

European Signal Processing Conference 2011

View Interpolation With Structured Depth From Multiview Video

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Outline

- Motivation
- Depth Consistency Testing
- Inter-view Connection Information
- Structured Depth Maps
- Virtual View Interpolation
- Experimental Results
- Conclusions



Imaging





Classical Imaging



Imaging













Multiview Imaging







User



























User



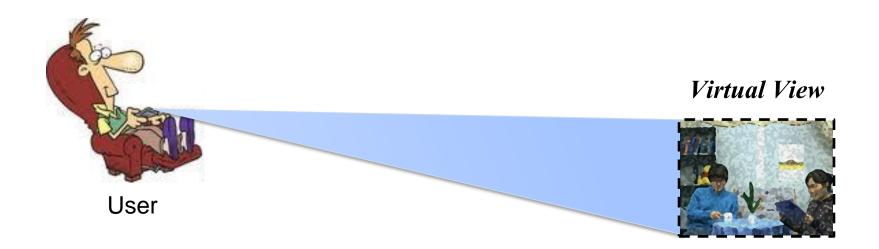




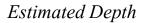
User











 $view_{n+1}$

 $view_{n-1}$



Reference Texture

3D Warping

3D Warping

Warped Texture





Hole Filling &

Hole Filling & Inpainting



virtual view_n

Virtual Texture

Estimated Depth



Reference Texture



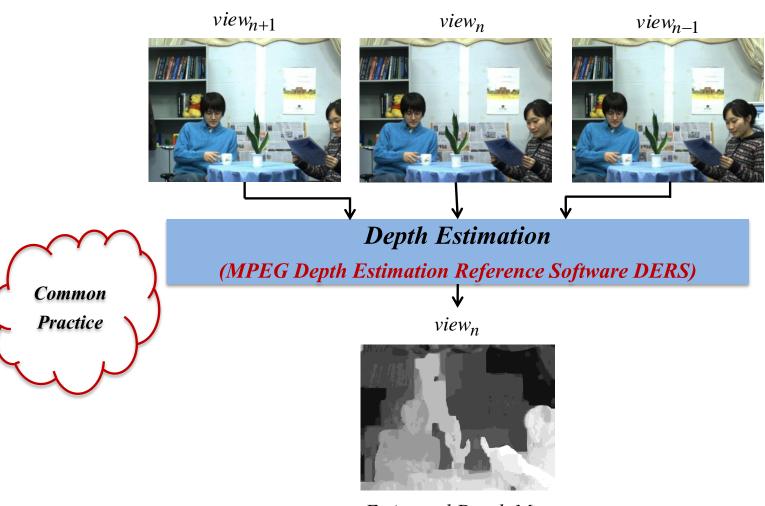
Warped Texture

MPEG View Synthesis Reference Software 3.5 (VSRS 3.5)



