

Multiview Depth Image Enhancement for Free-viewpoint Television

Pravin Kumar Rana, Zhanyu Ma, Jalil Taghia, and Markus Flierl

Opponents: Nasser Mohammadiha, Haopeng Li and, Jalil Taghia

Internal seminar, Communication Theory, KTH

June 27, 2013

Motivation & Background

Conventional Television



User



Display

Conventional Television



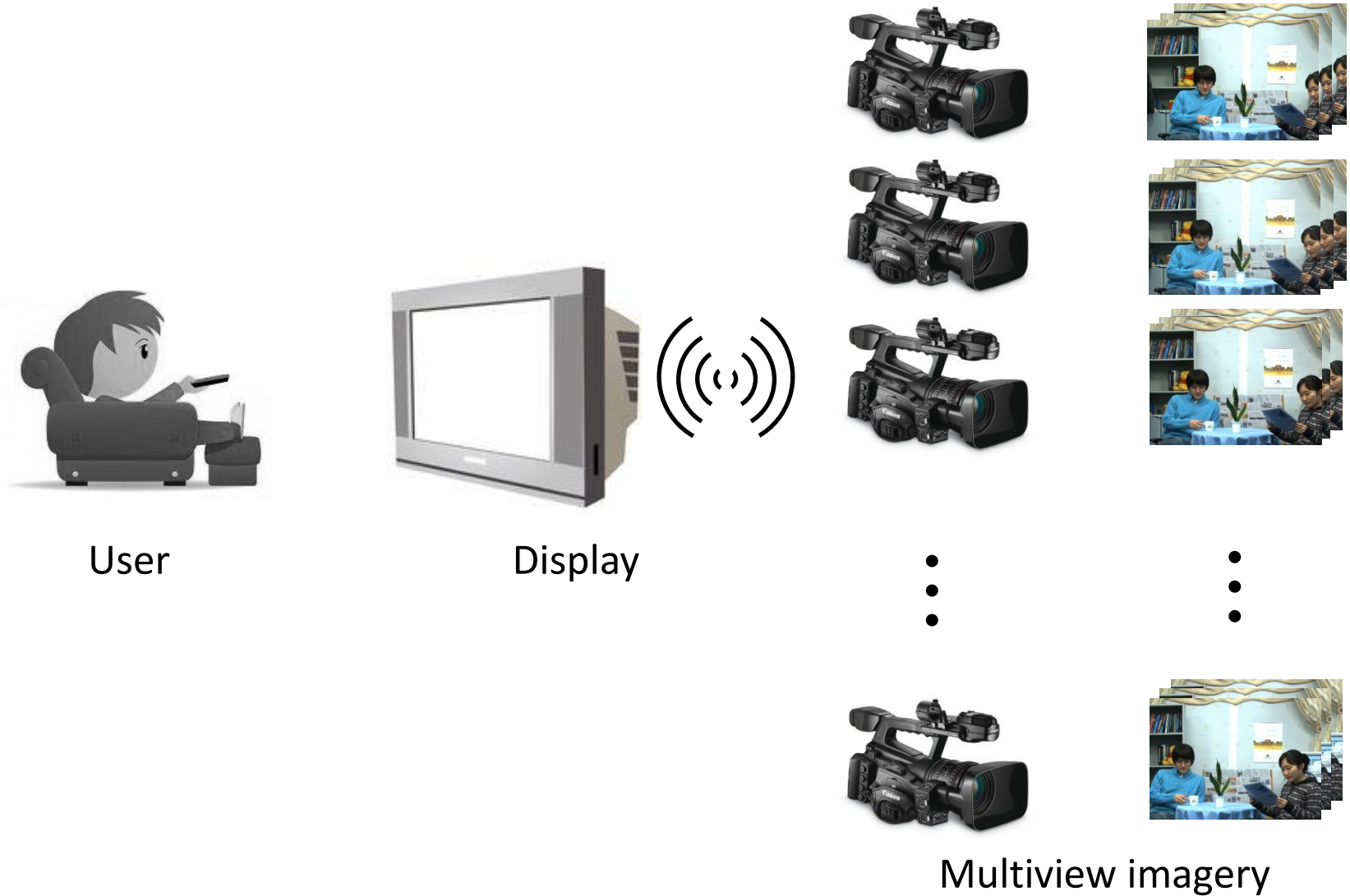
User



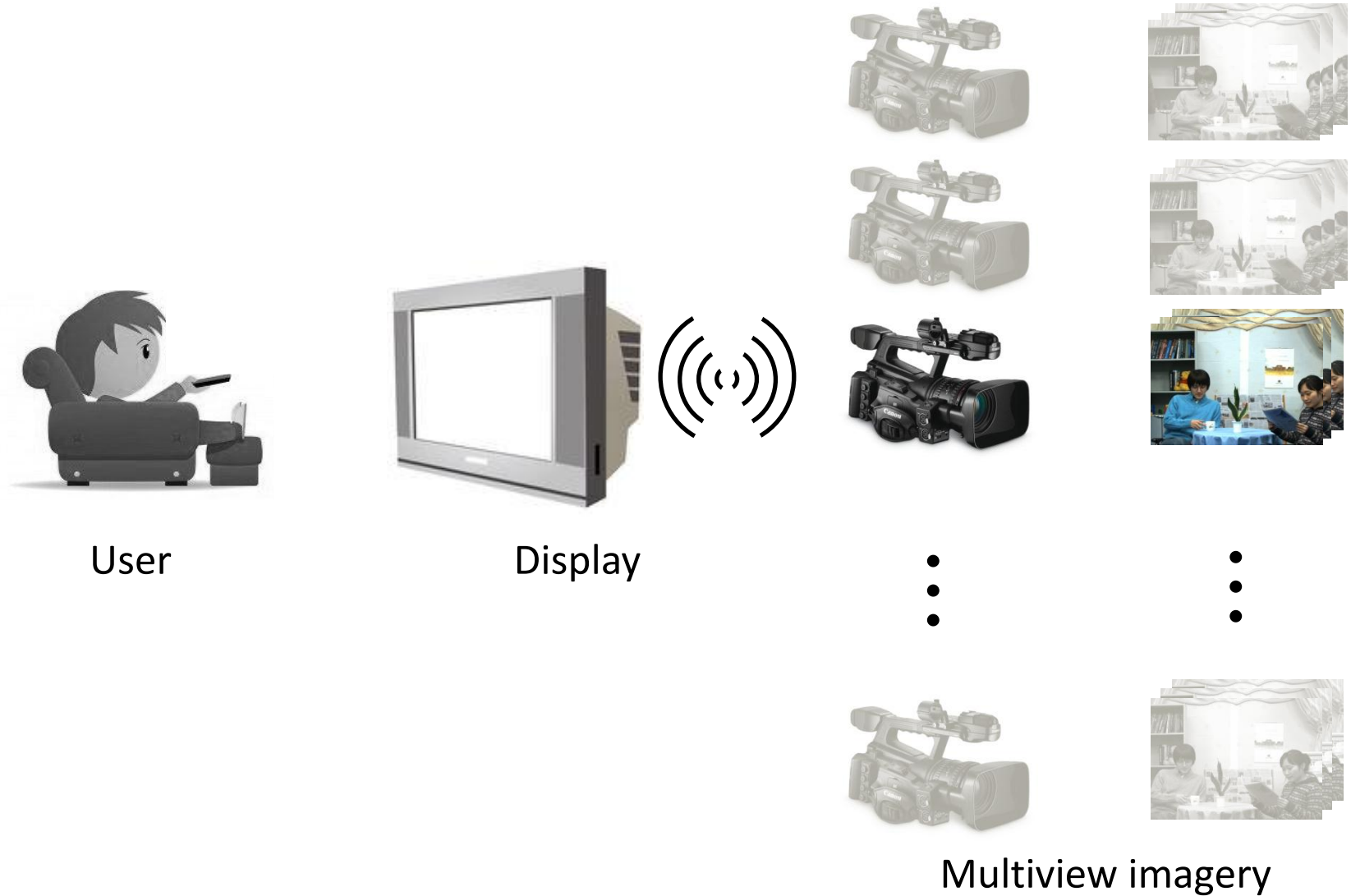
Display



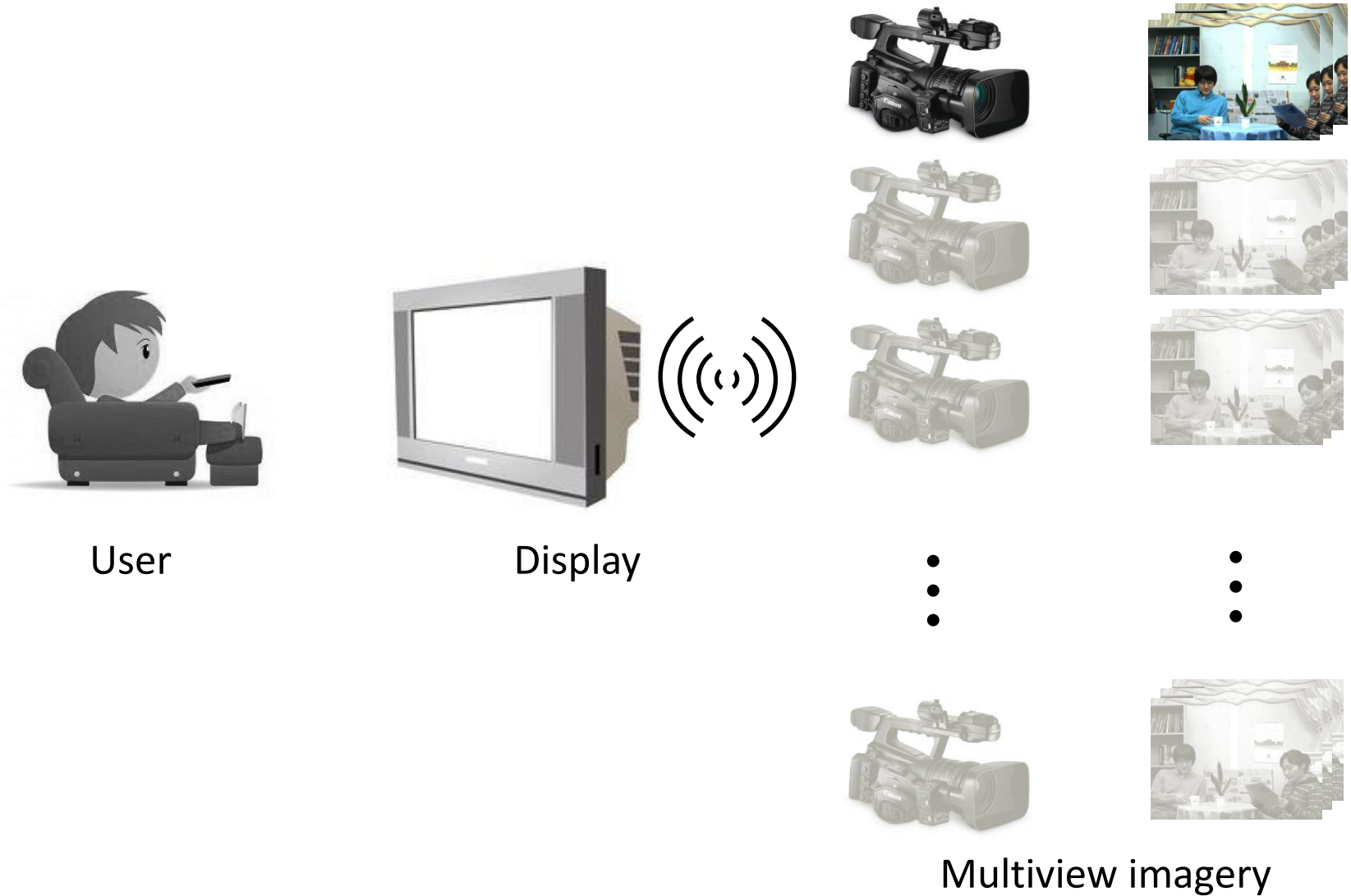
Free-viewpoint Television



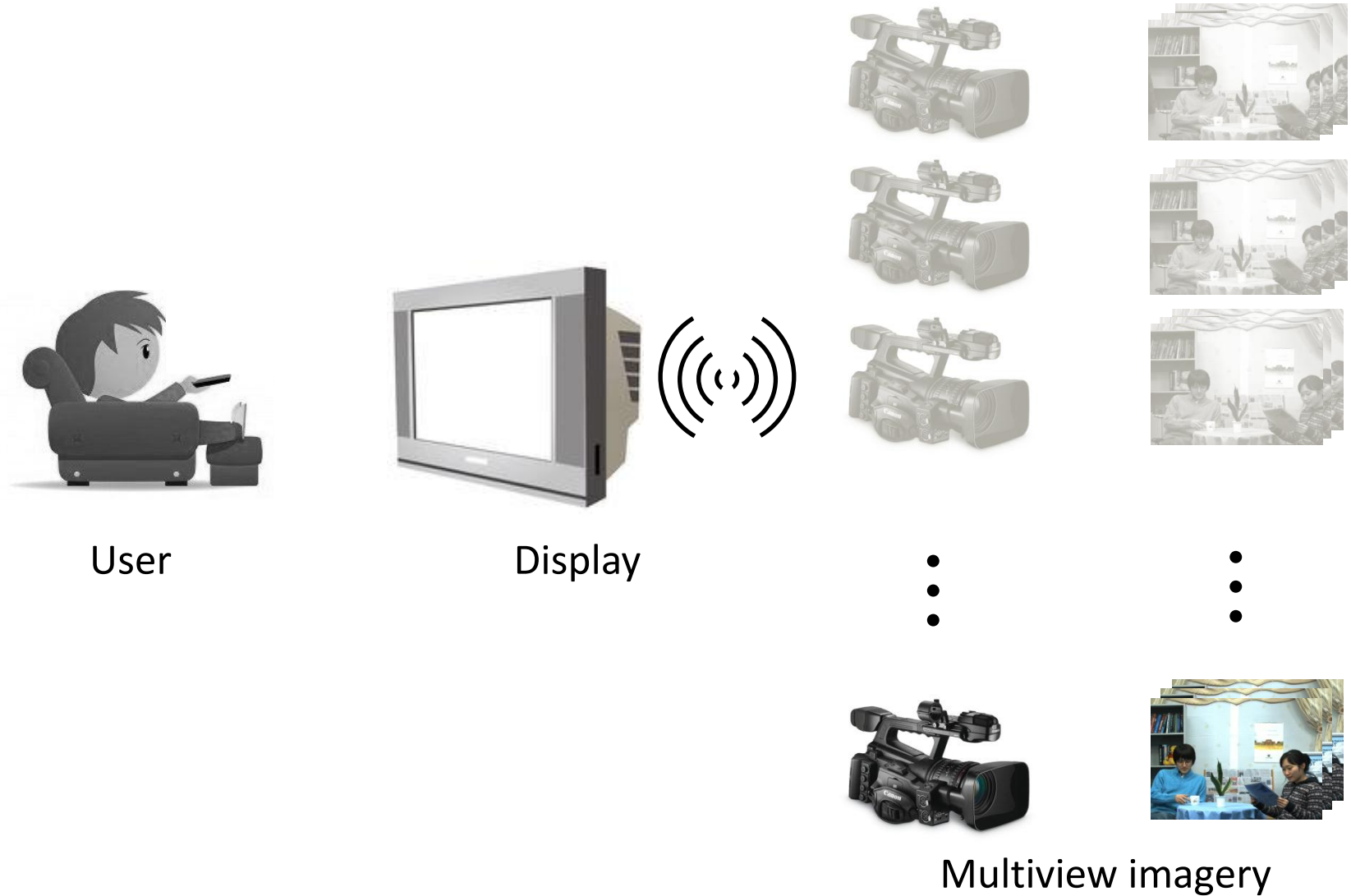
Free-viewpoint Television



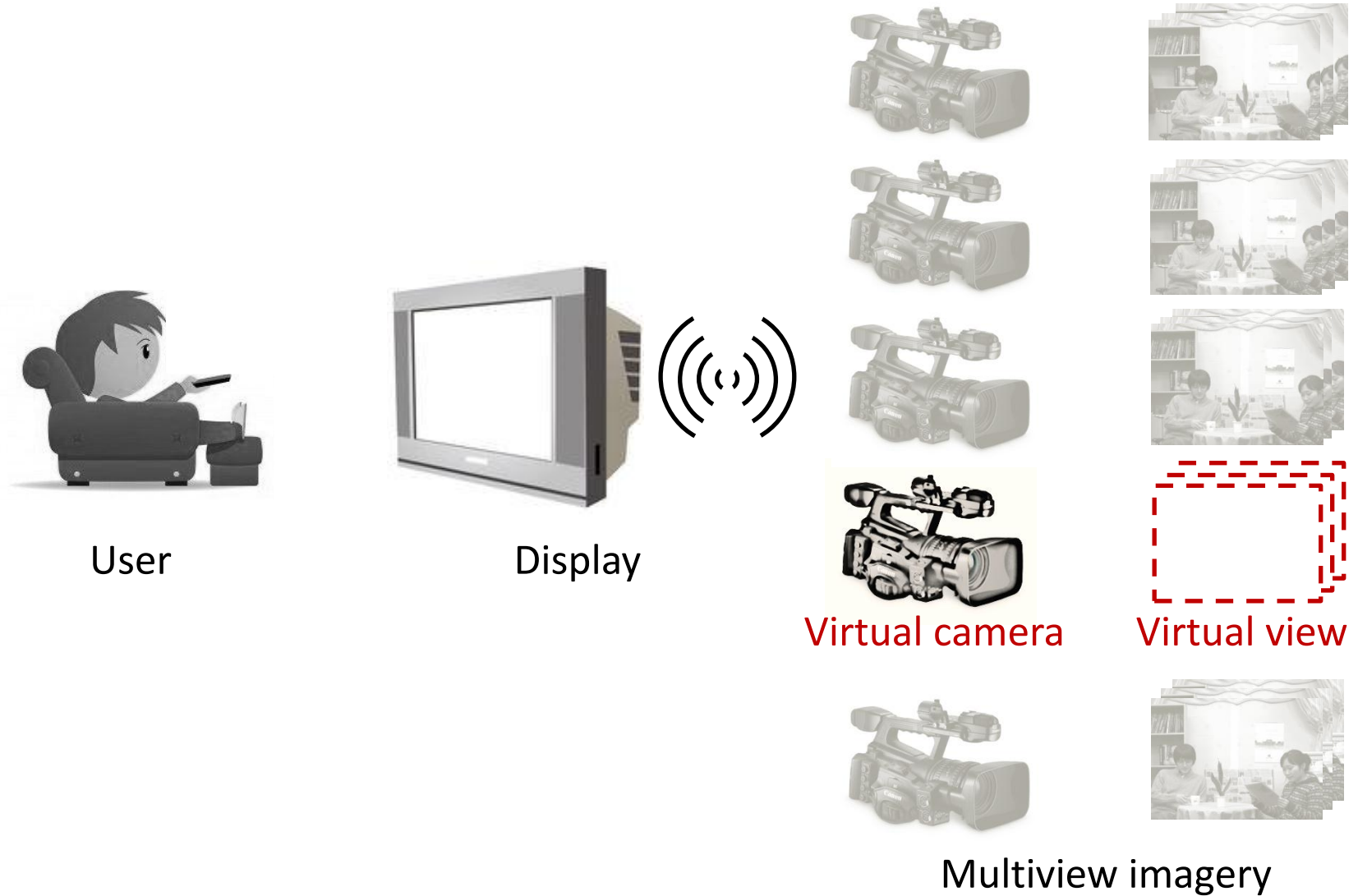
Free-viewpoint Television



Free-viewpoint Television



Free-viewpoint Television



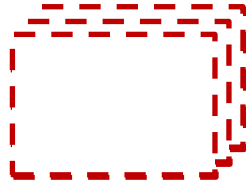
Virtual View Synthesis



Virtual camera



Multiview imagery



Virtual view



Depth Image Based Rendering

Depth Image Based Rendering



Depth image



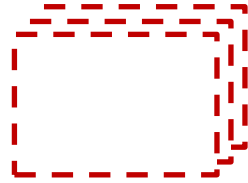
Near



Far



Virtual camera



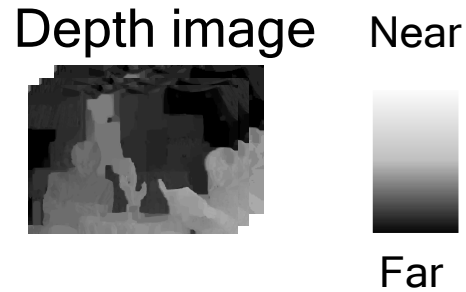
Virtual view



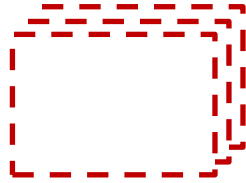
Multiview imagery

Depth Image Based Rendering

- Depth pixels represent shortest distance between object points and the camera plane
- To be estimated from multiview imagery



Virtual camera



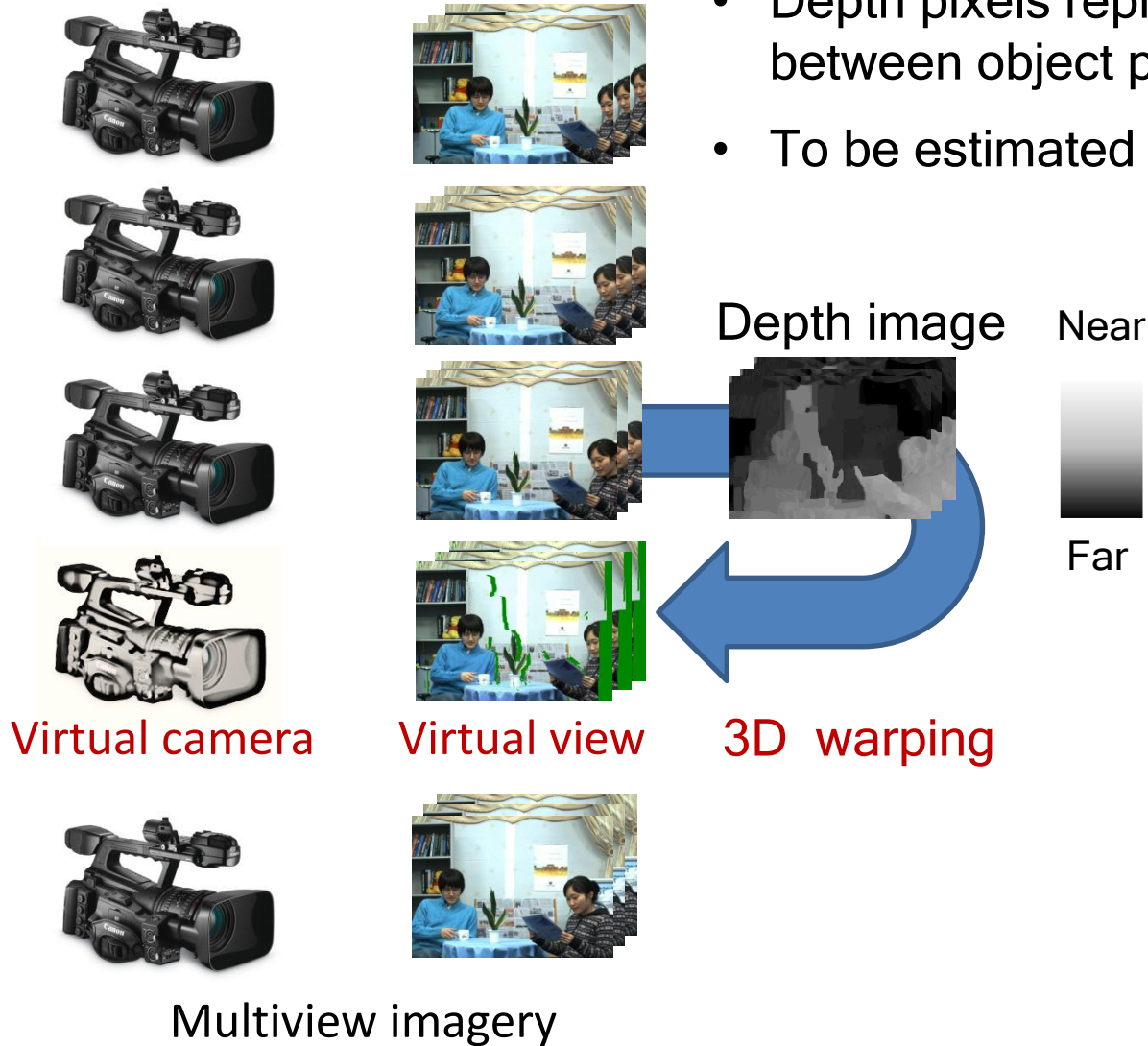
Virtual view



Multiview imagery

Depth Image Based Rendering

