## **GROUP-15**

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#### **Problem statement:**

Write C program to demonstrate the concept of mailbox. Task 1- Take data from serial port and save in mailbox. Task 2- take data from mailbox and display on UART using LPC2148.

Under the Guidance of

Guide Signature

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#### Code

```
#include <rtl.h>
#include <stdio.h>
#include <lpc214x.h>
OS TID t1;
                                        /* Declare an RTX mailbox */
os_mbx_declare(MsgBox, 100);
U32 mpool[8 * sizeof(U32)];
                                     /* Reserve memory for 16 messages */
unsigned int cnt1, cnt2;
char arr1[20];
char arr2[20];
int i = 0;
__task void task2(void);
 _task void task1(void)
  /* This task will send a count value. */
  U32 *mptr;
  os_tsk_create(task2, 0);
  os_mbx_init(MsgBox, sizeof(MsgBox));
  mptr = _alloc_box(mpool);
                                     /* Allocate memory for the message */
  // Initialize UART0 for LPC2148
  PINSEL0 |= 0x00000005; // Select TXD0 and RXD0
                    // 8-bit data, 1 stop bit, no parity, enable DLAB
  U0LCR = 0x83;
  U0DLL = 97;
                       // 9600 baud rate for PCLK = 15MHz
  U0LCR = 0x03;
                        // 8-bit data, 1 stop bit, no parity
  while (1)
    cnt1++;
    sprintf(arr1, "counter1: %d", cnt1);
     while (arr1[i] != '\0')
       os_dly_wait(1);
       while (!(U0LSR & 0x20))
       U0THR = arr1[i];
       i++;
     }
    i = 0:
    while (!(U0LSR & 0x20))
    U0THR = '\n';
    os_dly_wait(5);
    // Send the count value to 'task2' continuously
    mptr[0] = cnt1;
    os_mbx_send(MsgBox, mptr, 0xffff);
     os_dly_wait(100);
}
```

```
__task void task2(void)
  /* This task will receive and display the count value. */
  U32 *rptr;
  os_mbx_wait(MsgBox, (void**)&rptr, 0xffff); /*Wait for the initial message to arrive. */
  while (1)
    cnt2 = rptr[0]; /*Copy the count value from task1 to cnt2*/
    sprintf(arr2, "counter2: %d", cnt2);
    os_dly_wait(2);
    while (arr2[i] != '\0')
       os_dly_wait(1);
       while (!(U0LSR & 0x20))
       U0THR = arr2[i];
       i++;
     }
    i = 0;
    while (!(U0LSR & 0x20))
    U0THR = '\n';
    os_mbx_wait(MsgBox, (void**)&rptr, 0xffff); /*Wait for the next message to arrive. */
  }
}
void main(void)
  _init_box(mpool, sizeof(mpool), sizeof(U32));
  os_sys_init_prio(task1, 10);
```

### Output / Hardware

# **Implementation**





