

# NOTES FOR ~~MATH~~ MTH100 - SYMMETRIC MATRICES - done on 20161109-10 (WED-THU)

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## PRELIMINARY NOTES FOR PROP. 54.

Another way to interpret matrix multiplication:

Suppose  $A$  is an  $m \times n$  matrix and  $B$  is an  $n \times k$  matrix, so that  $AB$  is well-defined and  $AB$  is  $m \times k$ . Let  $AB = C = [c_{ij}]$

$$\text{let } A = \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{m1} & \dots & a_{mn} \end{bmatrix} = \begin{bmatrix} \bar{r}_1 \\ \vdots \\ \bar{r}_m \end{bmatrix}, \text{ where the } \bar{r}_i \text{ are rows of } A.$$

$$\text{let } B = \begin{bmatrix} b_{11} & \dots & b_{1k} \\ \vdots & & \vdots \\ b_{n1} & \dots & b_{nk} \end{bmatrix} = \begin{bmatrix} \bar{v}_1 & \dots & \bar{v}_k \end{bmatrix}, \text{ where the } \bar{v}_i \text{ are columns of } B,$$

$$\text{Now, } c_{11} = a_{11}b_{11} + a_{12}b_{21} + \dots + a_{1n}b_{n1}$$

$$= [a_{11} \dots a_{1n}] \begin{bmatrix} b_{11} \\ \vdots \\ b_{n1} \end{bmatrix}; \text{ it is a product of a } 1 \times n \text{-matrix and an } n \times 1 \text{-matrix, hence, a } 1 \times 1 \text{-matrix or scalar}$$

$$= \bar{r}_1 \bar{v}_1 \text{ (matrix product)}$$

We can also interpret it as the dot-product of the 1st row of  $A$  with 1st column of  $B$ .

Hence, we can write:

$$AB = \begin{bmatrix} \bar{r}_1 \bar{v}_1 & \bar{r}_1 \bar{v}_2 & \dots & \bar{r}_1 \bar{v}_k \\ \vdots & \vdots & & \vdots \\ \bar{r}_m \bar{v}_1 & \bar{r}_m \bar{v}_2 & \dots & \bar{r}_m \bar{v}_k \end{bmatrix} = [\bar{r}_i \bar{v}_j], \text{ i.e. } c_{ij} = \bar{r}_i \bar{v}_j$$

Proof of  
Prop. ~~53~~

$A$  - symmetric

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let  $\lambda_1, \lambda_2$  be two distinct eigenvalues.

let  $\bar{v}_1$  and  $\bar{v}_2$  be their corresp. eigenvectors.

$$\begin{aligned} & \lambda_1 (\bar{v}_1 \circ \bar{v}_2) \\ &= (\lambda_1 \bar{v}_1 \circ \bar{v}_2) \\ &= (A\bar{v}_1) \circ \bar{v}_2 \quad (\because \bar{v}_1 \text{ is an eigenvector for } \lambda_1) \\ &= (A\bar{v}_1)^T \bar{v}_2 \quad (\text{by defn.}) \end{aligned}$$

$$= \bar{v}_1^T A^T \bar{v}_2$$

$$= \bar{v}_1^T (A \bar{v}_2) \quad \text{since } A^T = A$$

$$\begin{aligned} &= \bar{v}_1^T (\lambda_2 \bar{v}_2) \quad - \because \bar{v}_2 \text{ is an eigenvector for } \lambda_2 \\ &\equiv \bar{v}_1 \circ \lambda_2 \bar{v}_2 \end{aligned}$$

$$\lambda_1 (\bar{v}_1 \circ \bar{v}_2) = \lambda_2 (\bar{v}_1 \circ \bar{v}_2)$$

$$\therefore \bar{v}_1 \circ \bar{v}_2 = 0 \quad - \text{ as we wanted}$$

~~Tuesday 11th November~~

## NUMERICAL EXAMPLE FOR SYMMETRIC MATRICES (3)

$$A = \begin{bmatrix} 2 & 1 & 1 \\ -1 & 2 & 1 \\ 1 & 1 & 2 \end{bmatrix}$$

$$\det(A - \lambda I) = -(\lambda-1)^2(\lambda-4)$$

Putting  $\lambda = 4$ :  $A - \lambda I = \begin{bmatrix} -2 & 1 & 1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{bmatrix}$

$$\rightarrow \begin{bmatrix} 1 & 1 & -2 \\ 1 & -2 & 1 \\ -2 & 1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & -2 \\ 0 & -3 & 3 \\ 0 & 3 & -3 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & 1 & -2 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix} \leftarrow \text{RREF}$$

Solving the system, we get  $\vec{u}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$  as

an eigenvector, normalizing:  $\vec{v}_1 = \frac{1}{\sqrt{3}} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ .

Putting  $\lambda = 1$ ,  $A - \lambda I = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$

$$\rightarrow \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \leftarrow \text{RREF}$$

$$\text{or } \vec{x} = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} x_2 + \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} x_3$$

(P.T.O.)

We thus get  $\bar{u}_2 = \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$  and  $\bar{u}_3 = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$

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are eigenvectors. We see that  $\bar{u}_1 \cdot \bar{u}_2 = \bar{u}_1 \cdot \bar{u}_3 = 0$ , but  $\bar{u}_2 \cdot \bar{u}_3 = 1 \neq 0$ .

