

# Step-by-step: Object detection on a Fresh/New Raspberry pi 4 using TensorFlow Lite

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I recently bought a Raspberry pi 4(4GB) which is an amazing board with diverse set of capabilities and features available. It's kind of a mini-computer. I wanted to leverage Raspberry pi to detect objects in a live cam. Tensorflow Lite has made is very simple to perform this.

This is a step-by-step tutorial right from opening a new Raspberry pi 4 till a working prototype.

Tutorial is divided into 4 stages

1. Hardware and Software
2. Setup new Raspberry pi 4
3. Setup Camera
4. Deploy Image Classification Model

## Note:

- The Instructions are preformed on Windows 10 Machine
- Commands are in *italics* and needs to be executed on terminal

## Hardware and Software

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### Hardware

- [Raspberry\\_pi 4 \(1GB, 2GB or 4GB\)](#)



- Micro SD Card >= [8GB](#)
- Micro SD card Reader OR Adapter
  - [Reader](#)

- [Adapter](#)

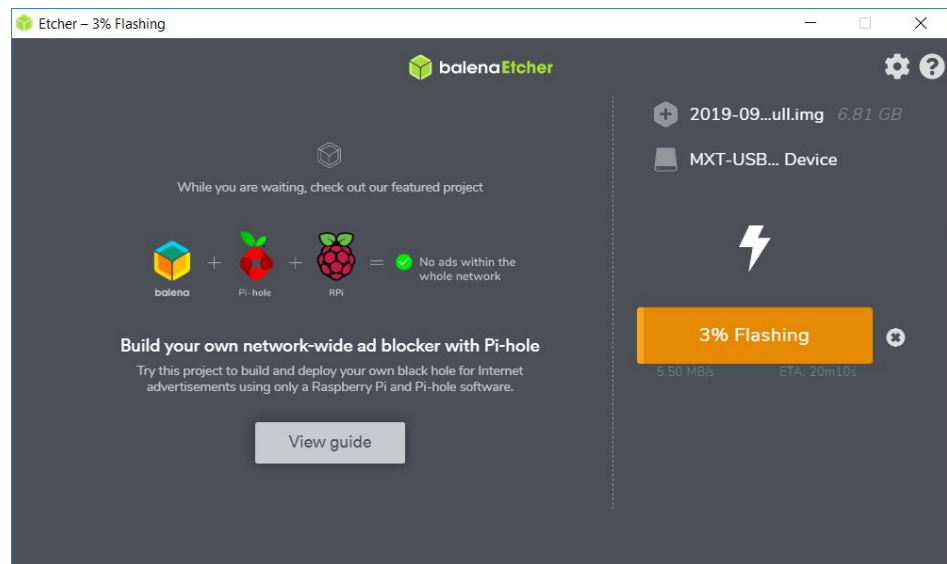
## Software

- [Raspbian OS image](#)
- [SD Association's Formatting Tool](#)
- [OS Image burning software - Balena](#)
- [Remote access to Raspberry Pi - MobaXterm](#)

