

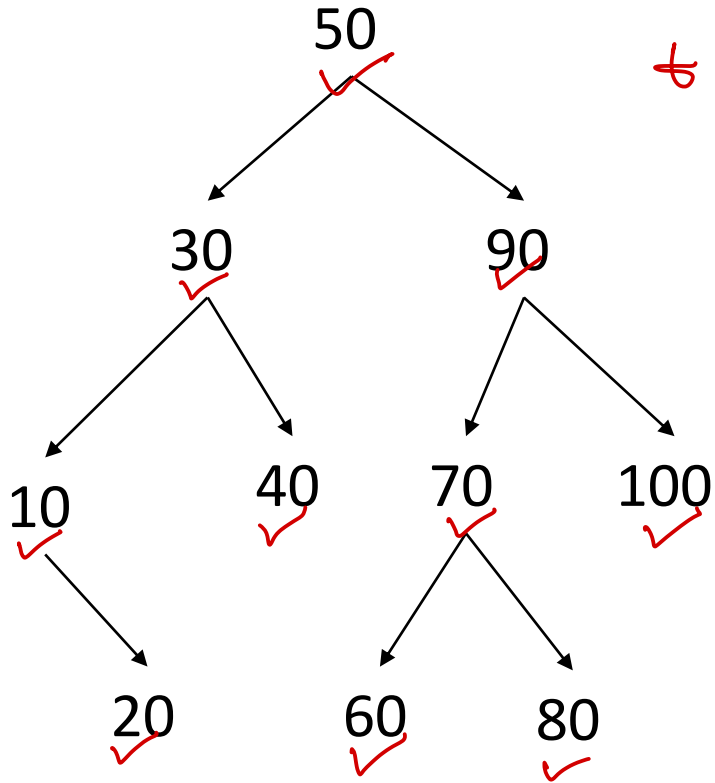


# Data Structure & Algorithms

*Sunbeam Infotech*



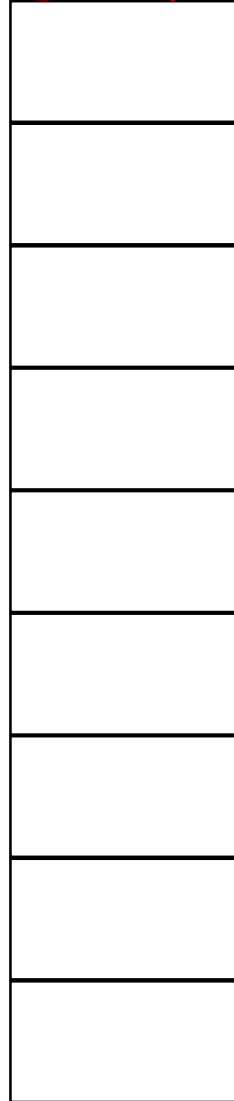
# BST - post order ( )



20 10 40 30 60

80 70 100 90 50

Stack



```
trav = root;
while (trav != null || !s.isEmpty()) {
    while (trav != null) {
        s.push(trav);
        trav = trav.left;
    }
    if (!s.isEmpty()) {
        trav = s.pop();
        if (trav.right != null &&
            !trav.right.visited) {
            s.push(trav);
            trav = trav.right;
        }
        else {
            print(trav.data);
            trav.visited = true;
            trav = null;
        }
    }
}
```

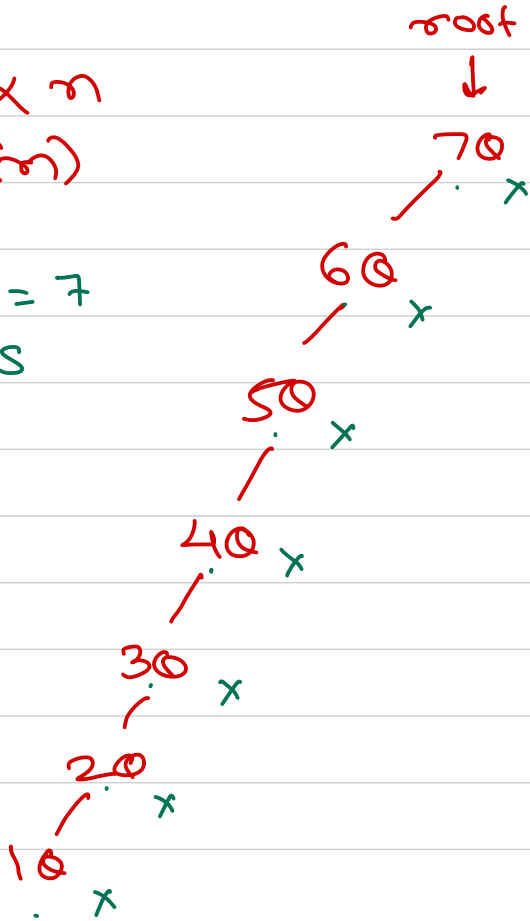
} } }



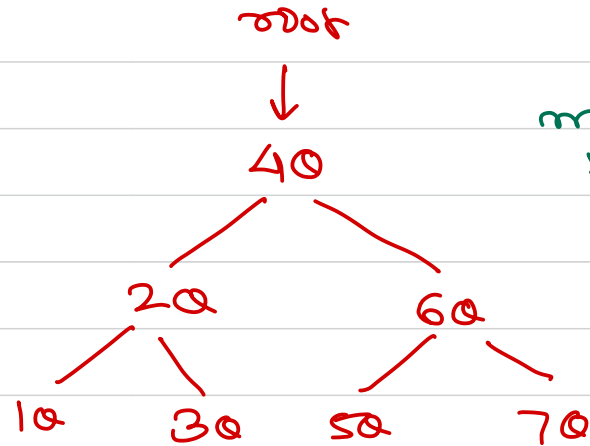
skewed BST  $\rightarrow$  max height

$T \propto n$   
 $O(n)$

max = 7  
itrs

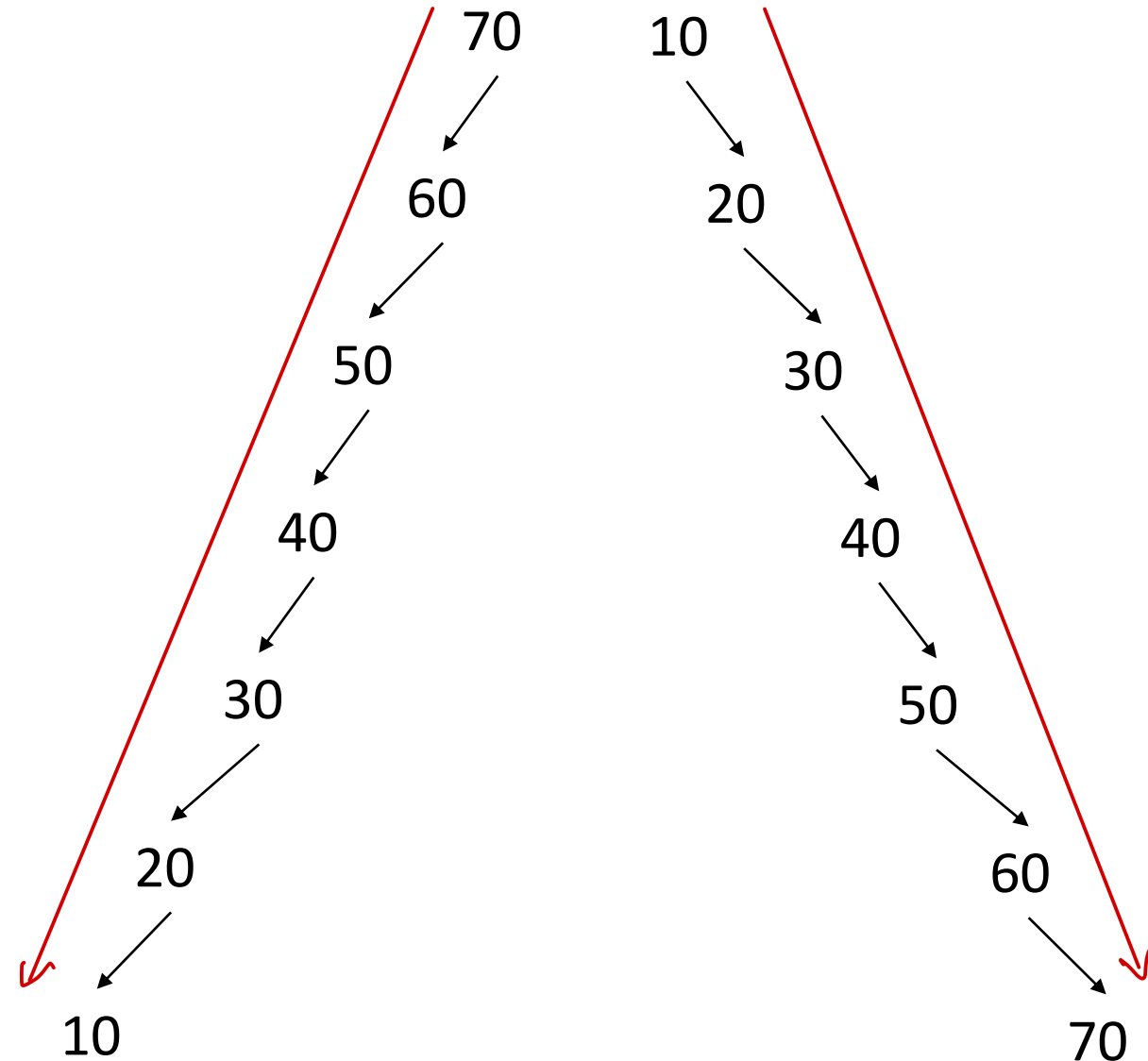


Balanced BST  
min height.



