

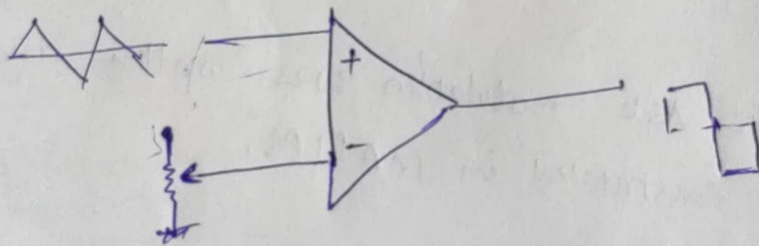
Aim:- To develop a MATLAB program for pulse width modulation of given message of a given message signals.

Tools - MATLAB R2021b.

Theory - PWM uses digital signal to control power application. Digital system don't generally generate as much heat. Almost all the heat generated by a switching device is duration the transition which is quickly done. while the device is neither on or off. but in b/w. This is because power follows this formula

$$P = \text{Voltage} * \text{Current}$$

If either of voltage or current tends to zero, power will approach zero.



### Procedure

- ① A sinusoidal message signal was taken of freq. 20 Hz and amplitude equal to 1V.
- ② for the carrier, a sawtooth signal of  $f=40\text{ Hz}$  and amplitude 3V was generated.
- ③ The carrier signal decides the sampling rate of PWM and hence freq. was taken at least twice



of message frequency.

- 4) A total of 1000 time values were taken 0 to 1 in step of 0.0001.
- 5) `sawtooth()` and `sine()` function were used to generate the samples and message signals respectively.
- 6) Now, PWM logic must be logic high when the value of the message exceeds that of the carrier, otherwise zero.
- 7) Using this logic and a 'pwm' variable the required values of the PWM wave were obtained.
- 8) Finally, the three signals (sinusoidal message, sawtooth carrier, resultant PWM waveform) were successfully plotted using `plot()` function.

