

# Depth Enhancement Tool & Rendering with Connection Information

Pravin Kumar Rana  
Sound and Image Processing Lab.(SIP)  
KTH - Royal Institute of Technology  
SE-10044 Stockholm, Sweden



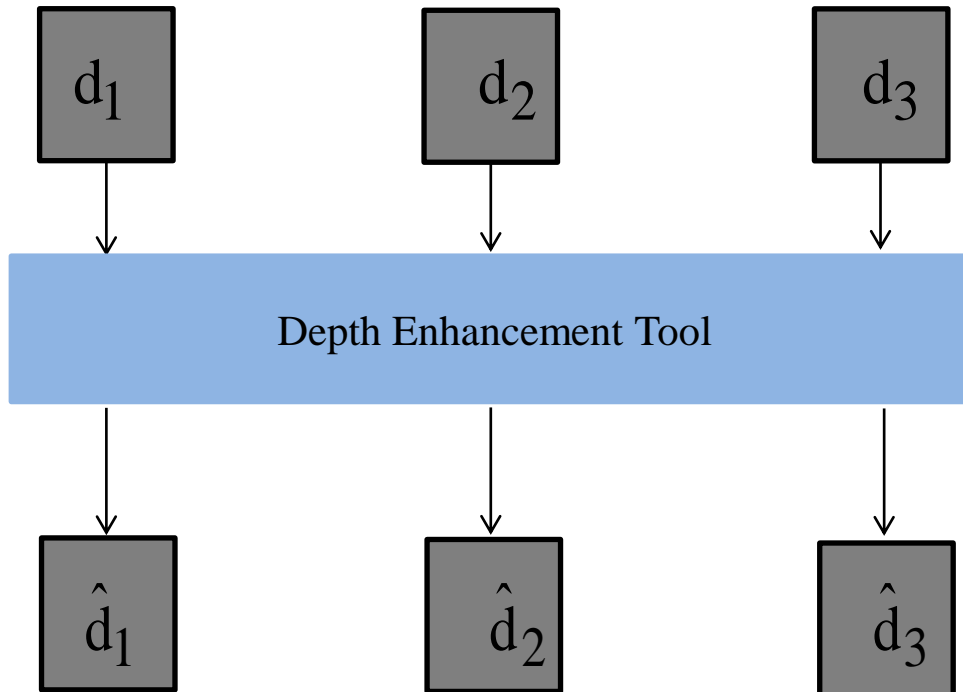
# Outline

- Results
  - Depth Enhancement Tool
  - View Synthesis with Connection information
  - Rendering with Structured-Depth

# Depth Enhancement Tool

# Depth Enhancement Tool

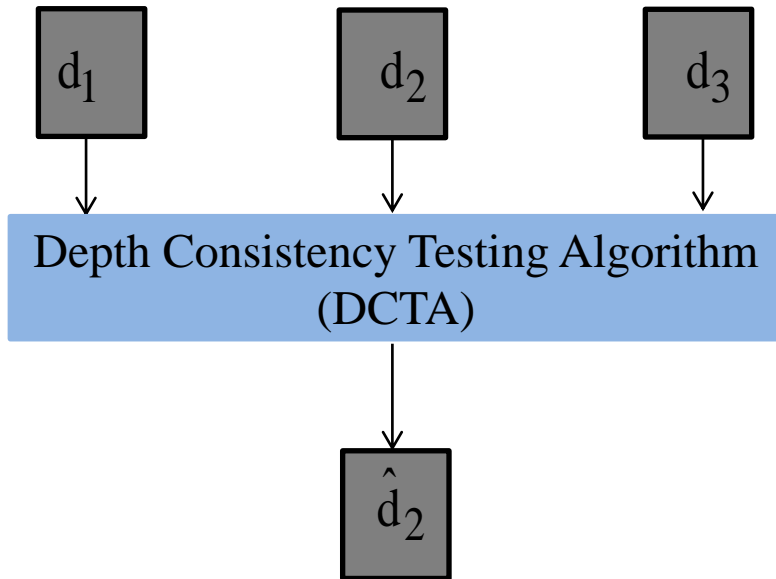
## MPEG Depth Maps (MPEG/D)