max = 3  
itrs

# Skewed Binary Tree

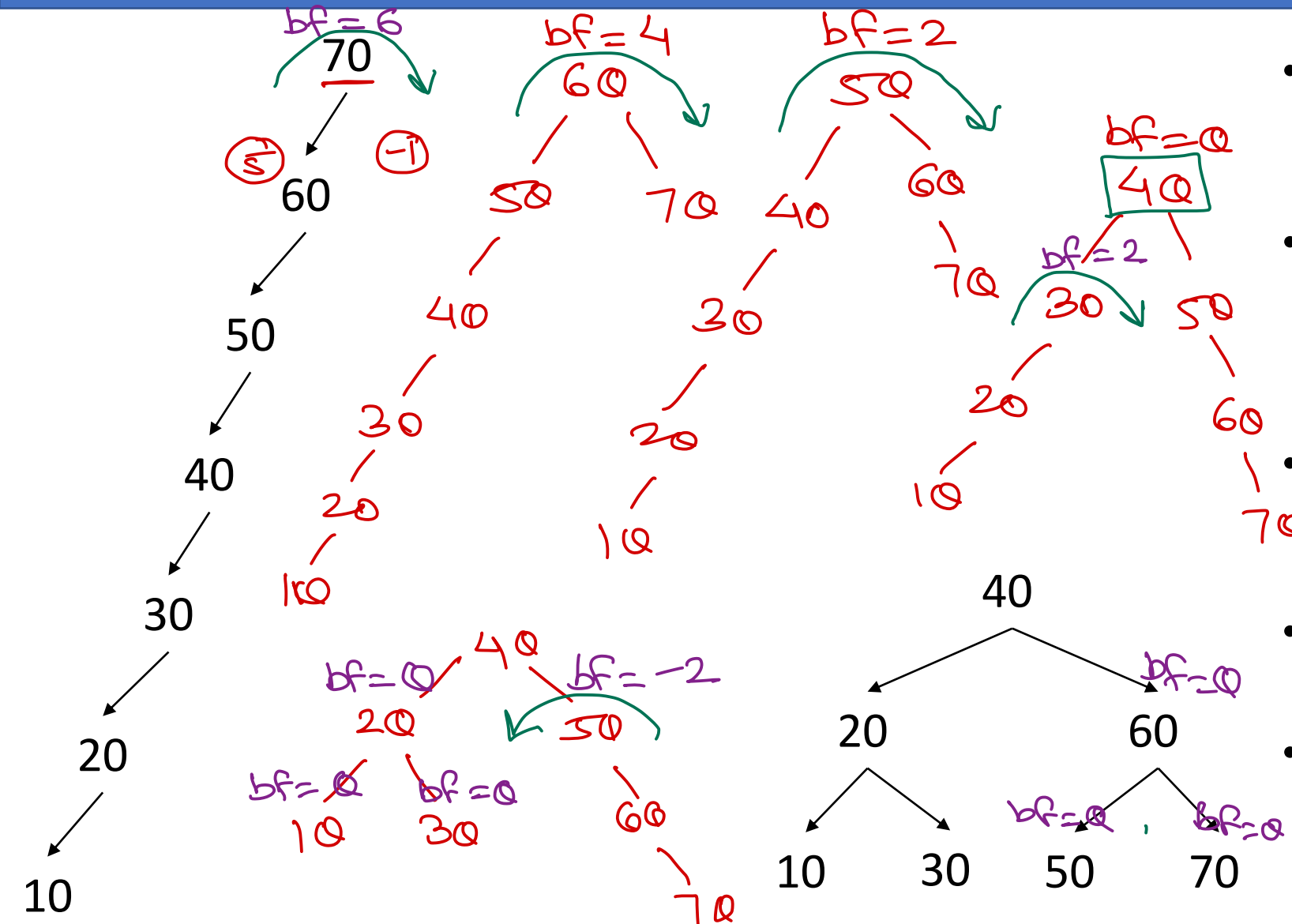


- In Binary tree if only left or only right links are used, tree grows only on one side. Such tree is called as skewed binary tree.
  - Left skewed binary tree
  - Right skewed binary tree
- Time complexity of any BST is  $O(h)$ .
- Such tree have maximum height i.e. same as number of elements.
- Time complexity of searching in skewed BST is  $O(n)$ . *→ like linked list*

*height*



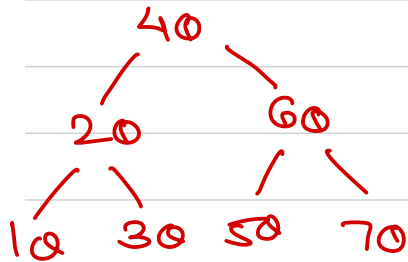
# Balanced BST



- To speed up searching, height of BST should minimum as possible.
- If nodes in BST are arranged so that its height is kept as less as possible, is called as Balanced BST.
- Balance factor
  - = Height of left sub tree – Height of right sub tree
- In balanced BST, BF of each node is -1, 0 or +1.
- A tree can be balanced by applying series of left or right rotations on unbalanced nodes.



height = 2



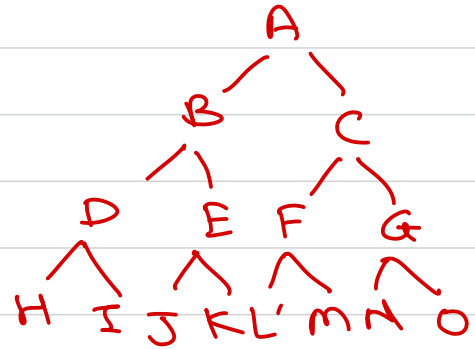
$n = 7$

$$n = 2^{h+1} - 1$$

leaf nodes =  $2^h$   
(external)

non-leaf nodes =  $2^h - 1$   
(internal)

height = 3

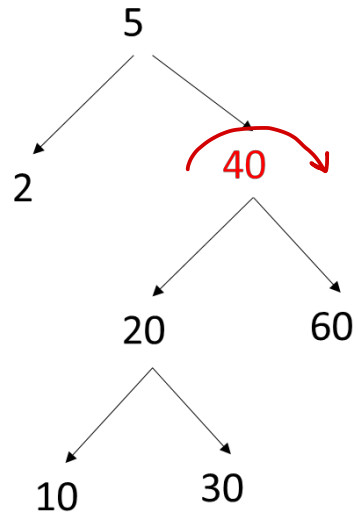
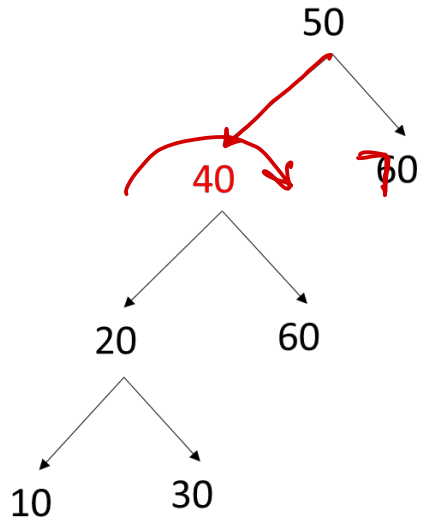
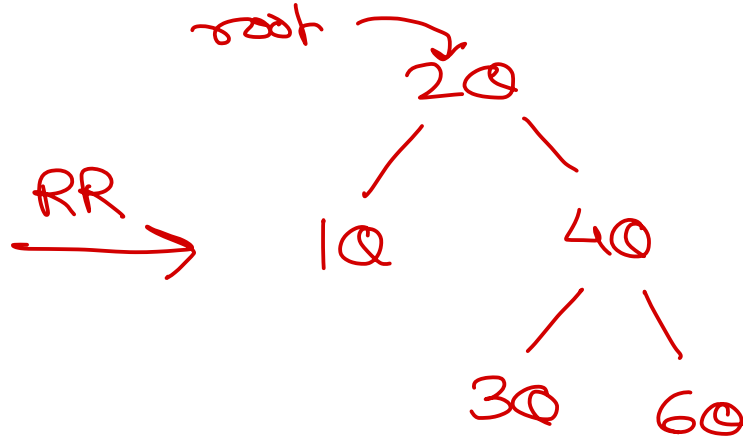
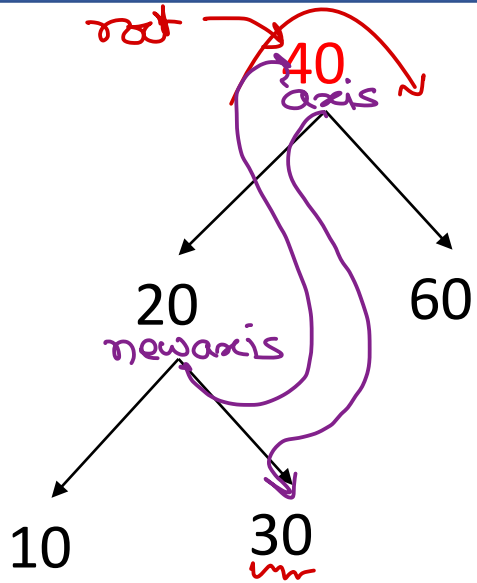