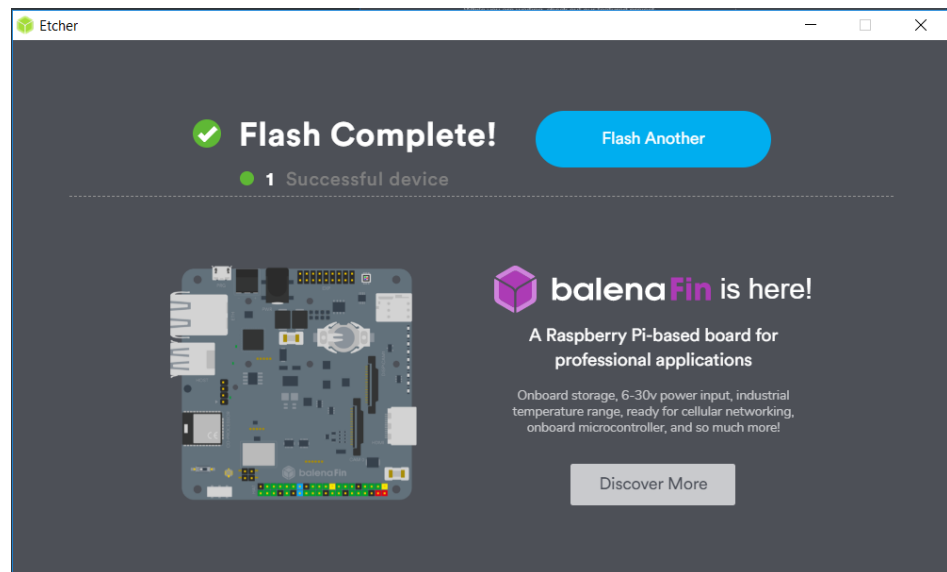
## Setup new Raspberry pi 4

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- **Non-Headless setup:** Follow Official setup page in case Monitor, Keyboard and mouse is present [Setup Raspberry pi - Raspberry website](#)
- **Headless Setup:** This is followed when external Monitor, Keyboard and Mouse is not present. A PC/Laptop is present.
  - **References:**
    - [Headless Raspberry pi ssh wifi setup](#)
    - [Raspberry Pi Headless Setup With WiFi and SSH Enabled](#)
  - **PC/Laptop**
    - Raspbian OS: Download from [link](#)
      - Raspbian Buster with desktop and recommended software
        - Size(img file) ~ 6 GB
        - Full featured, supports Remote desktop, VNC
        - Used in this tutorial
      - Raspbian Buster Lite
        - Size(img file) ~ 400 MB
        - Minimal features, no Remote desktop or VNC
    - Micro SD Card
      - Attach Micro SD card to Its reader/adapter and plug it to PC/Laptop
      - For old Micro SD card, take backup and format it using [SD Association's Formatting Tool](#)
      - Micro SD card will appear as a USB drive in the PC.
      - Note down the letter of drive(E:). Double click to open the drive
    - Burn Raspbian image to Micro SD card
      - Download [Balena\(Image burning software\)](#)
      - Launch application:
        - Select raspbian os image (2019-09-26-raspbian-buster-full.img)
        - Select MicroSD drive(E:)
        - Click Flash
      - In-Progress



#### ■ Completed



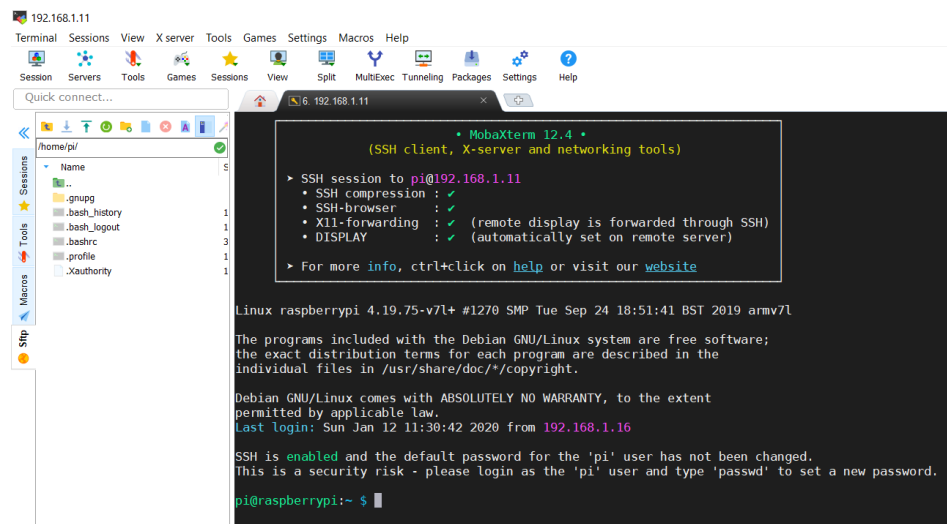
- **Failure:** In case there is a failure due to checksum error, please follow steps in below link
  - [How to prevent creation of "System Volume Information" folder in Windows 10 for USB flash drives?](#)
    - [Checksums do not match](#)
- Re-insert the MicroSD card
  - A drive might have been created with name as 'boot'
  - Double click to navigate to this drive
- Enable SSH for remote login
  - Create an empty file by name 'ssh', and put it in the root folder of SD card. No extension to file
- Enable Wifi
  - Create a file with name 'wpa\_supplicant.conf' and place it in the boot root folder
  - Give proper country, ssid and password

```
ctrl_interface=DIR=/var/run/wpa_supplicant GROUP=netdev
update_config=1
ap_scan=1
fast_reauth=1
country=IN

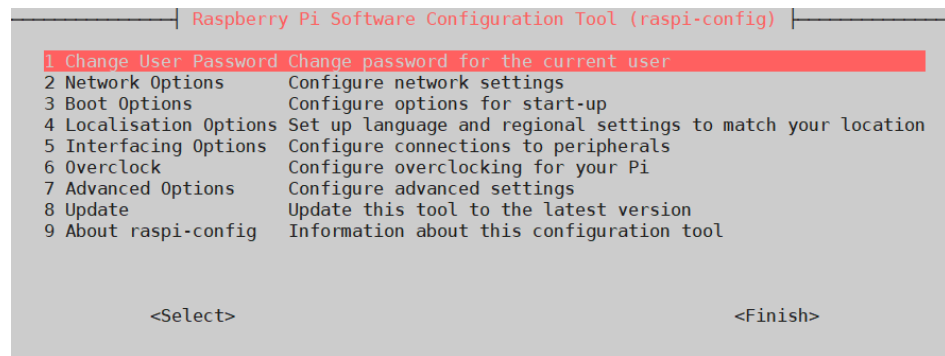
network={
    ssid="NETWORK-NAME"
    psk="NETWORK-PASSWORD"
    id_str="0"
    priority=100
}
```