## Enhanced Depth Maps (ED)

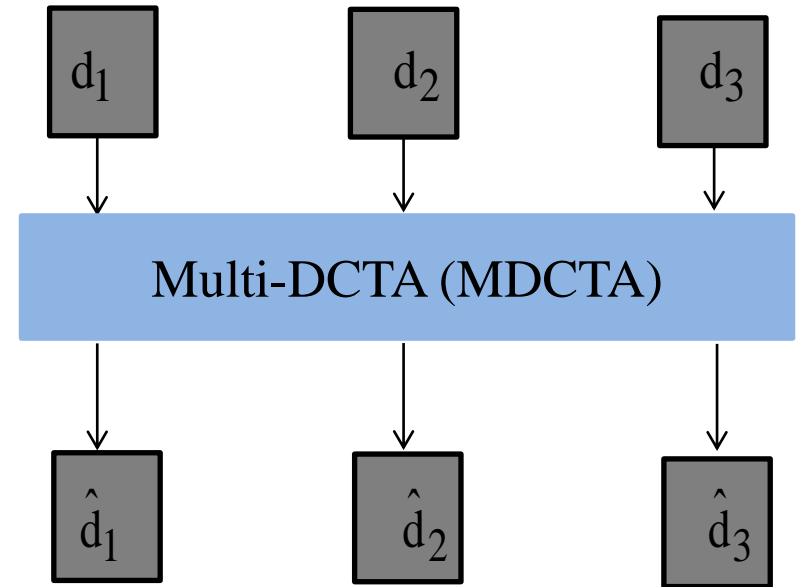
# Depth Enhancement Tool

## Depth Consistency Testing



Testing pixels in 2

## Depth Enhancement Tool

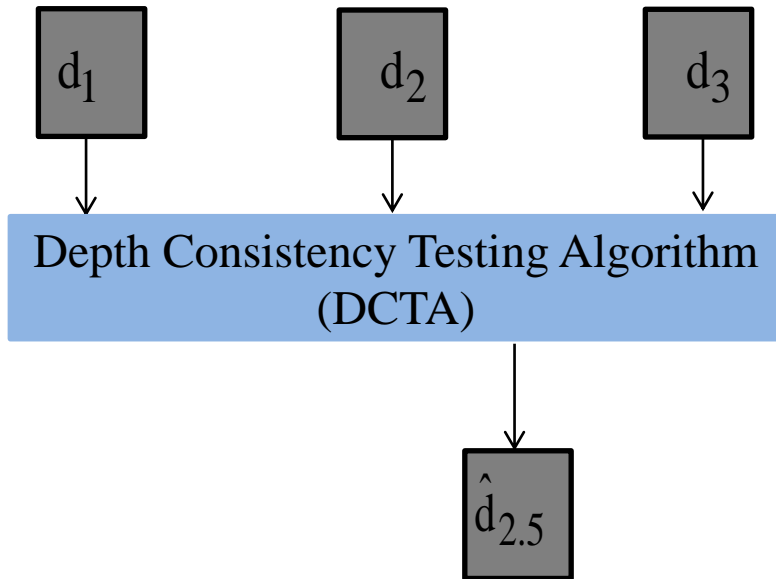


Testing pixels in 1, 2, and 3

**MDCTA/ED**

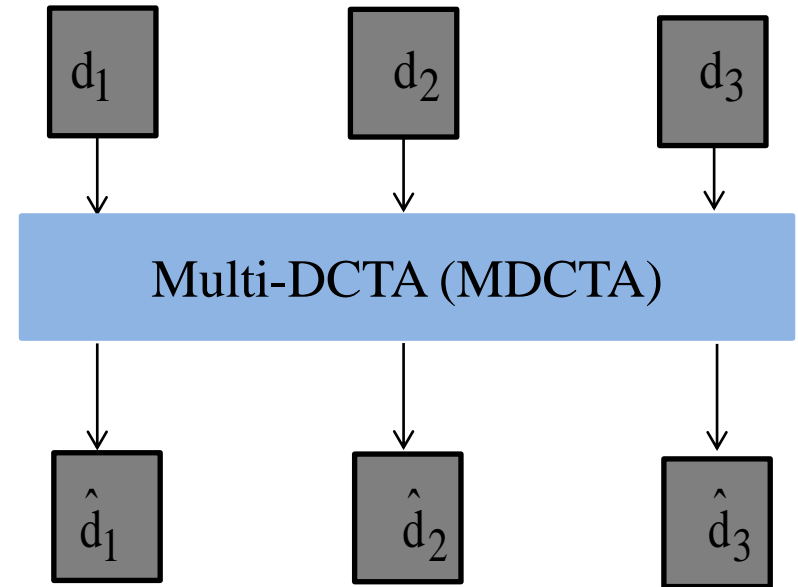
# Depth Enhancement Tool

## Depth Consistency Testing



Testing pixels in 2

## Depth Enhancement Tool

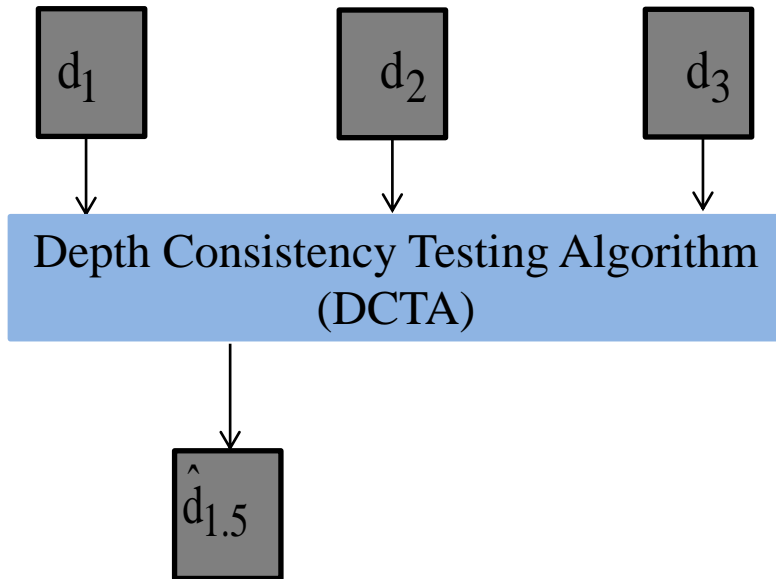


Testing pixels in 1, 2, and 3

**MDCTA/ED**

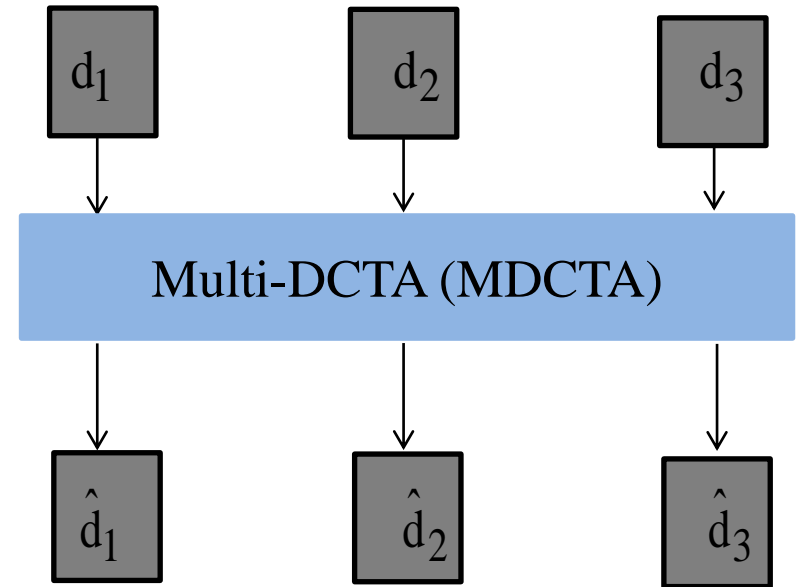
# Depth Enhancement Tool

## Depth Consistency Testing



Testing pixels in 2

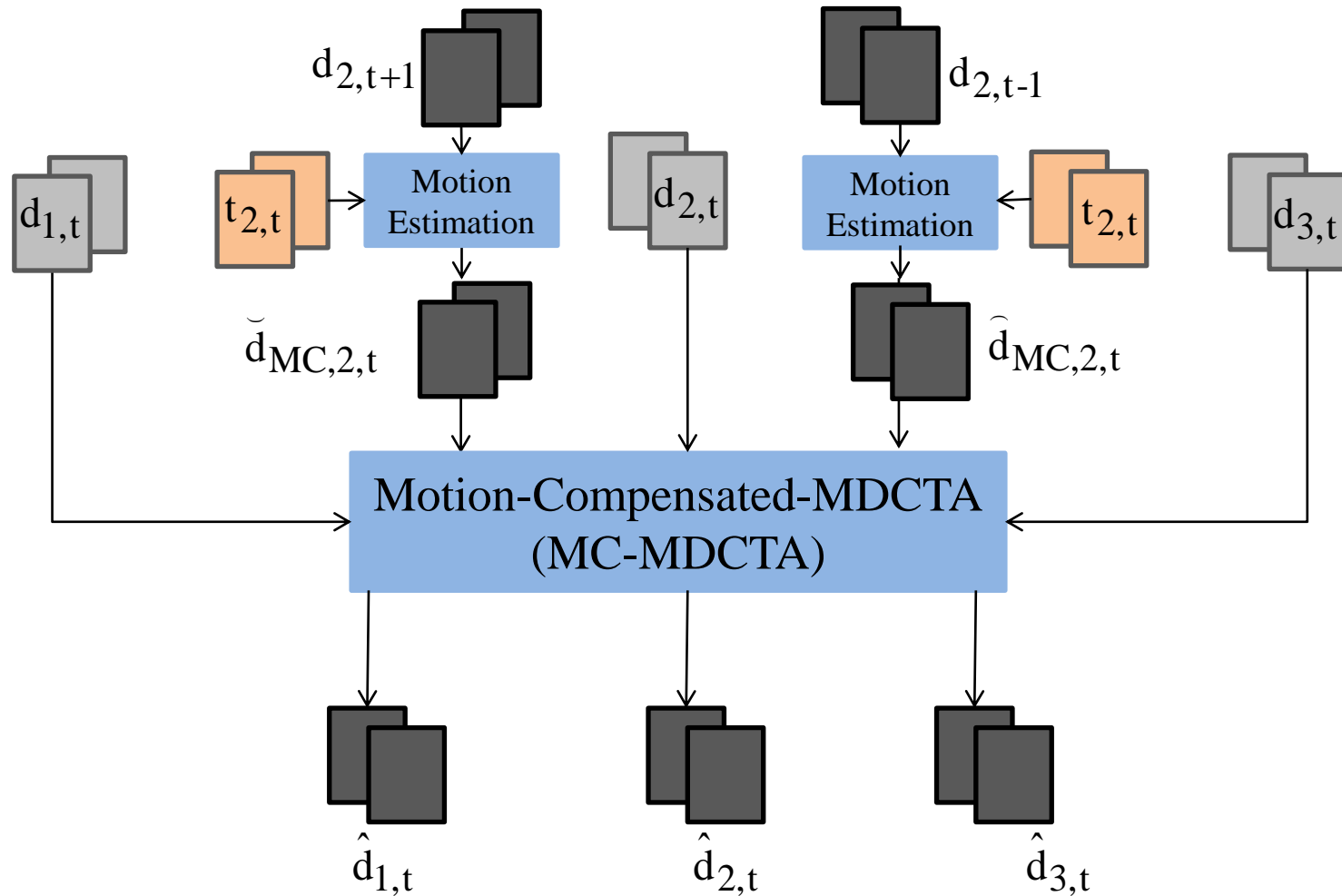
## Depth Enhancement Tool



Testing pixels in 1, 2, and 3

**MDCTA/ED**

# Depth Enhancement Tool



**MC-MDCTA/ED**



# VSRS 3.5 Configuration file

The best VSRS parameters setting[1]:

- 1D Synthesis mode
- Boundary Noise Removal off
- View Blending off, not used in the 1D mode
- Half-pel precision
- Any setting for the Filter parameter

[1] Study of VSRS input parameters, Martin Pettersson, Ericsson, 2011-02-28

# Results

**MPEG/D → MDCTA/ED → VSRS 3.5**

Sequence ID	Test Sequence	Spatial Resolution	No. Frames	Virtual View	MPEG/D → VSRS 3.5 [dB]	MDCTA/ED → VSRS 3.5 [dB]