$n = 15$

leaf = 8

non-leaf = 7

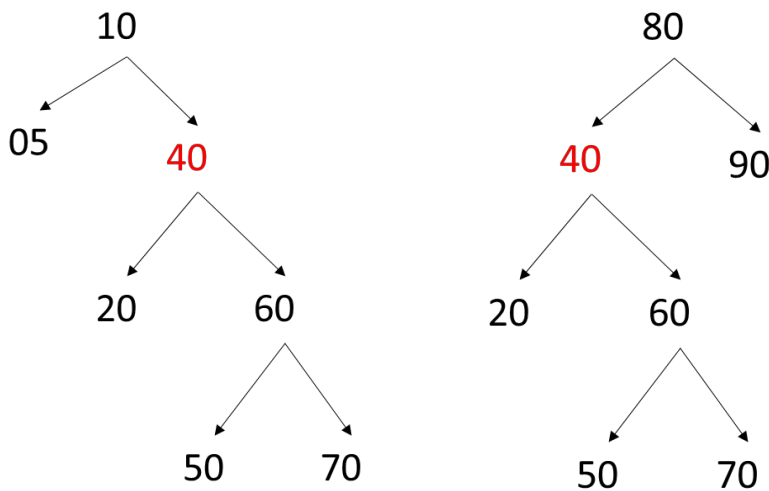
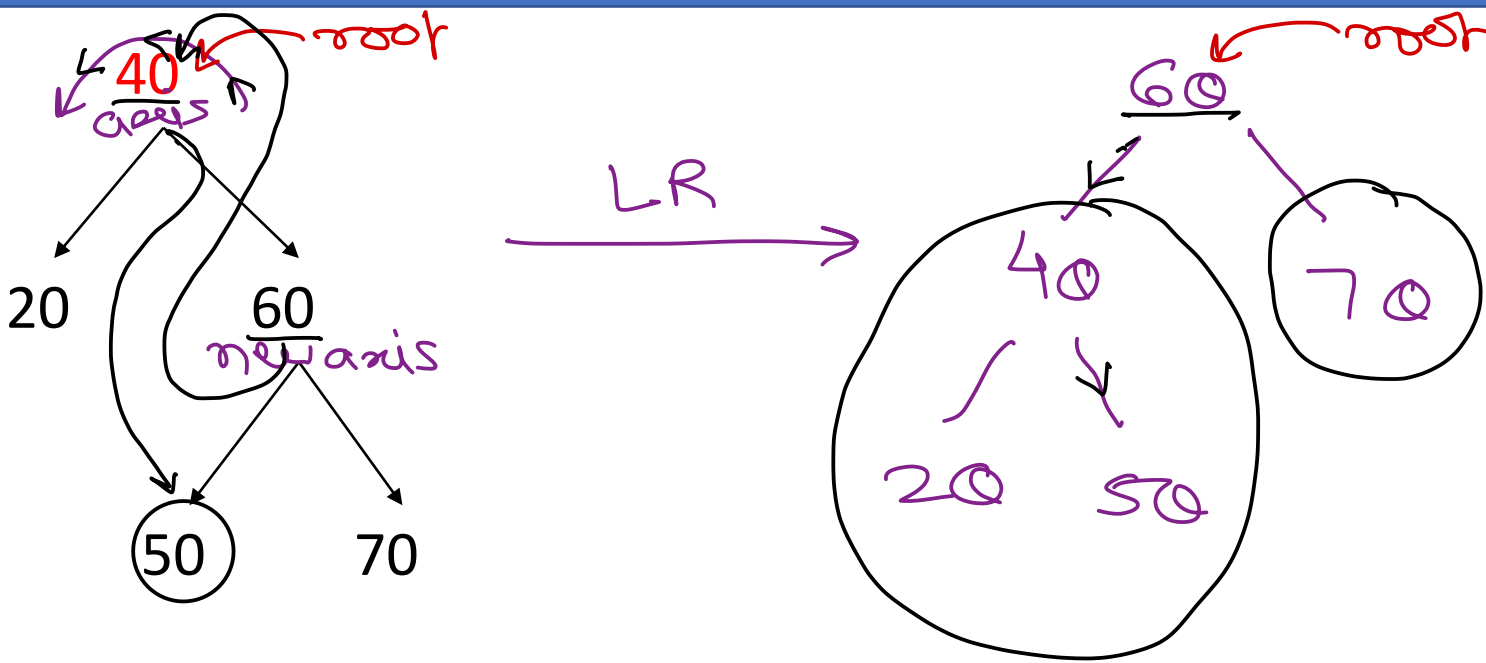
# Right rotation



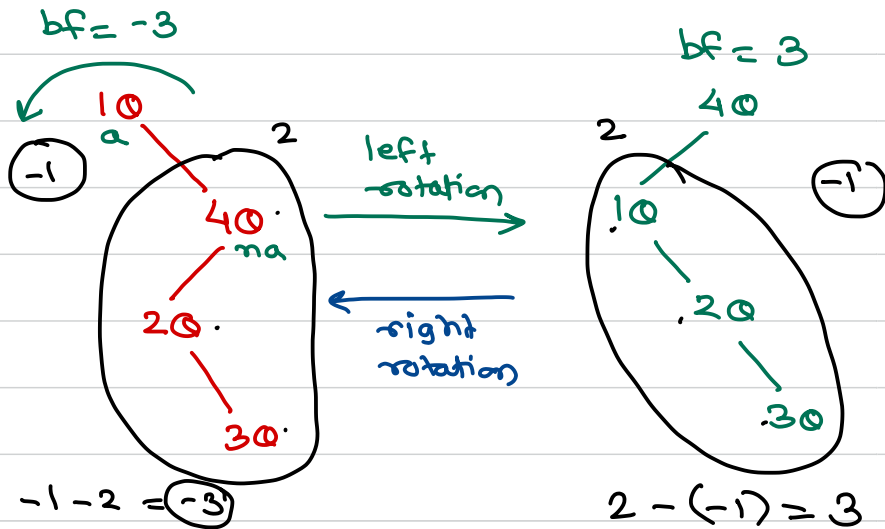
newaxis = axis . left;  
 axis . left = newaxis . right;  
 newaxis . right = axis;  
 if (axis == root)  
     root = new axis;