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Depth Image Based Rendering

3D Warping

Physical camera
parameters



Virtual camera
parameters



Depth Image Based Rendering

3D Warping

Physical camera
parameters



Virtual camera
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Depth Image Based Rendering

3D Warping

Physical camera
parameters



Virtual camera
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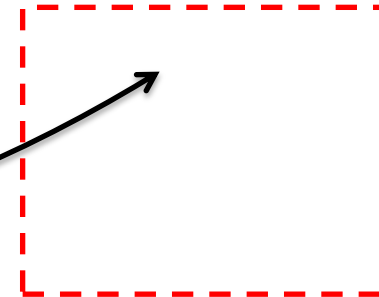
Depth Image Based Rendering

3D Warping

Physical camera
parameters

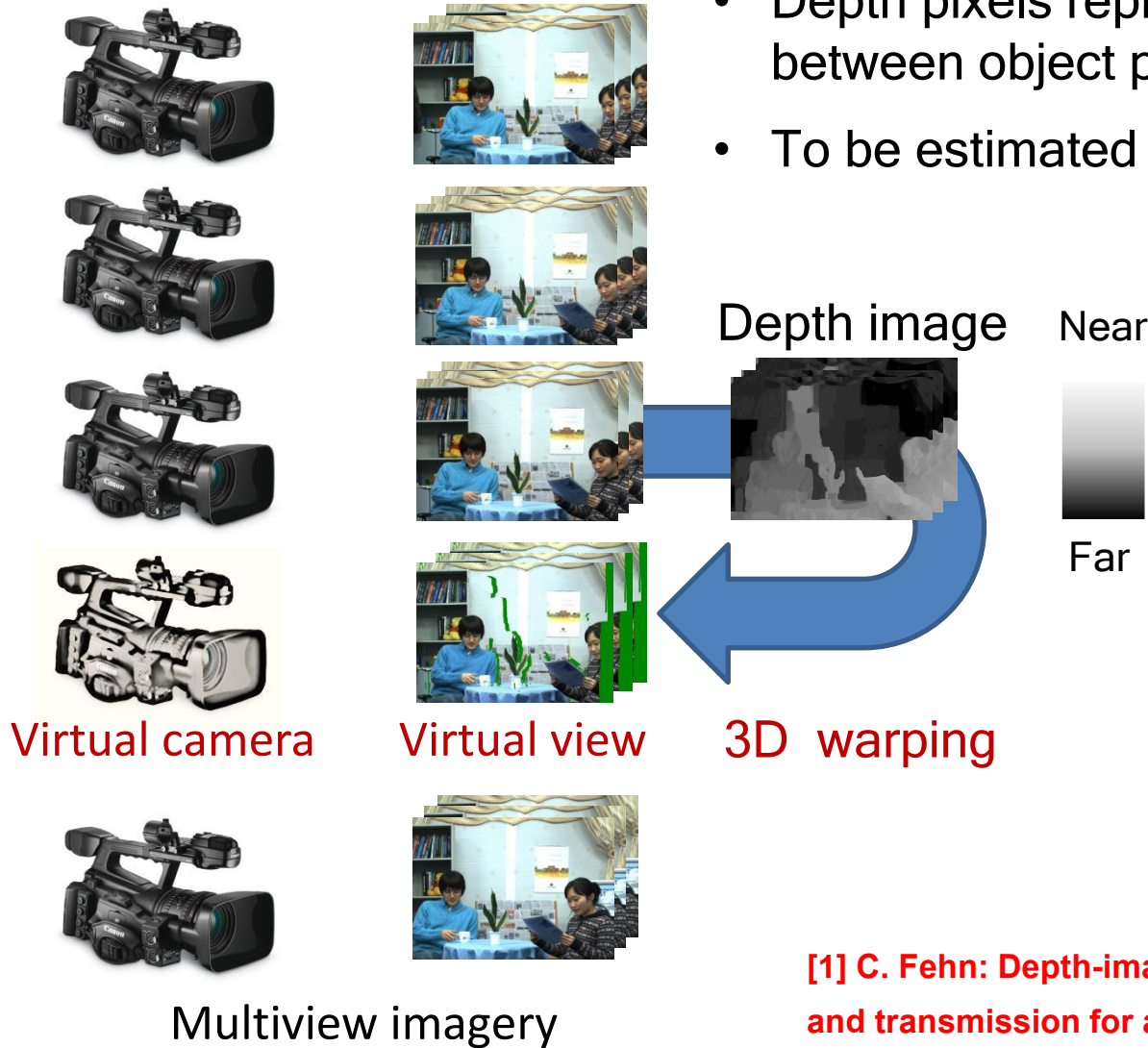


Virtual camera
parameters



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[1] C. Fehn: Depth-image-based rendering DIBR, compression, and transmission for a new approach on 3D-TV, SPIE, 2004.

Depth Image Estimation

MPEG Depth Estimation Reference Software (DERS)

View (n-2)

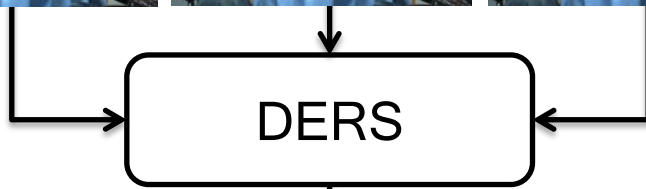
View (n-1)

View (n)

View (n+1)

View (n+2)

View (n+3)



DERS



Estimated depth maps

View (n-1)

Depth Image Estimation

MPEG Depth Estimation Reference Software (DERS)

View (n-2)

View (n-1)

View (n)

View (n+1)

View (n+2)

View (n+3)



Stereo-matching algorithm with
Graph-cut optimization

View (n-1)

Depth Image Estimation

MPEG Depth Estimation Reference Software (DERS)

View (n-2)

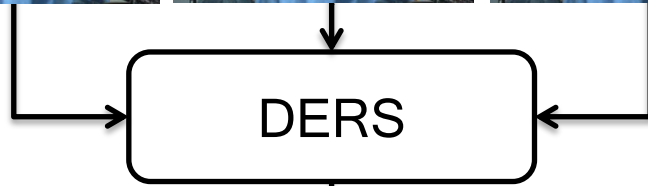
View (n-1)

View (n)

View (n+1)

View (n+2)

