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**Supplementary Material for A Guide to
Pre-processing High-Frequency Animal
Tracking Data**

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31 1 Validating the Residence Patch Method with 32 Calibration Data

33 Here we show how the residence patch method (Barraquand and Benhamou 2008; Bijleveld et al. 2016;
34 Oudman et al. 2018) accurately estimates the duration of known stops in a track collected as part of a
35 calibration exercise in the Wadden Sea.

36 1.1 Outline of Cleaning Steps

37 We began by visualising the data to check for location errors, and found a single outlier position approx. 15km away from the study area (Fig. 1.1, 1.2; main text Fig. 7.a). This outlier was removed
38 by filtering data by the X coordinate bounds using the function `atl_filter\bounds`; X coordinate
39 bounds $\leq 645,000$ in the UTM 31N coordinate reference system were removed ($n = 1$; remaining positions
40 = 50,815; Fig. 1.2). We then calculated the incoming and outgoing speed, as well as the turning
41 angle at each position using the functions `atl_get_speed` and `atl_turning_angle` respectively, as a
42 precursor to targeting large-scale location errors in the form of point outliers. We used the function
43 `atl_filter_covariates` to remove positions with incoming and outgoing speeds \geq the speed thresh-
44 old of 15 m/s ($n = 13,491$, 26.5%; remaining positions = 37,324, 73.5%; Fig. 1.3; main text Fig. 7.b).
45 This speed threshold was chosen as 5 m/s faster than the known boat speed, 10 m/s. Finally, we targeted
46 small-scale location errors by applying a median smooth with a moving window size $K = 5$ using the
47 function `atl_median_smooth` (Fig. 1.4; main text Fig. 7.c). Smoothing did not reduce the number of
48 positions. We thinned the data to a 30 second interval leaving 1,803 positions (4.8% positions of the
49 smoothed track)

51 1.2 Prepare libraries

52 First we prepare the libraries we need. Libraries can be installed from CRAN if necessary.

```
# load libs
library(data.table)
library(atlastools)
library(ggplot2)
library(patchwork)

pal <- RColorBrewer::brewer.pal(5, "Set1")
pal[3] <- "seagreen"
pal[2] <- RColorBrewer::brewer.pal(5, "Blues")[5]
```

53 1.3 Access data and preliminary visualisation

54 First we access the data from a local file using the `data.table` package (Dowle and Srinivasan 2020).
55 We then visualise the raw data.

```
# read and plot example data
data <- fread("data/atlas1060_allTrials_annotated.csv")
data_raw <- copy(data)
```

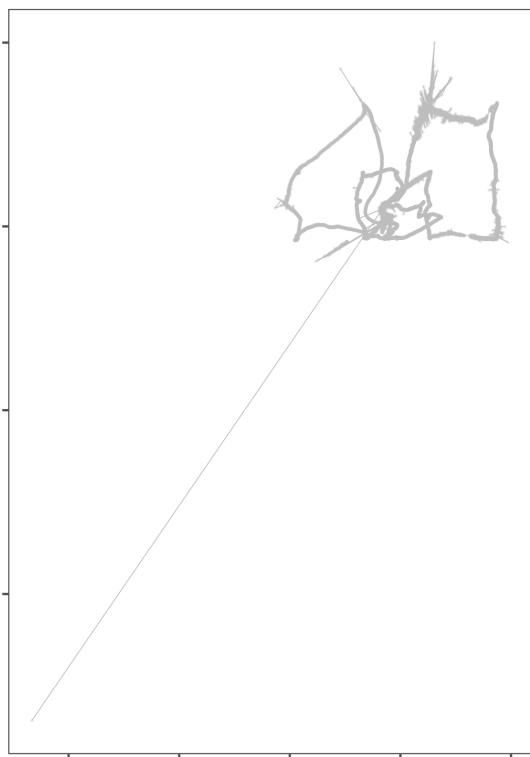


Figure 1.1: The raw data from a calibration exercise conducted around the island of Griend in the Dutch Wadden Sea. A handheld WATLAS tag was used to examine how ATLAS data compared to GPS tracks, and we use the WATLAS data here to demonstrate the basics of the pre-processing pipeline, as well as validate the residence patch method. It is immediately clear from the figure that the track shows location errors, both in the form of point outliers as well as small-scale errors around the true location.

56 1.4 Filter by bounding box

57 We first save a copy of the data, so that we can plot the raw data with the cleaned data plotted over it for
58 comparison.

```
# make a copy using the data.table copy function
data_unproc <- copy(data)
```

59 We then filter by a bounding box in order to remove the point outlier to the far south east of the main
60 track. We use the atl_filter_bounds functions using the x_range argument, to which we pass the
61 limit in the UTM 31N coordinate reference system. This limit is used to exclude all points with an X
62 coordinate < 645,000.

63 We then plot the result of filtering, with the excluded point in black, and the points that are retained in
64 green.

```
# remove inside must be set to FALSE
data <- atl_filter_bounds(
  data = data,
  x = "x", y = "y",
  x_range = c(645000, max(data$x)),
  remove_inside = FALSE
)
```

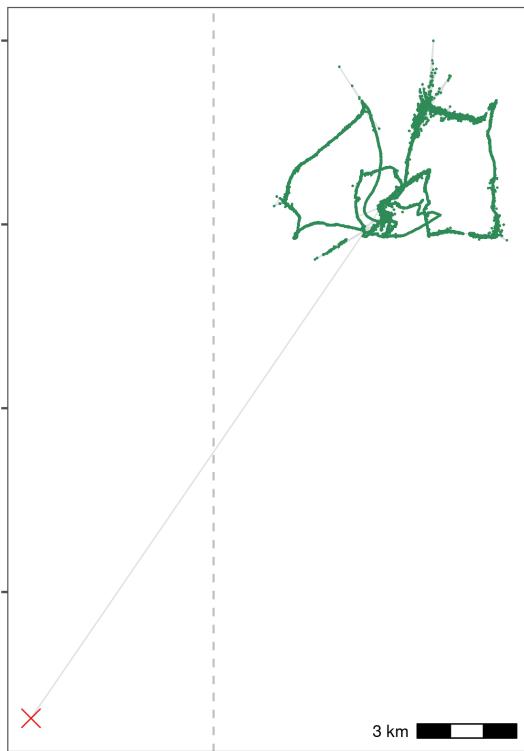


Figure 1.2: Removal of a point outlier using the function atl_filter_bounds. The point outlier (black point) is removed based on its X coordinate value, with the data filtered to exclude positions with an X coordinate < 645,000 in the UTM 31N system. Positions that are retained are shown in green.