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Result - The MATLAB program for PWM was developed and the plots were obtained successfully.

```

clc;
close all;
t = 0:0.001:1;
fc = input( 'Enter the Frequency of Carrier Signal (Sawtooth) = ' );
fm = input( 'Enter the Frequency of Message Signal (Sinusoidal) = ' );
a = input( 'Enter the Amplitude of Carrier Signal = ' );
b = input( 'Enter the Amplitude of Message Signal(should be < Carrier)=');
vc = a.*sawtooth(2*pi*fc*t);
vm = b.*sin(2*pi*fm*t);
n = length(vc);
for i = 1:n
    if (vm(i)>=vc(i))
        pwm(i) = 1;
    else
        pwm(i) = 0;
    end
end

% Representation of the Message Signal
subplot(3,1,1);
plot(t,vm, 'black' );
xlabel( 'Time ----->' );
ylabel( 'Amplitude ----->' );
title( 'Message Signal' );
legend( 'Message Signal ----->' );
grid on ;

% Representation of the Carrier Signal
subplot(3,1,2);
plot(t,vc);
xlabel( 'Sample ----->' );
ylabel( 'Amplitude ----->' );
title( 'Carrier Signal' );
legend( 'Carrier Signal ----->' );
grid on ;

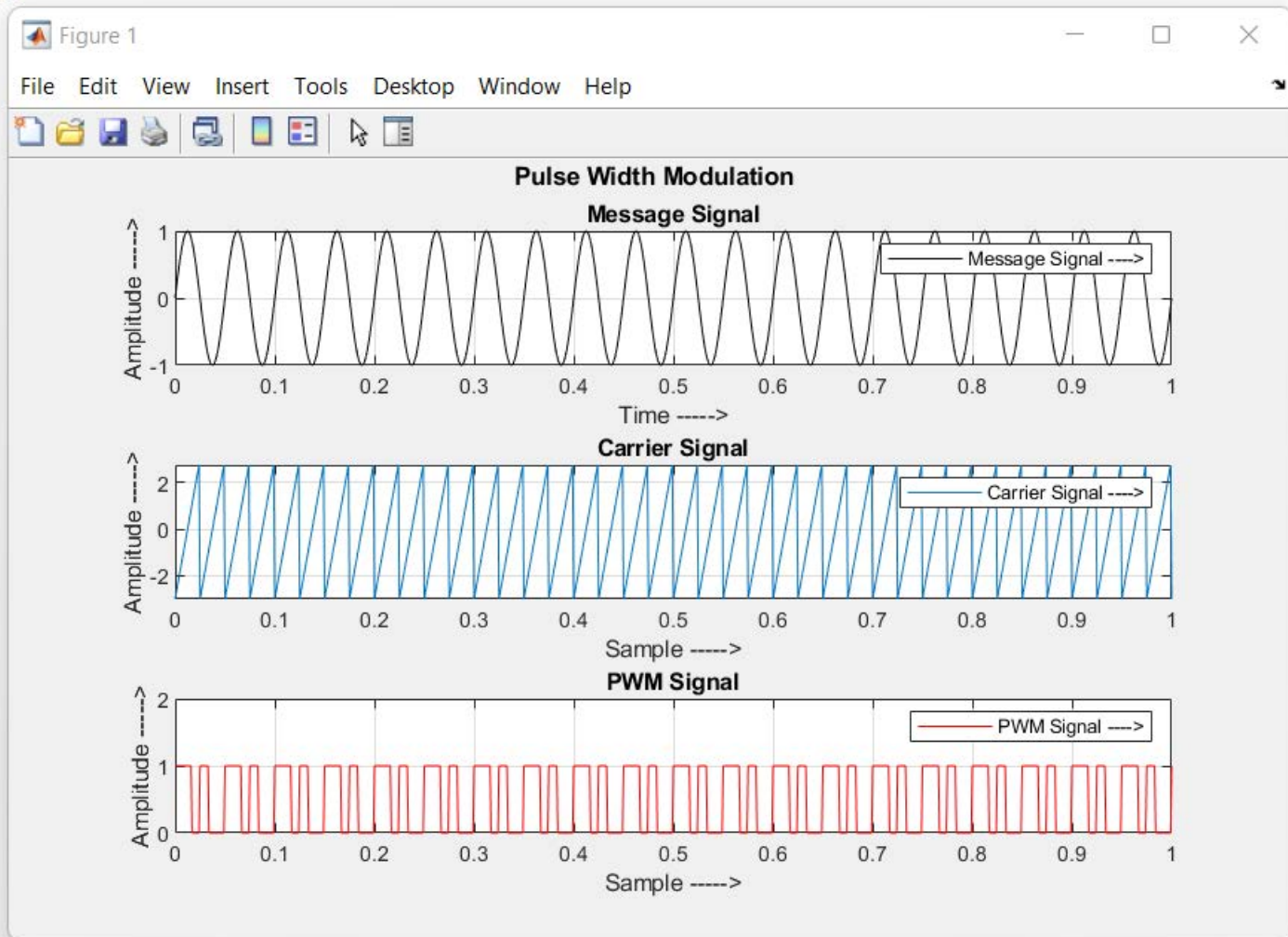
% Representation of the PWM Signal
subplot(3,1,3);
plot(t,pwm, 'red' );
xlabel( 'Sample ----->' );
ylabel( 'Amplitude ----->' );
title( 'PWM Signal' );
legend( 'PWM Signal ----->' );
axis([0 1 0 2]);
grid on ;

% Add title to the Overall Plot
ha = axes ( 'Position' ,[0 0 1 1], 'Xlim' ,[0 1], 'Ylim' ,[0 1], 'Box' , 'off' ,
'Visible' , 'off' , 'Units' , 'normalized' , 'clipping' , 'off' );
text (0.5, 1, '\bf Pulse Width Modulation' , 'HorizontalAlignment' , 'center' ,
'VerticalAlignment' , 'top' )

```

```
Enter the Frequency of Carrier Signal (Sawtooth) = 40
Enter the Frequency of Message Signal (Sinusoidal) = 20
Enter the Amplitude of Carrier Signal = 3
Enter the Amplitude of Message Signal(should be < Carrier)=1
```

*fx* >>







### Pulse Width Modulation

