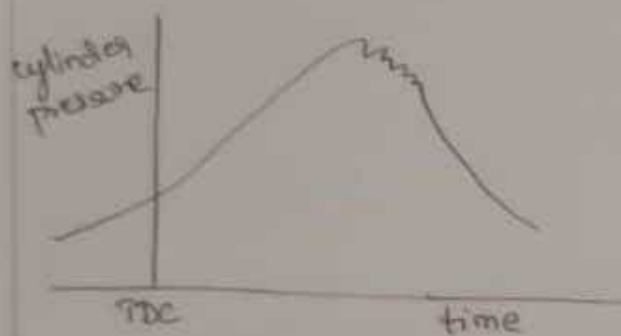
After combustion: EGO sensor is present at exhaust gas recirculation system. Based on concentration of oxygen which is in exhaust gas the type of mixture is determined.

- Most of sensors use Zirconium dioxide [ZrO_2] & titanium dioxide [TiO_2]
- ZrO_2 is most commonly used because it is very sensitive to the presence of O_2 .
- The resistance of ZrO_2 in the presence of O_2 change rapidly with the change in conc of O_2 at the particular constant pressure & temperature.
- Thus by ZrO_2 variations in its resistance we can measure O_2 concentration at exhaust gas at constant pressure & temperature.

Knock Sensor:

- Due to automobile aging there are some noises produced by parts. The noises produced by engine is called knock.
 - Noise is due to the sudden rise of pressure in engine cylinders.
 - Knocking will also occur when burning of fuel is uneven. This uneven burning is because of faulty spark plugs.
 - Aging of plugs leads to malfunctions & results in knock.
 - Engine performance & efficiency reduces due to the knocking. So knocking should be detected & protected so as to minimize the engine & valves damage.
 - Knock sensor prevents knocks & it will help to vary spark advance to prevent.
- ① We can sense the knocking and we can retard or delay the ignition until knocking stops completely.
- It uses magnetostri^otion principle - it is a phenomenon in which the magnetic property of the material changes depending on stress.

- Magnetostrictive rods are in coil
- magnet is inserted in the coil.
- In steady state condition, the magnetic flux linked with magnet to fixed & voltage level is induced in the coil is zero.
- Change in flux is required to generate the emf.
- When knock occurs, it exerts pressure on the engine walls, the magnetostrictive rods will get modified.
- This will change magnetic property of rods & emf will get induced.
- We will receive pulses at terminal.



- Piston comes near TDC, cylinder pressure increases gradually i.e., after combustion
- Deviations in curve represents knocking.

- Other sensors use piezoelectric crystals or the piezo-resistance of doped Si semiconductor.
- Knocking occurring in a cylinder alerts the sensor of its cylinder remaining won't range
- Here, the piston near TDC occurs, the cylinder pressure increases gradually after combustion.
- It also contains soft magnetic shell, insulator in the sensor.