65 **1.5 Filter trajectories**

66 **1.5.1 Handle time**

67 Time in ATLAS tracking is counted in milliseconds and is represented by a 64-bit integer (type `long`),
68 which is not natively supported in R; it will instead be converted to a `numeric`, or `double`.

69 This is not what is intended, but it works. The `bit64` package can help handle 64-bit integers if you want
70 to keep to intended type.

71 A further issue is that 64-bit integers (whether represented as `bit64` or `double`) do not yield meaningful
72 results when you try to convert them to a date-time object, such as of the class `POSIXct`.

73 This is because `as.POSIXct` fails when trying to work with 64-bit integers (it cannot interpret this type),
74 and returns a date many thousands of years in the future (approx. 52,000 CE) if the time column is
75 converted to `numeric`.

76 There are two possible solutions. The parsimonious one is to convert the 64-bit number to a 32-bit short
77 integer (dividing by 1000), or to use the `nanotime` package.

78 The conversion method loses an imperceptible amount of precision. The `nanotime` requires installing
79 another package. The first method is shown here.

80 In the spirit of not destroying data, we create a second lower-case column called `time`.

```
# divide by 1000, convert to integer, then convert to POSIXct
data[, time := as.integer(TIME / 1000)]
```

81 **1.5.2 Add speed and turning angle**

```
# add incoming and outgoing speed
data[, `:=`(
  speed_in = atl_get_speed(data,
    x = "x",
    y = "y",
    time = "time"
  ),
  speed_out = atl_get_speed(data, type = "out")
)]

# add turning angle
data[, angle := atl_turning_angle(data = data)]
```

82 **1.5.3 Get 95th percentile of speed and angle**

```
# use sapply
speed_angle_thresholds <-
  sapply(data[, list(speed_in, speed_out, angle)],
    quantile,
    probs = 0.9, na.rm = T
  )
```

83 **1.5.4 Filter on speed**

84 Here we use a speed threshold of 15 m/s, the fastest known boat speed. We then plot the data with the
85 extreme speeds shown in grey, and the positions retained shown in green.

```
# make a copy
data_unproc <- copy(data)

# remove speed outliers
```

```

data <- atl_filter_covariates(
  data = data,
  filters = c("(speed_in < 15 & speed_out < 15)")
)

# recalculate speed and angle
data[, `:=`(
  speed_in = atl_get_speed(data,
    x = "x",
    y = "y",
    time = "time"
  ),
  speed_out = atl_get_speed(data, type = "out")
)]
```

add turning angle

```
data[, angle := atl_turning_angle(data = data)]
```



Figure 1.3: Improving data quality by filtering out positions that would require unrealistic movement. We removed positions with speeds ≥ 15 m/s, which is the fastest possible speed in this calibration data, part of which was collected in a moving boat around Griend. Grey positions are removed, while green positions are retained. Rectangles indicate areas expanded for visualisation in following figures.

86 1.6 Smoothing the trajectory

87 We then apply a median smooth over a moving window ($K = 5$). This function modifies in place, and
88 does not need to be assigned to a new variable. We create a copy of the data before applying the smooth
89 so that we can compare the data before and after smoothing.

```
# apply a 5 point median smooth, first make a copy
data_unproc <- copy(data)

# now apply the smooth
atl_median_smooth(
  data = data,
  x = "x", y = "y", time = "time",
  moving_window = 5
)
```

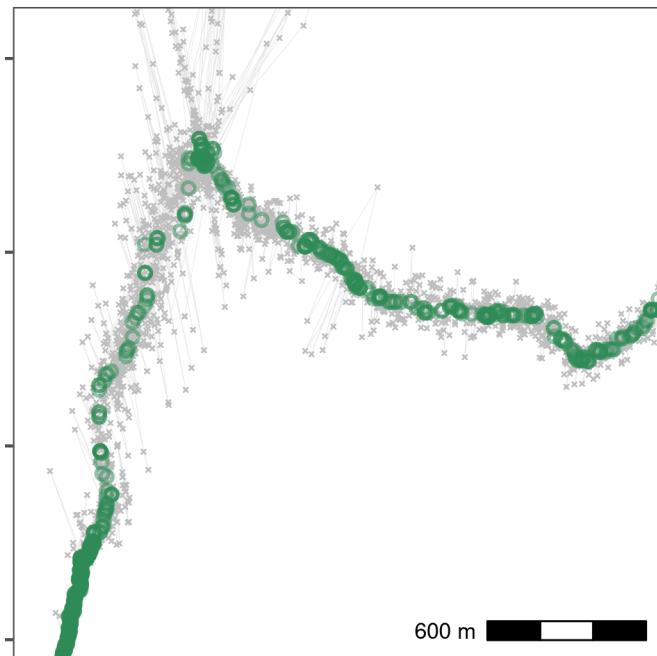


Figure 1.4: Reducing small-scale location error using a median smooth with a moving window $K = 5$. Median smoothed positions are shown in green, while raw, unfiltered data is shown in grey. Median smoothing successfully recovers the likely path of the track without a loss of data. The area shown is the upper rectangle from Fig. 1.3.

90 1.7 Thinning the data

91 Next we thin the data to demonstrate thinning by median smoothing. Following this, we plot the median
92 smooth and thinning by aggregation.

```
# save a copy
data_unproc <- copy(data)

# remove columns we don't need
data <- data[, setdiff(
  colnames(data),
  c("tID", "Timestamp", "id", "TIME", "UTCtime")
),
with = FALSE
```

```

]
# thin to a 30s interval
data_thin <- atl_thin_data(
  data = data,
  interval = 30,
  method = "aggregate",
  id_columns = "TAG"
)