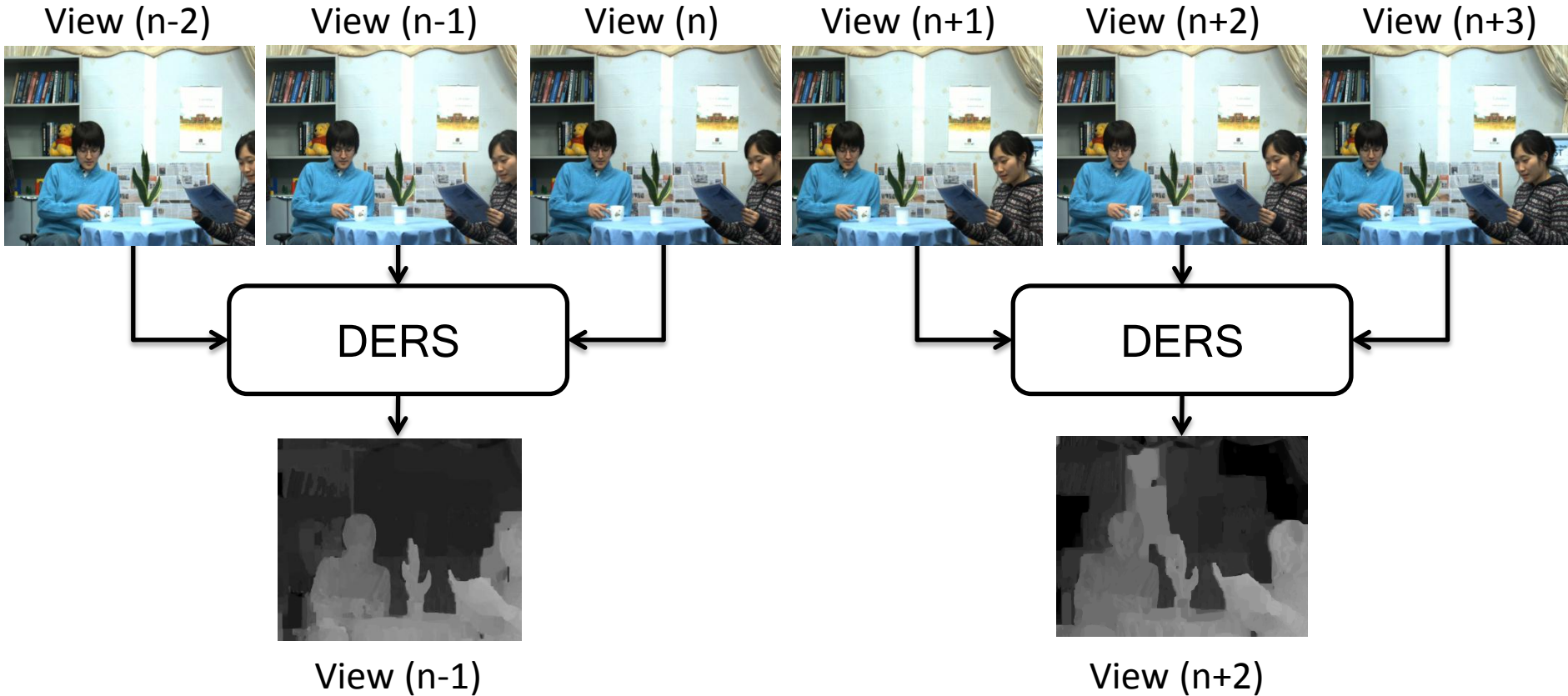
View (n+3)



View (n-1)

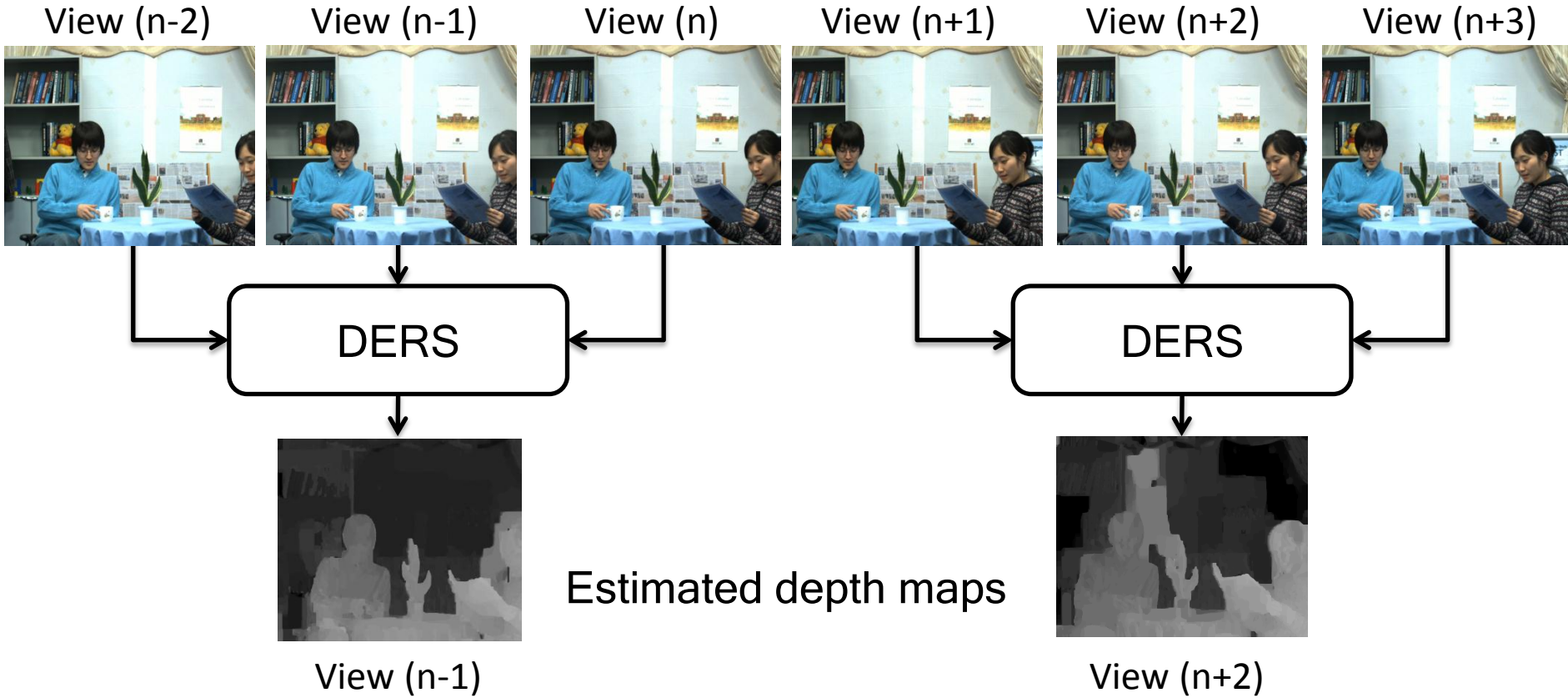
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MPEG Depth Estimation Reference Software (DERS)



Depth Image Estimation

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Depth Image Estimation

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View (n-1)

View (n)

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View (n+3)



View (n-1)



View (n+2)

Note: we assume a 1D-parallel camera arrangement

Depth Image Estimation

MPEG Depth Estimation Reference Software (DERS)

View (n-2)

View (n-1)

View (n)

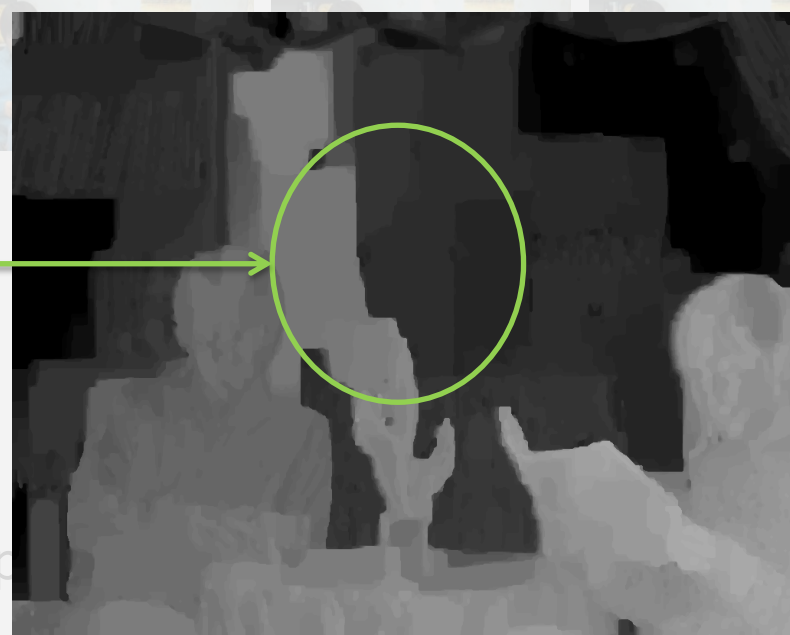
View (n+1)

View (n+2)

View (n+3)



View (n-1)



View (n+2)

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Depth Image Estimation

MPEG Depth Estimation Reference Software (DERS)

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View (n-1)

View (n)

View (n+1)

View (n+2)

View (n+3)



View (n-1)



View (n+2)

Note: we assume a 1D-parallel camera arrangement



Depth Image Estimation

MPEG Depth Estimation Reference Software (DERS)

View (n-2) View (n-1) View (n) View (n+1) View (n+2) View (n+3)



View (n-1)



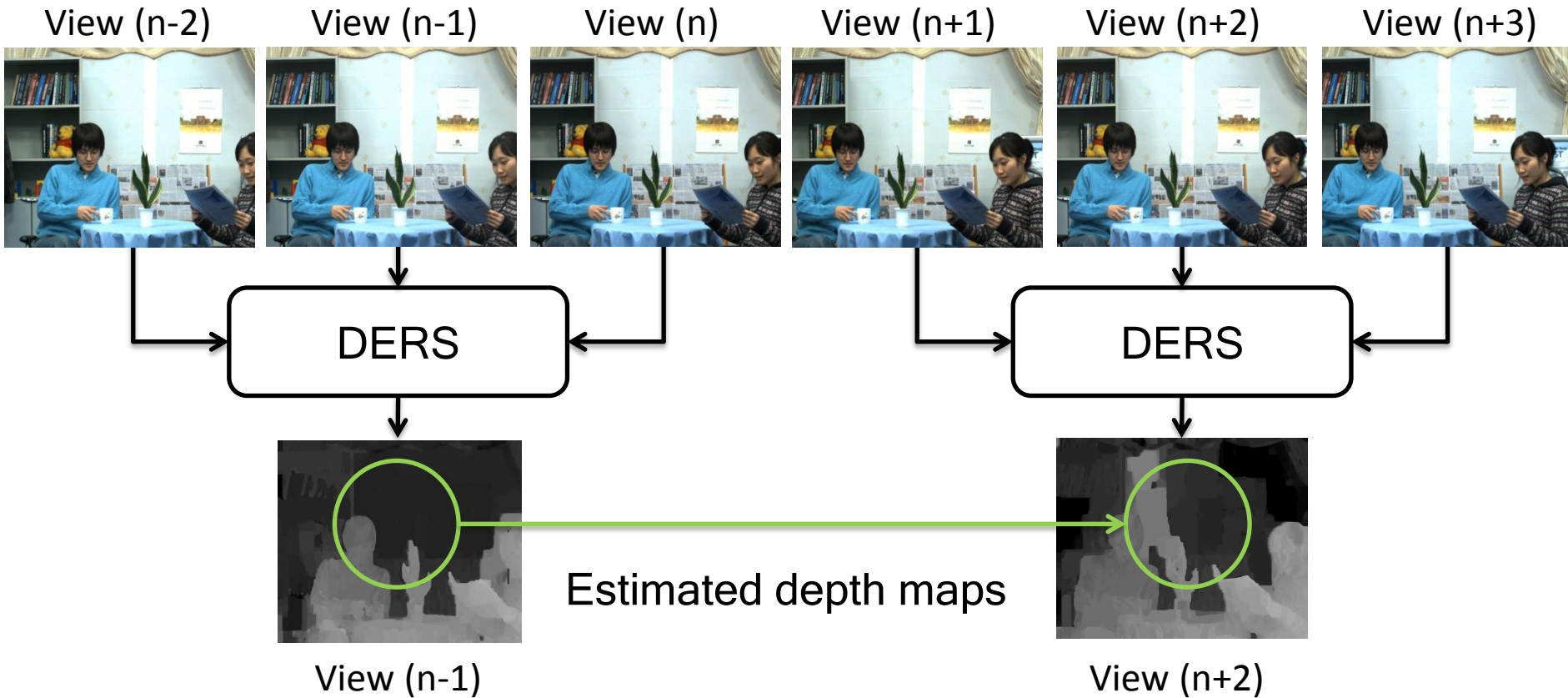
View (n+2)

Problem: Inter-view depth inconsistency

Note: we assume a 1D-parallel camera arrangement

Depth Image Estimation

MPEG Depth Estimation Reference Software (DERS)