S01	Poznan Hall 2	1920x1088	200	6.5	SE	SE <sup>(1)</sup>
S02	Poznan Street	1920x1088	250	3.5	SE	SE
S03	Undo Dancer	1920x1080	250	03	38.50	38.11 <sup>(2)</sup>
S04	GT Fly	1920x1080	250	04	x	x
S03	Kendo	1024x768	300	04	37.66	37.30 <sup>(2)</sup>
S06	Balloons	1024x768	300	04	36.60	36.60
S07	Lovebird1	1024x768	240	07	28.68	28.72
S07*	Lovebird1	1024x768	240	07	30.37	30.00
S08	Newspaper	1024x768	300	05	32.35	32.40 <sup>(2)</sup>

- Old mpeg depth maps
- (1) Good subjective result
- (2) Subjective improvement

# Results

**MPEG/D → MC-MDCTA/ED → VSRS 3.5**

Sequence ID	Test Sequence	Spatial Resolution	No. Frames	Virtual View	MPEG/D → VSRS 3.5 [dB]	MDCTA/ED → VSRS 3.5 [dB]	MC-MDCTA /ED → VSRS 3.5 [dB]
S01	Poznan Hall 2	1920x1088	200	6.5	SE	SE <sup>(1)</sup>	-
S02	Poznan Street	1920x1088	250	3.5	SE	SE	-
S03	Undo Dancer	1920x1080	250	03	38.50	38.11 <sup>(2)</sup>	38.05
S04	GT Fly	1920x1080	250	04	x	x	x
S03	Kendo	1024x768	300	04	37.66	37.30 <sup>(2)</sup>	37.65
S06	Balloons	1024x768	300	04	36.60	36.60	36.74
S07	Lovebird1	1024x768	240	07	28.68	28.72	28.72
S07*	Lovebird1	1024x768	240	07	30.37	30.00	30.30
S08	Newspaper	1024x768	300	05	32.35	32.40 <sup>(2)</sup>	32.56