```

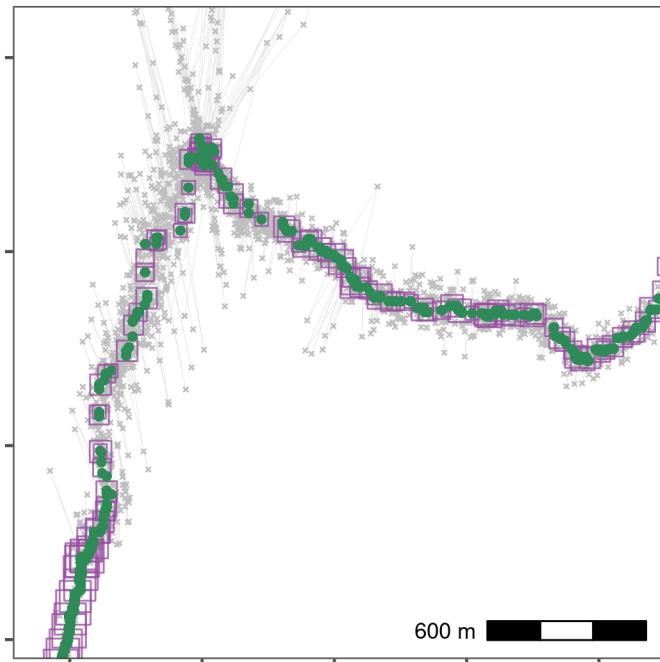


Figure 1.5: Thinning by aggregation over a 30 second interval (down from 1 second) preserves track structure while reducing the data volume for computation. Here, thinned positions are shown as purple squares, with the size of the square indicating the number of positions within the 30 second bin used to obtain the average position. Green points show the median smoothed data from Fig. 1.4, while the raw data are shown in grey. The area shown is the upper rectangle in Fig. 1.3.

93 1.8 Residence patches

94 1.8.1 Get waypoint centroids

95 We subset the annotated calibration data to select the waypoints and the positions around them which are
 96 supposed to be the locations of known stops. Since each stop was supposed to be 5 minutes long, there
 97 are multiple points in each known stop.

```

library(stringi)
data_res <- data_unproc[stri_detect(tID, regex = "(WP"))]

From this data, we get the centroid of known stops, and determine the time difference between the first
and last point within 50 metres, and within 10 minutes of the waypoint positions' median time.

Essentially, this means that the maximum duration of a stop can be 20 minutes, and stops above this
duration are not expected.

# get centroid
data_res_summary <- data_res[, list(

```

```

    x_median = median(x),
    y_median = median(y),
    t_median = median(time)
),
by = "tID"
]

# now get times 10 mins before and after
data_res_summary[, `:=`(
  t_min = t_median - (10 * 60),
  t_max = t_median + (10 * 60)
)]
```

make a list of positions 10min before and after

```

wp_data <- mapply(function(l, u, mx, my) {
  tmp_data <- data_unproc[inrange(time, l, u)]
  tmp_data[, distance := sqrt((mx - x)^2 + (my - y)^2)]

  # keep within 50
  tmp_data <- tmp_data[distance <= 50, ]

  # get duration
  return(diff(range(tmp_data$time)))
}, data_res_summary$t_min, data_res_summary$t_max,
data_res_summary$x_median, data_res_summary$y_median,
SIMPLIFY = TRUE
)
```

102 1.8.2 Prepare data

- 103 An indicator of individual residence at or near a position can be useful when attempting to identify
 104 residence patches. Positions can be filtered on a metric such as residence time (Bracis, Bildstein, and
 105 Mueller 2018).

106 1.8.3 Calculate residence time

- 107 First we calculate the residence time with a radius of 50 metres. For this, we need a dataframe with
 108 coordinates, the timestamp, and the animal id. We save this data to file for later use.

```

# load recurse
library(recurse)

# get 4 column data
data_for_patch <- data_thin[, list(x, y, time, TAG)]

# get recurse data for a 10m radius
recurse_stats <- getRecursions(data_for_patch,
  radius = 50, timeunits = "mins"
)

# assign to recurse data
data_for_patch[, res_time := recurse_stats$residenceTime]

# save recurse data
fwrite(data_for_patch, file = "data/data_calib_for_patch.csv")
```

109 1.8.4 Run residence patch method

110 We subset data with a residence time > 5 minutes in order to construct residence patches. From this subset,
111 we construct residence patches using the parameters: `buffer_radius = 5 metres`, `lim_spat_indep =`
112 `50 metres`, `lim_time_indep = 5 minutes`, and `min_fixes = 3`.

```
# assign id as tag
data_for_patch[, id := as.character(TAG)]

# on known residence points
patch_res_known <- atl_res_patch(data_for_patch[res_time >= 5, ],
  buffer_radius = 5,
  lim_spat_indep = 50,
  lim_time_indep = 5,
  min_fixes = 3
)
```

113 1.8.5 Get spatial and summary objects

114 We get spatial and summary output of the residence patch method using the `atl_patch_summary` function
115 using the options `which_data = "spatial"` and `which_data = "summary"`. We use a buffer radius here
116 of 20 metres for the spatial buffer, despite using a buffer radius of 5 metres earlier, simply because it is
117 easier to visualise in the output figure.

```
# for the known and unknown patches
patch_sf_data <- atl_patch_summary(patch_res_known,
  which_data = "spatial",
  buffer_radius = 20
)

# assign crs
sf::st_crs(patch_sf_data) <- 32631

# get summary data
patch_summary_data <- atl_patch_summary(patch_res_known,
  which_data = "summary"
)
```

118 1.8.6 Prepare to plot data

119 We read in the island's shapefile to plot it as a background for the residence patch figure.

```
# read griend and hut
griend <- sf::st_read("data/griend_polygon/griend_polygon.shp")
hut <- sf::st_read("data/griend_hut.gpkg")
```

120 1.9 Compare patch metrics

121 We then merge the annotated, known stop data with the calculated patch duration. We filter this data to
122 exclude one exceedingly long outlier of about an hour (WP080), which how

```
# get known patch summary
data_res <- data_unproc[stringi::stri_detect(tID, regex = "(WP)"), ]

# get waypoint summary
patch_summary_real <- data_res[, list(
  nfixes_real = .N,
  x_median = round(median(x), digits = -2),
```