Problem: Inter-view depth inconsistency

Note: we assume a 1D-parallel camera arrangement

Depth Enhancement Framework

Overview of Depth Enhancement Framework

Multiview view and depth images



Color Classification

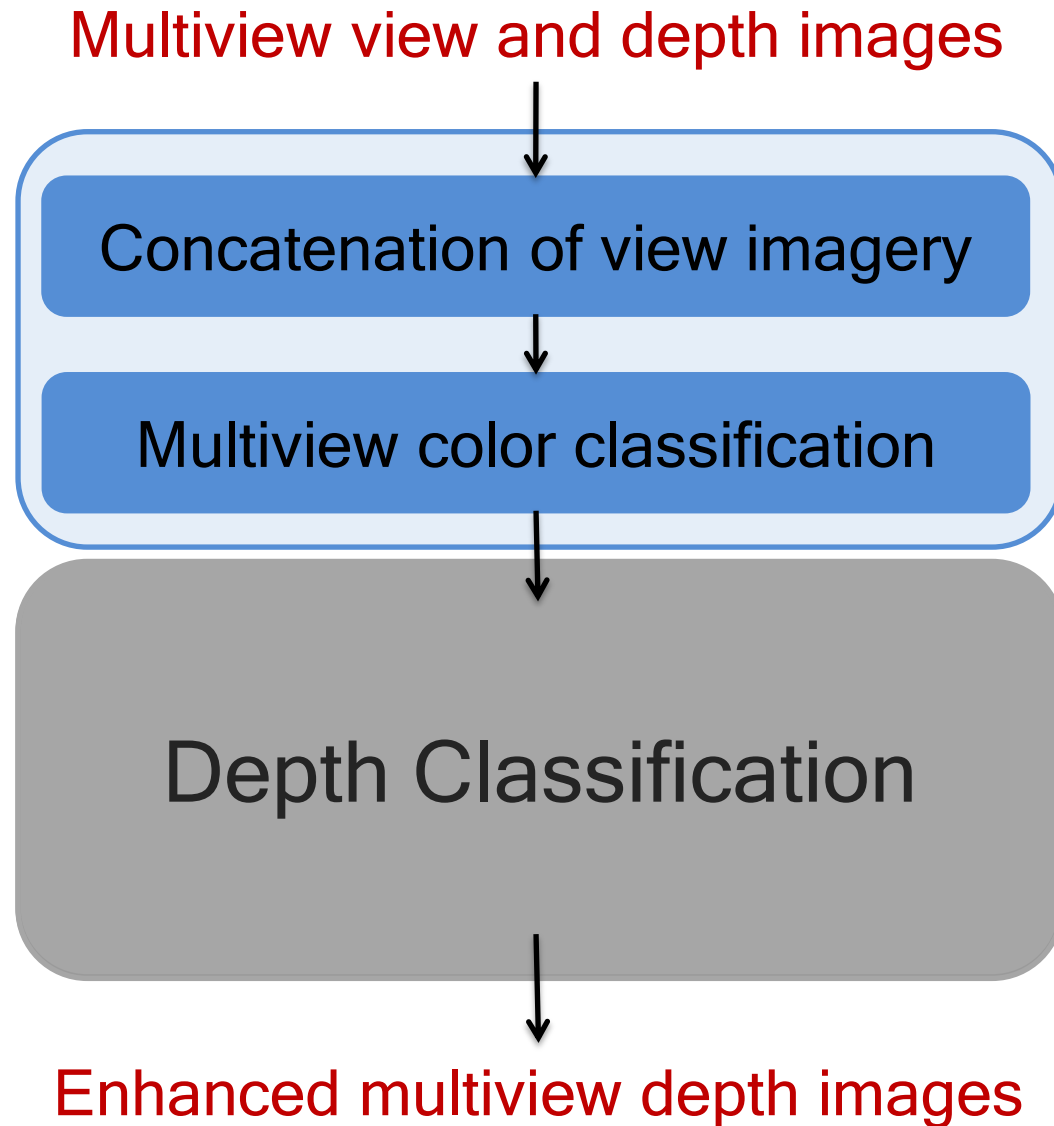


Depth Classification



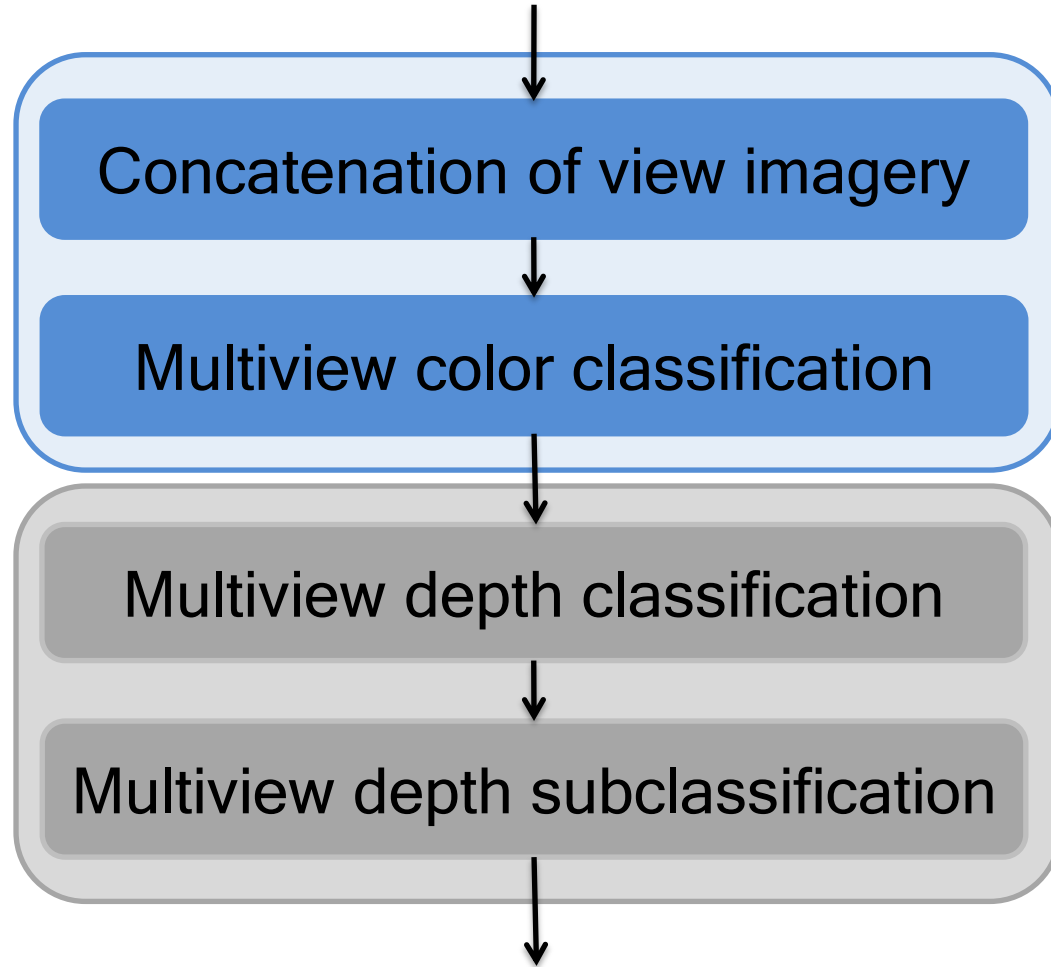
Enhanced multiview depth images

Overview of Depth Enhancement Framework



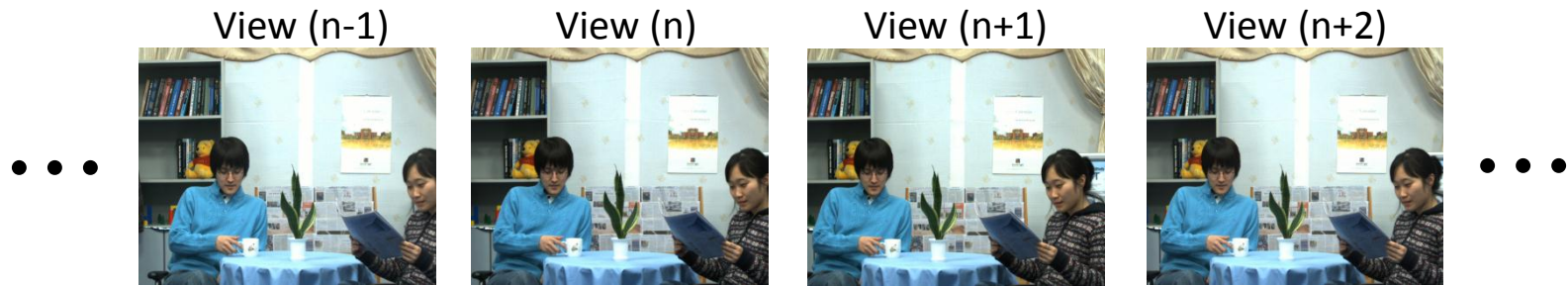
Overview of Depth Enhancement Framework

Multiview view and depth images

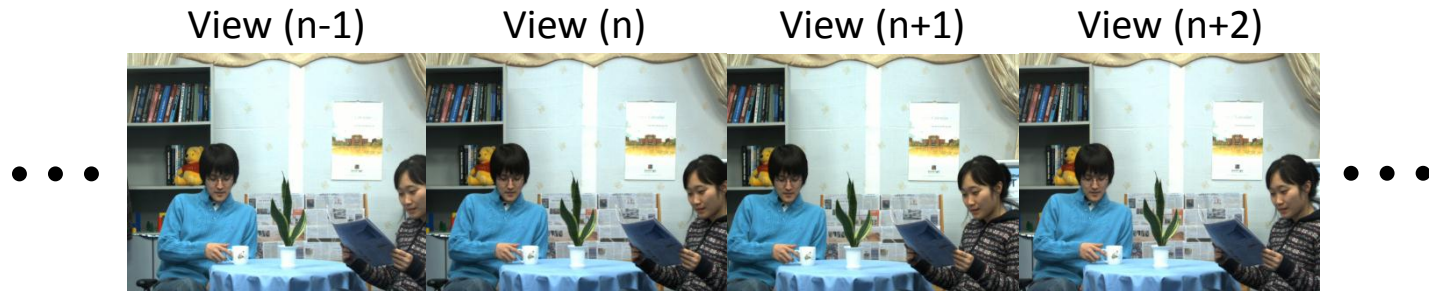
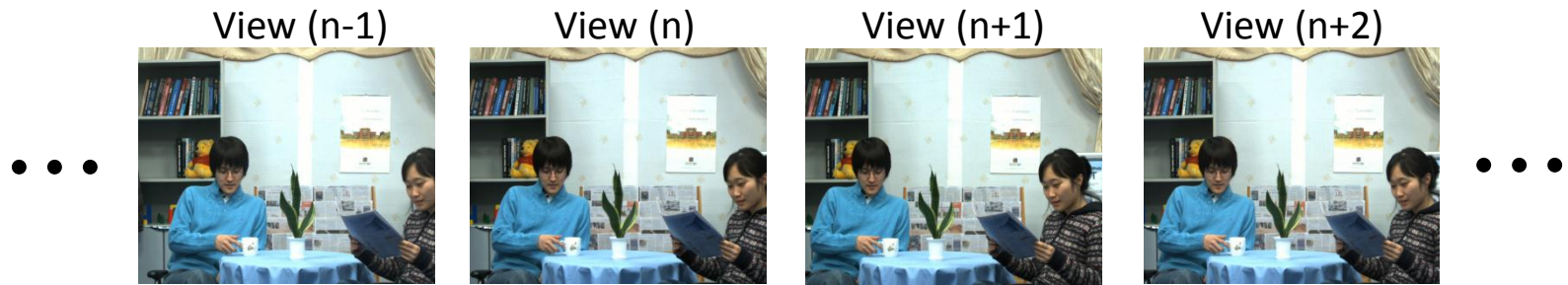


Enhanced multiview depth images

Concatenation of View Imagery



Concatenation of View Imagery



Multiview Color Classification

View (n)

View (n+1)

...



...

RGB Color space

Multiview Color Classification

View (n)

View (n+1)

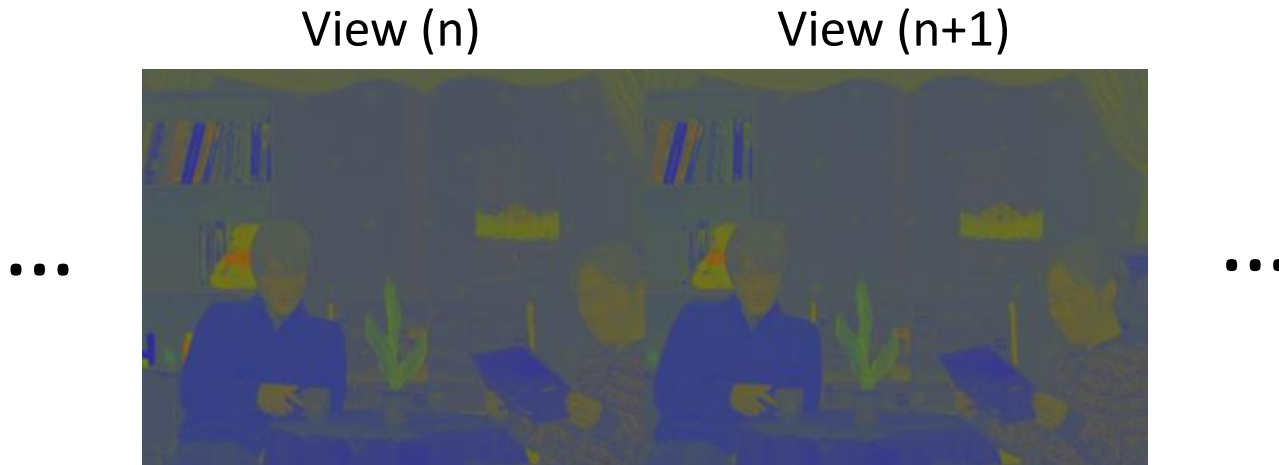
...



...

xyz Chromatic color space

Multiview Color Classification



xyz Chromatic color space

- Insensitive to the absolute luminance
- A pixel is described by a vector of three chromaticity coefficients $[x \ y \ z]^T$, where

$$x+y+z = 1$$

Multiview Color Classification

Why variational Bayes inference (VI)?

- The goal of classification is to partition an image into regions each of which has a reasonably homogeneous visual appearance
- Usually, clustering algorithm suffers from one major drawback that the number of clusters has to be known
- Bayesian approaches automatically and optimally select the number of clusters
- Use of variational inference (VI) framework for Bayesian approaches gives an analytically tractable solution

Multiview Color Classification

Why Dirichlet mixture models (DMM) ?

- The pixel vector in the chromaticity space has
 - nonnegative elements
 - bounded by the interval $[0,1]$
 - sum to one
- Assume that these pixel vectors are Dirichlet distributed
- DMM with variational inference is used to capture all underlying color clusters in multiview imagery
- It reduces complexity

[3] P. K. Rana, J. Taghia, and M. Flierl: A Variational Bayesian Inference Framework for Multiview Depth Image Enhancement, IEEE ISM, 2012.

[4] Z. Ma, P. K. Rana, J. Taghia, M. Flierl, and A. Leijon: Bayesian estimation of Dirichlet mixture model with variational inference, submitted, 2013.

Multiview Color Classification

Newspaper



Balloons



Kendo



Input multiview data

Multiview Color Classification

Newspaper



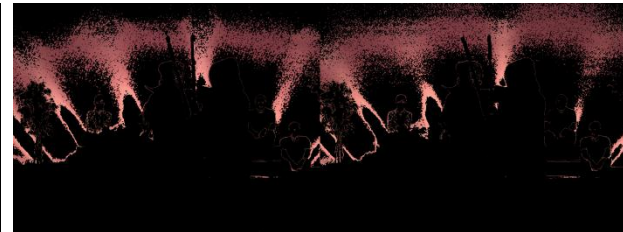
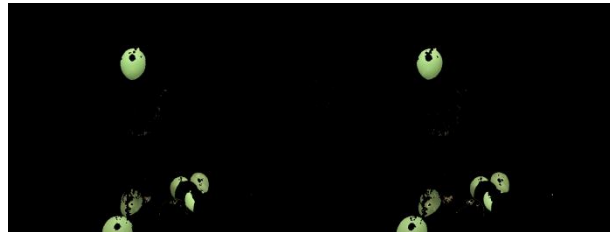
Balloons



Kendo



Input multiview data



Using VI-DMM

Multiview Color Classification

Newspaper



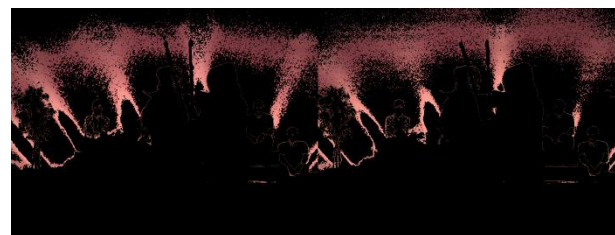
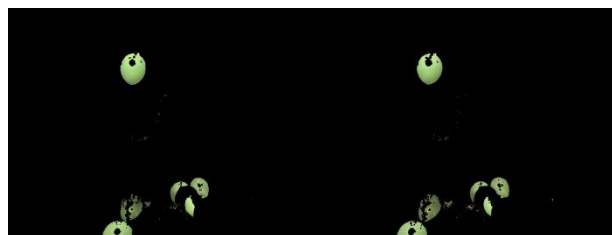
Balloons



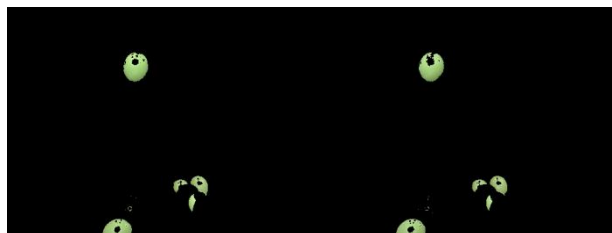
Kendo



Input multiview data



Using VI-DMM



Using VI-GMM

Multiview Color Classification

Newspaper



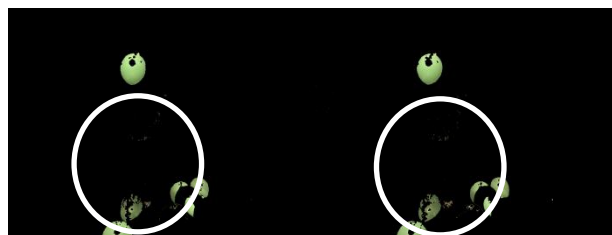
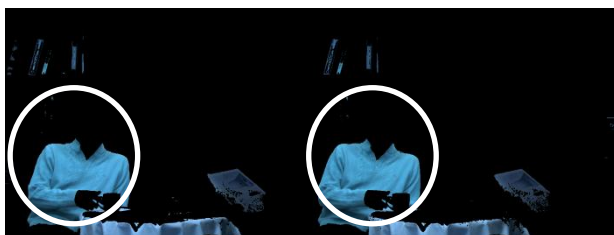
Balloons