## ◦ Raspberry Pi

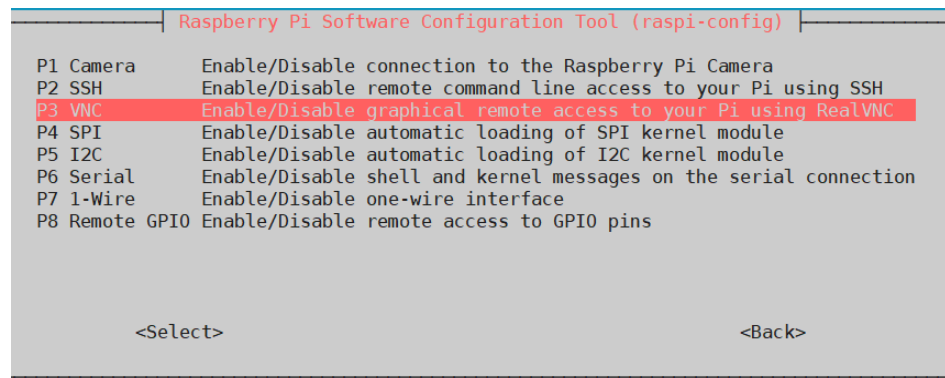
- Boot Raspberry Pi with SD card
  - Eject MicroSD card from PC
  - Connect Raspberry Pi to Router through LAN cable
  - Plug it into Raspberry Pi and wait for 2 minutes
- Router
  - Login to router such as 192.168.1.1
  - In the device list, a device containing 'raspberry pi' should appear
  - Get the IP of the this device such as 192.168.1.11
- Login Remotely over Wi-Fi
  - [Download](#) and install MobaXterm
  - Click on session and type pi IP(192.168.1.11) in Remote Host under Basic Settings. Click ok
  - Enter username: pi and password: raspberry



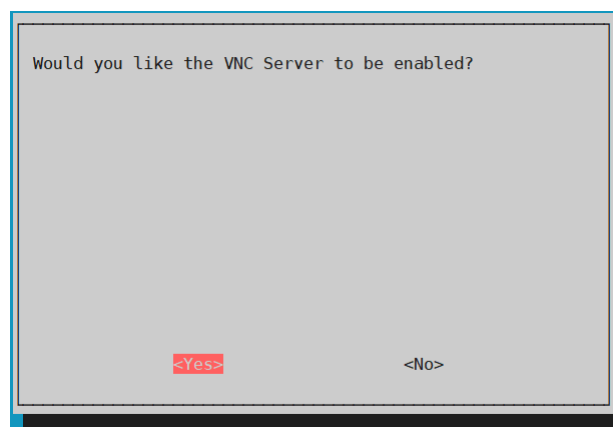
- Remote desktop vnc
  - Enter *sudo raspi-config*