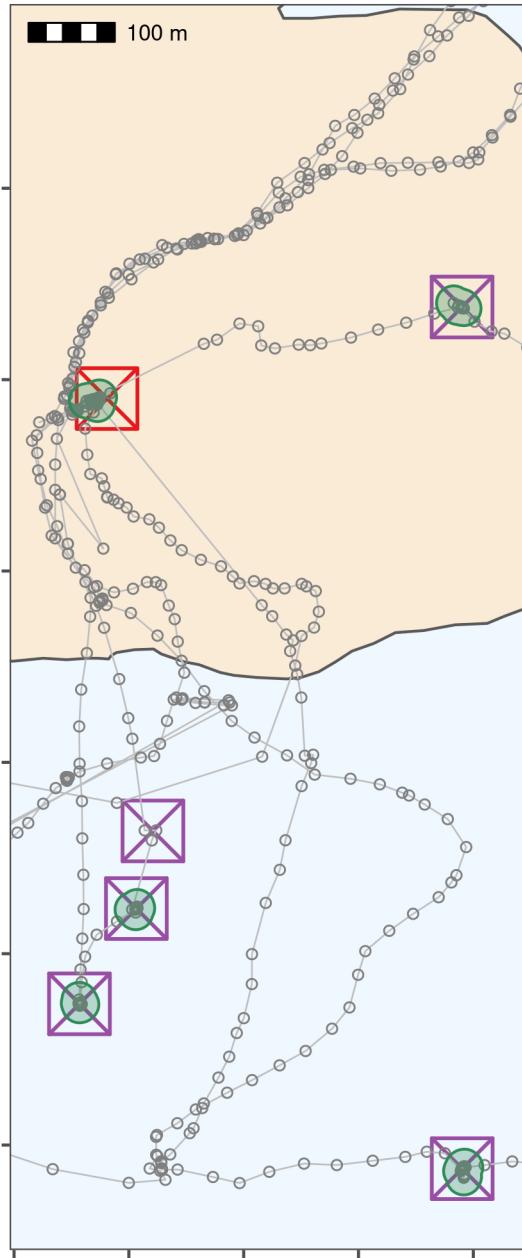


Figure 1.6: Classifying thinned data into residence patches yields robust estimates of the duration of known stops. The island of Griend (53.25°N , 5.25°E) is shown in beige. Residence patches (green polygons; function parameters in text) correspond well to the locations of known stops (purple crossed-squares). However, the algorithm identified all areas with prolonged residence, including those which were not intended stops ($n = 12$; green polygons without crossed-squares). The algorithm also failed to find two stops of 6 and 15 seconds duration, since these were lost in the data thinning step (crossed-square without green polygon shows one of these). The area shown is the lower rectangle in Fig. 1.3.

```

    y_median = round(median(y), digits = -2)
),
by = "tID"
]

# add real duration
patch_summary_real[, duration_real := wp_data]

# round median coordinate for inferred patches
patch_summary_inferred <-
  patch_summary_data[
  ,
  c(
    "x_median", "y_median",
    "nfixes", "duration", "patch"
  )
][, `:=`(
  x_median = round(x_median, digits = -2),
  y_median = round(y_median, digits = -2)
)]

# join with respatch summary
patch_summary_compare <-
  merge(patch_summary_real,
    patch_summary_inferred,
    on = c("x_median", "y_median"),
    all.x = TRUE, all.y = TRUE
  )

# drop nas
patch_summary_compare <- na.omit(patch_summary_compare)

# drop patch around WP080
patch_summary_compare <- patch_summary_compare[tID != "WP080", ]

123 7 patches are identified where there are no waypoints, while 2 waypoints are not identified as patches.
124 These waypoints consisted of 6 and 15 (WP098 and WP092) positions respectively, and were lost when
125 the data were aggregated to 30 second intervals.

```

1.9.1 Linear model durations

127 We run a simple linear model.

```

# get linear model
model_duration <- lm(duration_real ~ duration,
  data = patch_summary_compare
)

# get R2
summary(model_duration)

# write to file
writeLines(
  text = capture.output(
    summary(model_duration)
  ),
  con = "data/model_output_residence_patch.txt"
)

```

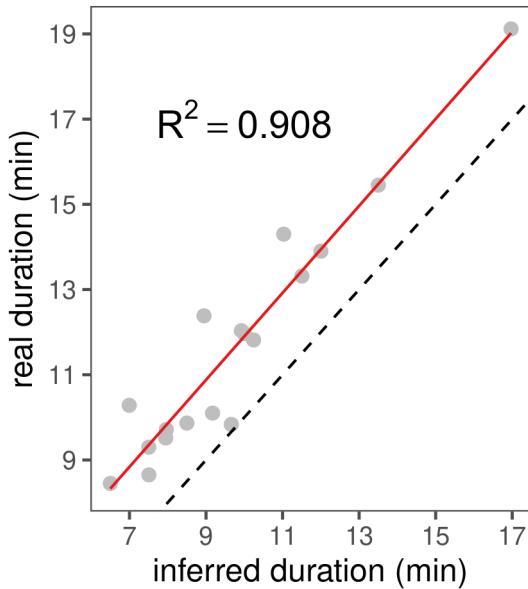


Figure 1.7: The inferred duration of residence patches corresponds very closely to the real duration (grey circles, red line shows linear model fit), with an underestimation of the true duration of around 2%. The dashed black line represents $y = x$ for reference.

1.9.2 Linear model summary

```

128 cat(
  readLines(
    con = "data/model_output_residence_patch.txt",
    encoding = "UTF-8"
  ),
  sep = "\n"
)
#>
#> Call:
#> lm(formula = duration_real ~ duration, data = patch_summary_compare)
#>
#> Residuals:
#>      Min        1Q     Median        3Q       Max
#> -103.237   -19.277   -2.917    7.003   93.431
#>
#> Coefficients:
#>             Estimate Std. Error t value Pr(>|t|)
#> (Intercept) 101.42061   47.66936   2.128   0.0493 *
#> duration     1.02108    0.07876  12.965 6.66e-10 ***
#> ---
#> Signif. codes:  0 ‘***’ 0.001 ‘**’ 0.01 ‘*’ 0.05 ‘.’ 0.1 ‘ ’ 1
#>
#> Residual standard error: 50.35 on 16 degrees of freedom
#> Multiple R-squared:  0.9131, Adjusted R-squared:  0.9077
#> F-statistic: 168.1 on 1 and 16 DF,  p-value: 6.655e-10

```

1.10 Plot figure 7

130 2 Processing Egyptian Fruit Bat Tracks

131 We show the pre-processing pipeline at work on the tracks of three Egyptian fruit bats (*Rousettus aegyptiacus*), and construct residence patches.

133 2.1 Prepare libraries

134 Install the required R libraries that are required from CRAN if not already installed.

```
# load libs
library(data.table)
library(RSQLite)
library(ggplot2)
library(patchwork)

# prepare a palette
pal <- RColorBrewer::brewer.pal(4, "Set1")
```

135 2.2 Install atlastools from Github.