Kendo



Input multiview data



Using VI-DMM



Using VI-GMM

Multiview Depth Classification

Exploiting the per-pixel association between color and depth

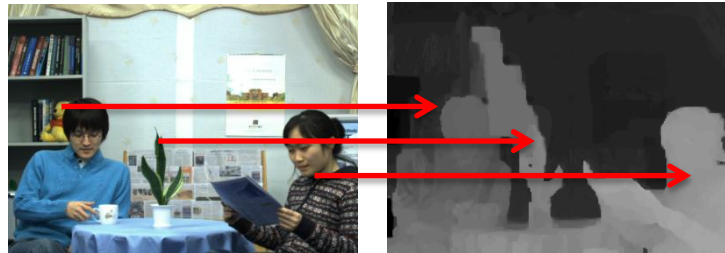


View image

Depth image

Multiview Depth Classification

Exploiting the per-pixel association between color and depth

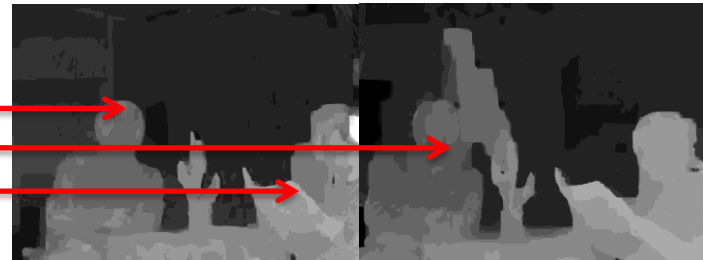


View image

Depth image



Concatenated view imagery



Concatenated depth imagery

Multiview Depth Classification

Newspaper



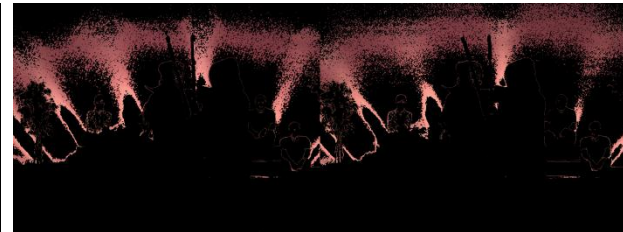
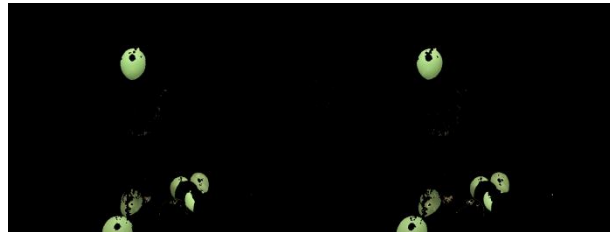
Balloons



Kendo



Input multiview data



Using VI-DMM

Multiview Depth Classification

Newspaper



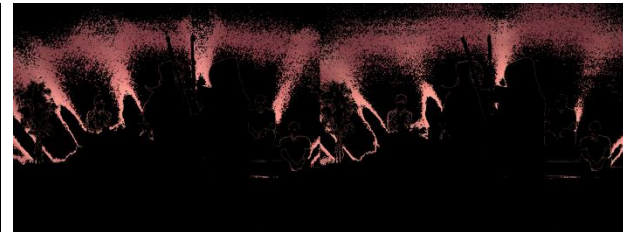
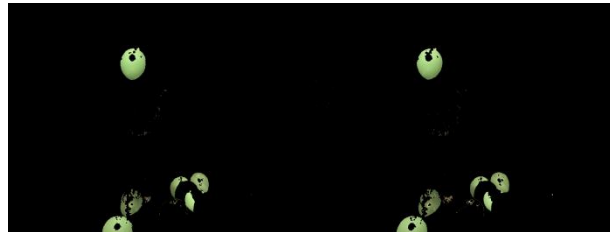
Balloons



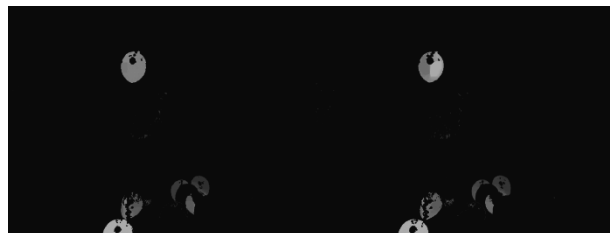
Kendo



Input multiview data



Using VI-DMM



Depth clusters

Multiview Depth Classification

Newspaper



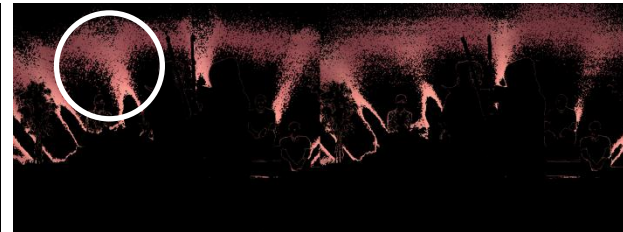
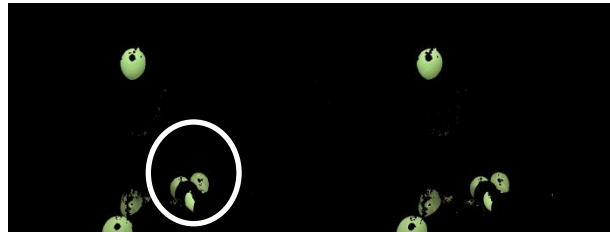
Balloons



Kendo



Input multiview data



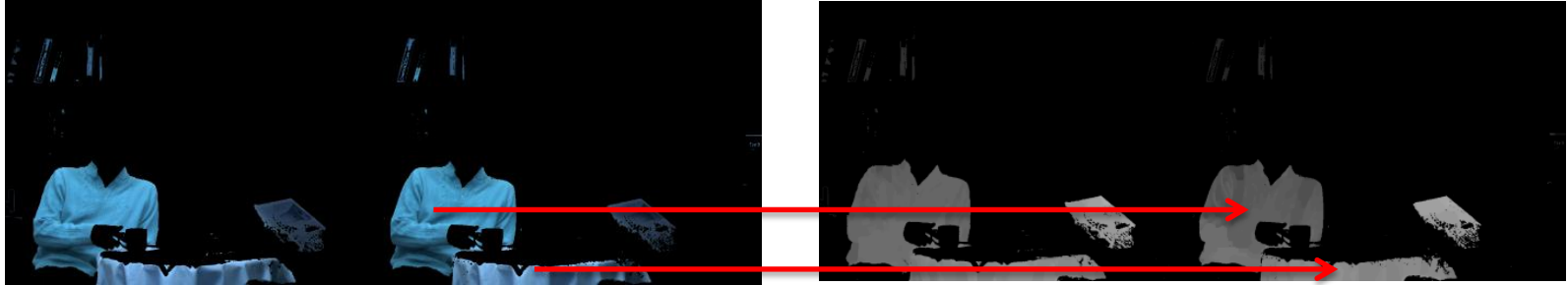
Using VI-DMM



Depth clusters

Multiview Depth Subclassification

Difference between color and depth clusters



- Members of color cluster have similar colors pixels
 - Members of depth cluster may have different depth values
-
- Why?
 - due to foreground and background depth difference
 - due to inter-view inconsistency

Multiview Depth Subclassification

Mean shift Clustering

- A nonparametric clustering technique
- Knowledge of the number of clusters not required
- Assigns the mean to depth pixels irrespective of the originating viewpoints
- Generative model based approaches imply higher computational complexity

Experimental Results

Experimental Results

MPEG 3DTV multiview data set



Newspaper
(1024 X 768)



Lovebird1
(1024 X 768)



Kendo
(1024 X 768)



Balloons
(1024 X 768)



Poznan street
(1920 X 1088)

Experimental Results

Multiview data set	Initial number of mixture components	Active number of mixture components (after convergence)	
		VI-GMM	VI-DMM
Lovebird1	100	31	24
Kendo	100	34	15

Depth Image-Based Rendering

MPEG View Synthesis Reference Software (VSRS) 3.5

Enhanced depth map

Left



Enhanced depth map

Right



Depth Image-Based Rendering

MPEG View Synthesis Reference Software (VSRS) 3.5

Enhanced depth map

Left



Reference view

Enhanced depth map

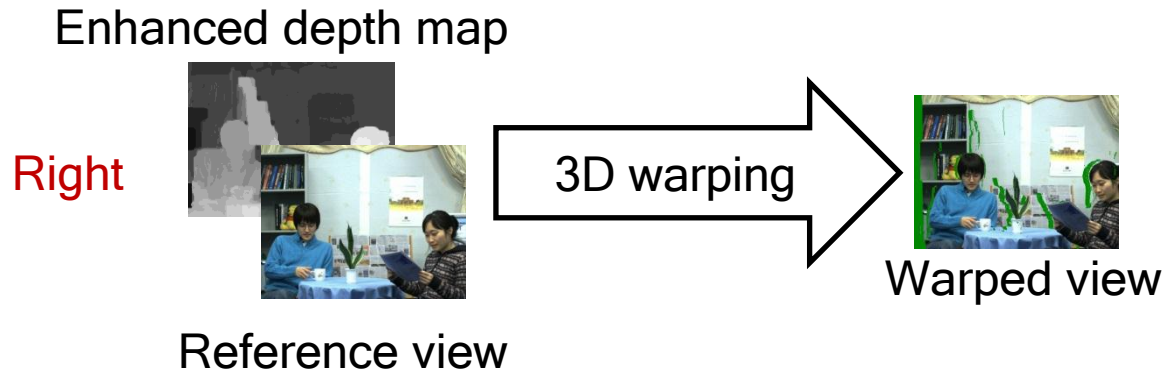
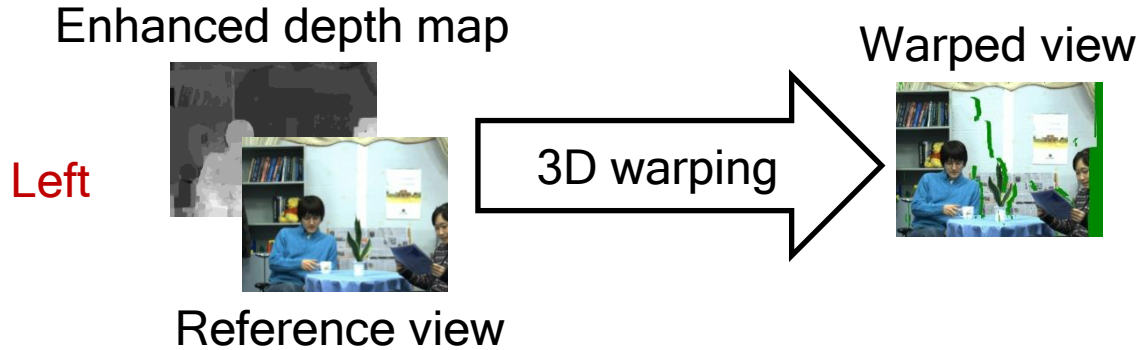
Right



Reference view

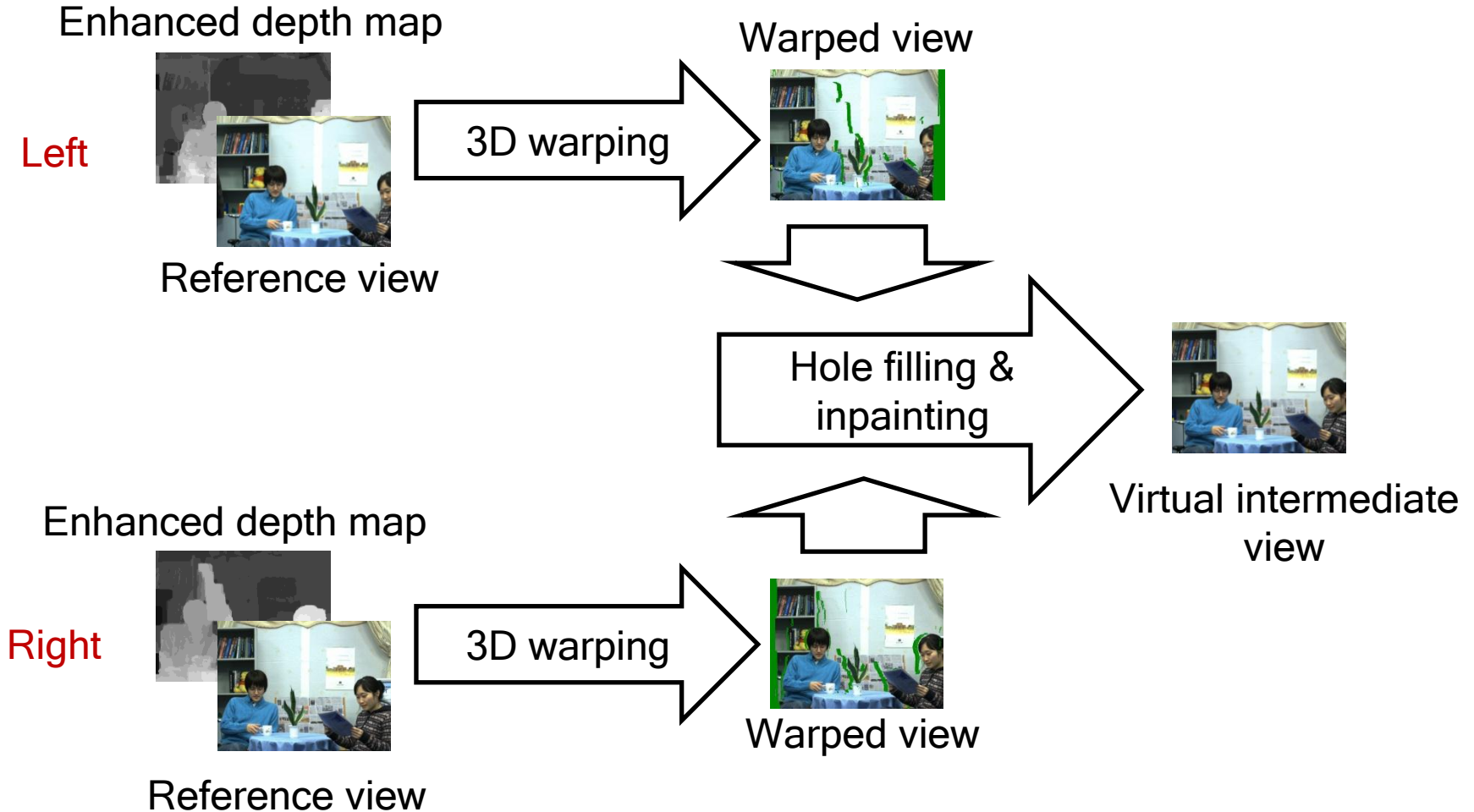
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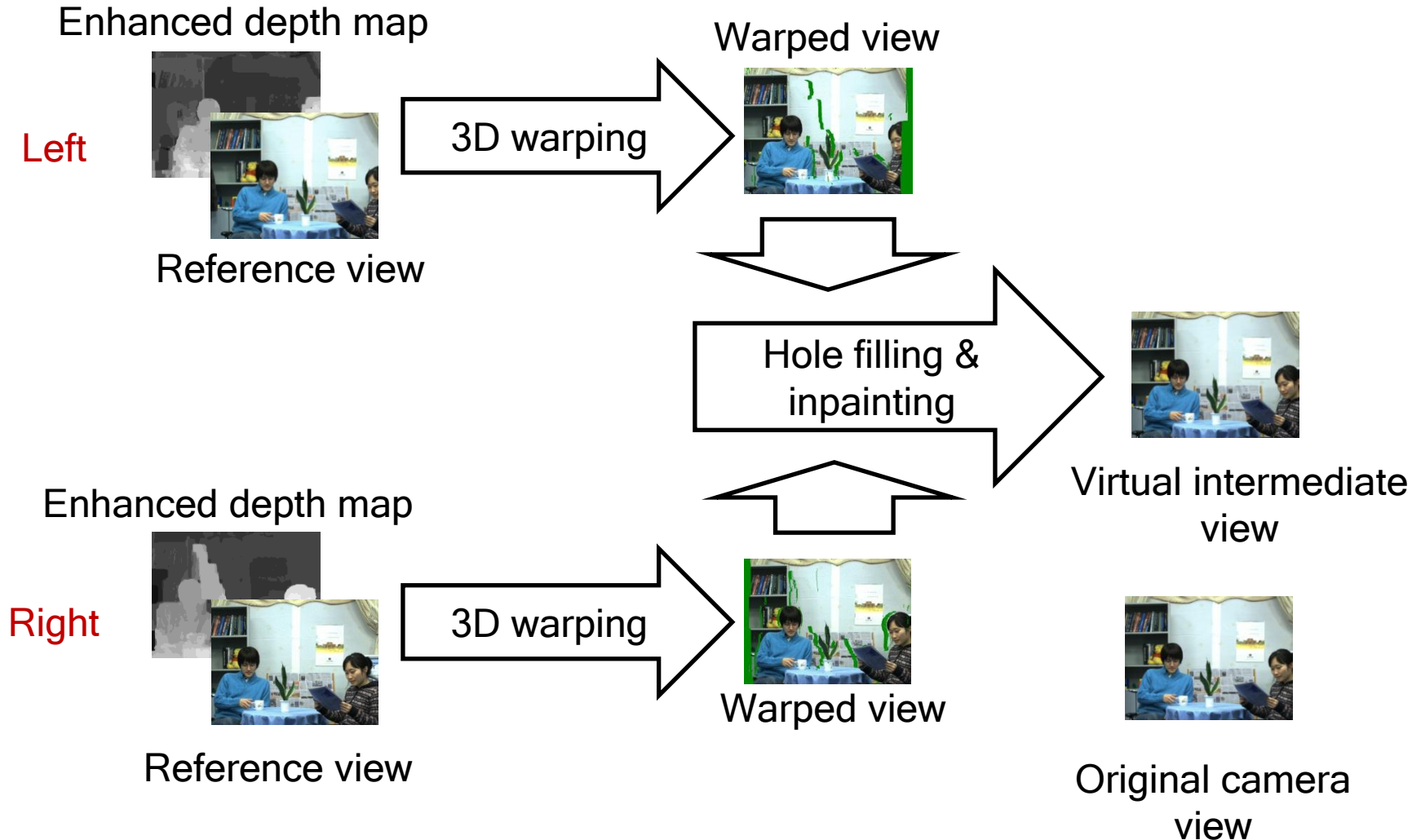
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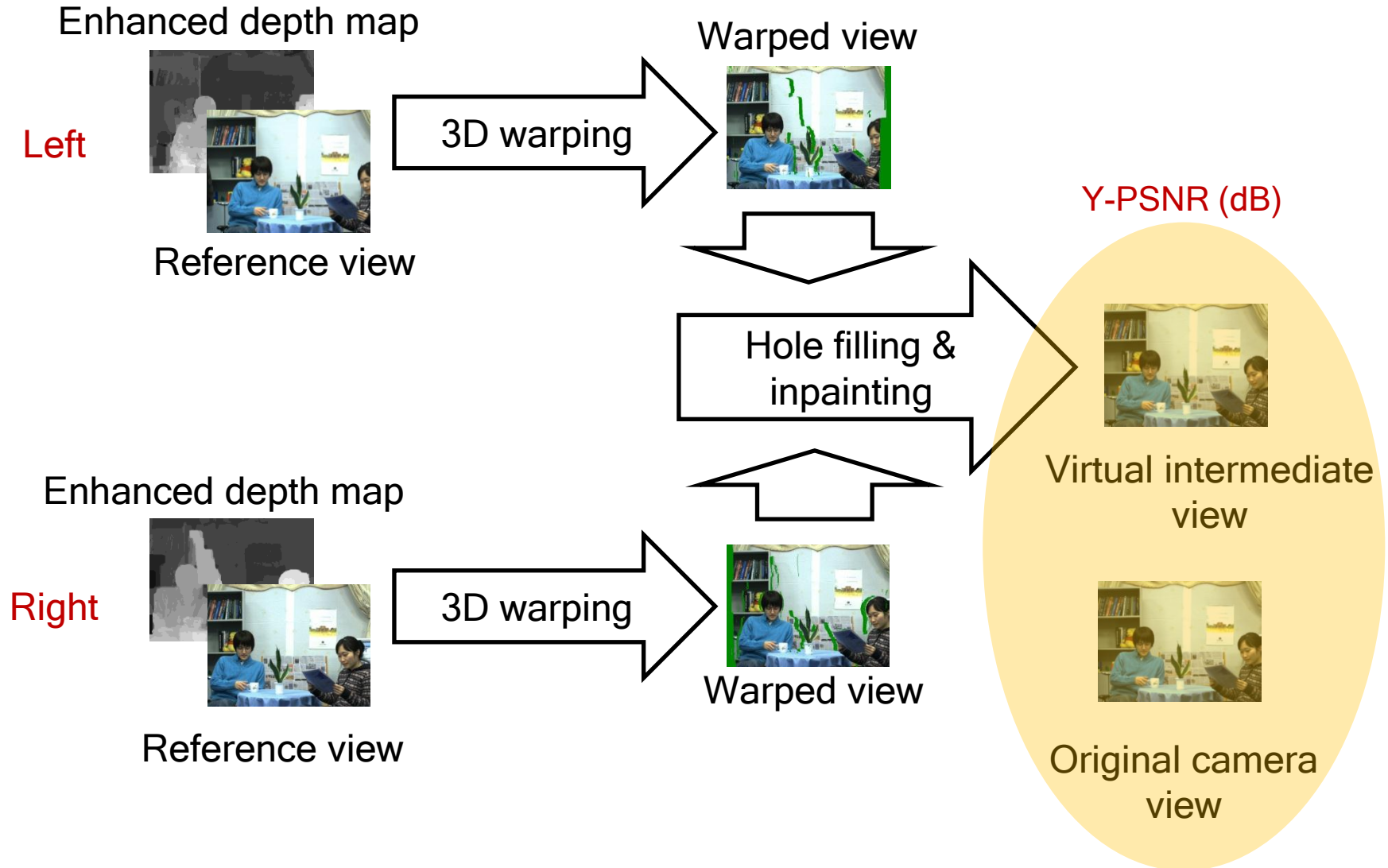
Depth Image-Based Rendering