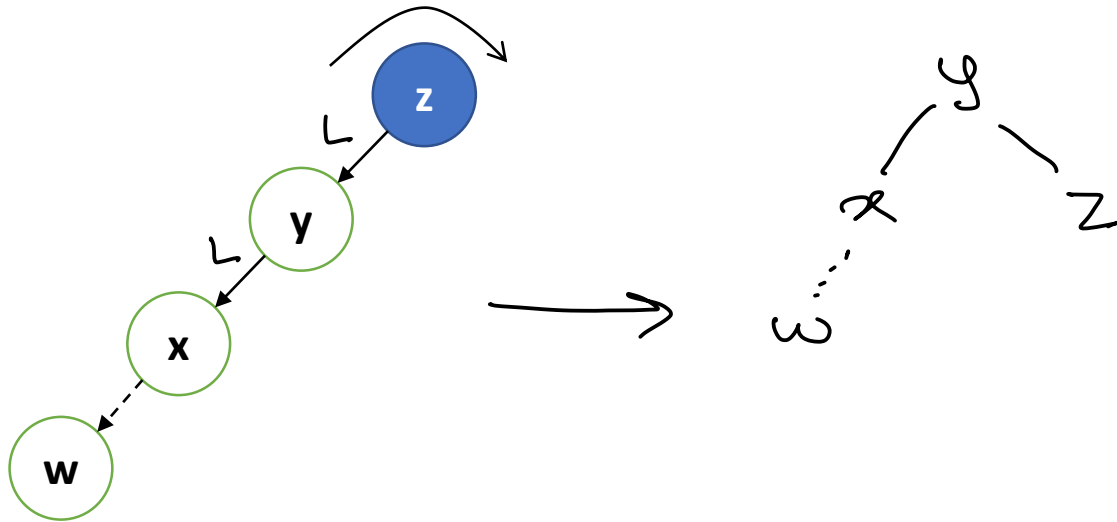
# Left rotation







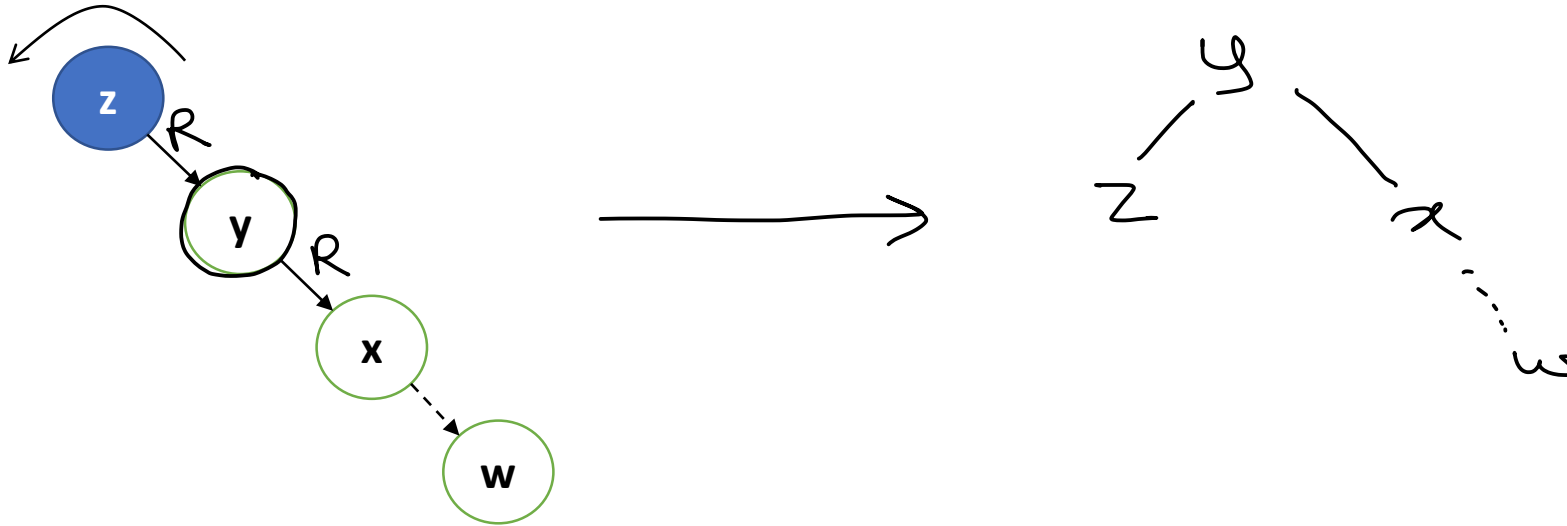
# Rotation cases



Left-Left case



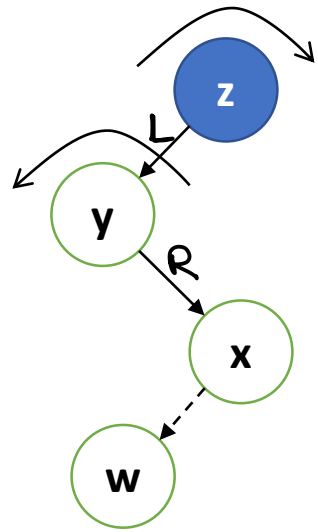
# Rotation cases



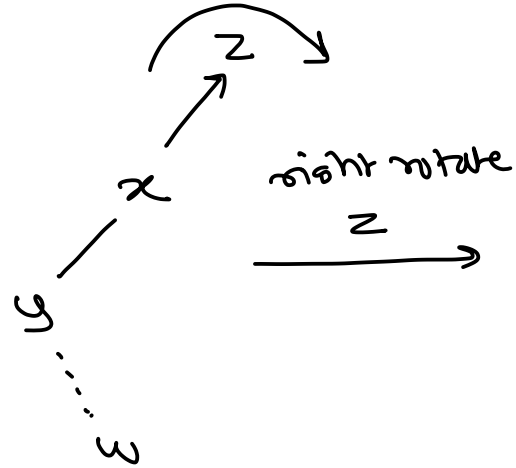
Right-Right case



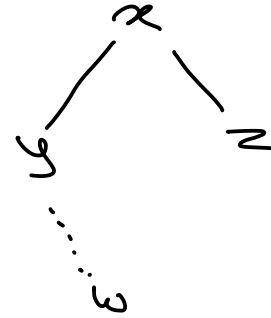
# Rotation cases



left rotate  
y



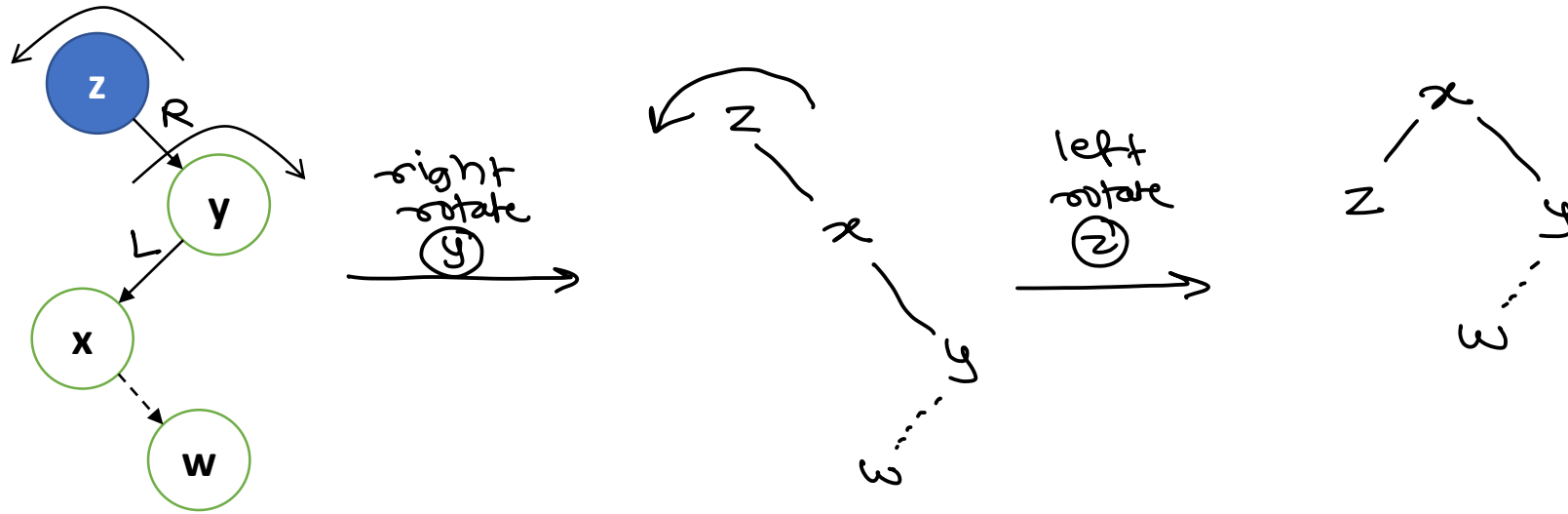
right rotate  
z



Left-Right case

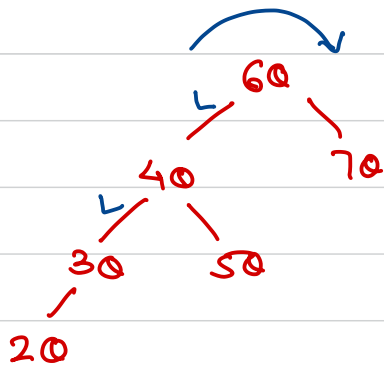
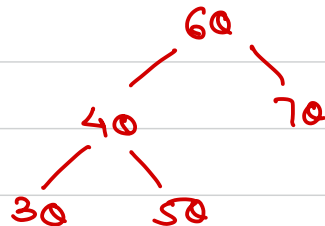
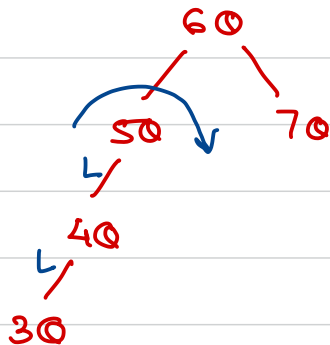
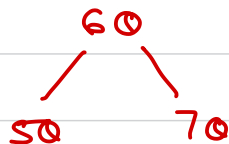
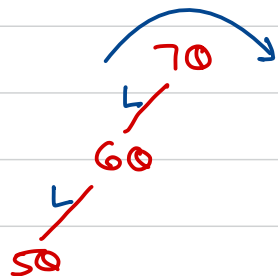


# Rotation cases



Right-Left case





# AVL Tree

- AVL tree is a self-balancing Binary Search Tree (BST).
- The difference between heights of left and right subtrees cannot be more than one for all nodes.
- Most of BST operations are done in  $O(h)$  i.e.  $O(\log n)$  time.
- Nodes are rebalanced on each insert operation and delete operation.
- Need more number of rotations as compared to Red & Black tree.