- Old mpeg depth maps
- (1) Good subjective result
- (2) Subjective improvement

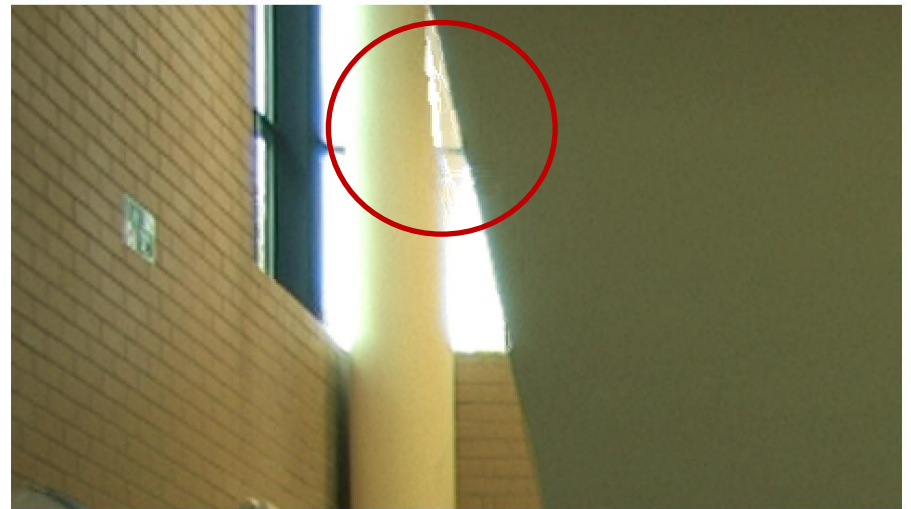
# Subjective Results



MPEG/D → VRSR 3.5

Poznan Hall2  
Frame 157

MPEG/D → MDCTA/ED → VRSR 3.5



# Subjective Results



Poznan Hall2  
Frame 121

MPEG/D → VSRS 3.5



MPEG/D → MDCTA/ED → VSRS 3.5

# Subjective Results



Original



MPEG/D → VSRS 3.5



MPEG/D → MDCTA/ED → VSRS 3.5



# Subjective Results



Original

Kendo 4  
Frame 202



MPEG/D  $\rightarrow$  VSRS 3.5



MPEG/D  $\rightarrow$  MDCTA/ED  $\rightarrow$  VSRS 3.5

# Subjective Results



Original

Kendo 4  
Frame 204



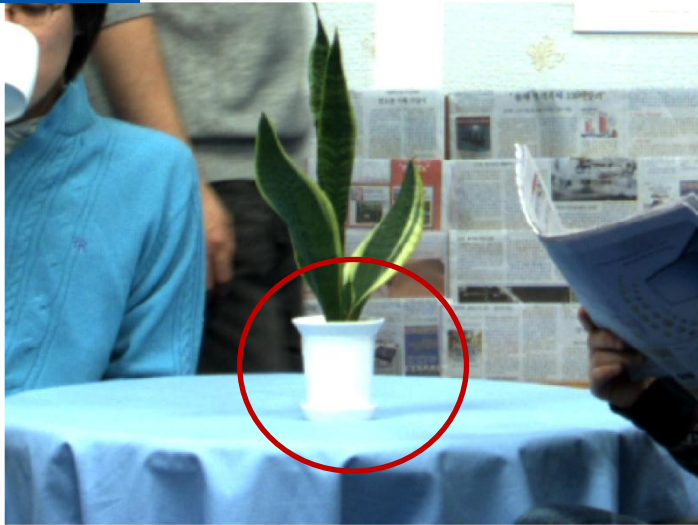
MPEG/D  $\rightarrow$  VSRS 3.5



MPEG/D  $\rightarrow$  MDCTA/ED  $\rightarrow$  VSRS 3.5

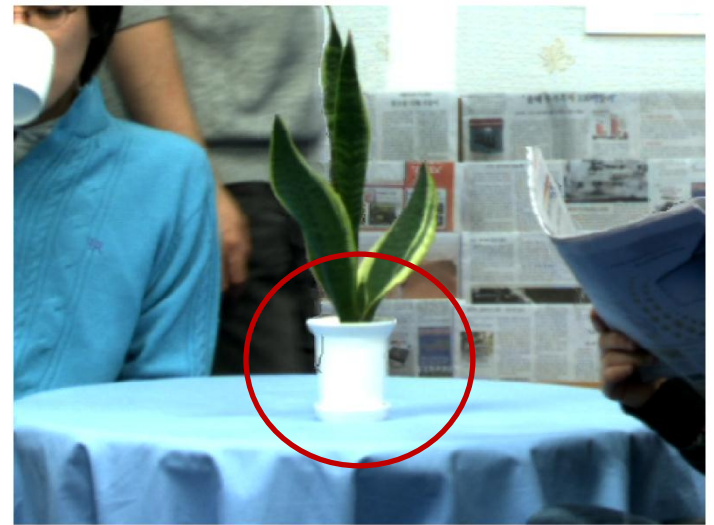


# Subjective Results

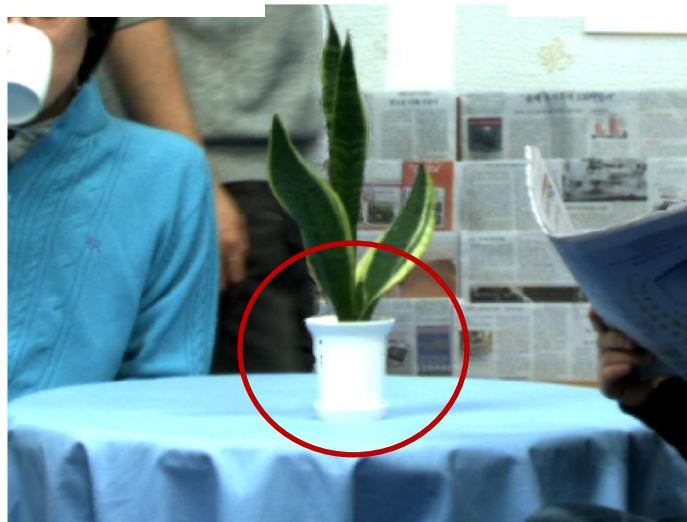


Original

Newspaper 5  
Frame 85



MPEG/D  $\rightarrow$  VSRS 3.5



MPEG/D  $\rightarrow$  MDCTA/ED  $\rightarrow$  VSRS 3.5

# Subjective Results



Original

Newspaper 5  
Frame 217



MPEG/D  $\rightarrow$  VSRS 3.5

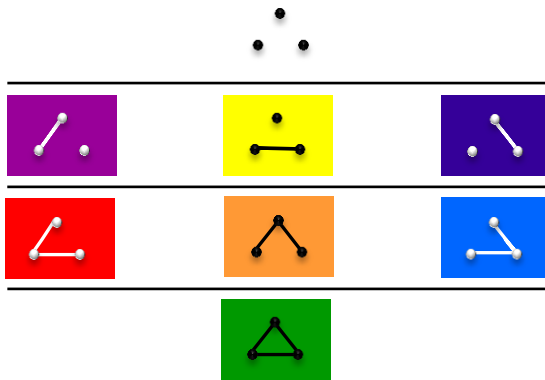


MPEG/D  $\rightarrow$  MDCTA/ED  $\rightarrow$  VSRS 3.5

# View Synthesis with Connection Information

# Inter-View Connection Information

*Possible cases of inter-view connectivity for  $n = 3$ :*

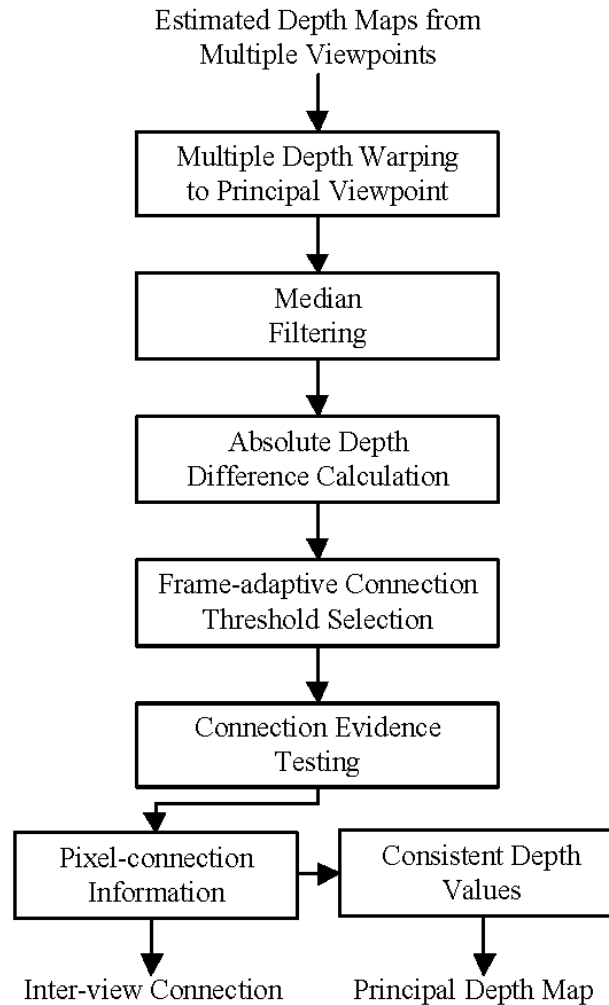


*Use of Connection Information:*

- *To obtain consistent depth values*
- *To combine texture pixels from multiple viewpoint reliably*