136 atlastools is available from Github and is archived on Zenodo (Gupte 2020). It can be installed using
137 remotes or devtools. Here we use the remotes function install_github.

```
install.packages("remotes")

# installation using remotes
remotes::install_github("pratikunterwegs/atlastools")
```

138 2.3 Read bat data

139 Read the bat data from an SQLite database local file and convert to a plain text csv file. This data can
140 be found in the “data” folder.

```
# prepare the connection
con <- dbConnect(
  drv = SQLite(),
  dbname = "data/Three_example_bats.sql"
)

# list the tables
table_name <- dbListTables(con)

# prepare to query all tables
query <- sprintf('select * from \'%s\'', table_name)

# query the database
data <- dbGetQuery(conn = con, statement = query)

# disconnect from database
dbDisconnect(con)
```

¹⁴¹ Convert data to csv, and save a local copy in the folder “data”.

```
# convert data to datatable  
setDT(data)  
  
# write data for QGIS  
fwrite(data, file = "data/bat_data.csv")
```

¹⁴² 2.4 A First Visual Inspection

¹⁴³ Plot the bat data as a sanity check, and inspect it visually for errors (Fig. 2.1). The plot code is hid-
¹⁴⁴ den in the rendered copy (PDF) of this supplementary material, but is available in the Rmarkdown file
¹⁴⁵ “06_bat_data.Rmd”. The saved plot is shown below as Fig. 2.1.

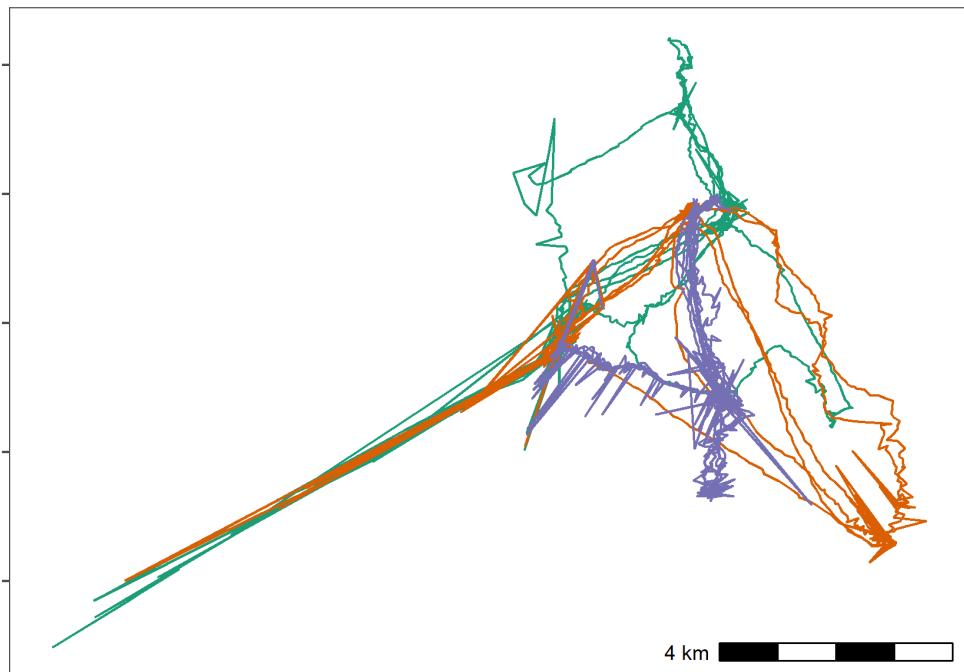


Figure 2.1: Movement data from three Egyptian fruit bats tracked using the ATLAS system (*Rousettus aegyptiacus*; (Toledo et al. 2020; Shohami and Nathan 2020)). The bats were tracked in the Hula Valley, Israel (33.1°N, 35.6°E), and we use three nights of tracking (5th, 6th, and 7th May, 2018), for our demonstration, with an average of 13,370 positions (SD = 2,173; range = 11,195 – 15,542; interval = 8 seconds) per individual. After first plotting the individual tracks, we notice severe distortions, making pre-processing necessary

¹⁴⁶ 2.5 Prepare data for filtering

¹⁴⁷ Here we apply a series of simple filters. It is always safer to deal with one individual at a time, so we
¹⁴⁸ split the data.table into a list of data.tables to avoid mixups among individuals.

¹⁴⁹ 2.5.1 Prepare data per individual

```
# split bat data by tag  
# first make a copy using the data.table function copy  
# this prevents the original data from being modified by atlastools  
# functions which DO MODIFY BY REFERENCE!
```

```

data_split <- copy(data)

# now split
data_split <- split(data_split, by = "TAG")

```

150 2.6 Filter by covariates

- 151 No natural bounds suggest themselves, so instead we proceed to filter by covariates, since point outliers
- 152 are obviously visible.
- 153 We use filter out positions with $SD > 20$ and positions calculated using only 3 base stations, using the
- 154 function `atl_filter_covariates`.
- 155 First we calculate the variable SD.

```

# get SD.
# since the data are data.tables, no assignment is necessary
invisible(
  lapply(data_split, function(dt) {
    dt[, SD := sqrt(VARX + VARY + (2 * COVXY))]
  })
)

```

- 156 Then we pass the filters to `atl_filter_covariates`. We apply the filter to each individual's data using
- 157 an `lapply`.

```

# filter for SD ≤ 20
# here, reassignment is necessary as rows are being removed
# the atl_filter_covariates function could have been used here
data_split <- lapply(data_split, function(dt) {
  dt <- atl_filter_covariates(
    data = dt,
    filters = c(
      "SD ≤ 20",
      "NBS > 3"
    )
  )
})

```

158 2.6.1 Sanity check: Plot filtered data

- 159 We plot the data to check whether the filtering has improved the data (Fig. 2.2). The plot code is once
- 160 again hidden in this rendering, but is available in the source code file.