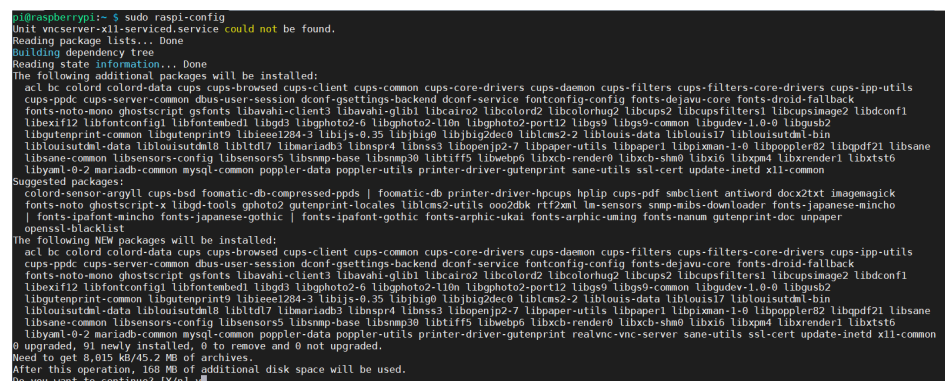
- Select Option 5: Interfacing Options



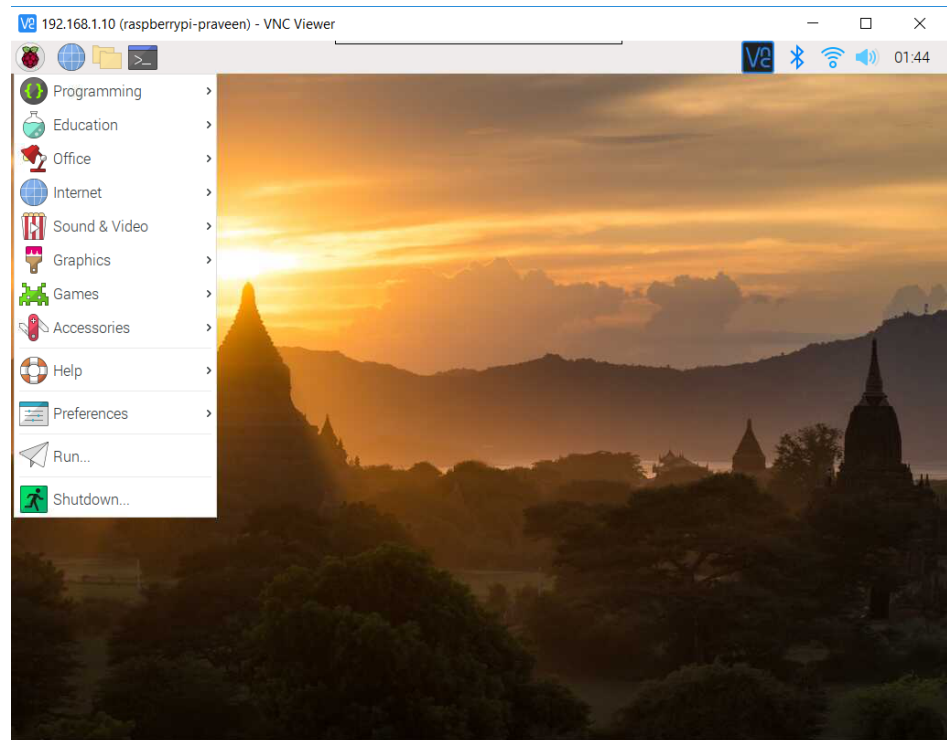
- Select P3-VNC and Press Yes



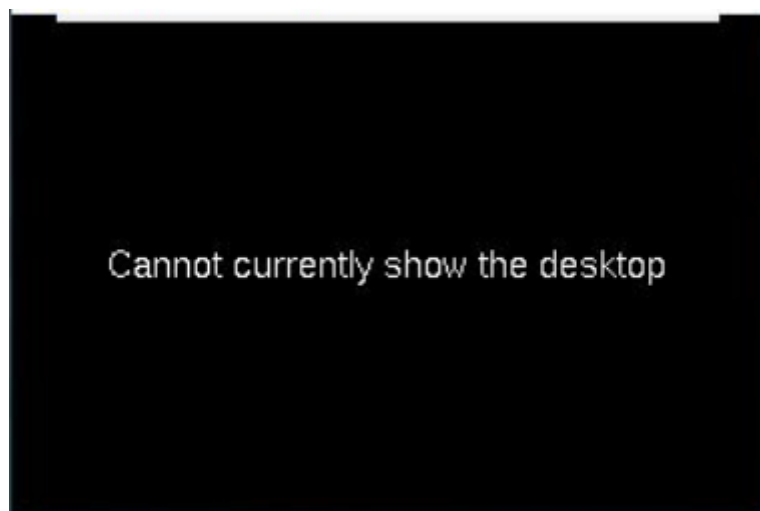
- Pres Y to continue



- Enter *sudo reboot now* to reboot in order the settings to take into effect
- Now start VNC and enter the IP of raspberry pi. It should display the Raspberry pi desktop.



- In case black screen with message 'Cannot currently show the desktop' is displayed, follow below steps



- Connect raspberry pi through SSH
- Enter `sudo raspi-config`
- Select 7 - Advanced Operations
- Select 5 - Resolution
- Select last option and press OK
- Restart Raspberry pi
- Start VNC and desktop will be displayed
- **[Optional] Installing On-screen keyboard**
  - [Matchbox Keyboard - Raspberry Pi Touchscreen Keyboard](#)
    - `sudo apt-get install matchbox-keyboard`
    - Enter `sudo matchbox-keyboard` to open keyboard
    - Launch keyboard through double click
      - Create a file on the Desktop 'keyboard.sh'
      - Write below statement in the file

```
#!/bin/bash
matchbox-keyboard
```

- Open terminal and enter below commands
  - `cd Desktop`
    - `chmod +x keyboard.sh`
    - Double click to launch keyboard
- [Optional] Setting Static IP
  - Reference
    - [How to Set Static IP for Raspberry Pi in Raspbian Jessie](#)
    - [2016: Assign a Static IP Address to Raspberry Pi](#)
    - [Raspberry Pi - Tutorial 12 - Networking - How to Configure a Static IP Address & Setup Wifi](#)