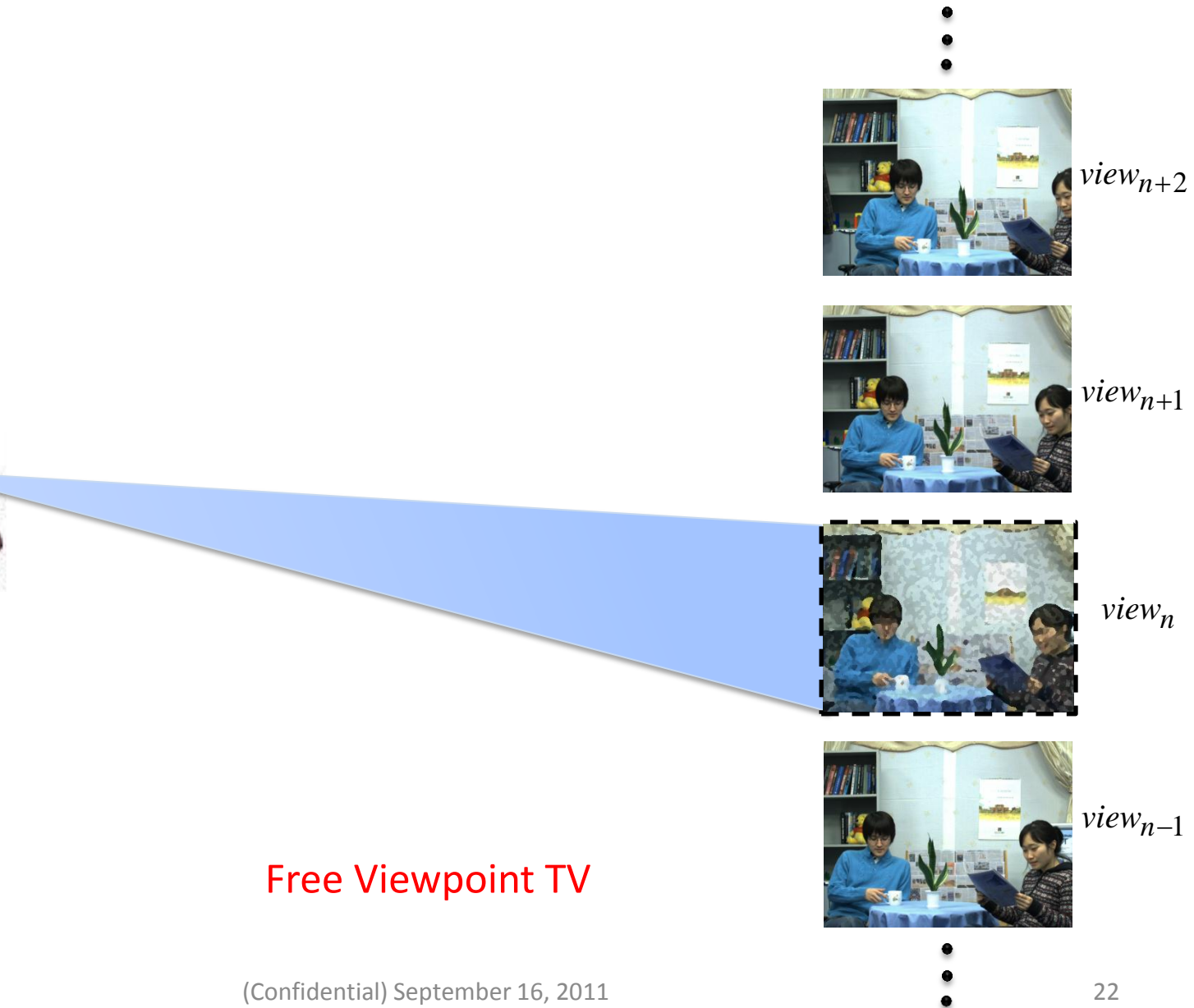
# Depth Consistency Testing



# Virtual View Rendering



User

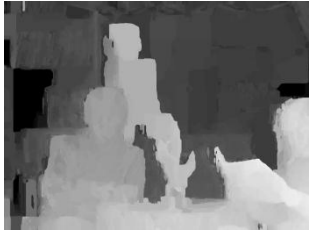


Free Viewpoint TV

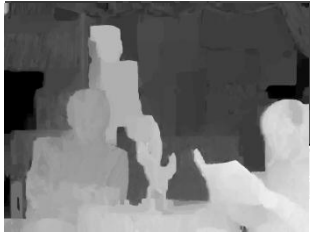


# Virtual View Synthesis (VSRS+)

$view_{n+2}$



$view_{n+1} = p$



$view_{n-1}$



*Enhanced depth maps*

# VSRS+

$view_{n+2}$



$view_{n+1} = p$



$view_{n-1}$



*Multiview Texture*



# VSRS+

$view_{n+2}$



*Warping*



*Warped views  
at virtual viewpoint n*

$view_{n+1} = p$



*Warping*



$view_{n-1}$



*Warping*



# VSRS+

$view_{n+2}$



*Warping*



*Warped views  
at virtual viewpoint n*

$view_{n+1} = p$



*Warping*



*Masked Inter-view  
Connection Information*



$view_{n-1}$



*Warping*



# VSRS+

$view_{n+2}$



*Warping*

*Warped views  
at virtual viewpoint  $n$*



$view_{n+1} = p$



*Warping*



*Masked Inter-view  
Connection Information*



$view_{n-1}$



*Warping*



*Connection-  
Adaptive  
Pixel Intensity  
Estimation*

*virtual view  $_n$*



# Results

**MPEG/D → MDCTA/ED → VSRS+**

Sequence ID	Test Sequence	Spatial Resolution	No. Frames	Virtual View	MPEG/D → VSRS 3.5 [dB]	MDCTA/ED → VSRS+	
						Adaptive Connection	Fixed Connection
S01	Poznan Hall 2	1920x1088	200	6.5	SE	SE	SE
S02	Poznan Street	1920x1088	250	3.5	SE	SE	SE
S03	Undo Dancer	1920x1080	250	03	38.50	38.84	38.84
S04	GT Fly	1920x1080	250	04	SE	x	x
S03	Kendo	1024x768	300	04	37.66	37.96	38.10
S06	Balloons	1024x768	300	04	36.63	36.88	36.89
S07	Lovebird1	1024x768	240	07	28.68	29.37	29.85
S07*	Lovebird1	1024x768	240	07	30.37	30.50	30.81
S08	Newspaper	1024x768	300	05	32.35	34.10	34.43

# Results

## MPEG/D → VSRS+

Sequence ID	Test Sequence	Spatial Resolution	No. Frames	Virtual View	MPEG/D → VSRS 3.5 [dB]	MDCTA/ED → VSRS+		MPEG/D → VSRS+
						Adaptive Connection	Fixed Connection	Adaptive Connection
S01	Poznan Hall 2	1920x1088	200	6.5	SE	SE	SE	SE
S02	Poznan Street	1920x1088	250	3.5	SE	SE	SE	SE
S03	Undo Dancer	1920x1080	250	03	38.50	38.84	38.84	39.46
S04	GT Fly	1920x1080	250	04	SE	x	x	x
S03	Kendo	1024x768	300	04	37.66	37.96	38.10	38.13
S06	Balloons	1024x768	300	04	36.63	36.88	36.89	37.00
S07	Lovebird1	1024x768	240	07	28.68	29.37	29.85	29.60
S07*	Lovebird1	1024x768	240	07	30.37	30.50	30.81	30.70
S08	Newspaper	1024x768	300	05	32.35	34.10	34.43	33.50



