AI3011: Lab Assignment Report

Lab Assignment 10

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Declaration

I, Pratik, certify that this project is my own work, based on my personal study and research and that I have acknowledged all material and sources used in its preparation, whether they be books, articles, reports, lecture notes, and any other kind of document, electronic or personal communication. I also certify that this project has not previously been submitted for assessment in any academic capacity and that I have not copied in part or whole or otherwise plagiarised the work of other persons. I confirm that I have identified and declared all possible conflicts that I may have.

Dated: 10 - 04 - 2023

Pratik Rana

Answers

Q1: What are the parallels between Biological NNs and Artificial NNs? List any three.

Ans. 1. BNNs and ANNs both consist of interconnected neurons/units.

- 2. They involve the transmission of signals (electrical impulses in BNNs, numerical values in ANNs). between neurons.
- 3. Both can learn and adapt based on experience or training data.

O2:

What was the McCulloch-Pitts Neuron model? List any two of its limitations.

Ans. The McCulloch-Pitts Neuron model was a simplified mathematical neural model of a biological neuron. Its limitations were:

- 1. It only supported binary(0,1) outputs, so couldn't represent complex patterns or continuous data.
- 2. It operated based on fixed rules without adjusting its parameters so it lacked the capability for learning/adaptation.

Q3: How does a perceptron learn?

Ans. The Perceptron learning process continues iteratively until the model converges to a satisfactory solution or reaches a predefined stopping criterion. It adjusts its weights based on the error between the predicted output and the actual output. It uses a learning rate to control the size of weight updates.

Q4: List any three activation functions and their respective output ranges.

Ans. 1. Sigmoid: 0, 1.

- 2. ReLU Rectified Linear Unit : 0, ∞
- 3. Tanh Hyperbolic Tangent: -1, 1.

Q5: Why was the classical perceptron not able to solve the XOR problem? Can you suggest a way to solve the XOR problem using neural networks but without going into a higher dimensional space?

Ans. The classical perceptron relies on a linear decision boundary, which cannot separate XOR data points effectively. We can use a multilayer perceptron with nonlinear activation functions allowing it to learn and represent nonlinear decision boundaries. A two-layer perceptron with one hidden layer ca be used to solve the XOR problem.

References:

1. Lecture Slides

Output and Code

```
In [ ]: import numpy as np
        import matplotlib.pyplot as plt
        from sklearn.model selection import train test split
        from sklearn.metrics import confusion matrix, ConfusionMatrixDisplay
In [ ]: np.random.seed(0)
In []: mu1 = [2, 2]
        sigma1 = [[0.9, -0.0255], [-0.0255, 0.9]]
        class1 samples = np.random.multivariate normal(mu1, sigma1, 250)
        mu2 = [5, 5]
        sigma2 = [[0.5, 0], [0, 0.3]]
        class2 samples = np.random.multivariate normal(mu2, sigma2, 250)
        class1 labels = np.zeros(250)
        class2 labels = np.ones(250)
        combined data = np.vstack((class1 samples, class2 samples))
        combined labels = np.hstack((class1 labels, class2 labels))
In [ ]: data with bias = np.column stack((np.ones(len(combined data)), combined d
In [ ]: X train, X test, y train, y test = train test split(data with bias, combi
In [ ]: def step activation(x):
            return 1 if x >= 0 else 0
        def train_perceptron(X, y, learning_rate, max_epochs):
            weights = np.random.rand(X.shape[1])
            for epoch in range(max epochs):
                for i in range(X.shape[0]):
                     prediction = step activation(np.dot(X[i], weights))
                    error = y[i] - prediction
                    weights += learning_rate * error * X[i]
            return weights
In [ ]: learning rate = 0.1
        \max \text{ epochs} = 1000
        optimal_weights = train_perceptron(X_train, y_train, learning_rate, max_e
In [ ]: plt.figure(figsize=(8, 6))
        plt.scatter(class1 samples[:, 0], class1 samples[:, 1], color='green', la
        plt.scatter(class2_samples[:, 0], class2_samples[:, 1], color='orange', l
        x vals = np.array([np.min(combined data[:, 0]), np.max(combined data[:, 0
        y vals = -(\text{optimal weights}[0] + \text{optimal weights}[1] * x vals) / \text{optimal we}
        plt.plot(x_vals, y_vals, color='black', label='Decision Boundary')
        plt.xlabel('X1')
        plt.ylabel('X2')
        plt.title('Perceptron Decision Boundary')
        plt.legend()
        plt.show()
        y_pred = [step_activation(np.dot(x, optimal_weights)) for x in X_test]
```