So now we have to apply Gram-Schmidt process to  $W =$  eigenspace of  $\lambda = 1$ .

$$\bar{v}_2 = \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$$

$$\bar{v}_3 = \bar{u}_3 - \frac{\bar{u}_3 \cdot \bar{v}_2}{\bar{v}_2 \cdot \bar{v}_2} \bar{v}_2 = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \\ -1 \end{bmatrix}$$

Now, normalize to get  $\bar{v}_2' = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$

$$\bar{v}_3' = \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix}$$

Check: we must have  $A = P D P^{-1} = P D P^T$

$$P = \begin{bmatrix} \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{3}} \\ 0 & 1 & 0 \\ \frac{1}{\sqrt{6}} & -\frac{1}{\sqrt{2}} & 0 \end{bmatrix}$$

or  $AP = PD$ ,

where  $P$  has  $\bar{v}_1', \bar{v}_2', \bar{v}_3'$  as columns

(See next page)

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Check for numerical example

$$\begin{aligned}
 & \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{bmatrix} = \begin{bmatrix} 3 \\ 4 \\ 4 \end{bmatrix} \\
 & \begin{bmatrix} \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & 0 & -\frac{2}{\sqrt{6}} \end{bmatrix} \begin{bmatrix} \frac{4}{\sqrt{3}} \\ \frac{4}{\sqrt{3}} \\ 0 \end{bmatrix} = \begin{bmatrix} \frac{4}{\sqrt{3}} \\ \frac{4}{\sqrt{3}} \\ 0 \end{bmatrix} \\
 & \begin{bmatrix} \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & 0 & -\frac{2}{\sqrt{6}} \end{bmatrix} \begin{bmatrix} \frac{4}{\sqrt{3}} \\ \frac{4}{\sqrt{3}} \\ 0 \end{bmatrix} = \begin{bmatrix} \frac{4}{\sqrt{3}} \\ \frac{4}{\sqrt{3}} \\ 0 \end{bmatrix} \\
 & \begin{bmatrix} \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & 0 & -\frac{2}{\sqrt{6}} \end{bmatrix} \begin{bmatrix} \frac{4}{\sqrt{3}} \\ \frac{4}{\sqrt{3}} \\ 0 \end{bmatrix} = \begin{bmatrix} \frac{4}{\sqrt{3}} \\ \frac{4}{\sqrt{3}} \\ 0 \end{bmatrix}
 \end{aligned}$$

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Proof of Theorem 9 (b): Every eigenvalue of a real symmetric ~~matrix~~ matrix is real, i.e. if  $A$  is an  $n \times n$  real symmetric matrix, then its characteristic poly. has only real roots (no complex roots).

Step 1 (Lay 2.3/3.41): let  $A$  be an  $n \times n$  real symmetric matrix, and let  $X \in \mathbb{C}^n$ . Put  $q = \bar{X}^T A X$ , where  $\bar{X}$  = complex conjugate of  $X$ . Then  $q$  is real.

Proof: We have:  $\bar{q} = \overline{\bar{X}^T A X}$  (by definition)

$$= X^T \overline{A X} \quad (\text{since } \overline{\bar{Y}} = Y \text{ for any } Y \in \mathbb{C}^n, \text{ and conjugate of a product is product of conjugates - this was a Futon problem})$$

$$= X^T A \bar{X} \quad - \text{ since } \bar{A} = A, \text{ as } A \text{ is real}$$

$$= (X^T A \bar{X})^T \quad - \text{ since the quantity in brackets is actually a scalar, hence its transpose is equal to itself}$$

$$= \bar{X}^T A^T X \quad \rightarrow \text{ since } (AB)^T = B^T A^T$$

$$= \bar{X}^T A X \quad - \text{ since } A \text{ is symmetric, } A^T = A$$

$$= q.$$

Since  $\bar{q} = q$ ,  $q$  is real.

[This is one of the ways to show a complex number  $z$  is real - i.e. show that  $\bar{z} = z$ ]

Proof (cont'd):-

⑦

Step 2 (Lay 24/341) Show that if  $AX = \lambda X$  for some non-zero vector  $X$  in  $\mathbb{C}^n$ , then  $\lambda$  is in fact real, and the real part of  $X$  is in fact an eigenvector of  $A$  (in  $\mathbb{R}^n$ ).

Proof: Consider  $q = \bar{X}^T A X$ .

By Step 1,  $q$  is known to be real.

Now,  $q = \bar{X}^T (\lambda X)$  since  $X$  is an eigenvector

$$= \lambda (\bar{X}^T X).$$

①

Now,  $\bar{X}^T X$  is real and  $> 0$  :-

Put  $X' = \begin{bmatrix} a_1 + b_1 i \\ \vdots \\ a_n + b_n i \end{bmatrix} = \begin{bmatrix} z_1 \\ \vdots \\ z_n \end{bmatrix}$ , where each  $z_i \in \mathbb{C}$ .

Then  $\bar{X}^T X = [\bar{z}_1 \dots \bar{z}_n] \begin{bmatrix} z_1 \\ \vdots \\ z_n \end{bmatrix}$  where  $\bar{z}_i$  = complex conjugate of  $z_i$

$$= z_1 \bar{z}_1 + \dots + z_n \bar{z}_n > 0 \text{ since } X \text{ is non-zero.}$$

Putting  $\bar{X}^T X = r \in \mathbb{R}$ ,  $r > 0$ ,

we get  $q = \lambda r$  from ①, whence  $\lambda = \frac{q}{r}$  is

again real, as desired.

Finally, if  $X = U + iV$ , where  $U, V \in \mathbb{R}^n$

$$\text{Then } AX = A(U + iV) = AU + iAV$$

$$= \lambda(X) = \lambda(U + iV) = \lambda U + i\lambda V.$$

Equating real and imaginary parts,  $AU = \lambda U$ , and we are done.