$$2^h \approx n$$

$$h \log 2 = \log n$$

$$h = \frac{\log n}{\log 2}$$

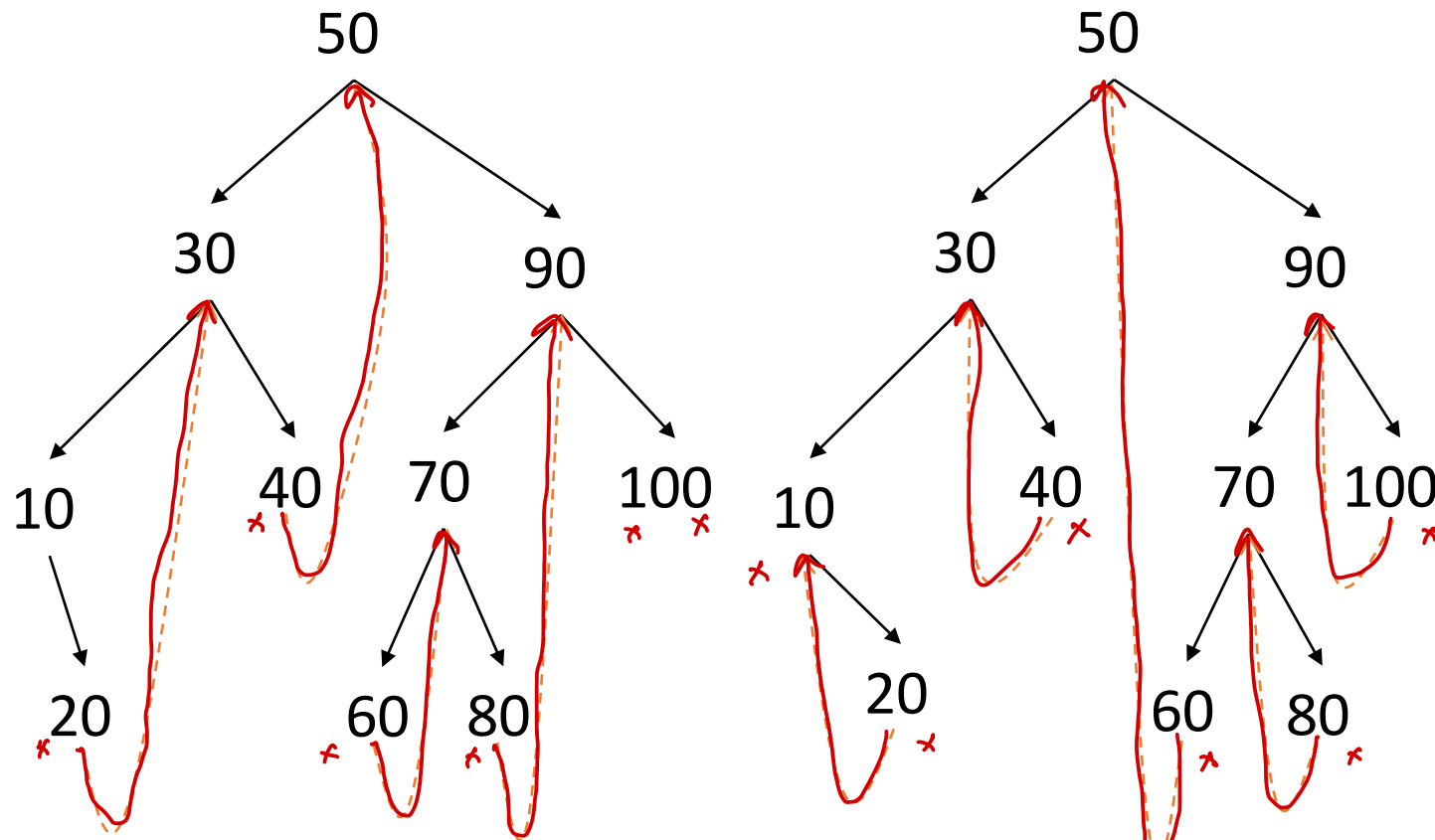
$$T \propto h$$

$$T \propto \frac{\log n}{\log 2}$$

$$\boxed{O(\log n)}$$



# Threaded BST

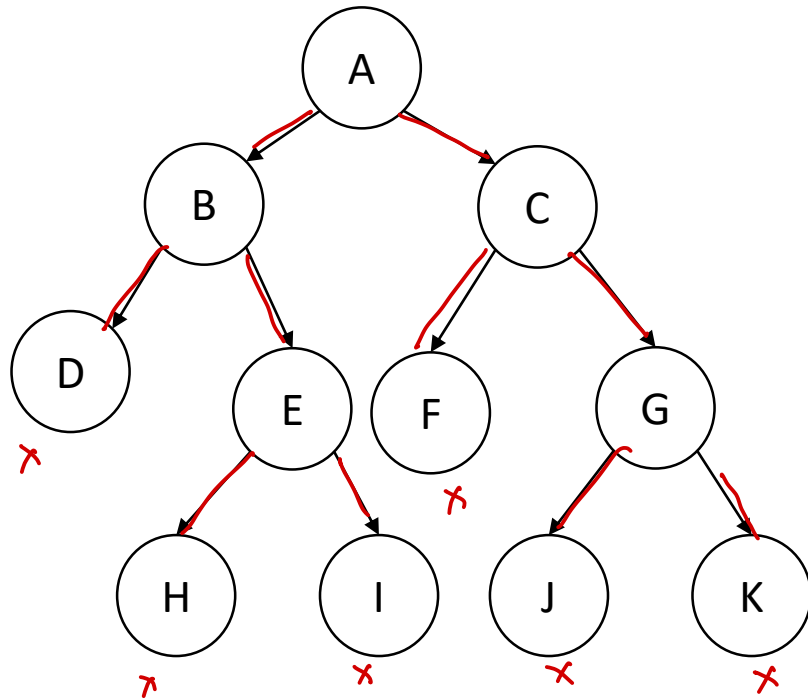


- Typical BST in-order traversal involves recursion or stack. It slows execution and also need more space.
- Threaded BST keep address of in-order successor or predecessor addresses instead of NULL to speed up in-order traversal (using a loop).
- Left threaded BST
- Right threaded BST
- In-threaded BST  
*left + right*



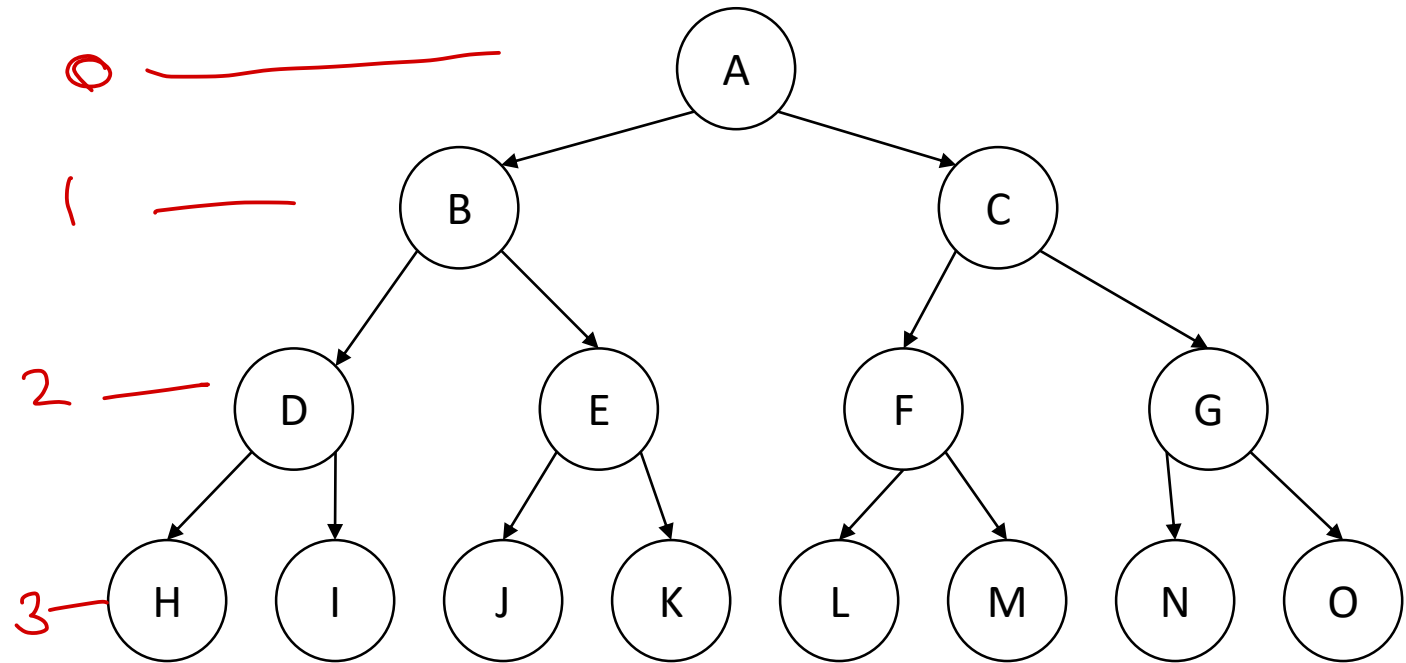


## Strict Binary Tree



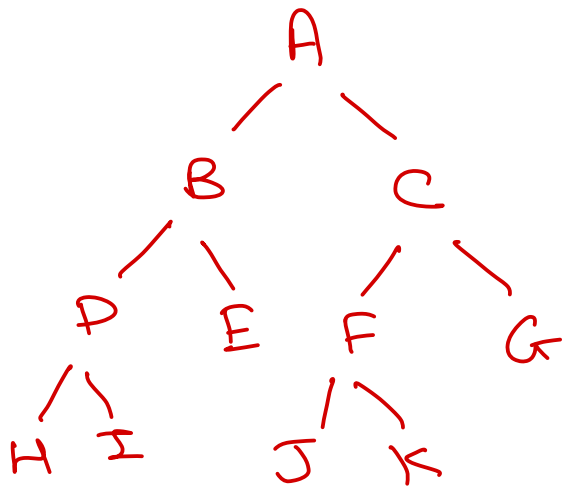
- Binary tree in which each non-leaf node has exactly two child nodes.