# Subjective Results



Original



MPEG/D  $\rightarrow$  VSRS 3.5



MPEG/D  $\rightarrow$  MDCTA/ED  $\rightarrow$  VSRS+



MPEG/D  $\rightarrow$  VSRS+

# Subjective Results

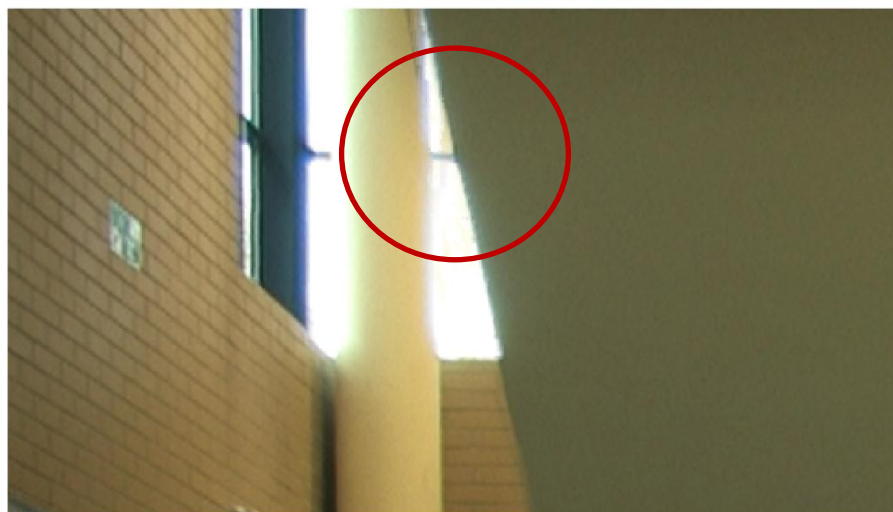
MPEG/D  $\rightarrow$  VSRS 3.5



Poznan Hall2  
Frame 159



MPEG/D  $\rightarrow$  MDCTA/ED  $\rightarrow$  VSRS+



MPEG/D  $\rightarrow$  VSRS+

# Subjective Results

MPEG/D  $\rightarrow$  VSRS 3.5



Poznan Street  
Frame 121



MPEG/D  $\rightarrow$  MDCTA/ED  $\rightarrow$  VSRS+



MPEG/D  $\rightarrow$  VSRS+



# Subjective Results

MPEG/D  $\rightarrow$  VSRS 3.5



Poznan Hall2  
Frame 122



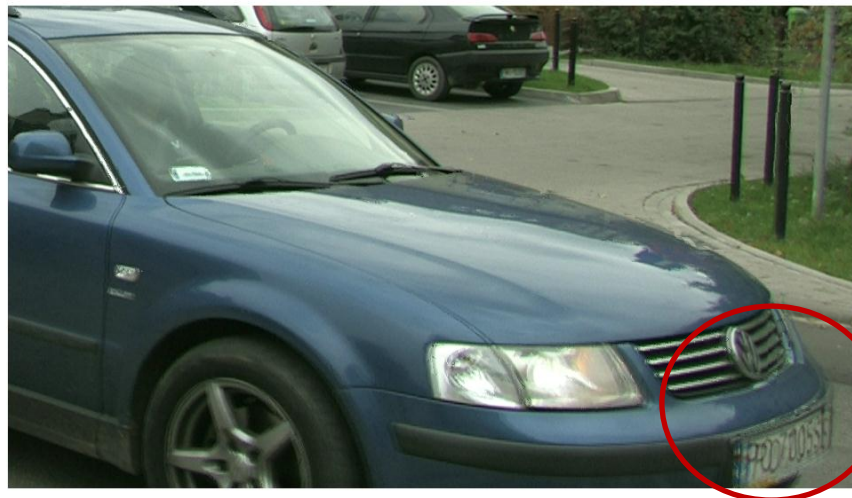
MPEG/D  $\rightarrow$  MDCTA/ED  $\rightarrow$  VSRS+