  - Execute `ifconfig` and note down the IP address (inet)

```
pi@raspberrypi:~$ ifconfig
eth0: flags=4163<UP,BROADCAST,RUNNING,MULTICAST> mtu 1500
    inet 192.168.1.11 netmask 255.255.255.0 broadcast 192.168.1.255
    inet6 fd54:25ea:1ee7:3e00:2c54:6b4c:6029:b3e4 prefixlen 64 scopeid 0x0<global>
    inet6 fe80::3c8a:37fe:5486:7a48 prefixlen 64 scopeid 0x20<link>
    ether dc:a6:32:48:4c:e2 txqueuelen 1000 (Ethernet)
    RX packets 152775 bytes 200562018 (191.2 MiB)
    RX errors 0 dropped 0 overruns 0 frame 0
    TX packets 87621 bytes 7361376 (7.0 MiB)
    TX errors 0 dropped 0 overruns 0 carrier 0 collisions 0

lo: flags=73<UP,LOOPBACK,RUNNING> mtu 65536
    inet 127.0.0.1 netmask 255.0.0.0
    inet6 ::1 prefixlen 128 scopeid 0x10<host>
    loop txqueuelen 1000 (Local Loopback)
    RX packets 0 bytes 0 (0.0 B)
    RX errors 0 dropped 0 overruns 0 frame 0
    TX packets 0 bytes 0 (0.0 B)
    TX errors 0 dropped 0 overruns 0 carrier 0 collisions 0

wlan0: flags=4163<UP,BROADCAST,RUNNING,MULTICAST> mtu 1500
    inet 192.168.1.10 netmask 255.255.255.0 broadcast 192.168.1.255
    inet6 fe80::a943:ea9e:ab80:d318 prefixlen 64 scopeid 0x20<link>
    inet6 fd54:25ea:1ee7:3e00:b13f:4fe2:7824:4eed prefixlen 64 scopeid 0x0<global>
    ether dc:a6:32:48:4c:e3 txqueuelen 1000 (Ethernet)
    RX packets 883 bytes 104740 (102.2 KiB)
    RX errors 0 dropped 0 overruns 0 frame 0
    TX packets 147 bytes 20576 (20.0 KiB)
    TX errors 0 dropped 0 overruns 0 carrier 0 collisions 0
```