161 2.7 Filter by speed

- 162 Some point outliers remain, and could be removed using a speed filter.
- 163 First we calculate speeds, using `atl_get_speed`. We must assign the speed output to a new column in
- 164 the data.table, which has a special syntax which modifies in place, and is shown below. This syntax is a
- 165 feature of the `data.table` package, not strictly of `atlastools` (Dowle and Srinivasan 2020).

```

# get speeds as with SD, no reassignment required for columns
invisible(
  lapply(data_split, function(dt) {

    # first process time to seconds
    # assign to a new column
  })
)

```

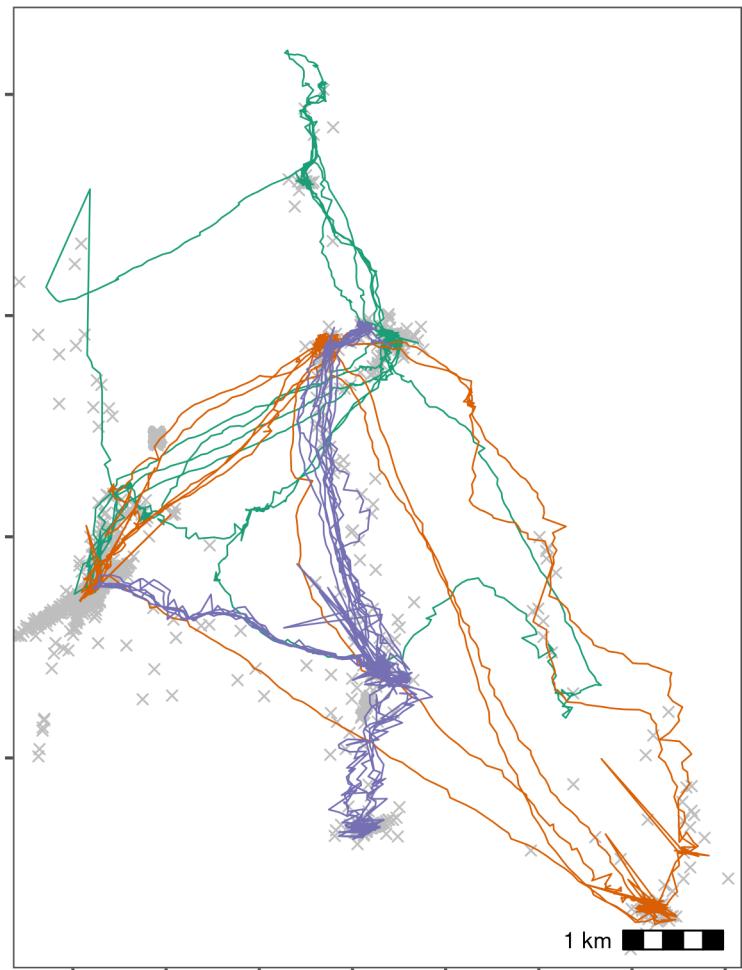


Figure 2.2: Bat data filtered for large location errors, removing observations with standard deviation > 20 . Grey crosses show data that were removed. Since the number of base stations used in the location process is a good indicator of error (Weiser et al. 2016), we also removed observations calculated using fewer than four base stations. Both steps used the function `atl_filter_covariates`. This filtering reduced the data to an average of 10,447 positions per individual (78% of the raw data on average). However, some point outliers remain.

```

    dt[, time := floor(TIME / 1000)]

    dt[, `:=`(
      speed_in = atl_get_speed(dt,
        x = "X", y = "Y",
        time = "time",
        type = "in"
      ),
      speed_out = atl_get_speed(dt,
        x = "X", y = "Y",
        time = "time",
        type = "out"
      )
    )]
  })
)

```

- 166 Now filter for speeds > 20 m/s (around 70 km/h), passing the predicate (a statement return TRUE or
 167 FALSE) to atl_filter_covariates. First, we remove positions which have NA for their speed_in
 168 (the first position) and their speed_out (last position).

```

# filter speeds
# reassignment is required here
data_split <- lapply(data_split, function(dt) {
  dt <- na.omit(dt, cols = c("speed_in", "speed_out"))

  dt <- atl_filter_covariates(
    data = dt,
    filters = c(
      "speed_in <= 20",
      "speed_out <= 20"
    )
  )
})

```

169 **2.7.1 Sanity check: Plot speed filtered data**

- 170 The speed filtered data is now inspected for errors (Fig. 2.3). The plot code is once again hidden.

171 2.8 Median smoothing

- 172 The quality of the data is relatively high, and a median smooth is not strictly necessary. We demonstrate
 173 the application of a 5 point median smooth to the data nonetheless (Fig. 2.4).
- 174 Since the median smoothing function atl_median_smooth modifies in place, we first make a copy of
 175 the data, using data.table's copy function. No reassignment is required, in this case. The lapply
 176 function allows arguments to atl_median_smooth to be passed within lapply itself.
- 177 In this case, the same moving window K is applied to all individuals, but modifying this code to use the
 178 multivariate version Map allows different K to be used for different individuals. This is a programming
 179 matter, and is not covered here further.

```

# since the function modifies in place, we shall make a copy
data_smooth <- copy(data_split)

# split the data again
data_smooth <- split(data_smooth, by = "TAG")