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Depth Image-Based Rendering

MPEG View Synthesis Reference Software (VSRS) 3.5



Objective Results

Test sequence	Input view pair	Virtual view	Y-PSNR [dB]		
			With MPEG depth maps	With VBIGMM + K-Means depth maps [3]	With VBIDMM + Mean-shift depth maps
Newspaper	(4, 6)	5	32.00	32.10	32.11
Kendo	(3, 5)	4	36.54	36.72	39.35
Lovebird1	(6, 8)	7	28.50	28.68	29.04
Balloons	(3, 5)	4	35.69	35.93	36.02
Poznan Street	(3, 5)	4	35.56	35.58	35.72

- K-means sub-clustering
 - Number of cluster : 12

[3] P. K. Rana, J. Taghia, and M. Flierl: A Variational Bayesian Inference Framework for Multiview Depth Image Enhancement, IEEE ISM, 2012.

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			With MPEG depth maps	With VI-GMM + K-Means depth maps [3]	With VI-DMM + Mean-shift depth maps
Newspaper	(4, 6)	5	32.00	32.10	32.11
Kendo	(3, 5)	4	36.54	36.72	39.35
Lovebird1	(6, 8)	7	28.50	28.68	29.04
Balloons	(3, 5)	4	35.69	35.93	36.02
Poznan Street	(3, 5)	4	35.56	35.58	35.72

- K-means sub-clustering
 - Number of cluster : 12

[3] P. K. Rana, J. Taghia, and M. Flierl: A Variational Bayesian Inference Framework for Multiview Depth Image Enhancement, IEEE ISM, 2012.