- Execute `netstat -nr`. Note down Gateway IP : 192.168.1.1, it will be used to set static\_routers

```
pi@raspberrypi:~$ netstat -nr
Kernel IP routing table
Destination        Gateway            Genmask           Flags        MSS Window  irtt Iface
0.0.0.0            192.168.1.1       0.0.0.0           UG           0 0        0 eth0
0.0.0.0            192.168.1.1       0.0.0.0           UG           0 0        0 wlan0
192.168.1.0        0.0.0.0           255.255.255.0     U            0 0        0 eth0
192.168.1.0        0.0.0.0           255.255.255.0     U            0 0        0 wlan0
```

- Execute `sudo nano /etc/dhcpd.conf`. File will be opened in edit mode. Add top four lines at the beginning of file. Ctrl+X and Y to save the file.

```
interface eth0
    static ip_address=192.168.1.11
    static_routers=192.168.1.1
    static_domain_servers=8.8.8.8
# A sample configuration for dhcpdd.
# See dhcpdd.conf(5) for details.
```

- Execute `sudo reboot` to reboot Raspberry Pi
- Execute `ifconfig` and check the inet address, it must be the one given above.



- References

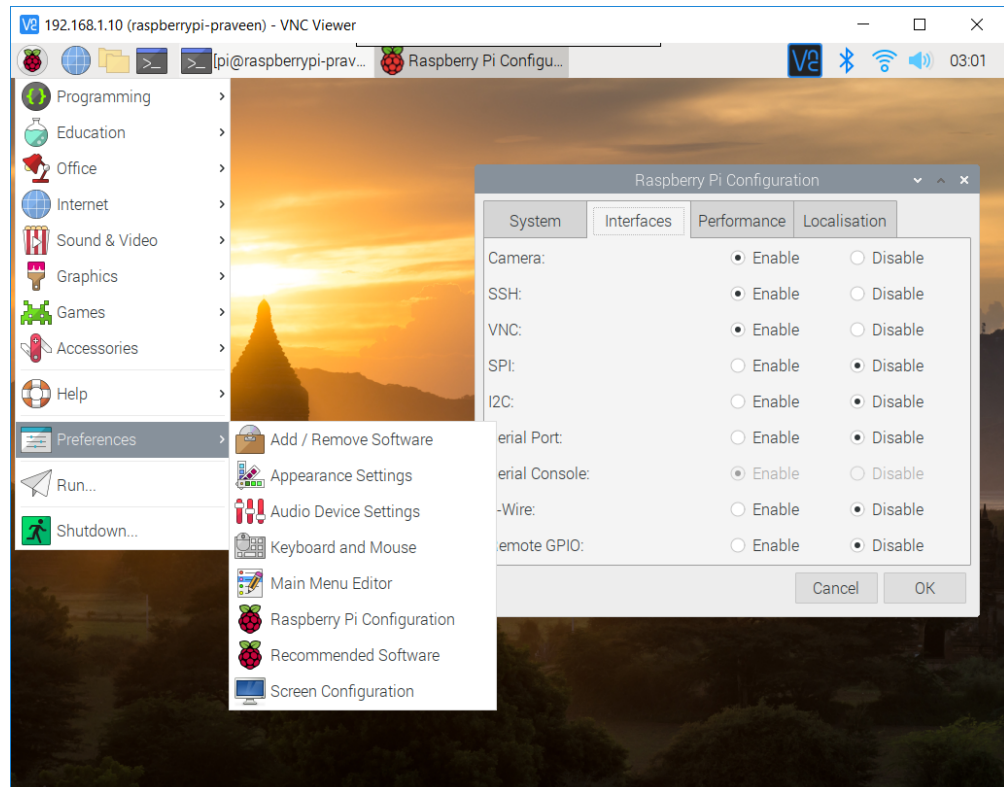
- <https://magpi.raspberrypi.org/articles/set-up-raspberry-pi-4>
- <https://projects.raspberrypi.org/en/projects/raspberry-pi-setting-up>
- <https://www.instructables.com/id/How-to-Setup-a-Raspberry-Pi/>