## Perfect Binary Tree

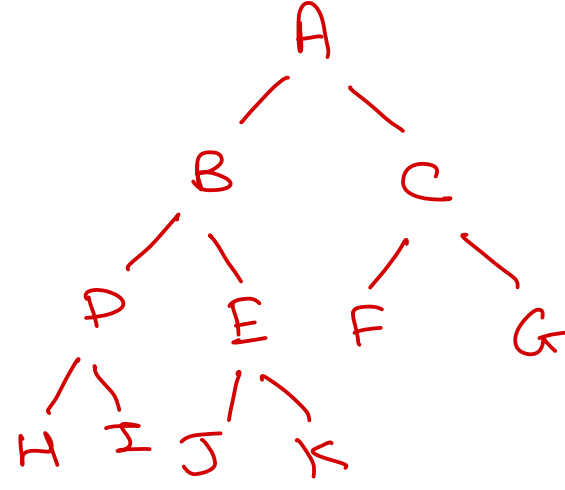


- Binary tree which is full for the given height i.e. contains maximum possible nodes.
- Number of nodes =  ~~$2^n - 1$~~   $2^{h+1} - 1$

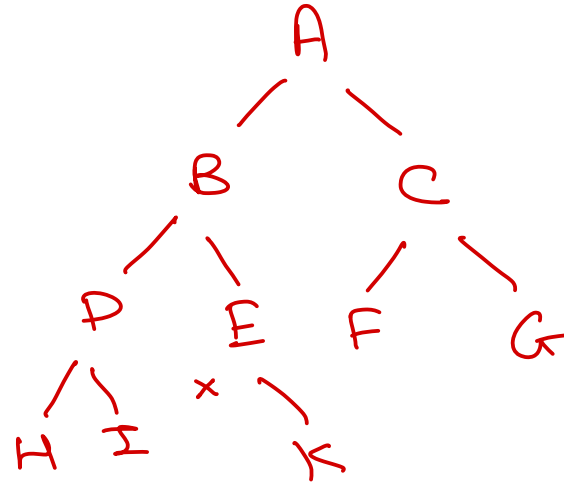




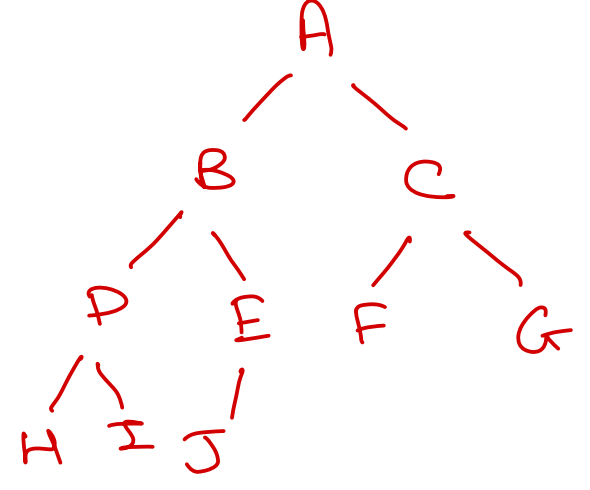
strict



strict  
complete



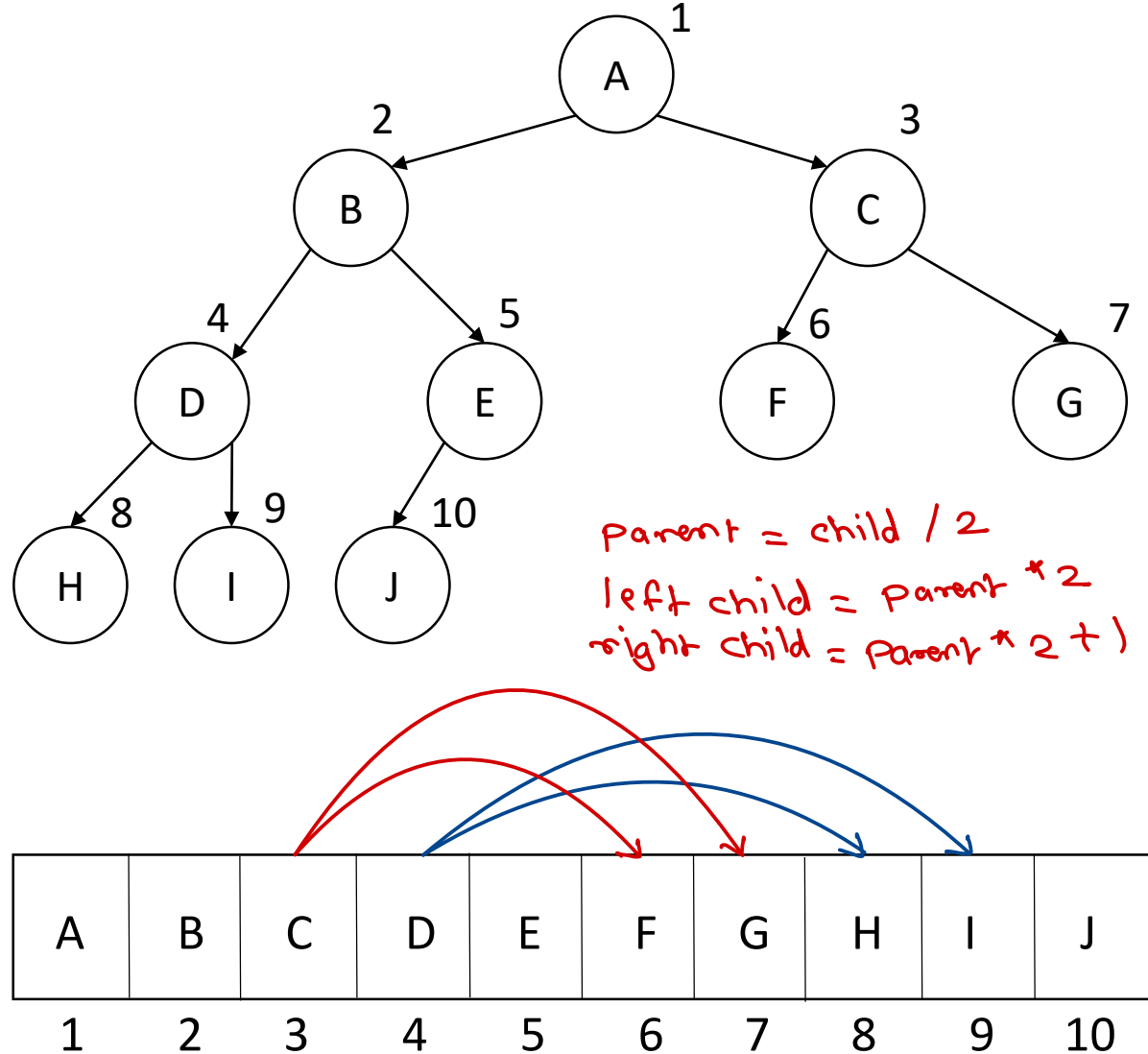
strict X  
complete X  
almost complete X



strict X  
complete ✓  
✓ almost complete



# Complete Binary Tree and Heap

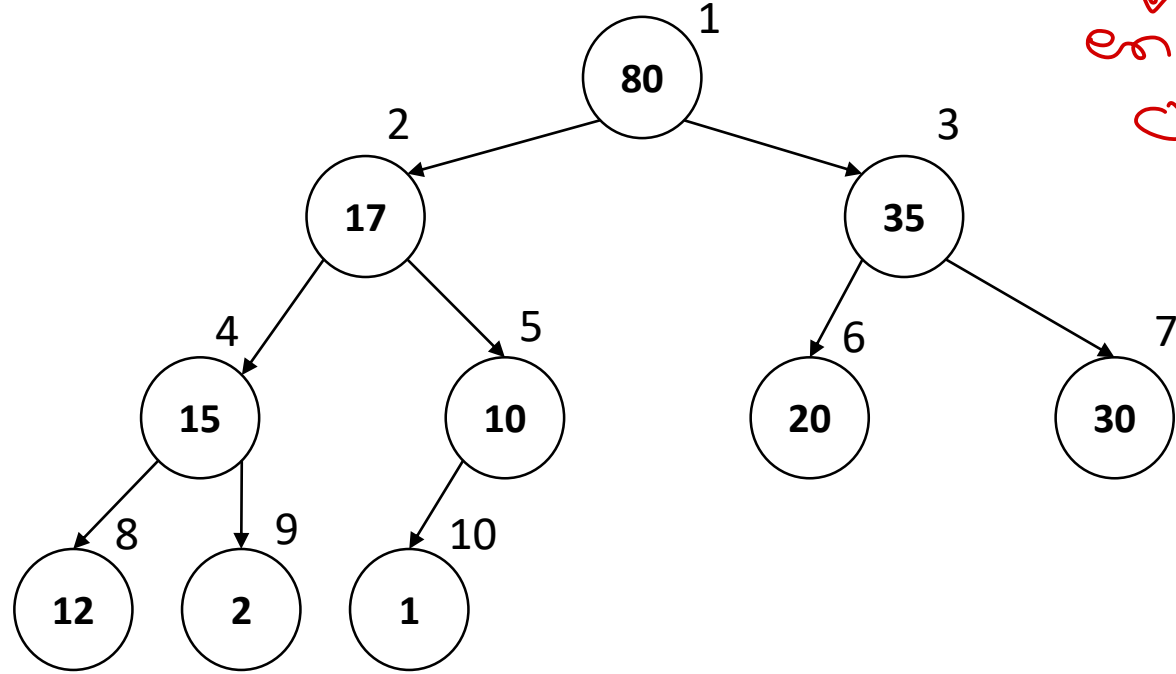


- A complete binary tree (CBT) is a binary tree in which every level, except possibly the last, is completely filled, and all nodes are as far left as possible.
- Almost complete binary tree is similar to CBT, but may not be strictly binary tree.
- Heap is array implementation of complete binary tree.
- Parent child relation is maintained through index calculations
  - parent index = child index / 2
  - left child index = parent index \* 2
  - right child index = parent index \* 2 + 1

