

ex1-2

October 15, 2024

1 ex1: Inverse Filtering

```
[1]: from scipy.fft import fft2, fftshift
from pathlib import Path
import numpy as np
import skimage
import matplotlib.pyplot as plt
```

```
[2]: ASSETS_FOLDER_PATH = "./assets"
OUTPUT_FOLDER_PATH = "."
```

```
[3]: Path(OUTPUT_FOLDER_PATH).mkdir(parents=True, exist_ok=True)
```

Cargamos la imagen

```
[4]: my_image = skimage.io.imread(fname=f"{ASSETS_FOLDER_PATH}/lena_gray.tif")
image_size = my_image.shape
```

Definimos las funciones a utilizar:

```
[5]: def fft2c(x: np.ndarray) -> np.ndarray:
    return fftshift(fft2(fftshift(x)))
```

```
[6]: def ifft2c(x: np.ndarray) -> np.ndarray:
    return fftshift(np.fft.ifft2(fftshift(x)))
```

```
[7]: def lowpass_kernel(kernel_size, image_dimensions):
    height, width = image_dimensions
    kernel = np.zeros((height, width))
    center_x, center_y = (height // 2, width // 2)
    kernel[center_x - kernel_size // 2: center_x + kernel_size // 2 + 1,
           center_y - kernel_size // 2: center_y + kernel_size // 2 + 1] = 1 / (
        kernel_size ** 2)
    return kernel
```

```
[8]: def plot_image(img, title):
    plt.imshow(img, cmap='gray')
    plt.axis('off')
```

```
plt.title(title)
plt.show()
```

```
[9]: def plot_images(img1, title1, img2, title2):
      fig = plt.figure(figsize=(6, 7))

      fig.add_subplot(1, 2, 1)
      plt.imshow(img1, cmap='gray')
      plt.axis('off')
      plt.title(title1)

      fig.add_subplot(1, 2, 2)
      plt.imshow(img2, cmap='gray')
      plt.axis('off')
      plt.title(title2)

      plt.subplots_adjust(wspace=0.05, hspace=0)
      plt.show()
```

```
[10]: def mse(original, variation):
       return np.mean((original - variation) ** 2)
```

1.1 Blur

Calculamos el kernel:

```
[11]: gks = 80
      gk = np.exp(-(np.arange(max(imsize)) - max(imsize) // 2) ** 2 / (2 * gks ** 2))
      gauss_kernel = np.outer(gk, gk)

      gauss_kernel = gauss_kernel[
          (max(imsize) - imsize[0]) // 2:(max(imsize) - imsize[0]) // 2 + imsize[0],
          (max(imsize) - imsize[1]) // 2:(max(imsize) - imsize[1]) // 2 + imsize[1]
      ]
```

```
[12]: # blur_kernel = gauss_kernel
      blur_kernel = lowpass_kernel(5, imsize)
```

Obtenemos la imagen con blur:

```
[13]: blurred_image = np.abs(iff2c(fft2c(my_image) * fft2c(blur_kernel)))
      plot_images(my_image, 'Original image', blurred_image, 'Blurred image')
```

Original image



Blurred image



Aplicando la operación inversa sobre la imagen borrosa:

```
[14]: restored_image_blur = np.abs(iff2c(fft2c(blurred_image) / fft2c(blur_kernel)))  
      plot_images(blurred_image, 'Blurred image', restored_image_blur, 'Restored_  
      ↪image')  
      print(f"mse: {mse(my_image, restored_image_blur)}")
```

Blurred image



Restored image



mse: 1.2837269174207216e-21

1.2 Blur + Noise

Definimos el signal-to-noise ratio:

```
[15]: SNR_dB = 10
```

Calculamos la desviación estándar de la imagen borrosa para el ruido:

```
[16]: sigma_blurred_image = np.std(blurred_image)
sigma_noise = np.sqrt((sigma_blurred_image ** 2) * (10 ** (-SNR_dB / 10)))
noise = np.random.normal(0, sigma_noise, (imsize[0], imsize[1]))
```

```
[17]: blurred_noise_image = blurred_image + noise
plot_images(my_image, 'Original image', blurred_noise_image, 'Blurred image_
↳with noise')
```



Aplicando la operación inversa:

```
[18]: restored_image_blur_noise = np.abs(iff2c(fft2c(blurred_noise_image)))
plot_images(blurred_noise_image, 'Blurred image with noise',
↳restored_image_blur_noise, 'Restored image')
print(f"mse: {mse(my_image, restored_image_blur_noise)}")
```

Blurred image with noise



Restored image



mse: 273.99873726572713

2 ex2: Wiener

Definimos un filtro de Wiener:

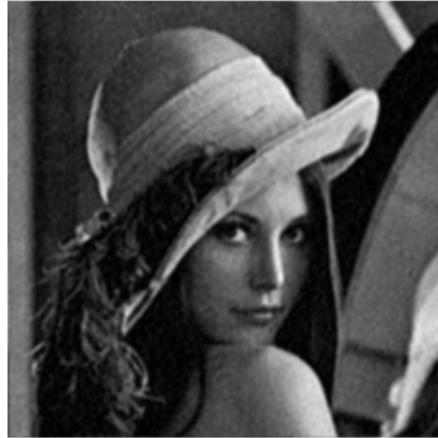
```
[19]: def wiener_filter_restoration(blurred_image, blur_kernel, noise):  
    blurred_fft = fft2c(blurred_image)  
    kernel_fft = fft2c(blur_kernel)  
    noise_psd = np.square(np.abs(fft2c(noise)))  
    wiener_filter = np.conj(kernel_fft) / (np.abs(kernel_fft) ** 2 + noise_psd /  
    ↪ np.square(np.abs(blurred_fft)))  
    restored_fft = wiener_filter * blurred_fft  
    restored_image = np.abs(iff2c(restored_fft))  
    return restored_image
```

```
[20]: restored_image_wiener = wiener_filter_restoration(blurred_noise_image, ↪  
    ↪ blur_kernel, noise)  
plot_images(blurred_noise_image, 'Blurred image with noise', ↪  
    ↪ restored_image_wiener, 'Restored Image')  
print(f"mse: {mse(my_image, restored_image_wiener)}")
```

Blurred image with noise



Restored Image



mse: 68.87812877972368