- **Setup Camera**

- Reference: <https://projects.raspberrypi.org/en/projects/getting-started-with-picamera>

- Enable Camera

- Open Raspberry Pi Configuration
- Go to 'Interfaces' tab and select Camera 'Enabled'



- Reboot *sudo reboot now*
- Attach camera to Raspberry pi
- Enter *raspistill -o Desktop/image.jpg* to take an image from raspberry pi. It gets saved on Desktop
- Check image

- **Deploy image classification model**

- Reference: [Part 2 - How to Run TensorFlow Lite Object Detection Models on the Raspberry Pi \(with Optional Coral USB Accelerator\)](#)

- TensorFlow Lite

- Followed step by step instructions in the tutorial and it worked without any issue. Summarized steps/commands.

1. *sudo apt-get update*
2. *sudo apt-get dist-upgrade* (Time consuming)
3. Download code from github

1. *git clone* <https://github.com/EdjeElectronics/TensorFlow-Lite-Object-Detection-on-Android-and-Raspberry-Pi.git>



2. Move code to tflite1 directory `mv TensorFlow-Lite-Object-Detection-on-Android-and-Raspberry-Pi tflite1`
3. Change directory `cd tflite1`
4. Create Virtual Environment for isolation
  1. Install virtual environment `sudo pip3 install virtualenv`
  2. Create virtual environment `source tflite1-env/bin/activate`
5. Install dependencies `bash get_pi_requirements.sh`
6. Google's sample TFLite model
  1. Download `wget https://storage.googleapis.com/download.tensorflow.org/models/tflite/coco\_ssd\_mobilenet\_v1\_1.0\_quant\_2018\_06\_29.zip`
  2. Unzip `unzip coco_ssd_mobilenet_v1_1.0_quant_2018_06_29.zip -d Sample_TFLite_model`
7. Run model to start webcam and start making predictions
  1. `python3 TFLite_detection_webcam.py --modeldir=Sample_TFLite_model`
8. Awesome!!!

## References

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- [How to Set Static IP for Raspberry Pi in Raspbian Jessie](#)
- [2016: Assign a Static IP Address to Raspberry Pi](#)
- [Raspberry Pi - Tutorial 12 - Networking - How to Configure a Static IP Address & Setup Wifi](#)
- <https://magpi.raspberrypi.org/articles/set-up-raspberry-pi-4>
- <https://projects.raspberrypi.org/en/projects/raspberry-pi-setting-up>
- <https://www.instructables.com/id/How-to-Setup-a-Raspberry-Pi/>
- <https://projects.raspberrypi.org/en/projects/getting-started-with-picamera>
- <https://www.youtube.com/watch?v=aimSGOAUI8Y>
- <https://www.techrepublic.com/article/raspberry-pi-and-machine-learning-how-to-get-started/>
- <https://www.youtube.com/watch?v=npZ-8Nj1YwY>
- [https://github.com/EdjeElectronics/TensorFlow-Lite-Object-Detection-on-Android-and-Raspberry-Pi/blob/master/Raspberry\\_Pi\\_Guide.md#step-1e-run-the-tensorflow-lite-model](https://github.com/EdjeElectronics/TensorFlow-Lite-Object-Detection-on-Android-and-Raspberry-Pi/blob/master/Raspberry_Pi_Guide.md#step-1e-run-the-tensorflow-lite-model)
- [https://github.com/EdjeElectronics/TensorFlow-Lite-Object-Detection-on-Android-and-Raspberry-Pi/blob/master/Raspberry\\_Pi\\_Guide.md](https://github.com/EdjeElectronics/TensorFlow-Lite-Object-Detection-on-Android-and-Raspberry-Pi/blob/master/Raspberry_Pi_Guide.md)
- <https://www.pyimagesearch.com/2017/10/02/deep-learning-on-the-raspberry-pi-with-opencv/>
- <https://www.pyimagesearch.com/2017/10/16/raspberry-pi-deep-learning-object-detection-with-opencv/>
- [Matchbox Keyboard - Raspberry Pi Touchscreen Keyboard](#)