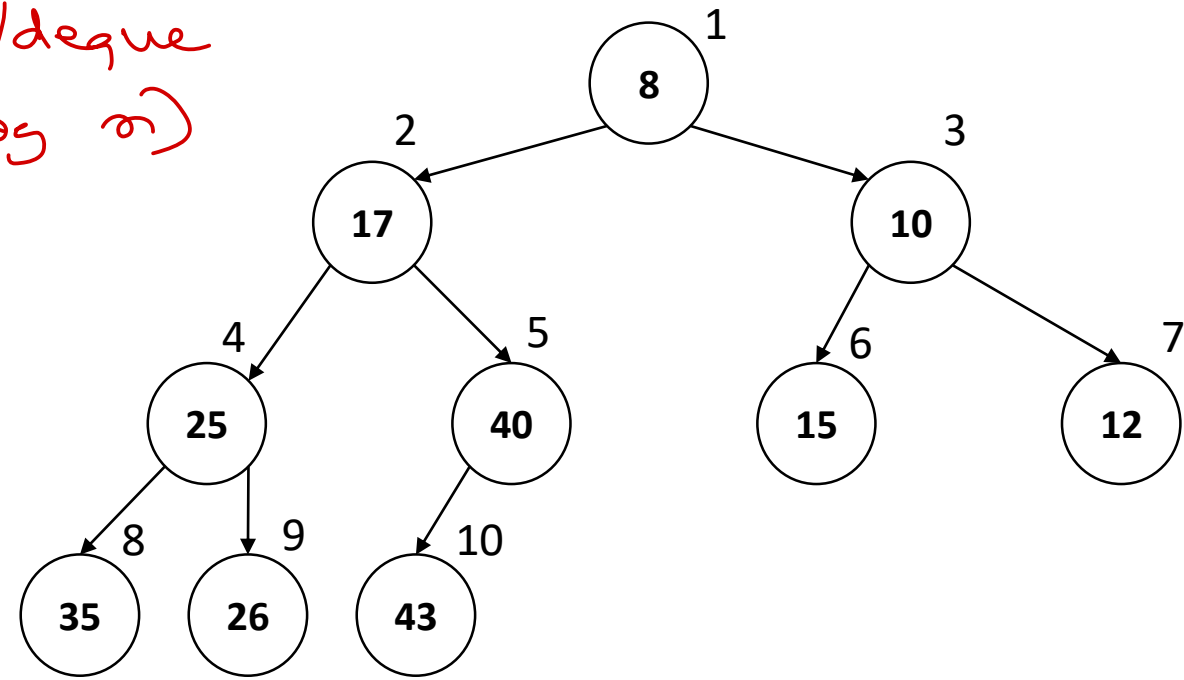


# Max Heap & Min Heap → used to implement priority queues.

enqueue/dequeue  
 $O(\log n)$



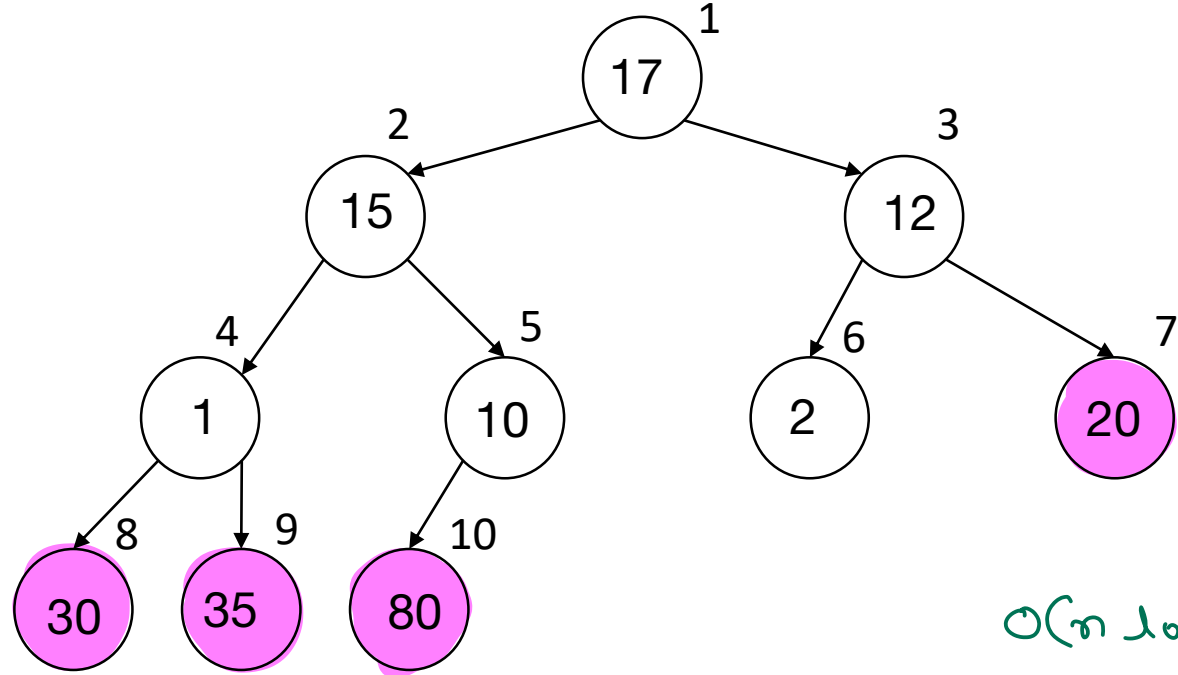
- Max heap is a heap data structure in which each node is greater than both of its child nodes.



- <sup>Min</sup>~~Max~~ heap is a heap data structure in which each node is smaller than both of its child nodes.



# Heap Sort

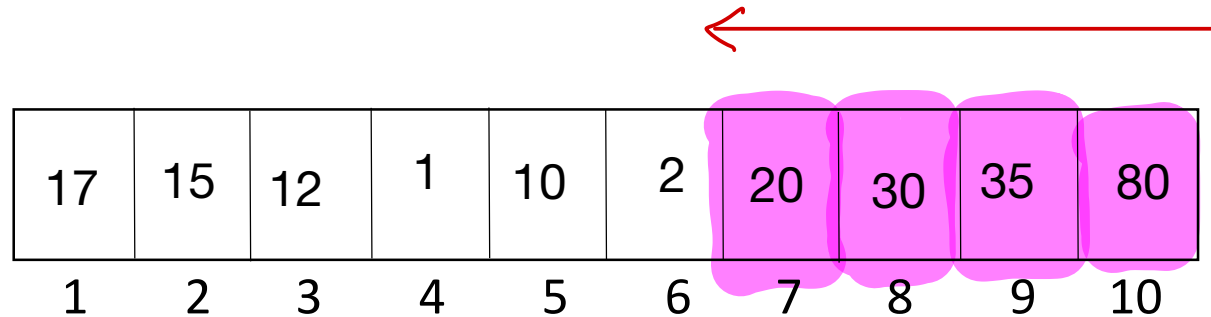


Heap Sort  $\rightarrow O(n \log n)$

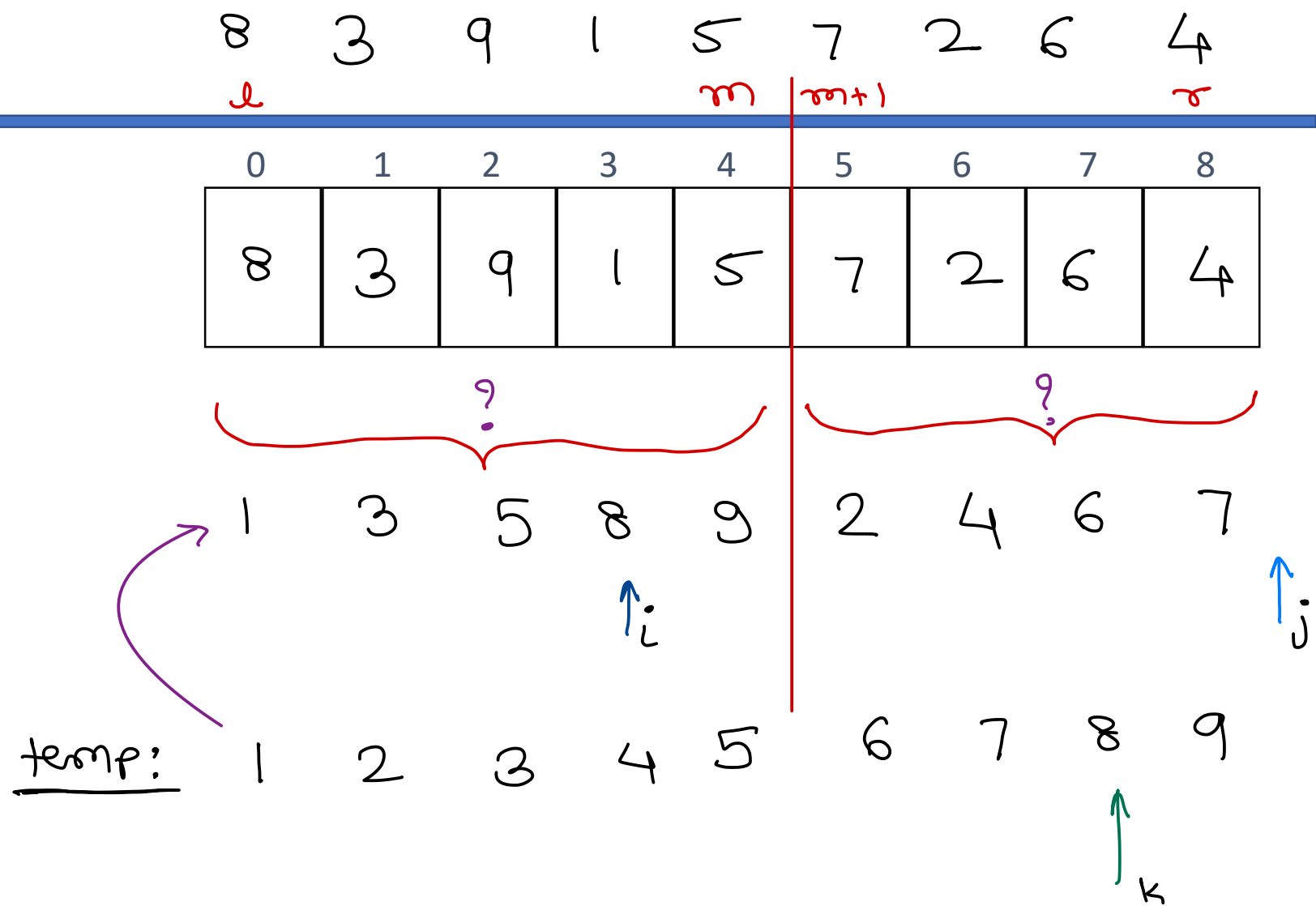
① make max heap;  $\rightarrow O(n \log n)$