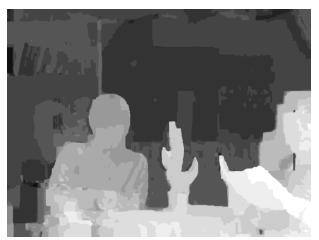
Depth Estimation

Reference Textures

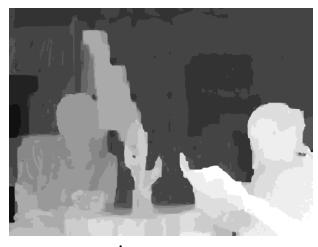


Estimated Depth Map









 $view_{n+1}$

 $view_n$

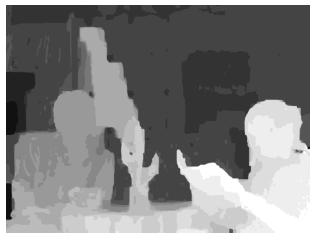
 $view_{n-1}$

Newspaper









 $view_{n+1}$

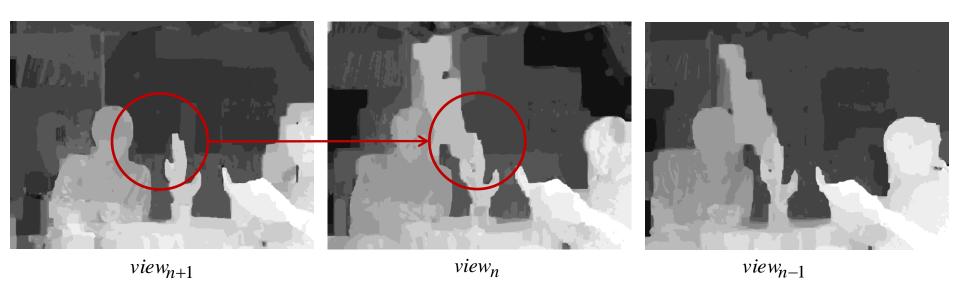
 $view_n$

 $view_{n-1}$

Newspaper

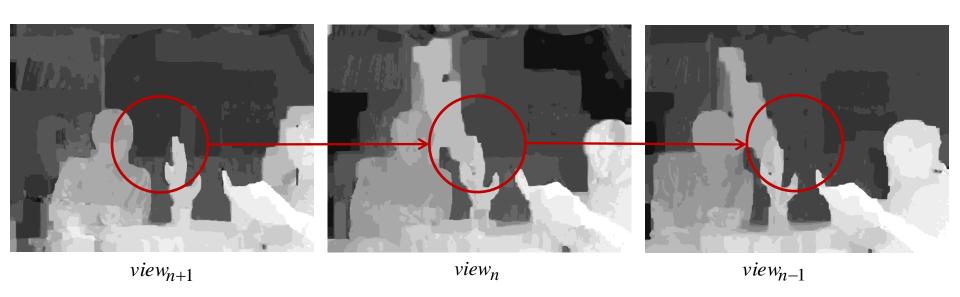
Slide 6





Newspaper





Newspaper









view 2



view n



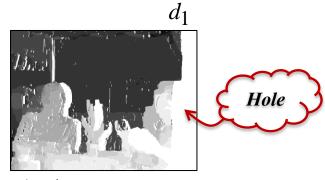


view 2



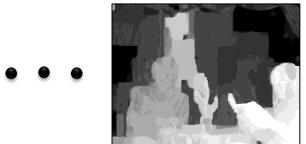
view n

3D Warping to a principal viewpoint p (1≤p≤n)



