µProject #6 "Shake it up"
Due Thursday 3/20

Purpose
This µproject involves driving a servo motor based on sensor input.

What to Build
Build a device which moves a servo motor under the control of a potentiometer. When the potentiometer is turned fully clockwise the servo motor should be turned fully clockwise. As the potentiometer is turned counter-clockwise, the servo should track this movement, turning counter-clockwise, and when the potentiometer is turned fully counter-clockwise, the servo should be turned fully counter-clockwise.

Turning the Assignment In and Grading
This assignment is turned in by having one of your classmates certify completion and turn in a "peer demo" sheet signed by them. This project is pass/fail. µProjects will be accepted without late penalty until Monday March 31st (after which a 10% per day late penalty will be applied).