```

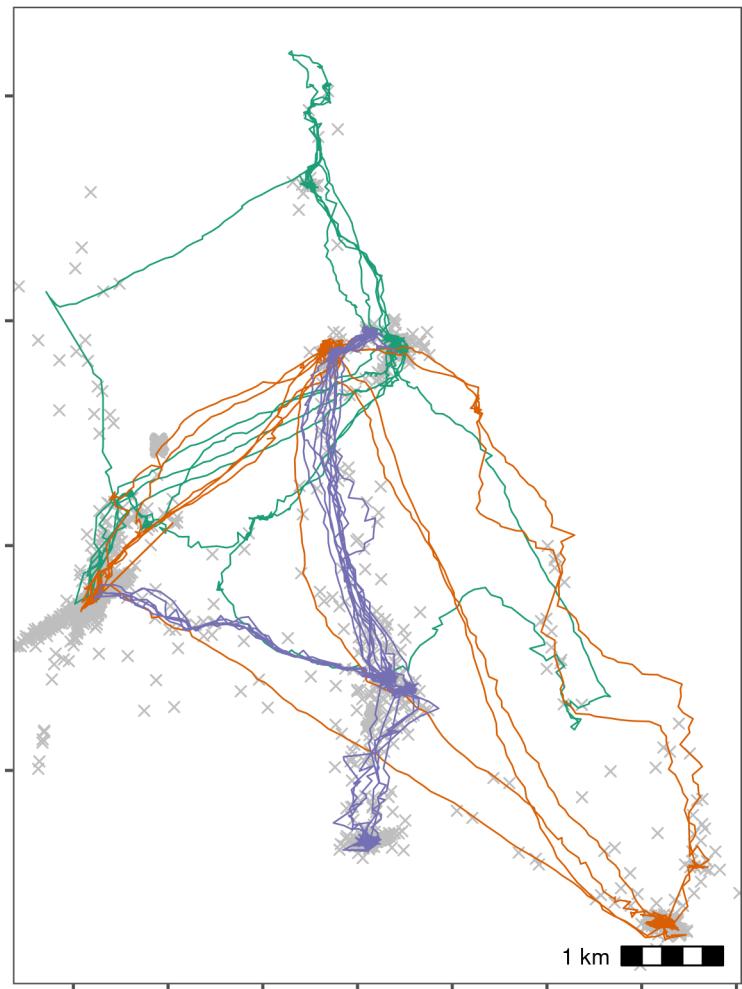


Figure 2.3: Bat data with unrealistic speeds removed. Grey crosses show data that were removed. We calculated the incoming and outgoing speed of each position using `atl_get_speed`, and filtered out positions with speeds > 20 m/s using `atl_filter_covariates`, leaving 10,337 positions per individual on average (98% from the previous step).

```

# apply the median smooth to each list element
# no reassignment is required as THE FUNCTION MODIFIES IN PLACE!
invisible(
  lapply(
    X = data_smooth,
    FUN = atl_median_smooth,
    time = "time", moving_window = 5
  )
)

```

¹⁸⁰ **2.8.1 Sanity check: Plot smoothed data**

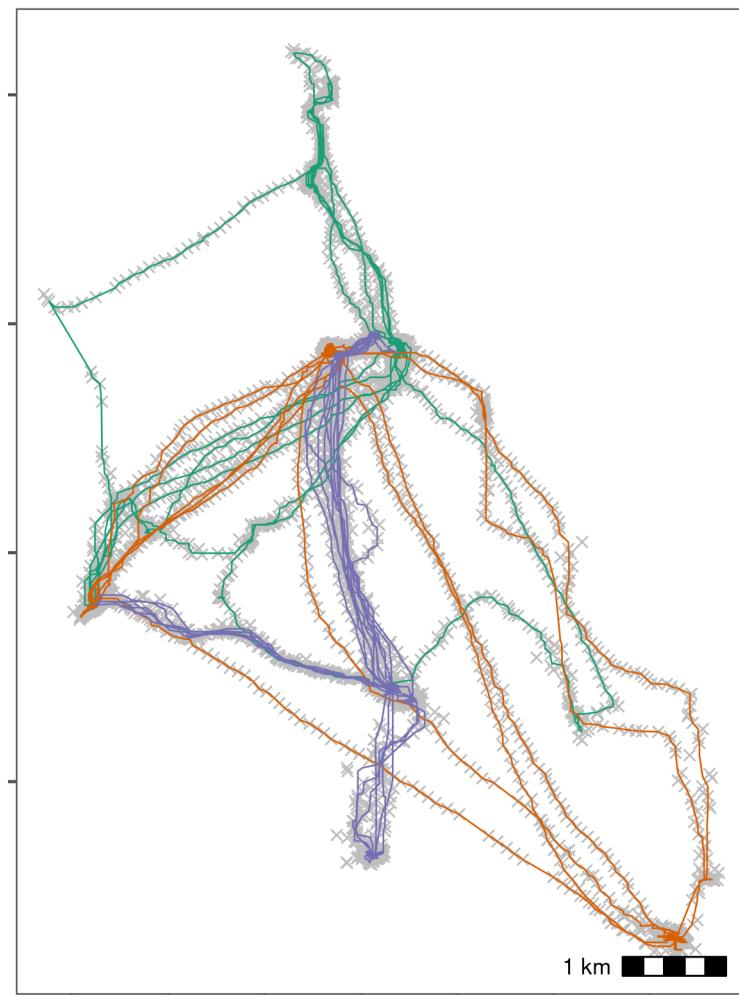


Figure 2.4: Bat data after applying a median smooth with a moving window $K = 5$. Grey crosses show data prior to smoothing. The smoothing step did not discard any data.

2.9 Making residence patches

2.9.1 Calculating residence time

183 First, the data is put through the `recurse` package to get residence time (Bracis, Bildstein, and Mueller
184 2018).

```
# load recurse
library(recurse)

# split the data
data_smooth <- split(data_smooth, data_smooth$TAG)

185 We calculated residence time, but since bats may revisit the same features, we want to prevent confusion
186 between frequent revisits and prolonged residence.

187 For this, we stop summing residence times within  $Z$  metres of a location if the animal exited the area for
188 one hour or more. The value of  $Z$  (radius, in recurse parameter terms) was chosen as 50m.

189 This step is relatively complicated and is only required for individuals which frequently return to the
190 same location, or pass over the same areas repeatedly, and for which revisits (cumulative time spent)
191 may be confused for residence time in a single visit.

192 While a simpler implementation using total residence time divided by the number of revisits is also
193 possible, this does assume that each revisit had the same residence time.

# get residence times

data_residence <- lapply(data_smooth, function(dt) {
  # do basic recurse
  dt_recurse <- getRecursions(
    x = dt[, c("X", "Y", "time", "TAG")],
    radius = 50,
    timeunits = "mins"
  )

  # get revisit stats
  dt_recurse <- setDT(
    dt_recurse[["revisitStats"]]
  )

  # count long absences from the area
  dt_recurse[, timeSinceLastVisit := 
    ifelse(is.na(timeSinceLastVisit), -Inf, timeSinceLastVisit)]
  dt_recurse[, longAbsenceCounter := cumsum(timeSinceLastVisit > 60),
    by = .(coordIdx)
  ]
  # get data before the first long absence of 60 mins
  dt_recurse <- dt_recurse[longAbsenceCounter < 1, ]

  dt_recurse <- dt_recurse[, list(
    resTime = sum(timeInside),
    fpt = first(timeInside),
    revisits = max(visitIdx)
  ),
    by = .(coordIdx, x, y)
  ]

  # prepare and merge existing data with recursion data
  dt[, coordIdx := seq(nrow(dt))]
```

```

    dt <- merge(dt,
      dt_recurse[, c("coordIdx", "resTime")],
      by = c("coordIdx")
    )

    setorder(dt, "time")
  })

```

194 We bind the data together and assign a human readable timestamp column.

```

# bind the list
data_residence <- rbindlist(data_residence)

# get time as human readable
data_residence[, ts := as.POSIXct(time, origin = "1970-01-01")]