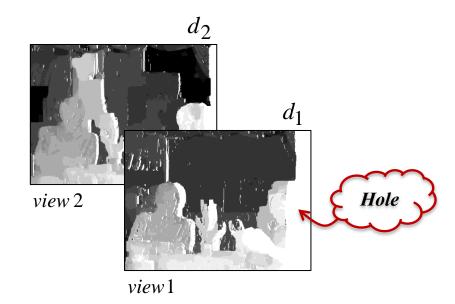
view1



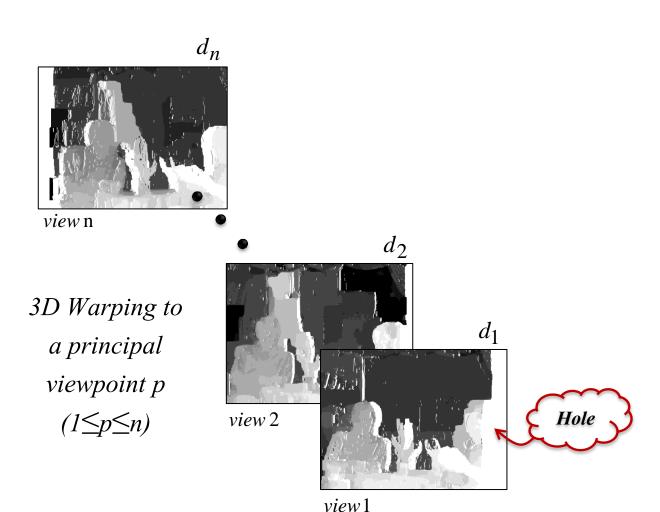


view n

3D Warping to a principal viewpoint p $(1 \le p \le n)$



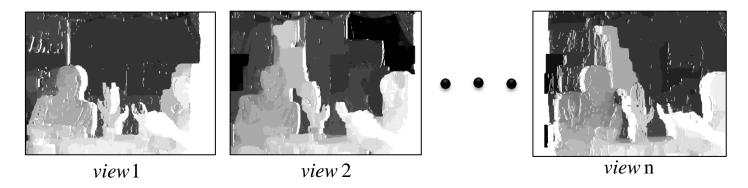




Multiple Warped Depth Maps at a principal viewpoint p



Connection Evidence



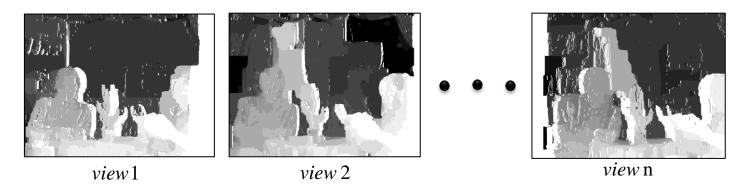
Absolute Difference

Matrix (ADM) =
$$\begin{bmatrix}
0 & \Delta_{1,2} & \cdots & \Delta_{1,n} \\
\Delta_{2,1} & 0 & \cdots & \Delta_{2,n} \\
\vdots & \vdots & \ddots & \vdots \\
\Delta_{n,2} & \Delta_{n,2} & \cdots & 0
\end{bmatrix}$$
Pixel 1

where, $\Delta_{ij} = |d_i - d_j|$ is the absolute difference of depth values between warped depth map d_i and warped depth map d_i at a principal pixel



Connection Evidence



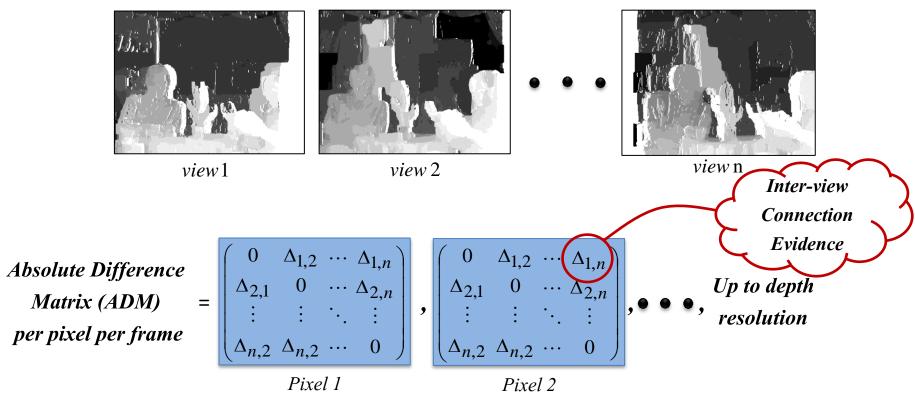
Absolute Difference
$$Matrix (ADM) = \begin{bmatrix} 0 & \Delta_{1,2} & \cdots & \Delta_{1,n} \\ \Delta_{2,1} & 0 & \cdots & \Delta_{2,n} \\ \vdots & \vdots & \ddots & \vdots \\ \Delta_{n,2} & \Delta_{n,2} & \cdots & 0 \end{bmatrix}, \begin{bmatrix} 0 & \Delta_{1,2} & \cdots & \Delta_{1,n} \\ \Delta_{2,1} & 0 & \cdots & \Delta_{2,n} \\ \vdots & \vdots & \ddots & \vdots \\ \Delta_{n,2} & \Delta_{n,2} & \cdots & 0 \end{bmatrix}, \bullet \bullet \bullet, Up to depth resolution$$

$$Pixel 1 \qquad Pixel 2$$

where, $\Delta_{ij} = |d_i - d_j|$ is the absolute difference of depth values between warped depth map d_i and warped depth map d_i at a principal pixel



Connection Evidence



where, $\Delta_{ij} = |d_i - d_j|$ is the absolute difference of depth values between warped depth map d_i and warped depth map d_i at a principal pixel