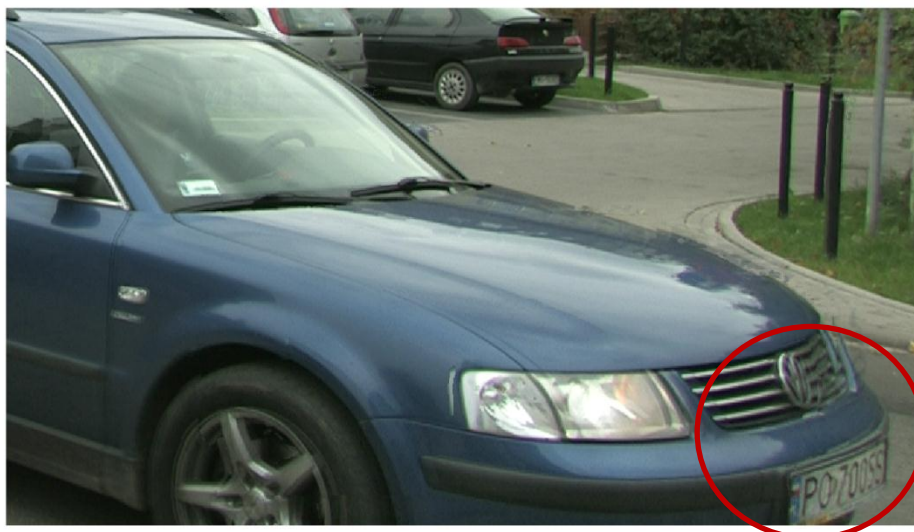
MPEG/D  $\rightarrow$  VSRS+

# Subjective Results

MPEG/D → VSRS 3.5



Poznan Street  
Frame 250



MPEG/D → MDCTA/ED → VSRS+



MPEG/D → VSRS+

# Subjective Results



Original

Kendo 4  
Frame 202



MPEG/D  $\rightarrow$  VSRS 3.5



MPEG/D  $\rightarrow$  MDCTA/ED  $\rightarrow$  VSRS+

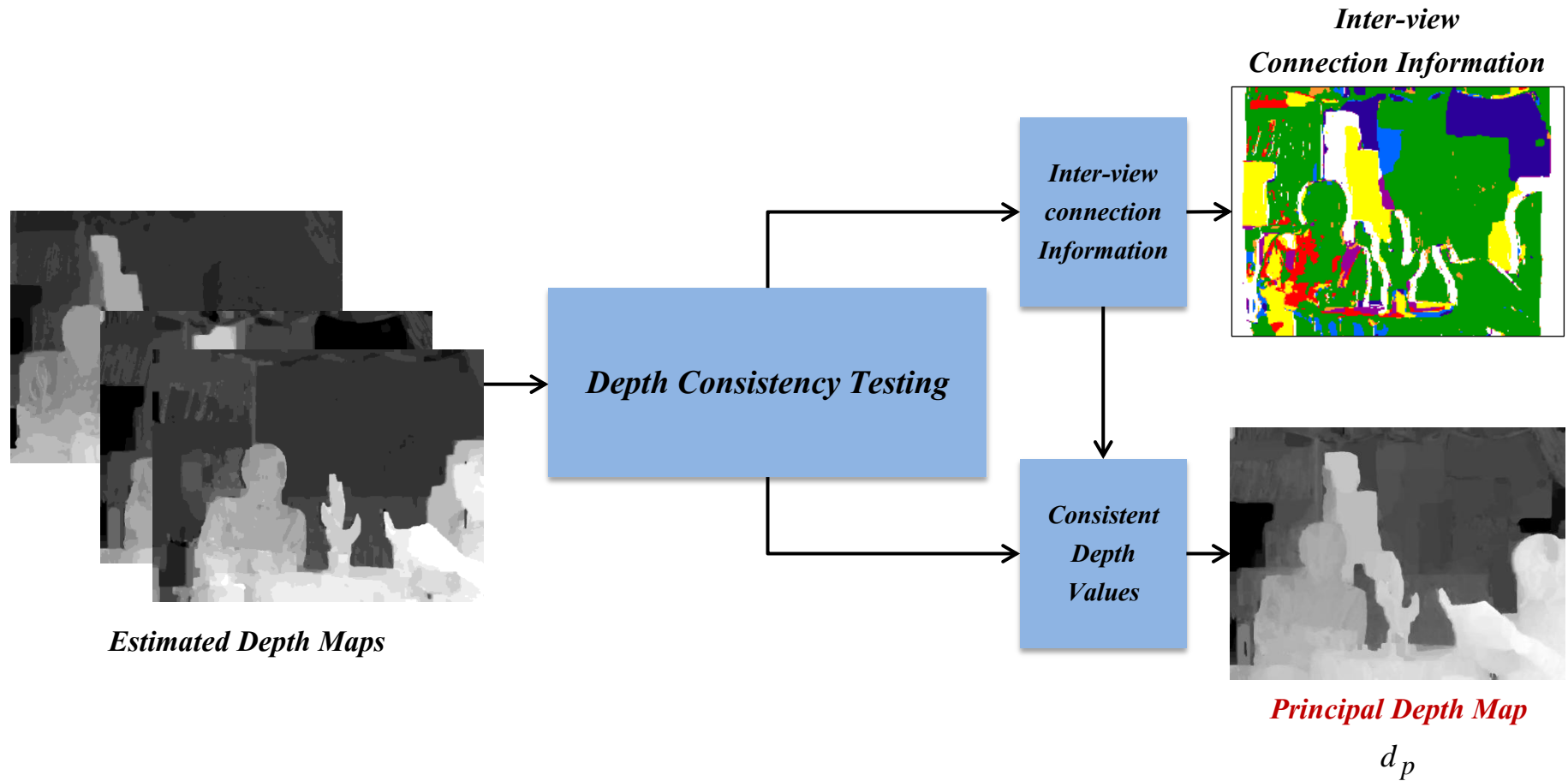


MPEG/D  $\rightarrow$  VSRS+

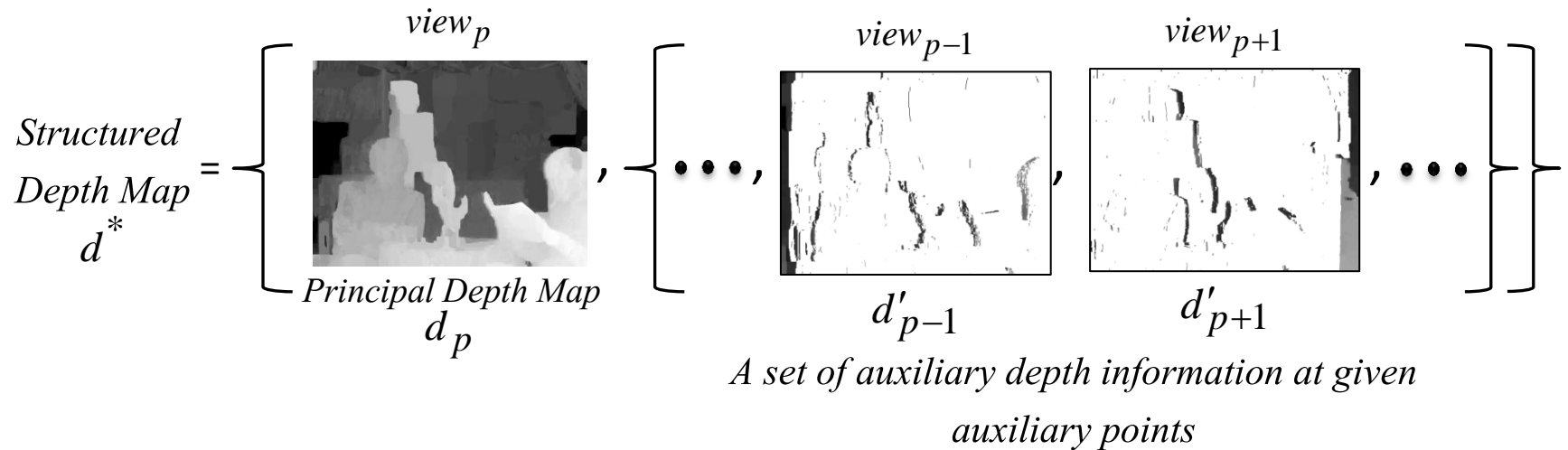
# Rendering with Structured-Depth



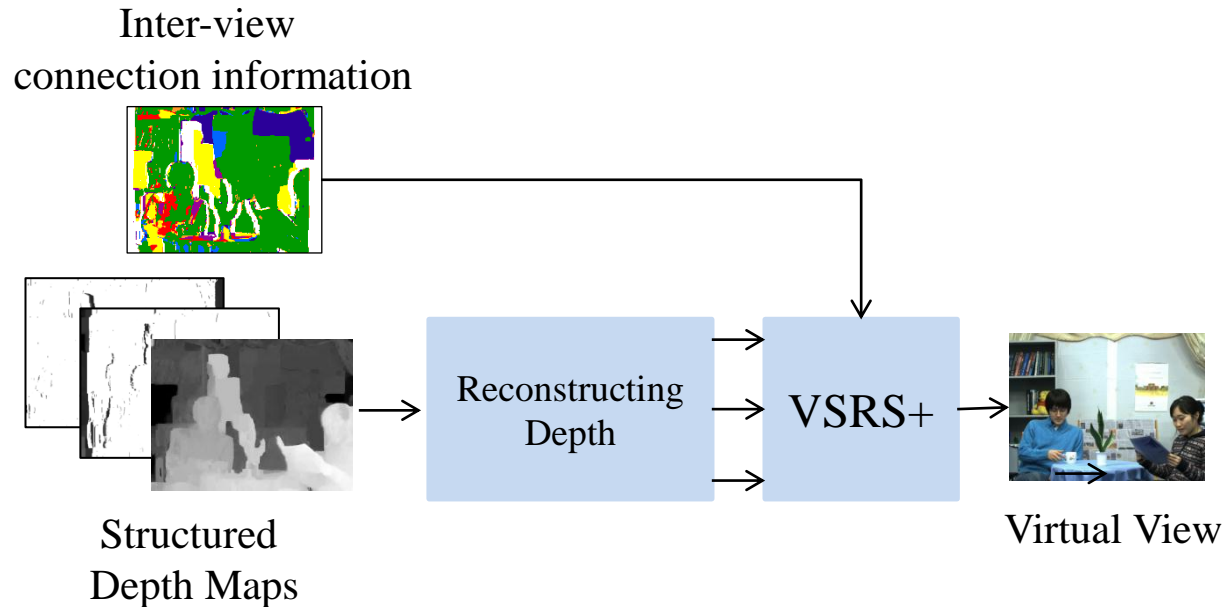
# Principal Depth Map



# Structured Depth Maps

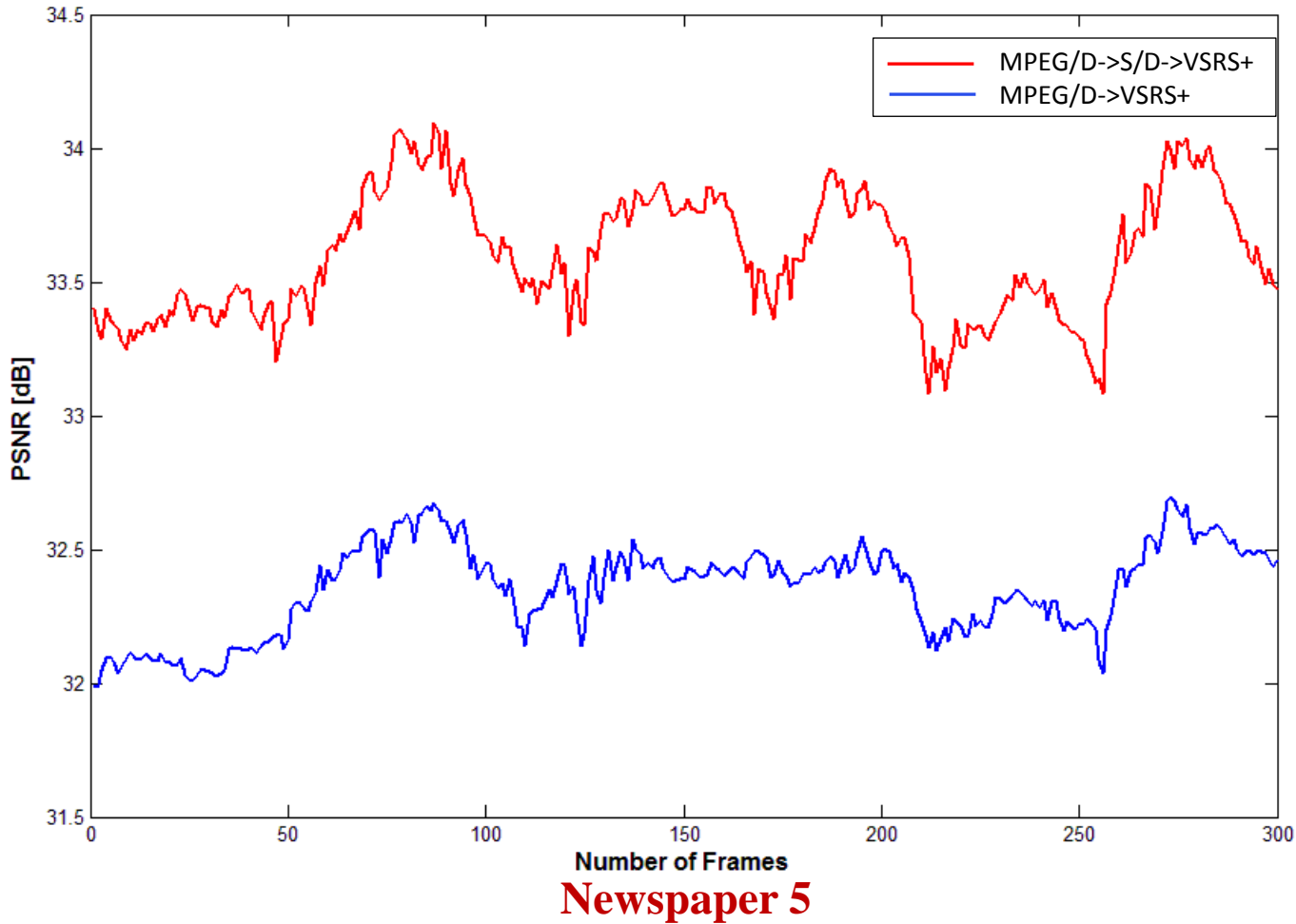


# Rendering with Structured Depth Maps



# Results

**MPEG/D→S/D→VSRS+**





# Results

## MPEG/D → S/D → VSRS+

Sequence ID	Test Sequence	Spatial Resolution	No. Frames	Virtual View	MPEG/D → VSRS 3.5 [dB]	MDCTA/ED → VSRS+		MPEG/D → VSRS+	MPEG/D → S/D → VSRS+	
						Adaptive Connection	Fixed Connection	Adaptive Connection	Adaptive Connection	Fixed Connection
