

REAL TIME OPERATING SYSTEM- (22EECP302) YEAR 2023-2024

REVIEW - I

Team members

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Problem Statement:- Write a C code to demonstrate the concept of task switching

1st Task – Toggle LEDs.

2nd Task- Display counter values on seven segment display.

Under Guidance of

Prof. S.M.Hunagund

Staff Signature

CODE:-
#include <lpc21xx.h></lpc21xx.h>
#include <rtl.h></rtl.h>
#include <stdio.h></stdio.h>
void sev(void);
void delay(unsigned int);
unsigned int i;
unsigned int $Disp[10] = \{0x003F0000, 0x00060000, 0x005B0000, 0x004F0000, 0x00660000, 0x006600000, 0x00660000, 0x00660000, 0x00660000, 0x00660000, 0x0060000, 0x0060000, 0x0060000, 0x0060000, 0x0060000, 0x0060000, 0x0060000, 0x0060000, 0x0060000, 0x00600000, 0x00600000, 0x0060000000, 0x00600000, 0x00600000, 0x00600000, 0x006000000, 0x006000000000, 0x0060000000, 0x0060000000000$
0x006D0000, 0x007D0000, 0x00070000, 0x007F0000 0x006F0000};
task void job1(void);
task void job2(void);
void delay(unsigned int j) {

```
unsigned int i;
  for (i = 0; i < j; i++);
}
  task void job1(void) {
  os_tsk_create(job2, 0);
  while (1) {
    sev();
  }
}
  _task void job2(void) {
  PINSEL0 = 0x00000000;
  IODIR0 |= 0x0000F000;
  while (1) {
    IOSET0 = 0x00008000;
    delay(650000);
    IOCLR0 = 0x0000F000;
```

sev();

```
IOSET0 = 0x00004000;
delay(650000);
IOCLR0 = 0x0000F000;
sev();
IOSET0 = 0x00002000;
delay(650000);
IOCLR0 = 0x0000F000;
sev();
IOSET0 = 0x00001000;
delay(650000);
IOCLR0 = 0x0000F000;
sev();
```

}

}

```
void sev(void) {
  IODIRO |= 0x0FF0000;
  IOSETO |= 0xF0000000;
  for (i = 0; i < 10; i++)
     {
    IOSETO |= Disp[i];
    delay(1000000);
    IOCLR0 |= 0x00FF0000;
  }
}
int main(void) {
  os_sys_init(job1);
  while (1);
}
```



OUTPUT:-