Connection Evidence Testing

Connection Threshold

- Define quality of the inter-view connection per frame

$$T=\mu + \lambda \sigma$$
,

where,

 $\mu = Mean \ of \ all \ ADM \ per \ frame$

 σ = Standard deviation of all ADM per frame

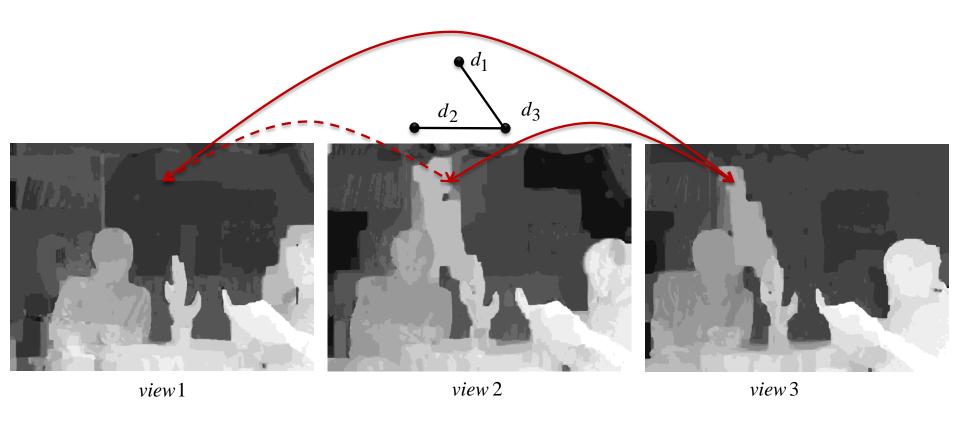
 λ = Trade-off between quality of connection and number of connection, in the rendering experiment λ = 0.8.

• Testing Rule

- Δ_{ij} < T : Accept the connection evidence and assume the corresponding depth pair have a consistent depth representation
- $-\Delta_{ij} \geq T$: Reject the connection evidence



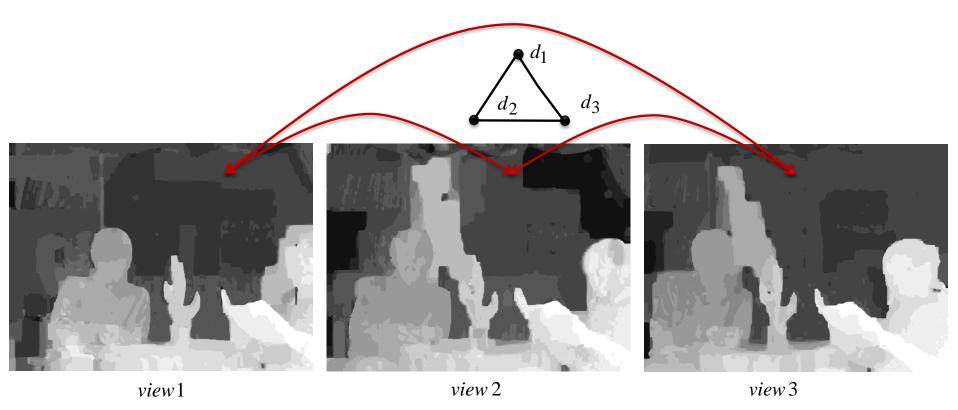
Inter-View Connection Information



Example for inter-view connection information with three reference views, n=3.



Inter-View Connection Information

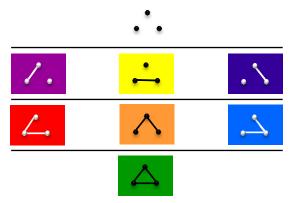


Example for inter-view connection information with three reference views, n=3.



Inter-View Connection Information

Possible cases of inter-view connectivity for n = 3:



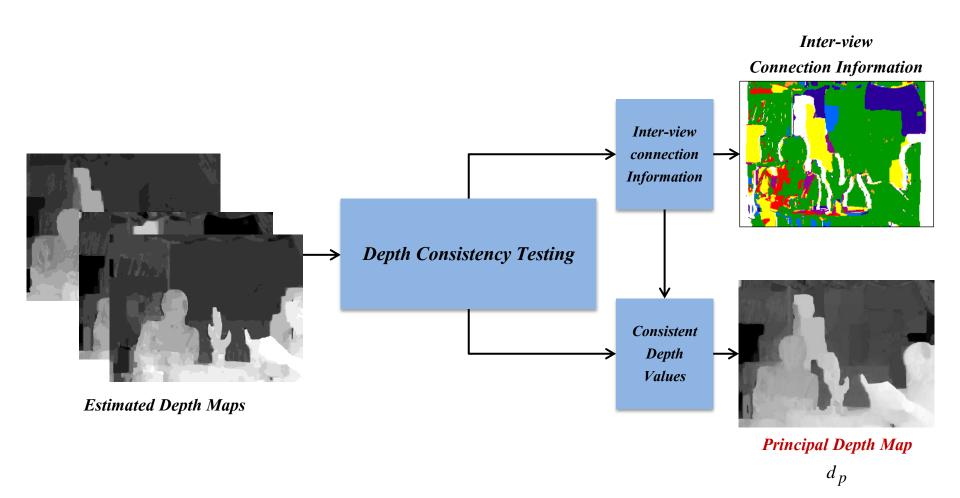
<u>Use of Connection Information:</u>

- To obtain consistent depth values
- To combine texture pixels from multiple viewpoint reliably





Principal Depth Map





Structured Depth Maps



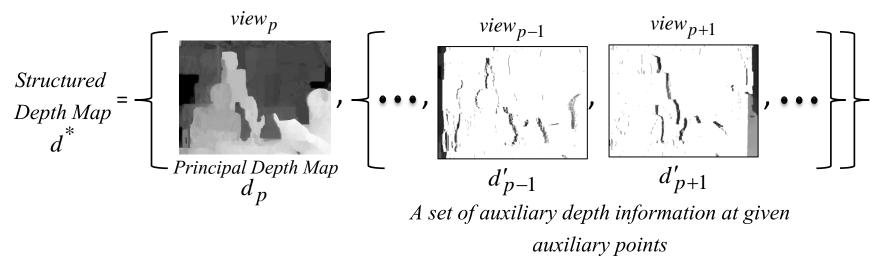




- To have inter-view consistent depth maps
- To remove **redundancy** from depth maps



Structured Depth Maps



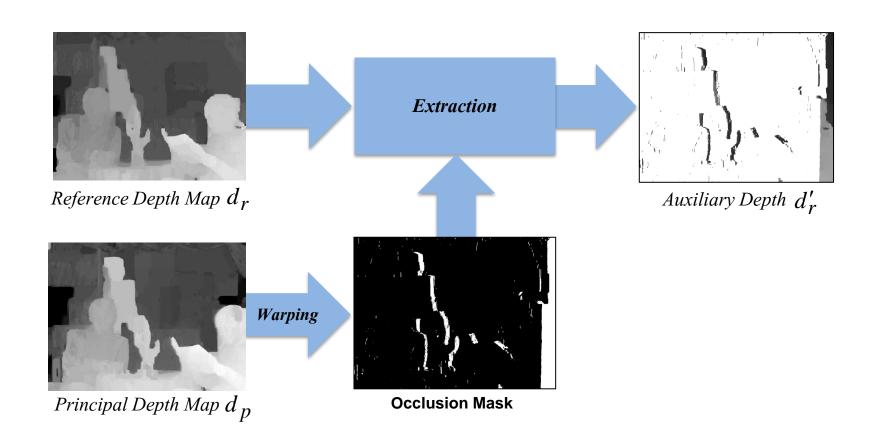
Cardinality of the set of auxiliary depth information:

$$|d'| = \begin{cases} (N-1) & \text{if } p=r, \text{ for all reference viewpoint } r, \\ N & \text{if } p \neq r \text{ for all reference viewpoint } r, \end{cases}$$

where, N= total number of reference views used in the depth consistency testing.