Subjective Results

Test sequence: Kendo



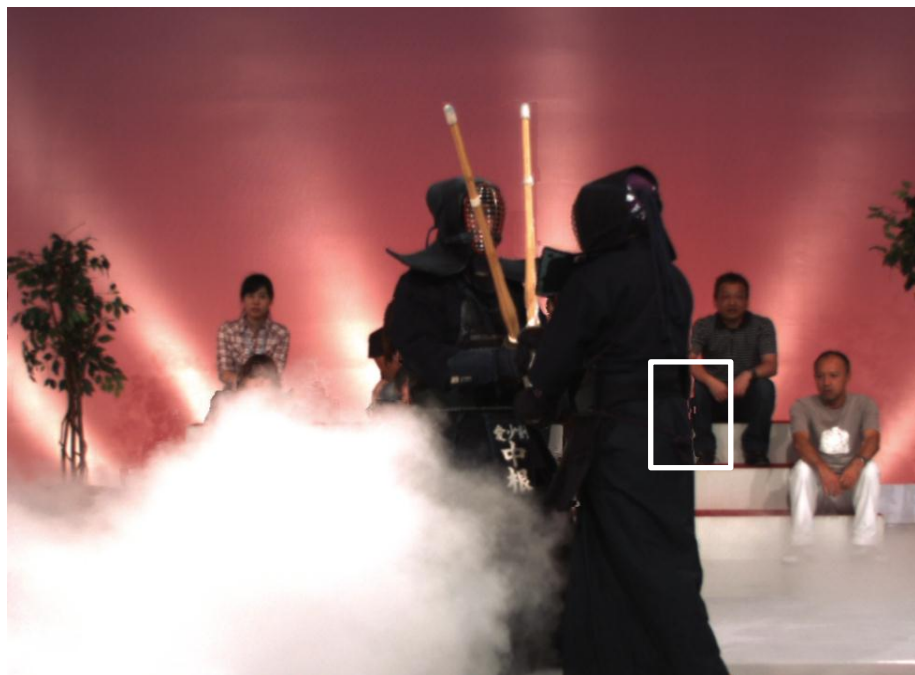
With MPEG depth map



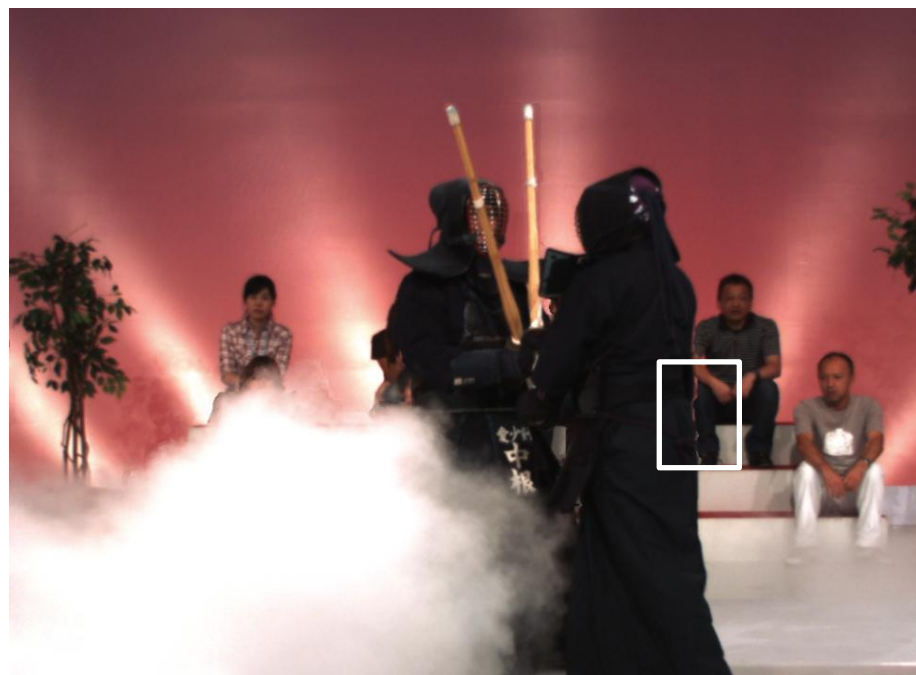
With VI-DMM+Mean-shift depth map

Subjective Results

Test sequence: Kendo



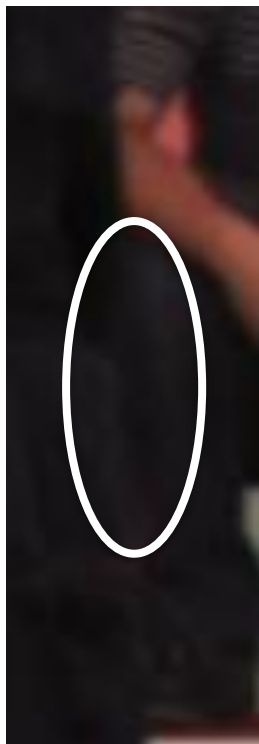
With MPEG depth map



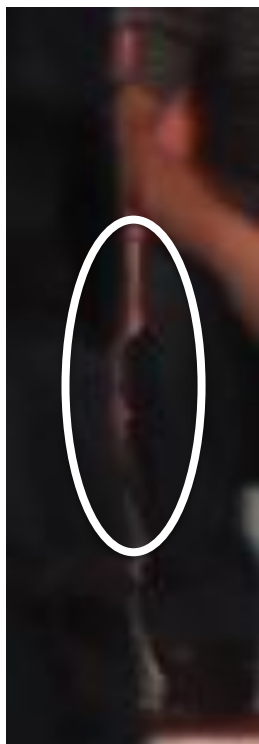
With VI-DMM+Mean-shift depth map

Subjective Results

Test sequence: Kendo



Original



With VI-DMM
+ Mean-Shift
depth maps



With VI-GMM
+ K-Means
depth maps

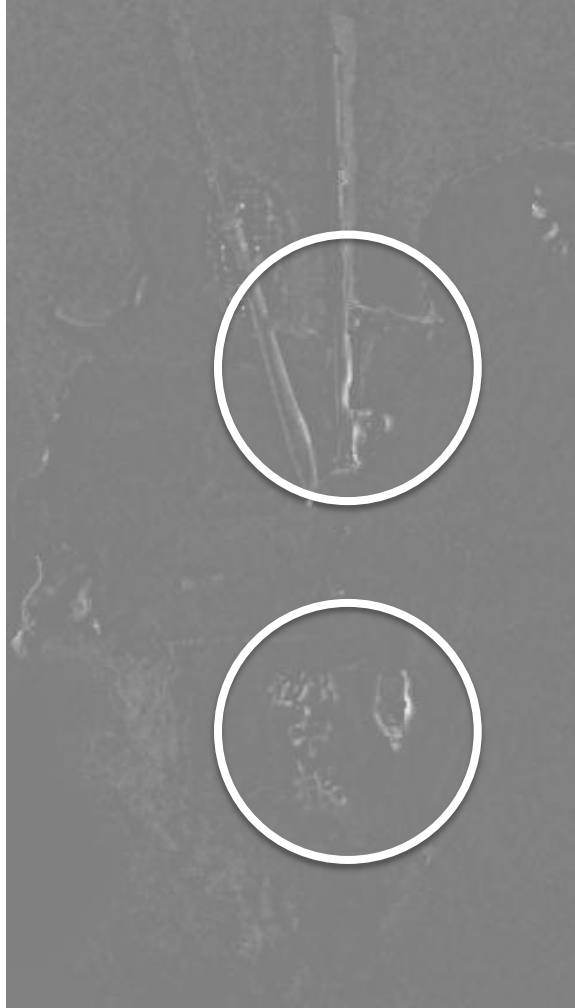


With MPEG
depth maps

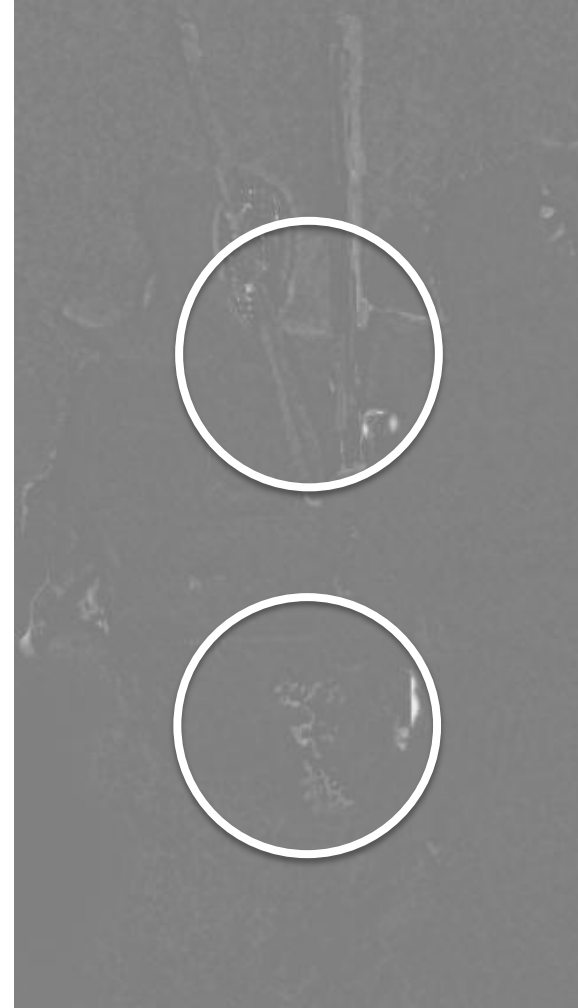
Subjective Results

Test sequence: Kendo

With VI-GMM
+K-Means
depth maps



With VI-DMM
+Mean-Shift
depth maps



Subjective Results

Test sequence: Lovebird 1



With MPEG depth map



With VI-DMM+Mean-shift depth map

Subjective Results

Test sequence: Lovebird 1



With MPEG depth map



With VI-DMM+Mean-shift depth map

Subjective Results

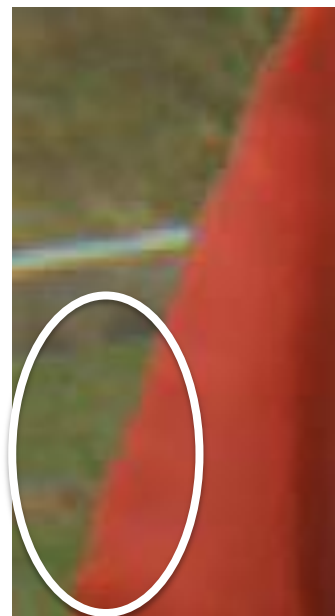
Test sequence: Lovebird 1



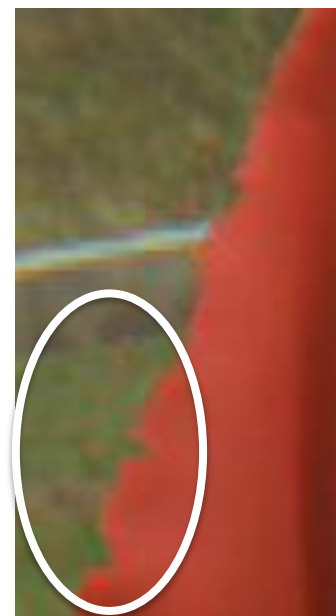
Original



With VI-DMM
+Mean-Shift
depth maps



With VI-GMM
+K-Means
depth maps



With MPEG
depth maps

Subjective Results

Test sequence: Lovebird 1



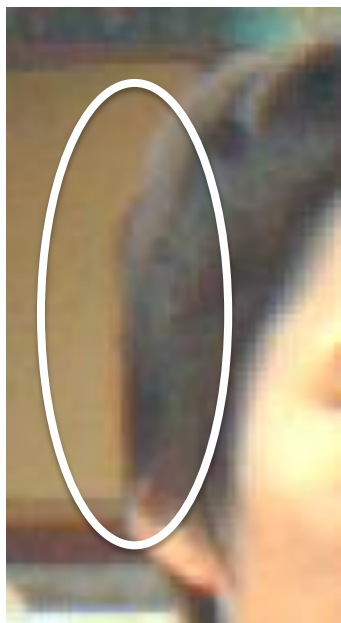
With MPEG depth map



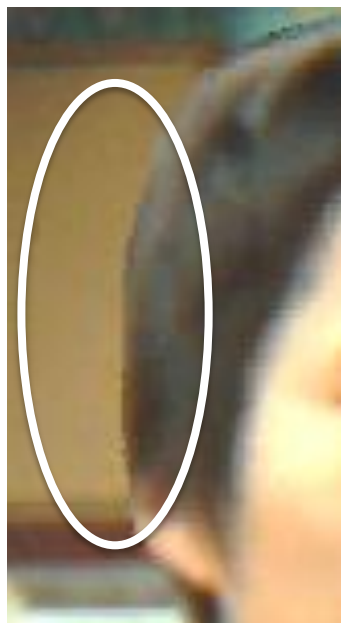
With VI-DMM+Mean-shift depth map

Subjective Results

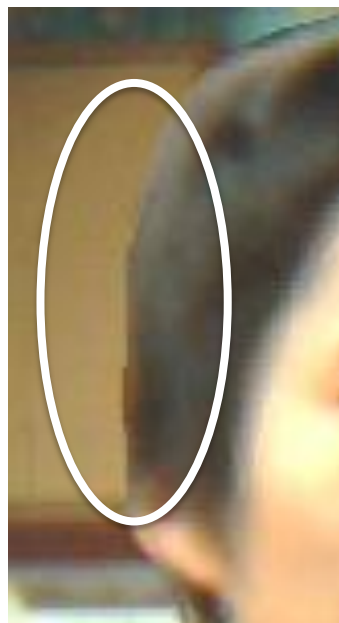
Test sequence: Lovebird 1



Original



With VI-DMM
+Mean-Shift
depth maps



With VI-GMM
+K-Means
depth maps



With MPEG
depth maps

Conclusions

- The inter-view depth consistency and hence, the free-viewpoint experience improve
- The per-pixel association between depth and color is exploited by classification
- Depth subclassification improves depth maps and hence, view rendering quality
- Both objective and subjective results improve

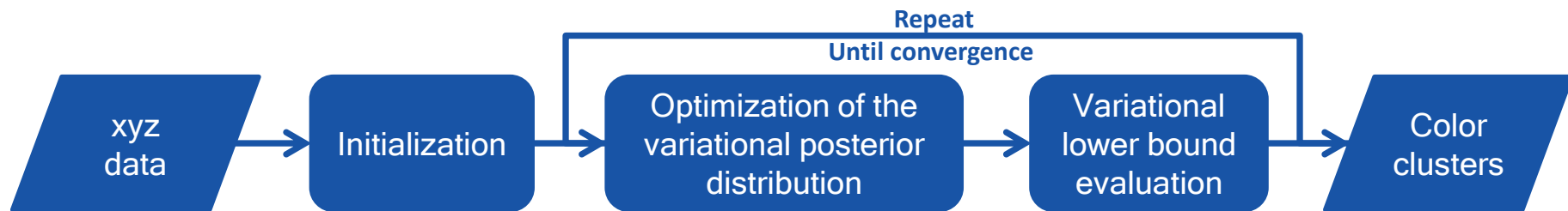
Future Directions

- A fully probabilistic multiview depth image enhancement
 - With improved computational efficiency
 - With improved depth subclassification

Thank You

Multiview color classification

Dirichlet mixture model with variational Bayes inference

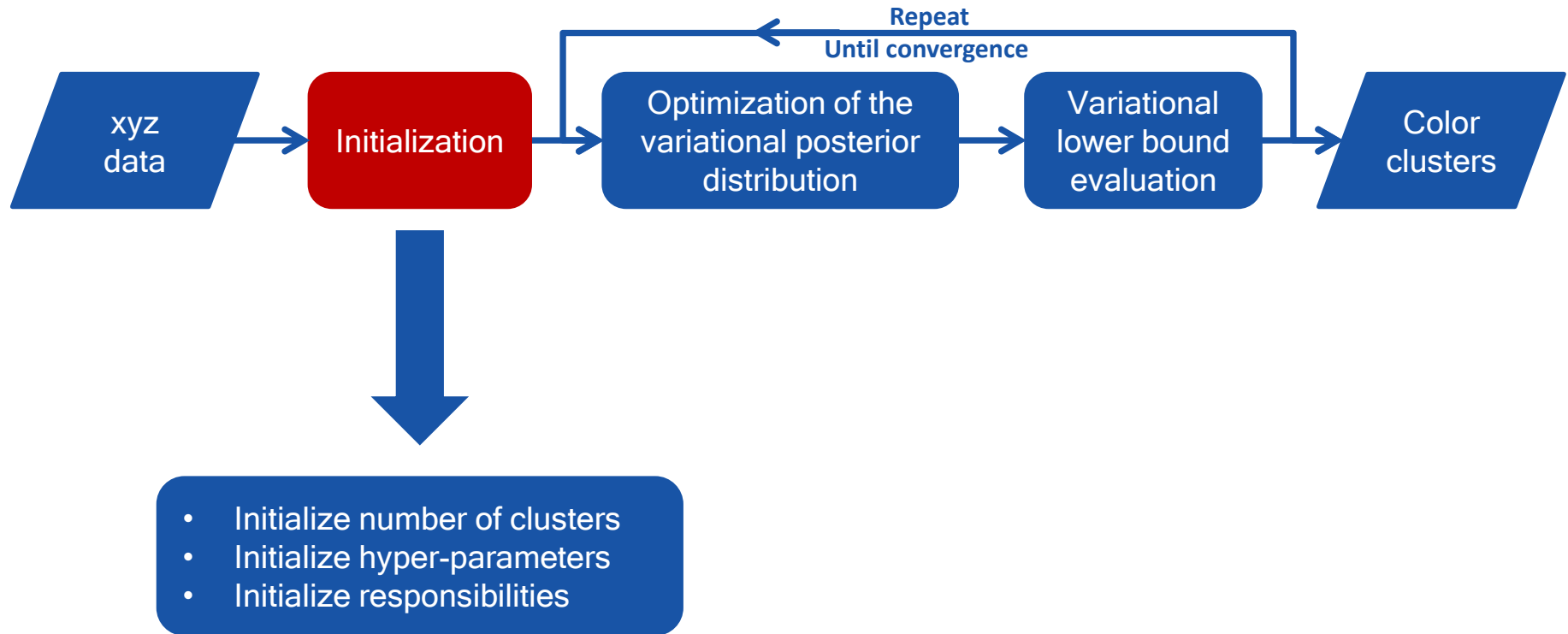


[1] C. M. Bishop, Pattern Recognition and Machine Learning, 1st ed. New York: Springer, 2006.

[2] Z. Ma, P. K. Rana, J. Taghia, M. Flierl, and A. Leijon, "Bayesian estimation of Dirichlet mixture model with variational inference," IEEE Trans. PAMI, submitted, 2013.

Multiview color classification

Dirichlet mixture model with variational Bayes inference

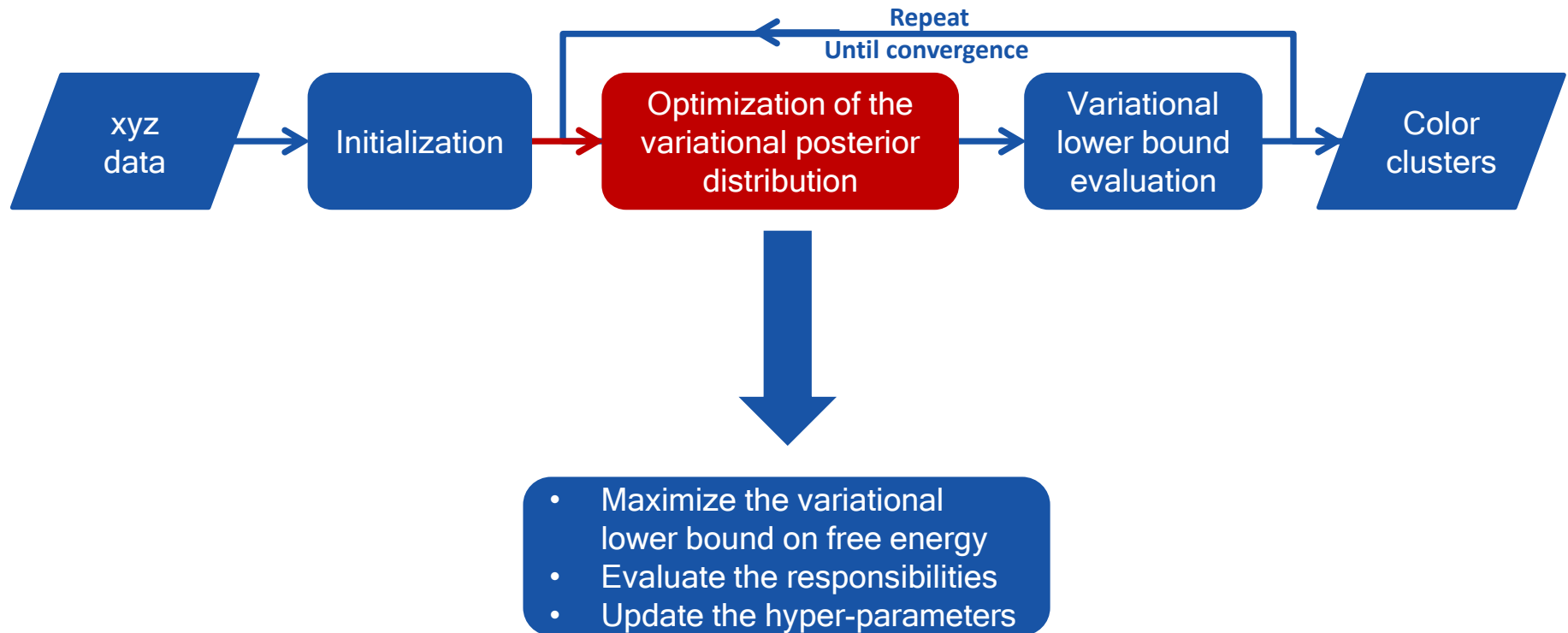


[1] C. M. Bishop, *Pattern Recognition and Machine Learning*, 1st ed. New York: Springer, 2006.

[2] Z. Ma, P. K. Rana, J. Taghia, M. Flierl, and A. Leijon, "Bayesian estimation of Dirichlet mixture model with variational inference," *IEEE Trans. PAMI*, submitted, 2013.

Multiview color classification

Dirichlet mixture model with variational Bayes inference

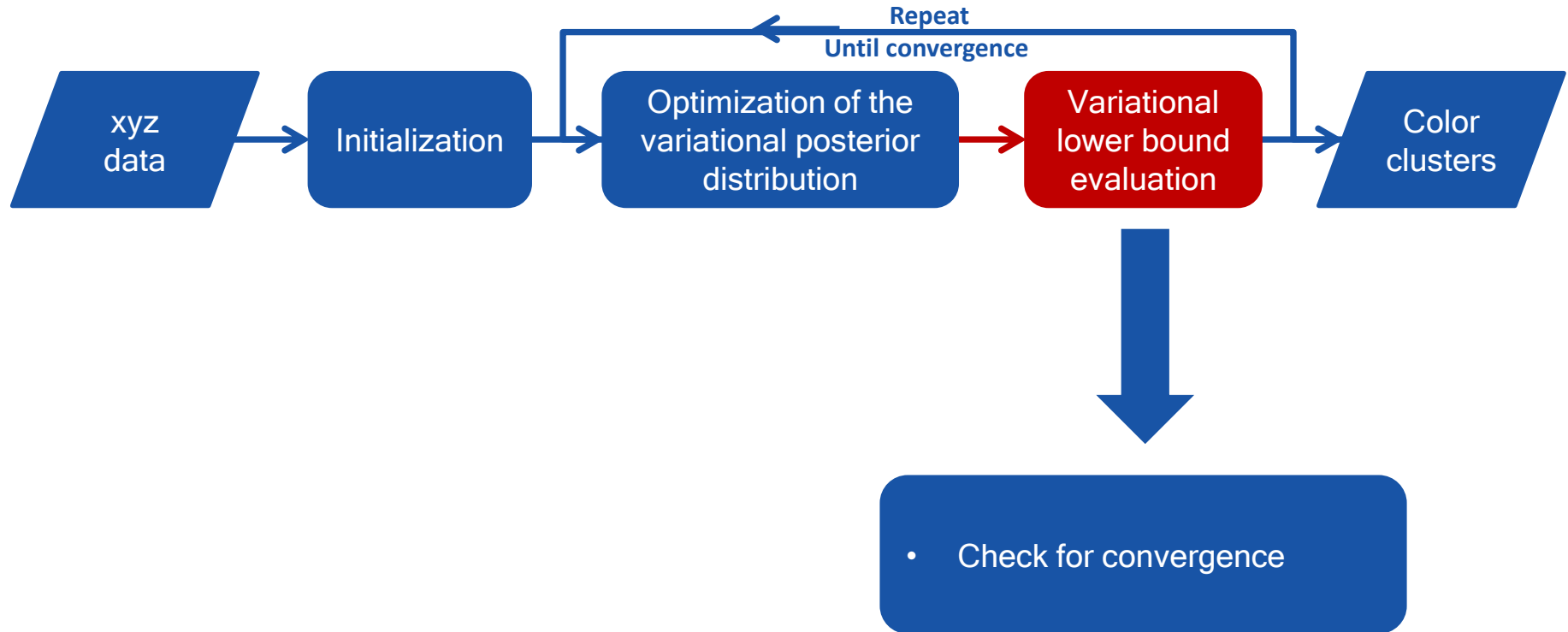


[1] C. M. Bishop, Pattern Recognition and Machine Learning, 1st ed. New York: Springer, 2006.