② while (heap is not empty)  
{  
    del ele from heap;  $\rightarrow O(\log n)$   
    put val at end;  
}

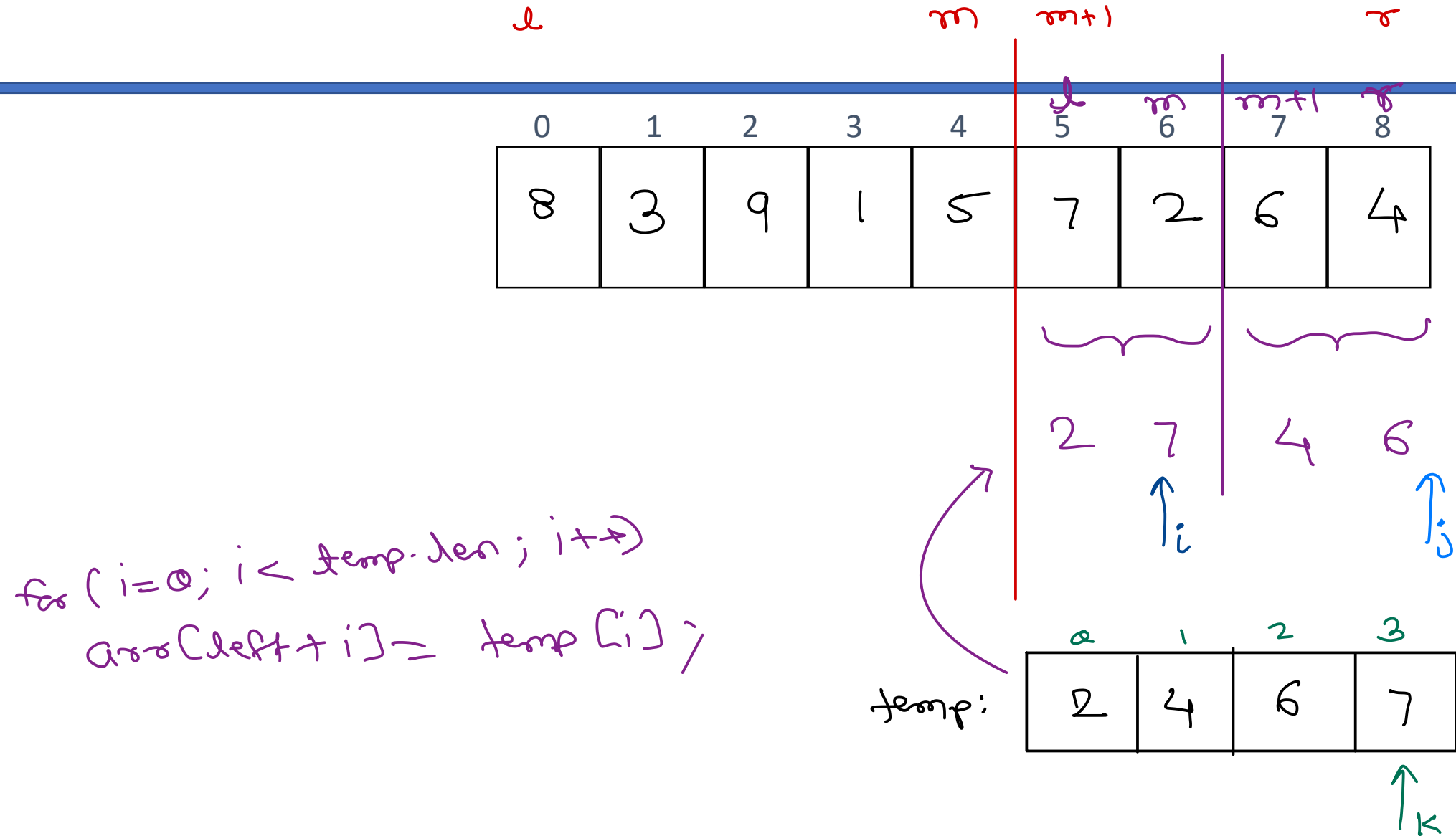
$O(n \log n)$



# Merge Sort

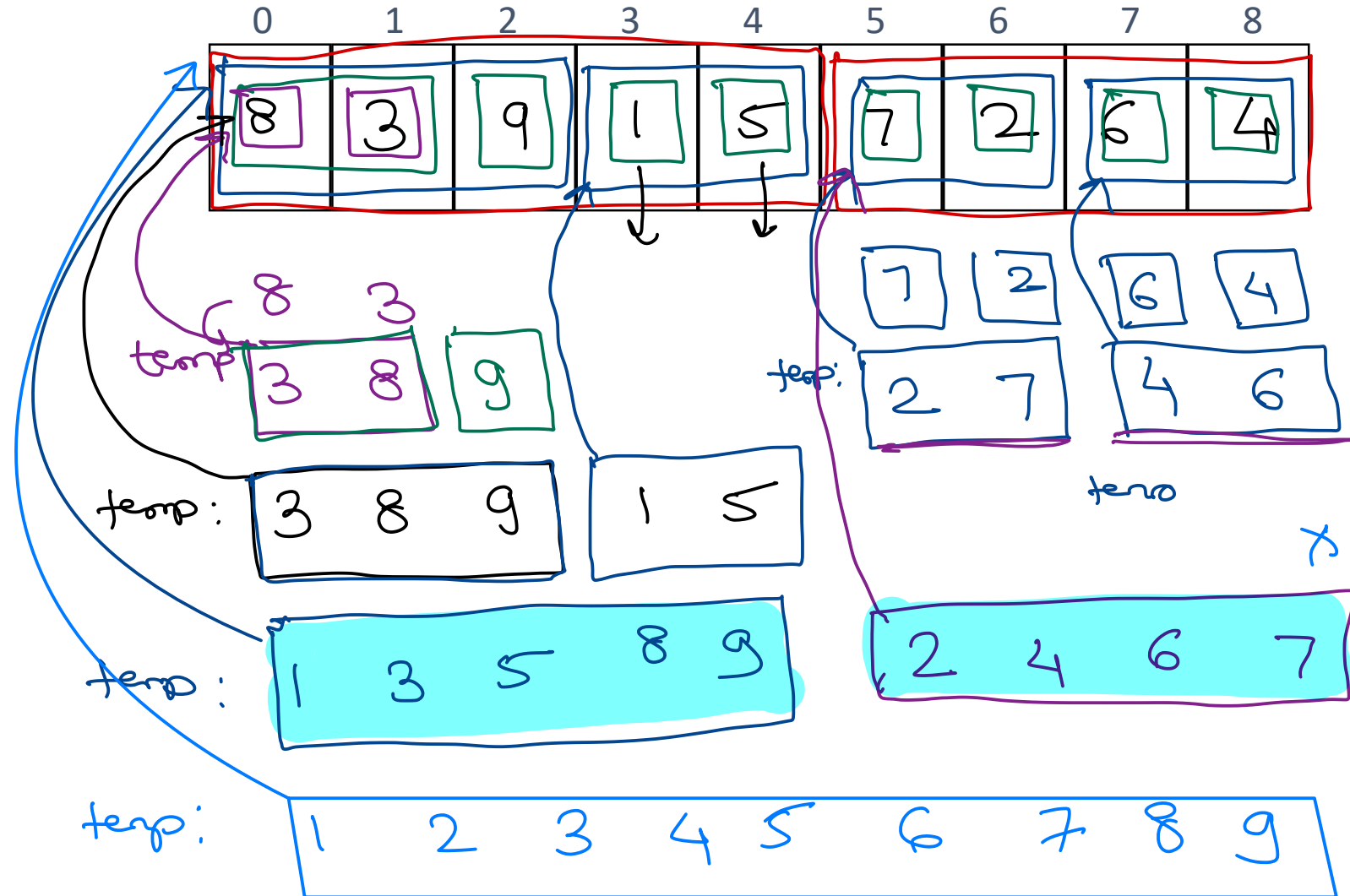


# Merge Sort



# Merge Sort

$l=0$   $m=4$   $r=8$







*Thank you!*

Nilesh Ghule <nilesh@sunbeaminfo.com>