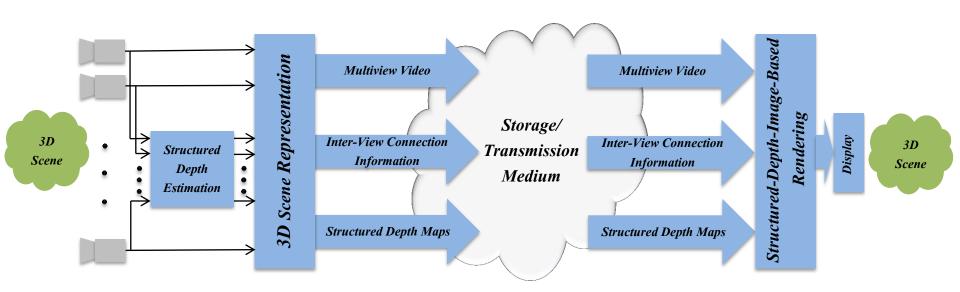


Extraction of Auxiliary Depth





Rendering Using Structured Depth Images











 $view_{n+1}$



view_n



 $view_{n-1}$



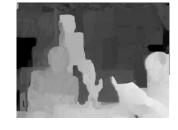
User



 $view_{n+2}$



 $view_{n+1} = p$



 $view_{n-1}$



Enhanced depth maps resulting from SDI



 $view_{n+2}$



 $view_{n+1} = p$

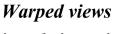


 $view_{n-1}$

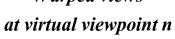


Multiview Texture





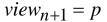






















Warping







Warped views at virtual viewpoint n







 $view_{n+1} = p$







Masked Inter-view
Connection Information













 $view_{n+2}$

Warped views at virtual viewpoint n



Warping



 $view_{n+1} = p$



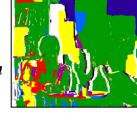
Warping



Masked Inter-view
Connection Information



Warping

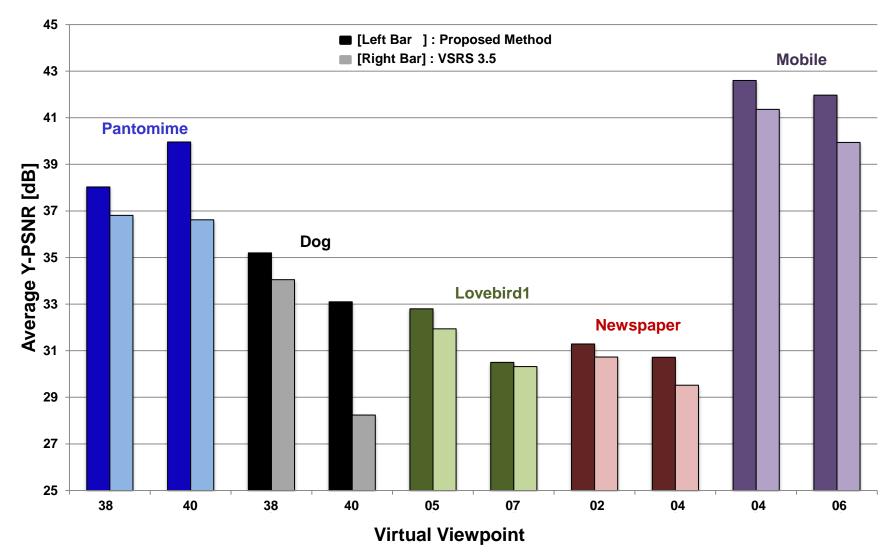


Connection-Adaptive Pixel Intensity Estimation virtual view_n





Experimental Results





Experimental Results

Original

Virtual View by VSRS 3.5

Virtual View by Proposed Method

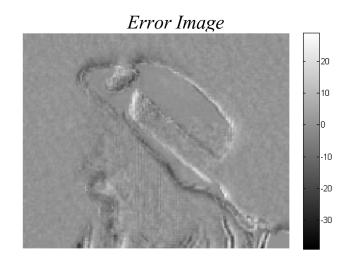






Error Image

- 30 - 20 - 10 - - 10 - - 20 - - 30



VSRS 3.5

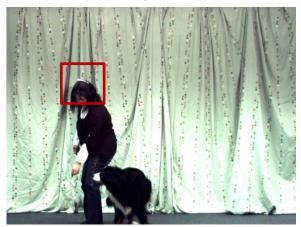
Pantomime

Proposed Method

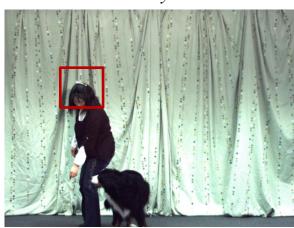


Experimental Results

Original



Virtual View by VSRS 3.5



Virtual View by Proposed Method



Original



Virtual View by VSRS 3.5



Virtual View by Proposed Method



Conclusions

• Depth consistency testing and resulting the inter-view connection information allow to exploit consistency among depth maps

• Structured depth addresses the problems of inter-view depth inconsistencies

• Structured depth permit an appealing 3D scene representation

• Structured depth maps and connection information improves the quality of rendered views

Thank You