[2] Z. Ma, P. K. Rana, J. Taghia, M. Flierl, and A. Leijon, "Bayesian estimation of Dirichlet mixture model with variational inference," IEEE Trans. PAMI, submitted, 2013.

Multiview color classification

Dirichlet mixture model with variational Bayes inference

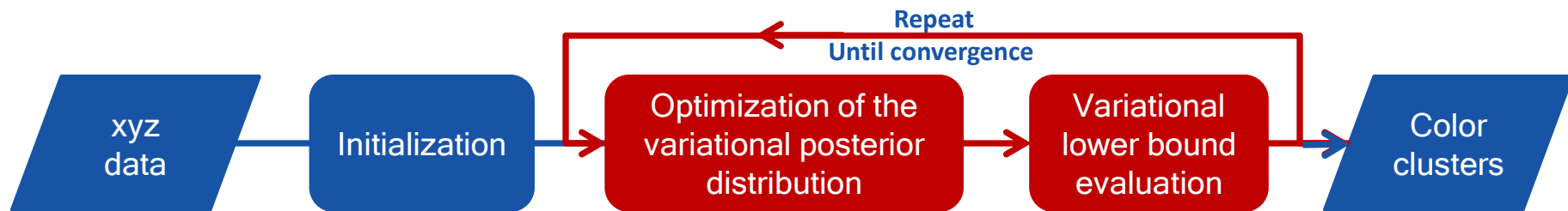


[1] C. M. Bishop, Pattern Recognition and Machine Learning, 1st ed. New York: Springer, 2006.

[2] Z. Ma, P. K. Rana, J. Taghia, M. Flierl, and A. Leijon, "Bayesian estimation of Dirichlet mixture model with variational inference," IEEE Trans. PAMI, submitted, 2013.

Multiview color classification

Dirichlet mixture model with variational Bayes inference

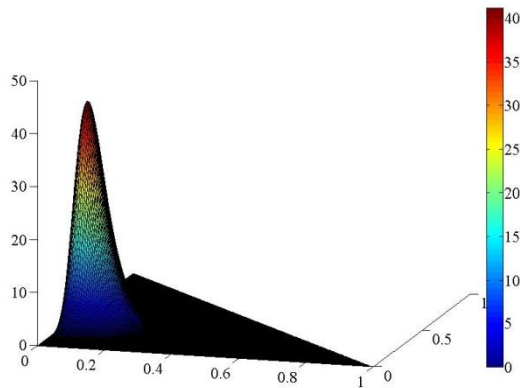


[1] C. M. Bishop, Pattern Recognition and Machine Learning, 1st ed. New York: Springer, 2006.

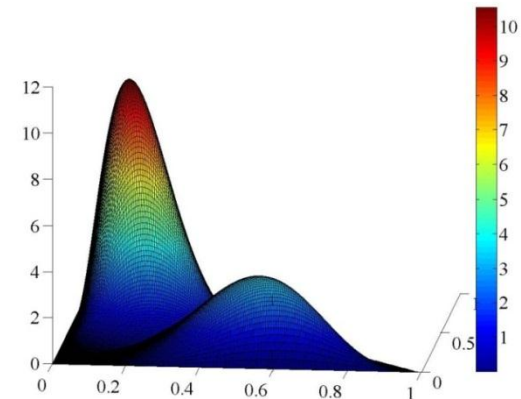
[2] Z. Ma, P. K. Rana, J. Taghia, M. Flierl, and A. Leijon, "Bayesian estimation of Dirichlet mixture model with variational inference," IEEE Trans. PAMI, submitted, 2013.

Dirichlet Plot Details

- For probability density function of Dirichlet distribution $\alpha = [2 \ 10 \ 15]$
- For probability density function of Dirichlet mixture model parameters $\alpha_1 = [6 \ 2 \ 4]$ and $\alpha_2 = [3 \ 8 \ 5]$ with mixture weights $\pi_1 = 0.3$ and $\pi_2 = 0.7$, respectively.



**Probability density function
of Dirichlet distribution**



**Probability density function
of Dirichlet mixture model**

Subjective Results

Test sequence: Newspaper



With MPEG depth map



With VBDMM Mean-shift depth map

Subjective Results

Test sequence: Newspaper



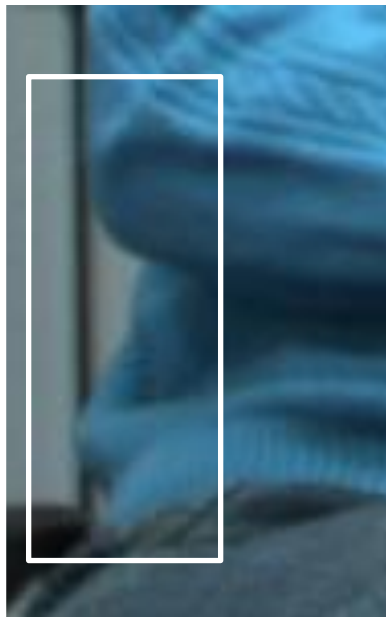
With MPEG depth map



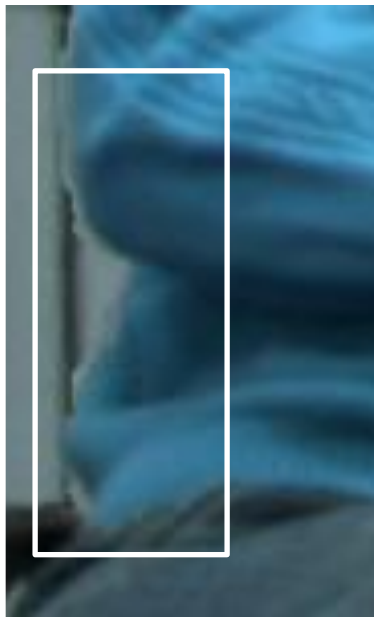
With VBDMM Mean-shift depth map

Subjective Results

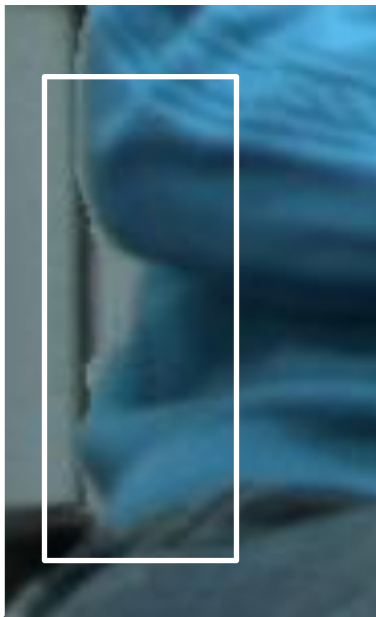
Test sequence: Newspaper



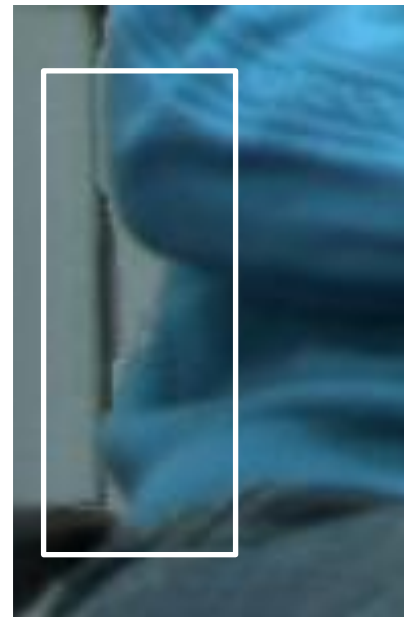
Original
depth maps



With MPEG
depth maps



With VBGMM
K-Means
depth maps



With VBDMM
Mean-Shift
depth maps

Subjective Results

Test sequence: Newspaper



With MPEG depth map



With VBDMM Mean-shift depth map

Subjective Results

Test sequence: Newspaper



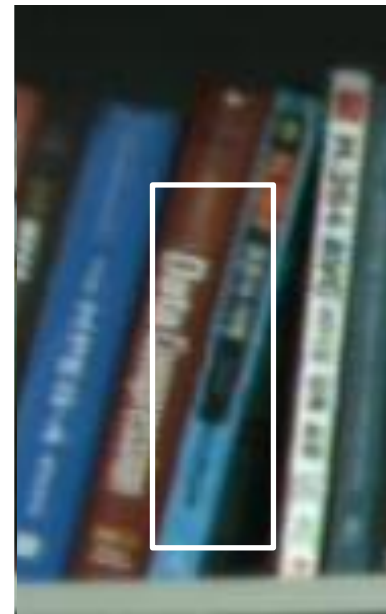
Original
depth maps



With MPEG
depth maps



With VBGMM
K-Means
depth maps



With VBDMM
Mean-Shift
depth maps

Subjective Results

Test sequence: Balloons



With MPEG depth map



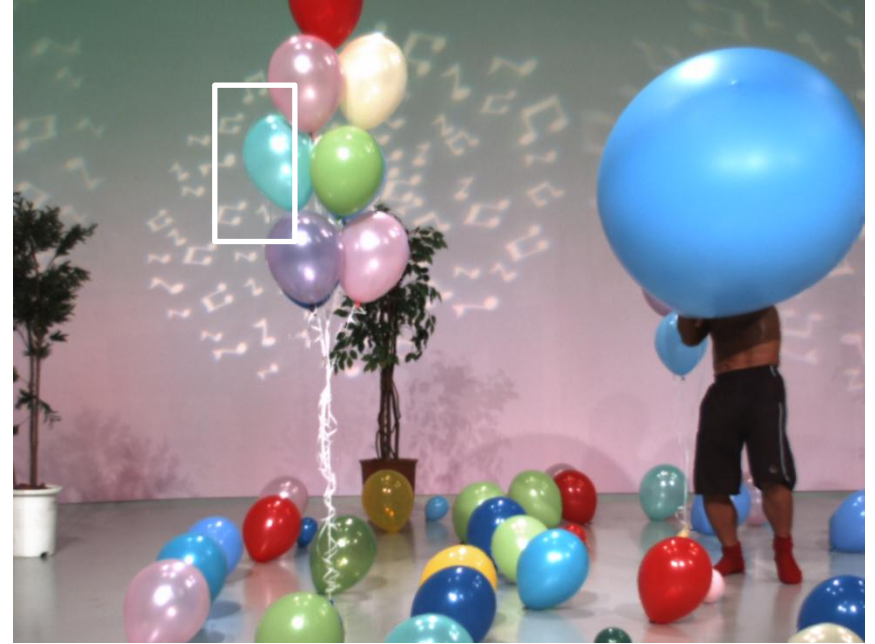
With VBDMM Mean-shift depth map

Subjective Results

Test sequence: Balloons



With MPEG depth map



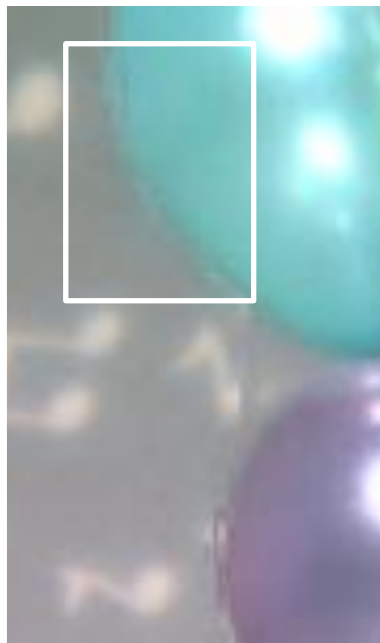
With VBDMM Mean-shift depth map

Subjective Results

Test sequence: Balloons



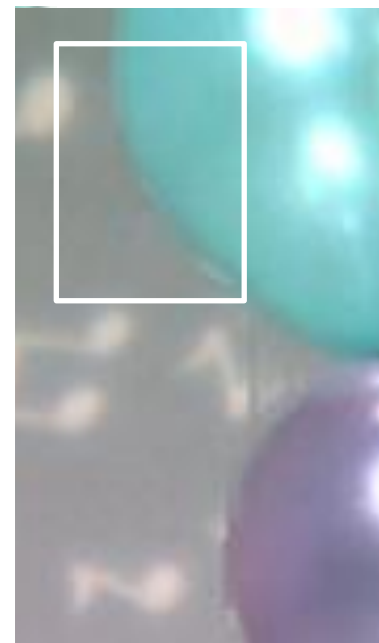
Original
depth maps



With MPEG
depth maps



With VBGMM
K-Means
depth maps



With VBDMM
Mean-Shift
depth maps

Subjective Results

Test sequence: Poznan Street



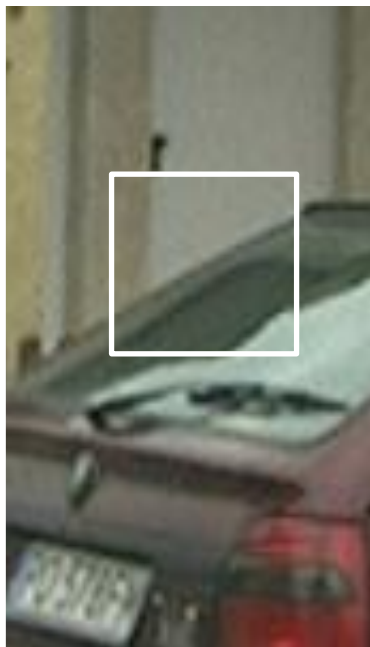
With MPEG depth map



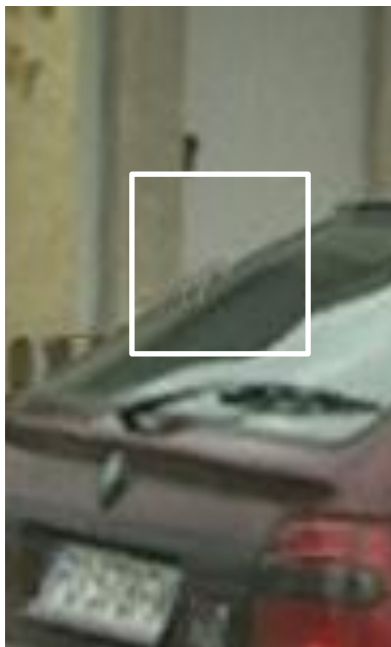
With VBDMM Mean-shift depth map

Subjective Results

Test sequence: Poznan Street



Original
depth maps



With MPEG
depth maps



With VBGMM
K-Means
depth maps



With VBDMM
Mean-Shift
depth maps

Subjective Results

Test sequence: Poznan Street



With MPEG depth map



With VBDMM Mean-shift depth map

Subjective Results

Test sequence: Poznan Street



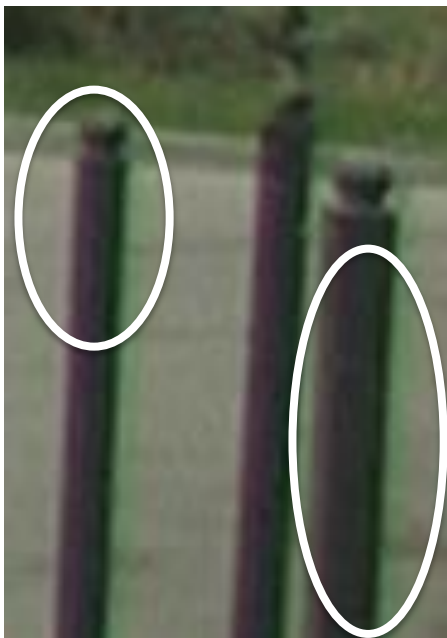
With MPEG depth map



With VBDMM Mean-shift depth map

Subjective Results

Test sequence: Poznan Street



Original



With MPEG
depth maps



With VBGMM
K-Means
depth maps



With VBDMM
Mean-Shift
depth maps