```

195 2.9.2 Constructing residence patches

196 Some preparation is required. First, the function requires columns `x`, `y`, `time`, and `id`, which we assign
197 using the `data.table` syntax. Then we subset the data to only work with positions where the individual
198 had a residence time of more than 5 minutes.

```

# add an id column
data_residence[, `:=`(
  id = TAG,
  x = X, y = Y
)]

# filter for residence time > 5 minutes
data_residence <- data_residence[resTime > 5, ]

# split the data
data_residence <- split(data_residence, data_residence$TAG)

```

199 We apply the residence patch method, using the default argument values (`lim_spat_indep = 100`
200 (metres), `lim_time_indep = 30` (minutes), and `min_fixes = 3`). We change the `buffer_radius` to
201 25 metres (twice the buffer radius is used, so points must be separated by 50m to be independent bouts).

```

# segment into residence patches
data_patches <- lapply(data_residence, atl_res_patch,
  buffer_radius = 25
)

```

202 2.9.3 Getting residence patch data

203 We extract the residence patch data as spatial sf-MULTIPOLYGON objects. These are returned as a list and
204 must be converted into a single sf object. These objects and the raw movement data are shown in Fig.
205 2.5.

```

# get data spatials
data_spatials <- lapply(data_patches, atl_patch_summary,
  which_data = "spatial",
  buffer_radius = 25
)

# bind list
data_spatials <- rbindlist(data_spatials)

# convert to sf

```

```
library(sf)
data_spatial <- st_sf(data_spatial, sf_column_name = "polygons")

# assign a crs
st_crs(data_spatial) <- st_crs(2039)

206 2.9.4 Write patch spatial representations

st_write(data_spatial,
  dsn = "data/data_bat_residence_patches.gpkg"
)

207 Write cleaned bat data.

data_clean <- fwrite(rbindlist(data_smooth),
  file = "data/data_bat_smooth.csv"
)

208 Write patch summary.

# get summary
patch_summary <- lapply(data_patches, atl_patch_summary)

# bind summary
patch_summary <- rbindlist(patch_summary)

# write
fwrite(
  patch_summary,
  "data/data_bat_patch_summary.csv"
)
```

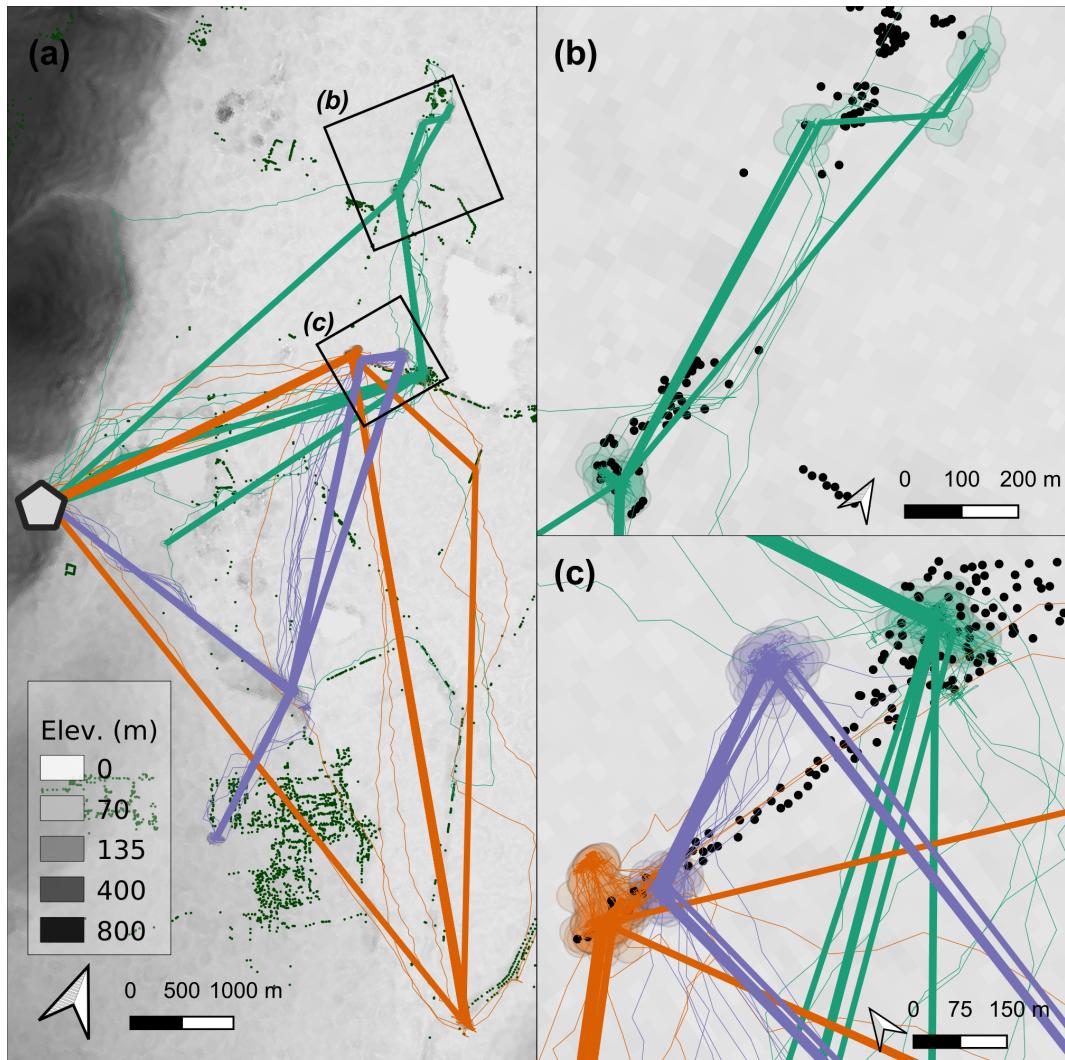


Figure 2.5: A visual examination of plots of the bats' residence patches and linear approximations of paths between them showed that though all three bats roosted at the same site, they used distinct areas of the study site over the three nights (a). Bats tended to be resident near fruit trees, which are their main food source, travelling repeatedly between previously visited areas (b, c). However, bats also appeared to spend some time at locations where no fruit trees were recorded, prompting questions about their use of other food sources (b, c). When bats did occur close together, their residence patches barely overlapped, and their paths to and from the broad area of co-occurrence were not similar (c). Constructing residence patches for multiple individuals over multiple activity periods suggests interesting dynamics of within- and between-individual overlap (b, c).

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