S01	Poznan Hall 2	1920x1088	200	6.5	SE	SE	SE	SE	SE	SE
S02	Poznan Street	1920x1088	250	3.5	SE	SE	SE	SE	SE	SE
S03	Undo Dancer	1920x1080	250	03	38.50	38.84	38.84	39.46	38.86	38.86
S04	GT Fly	1920x1080	250	04	SE	x	x	x	x	x
S03	Kendo	1024x768	300	04	37.66	37.96	38.10	38.13	37.79	37.82
S06	Balloons	1024x768	300	04	36.63			37.00	36.60	36.56
S07	Lovebird1	1024x768	240	07	28.68			29.60	29.50	30.00
S07*	Lovebird1	1024x768	240	07	30.37			30.70	30.32	30.34
S08	Newspaper	1024x768	300	05	32.35			33.50	33.60	33.90

# Subjective Results



MPEG/D  $\rightarrow$  S/D  $\rightarrow$  VSRS+: Fixed

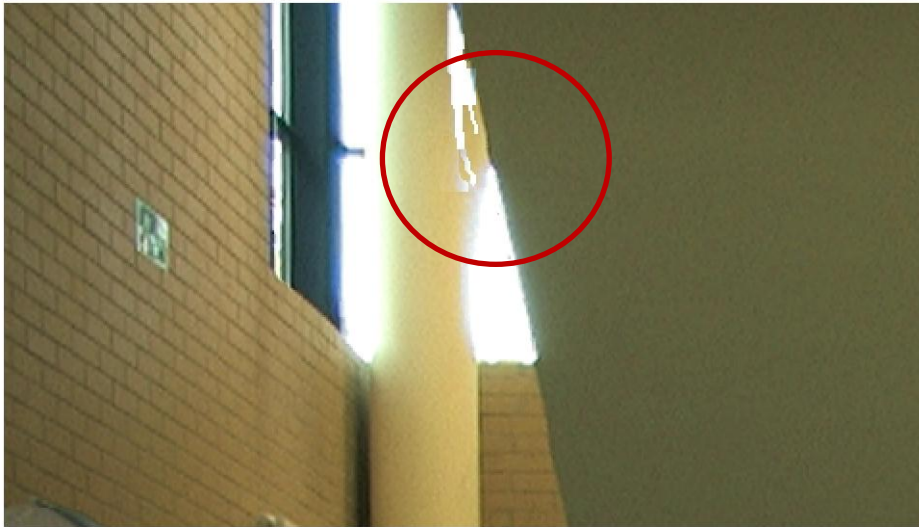
Newspaper 5  
Frame 105

Adaptive VSRS+  
vs.  
Fixed VSRS+

MPEG/D  $\rightarrow$  S/D  $\rightarrow$  VSRS+: Adaptive



# Subjective Results



Poznan Hall2  
Frame 151

MPEG/D  $\rightarrow$  S/D  $\rightarrow$  VSRS+

MPEG/D  $\rightarrow$  VSRS 3.5



# Subjective Results



Poznan Hall2  
Frame 121

MPEG/D  $\rightarrow$  VSRS 3.5



MPEG/D  $\rightarrow$  S/D  $\rightarrow$  VSRS+



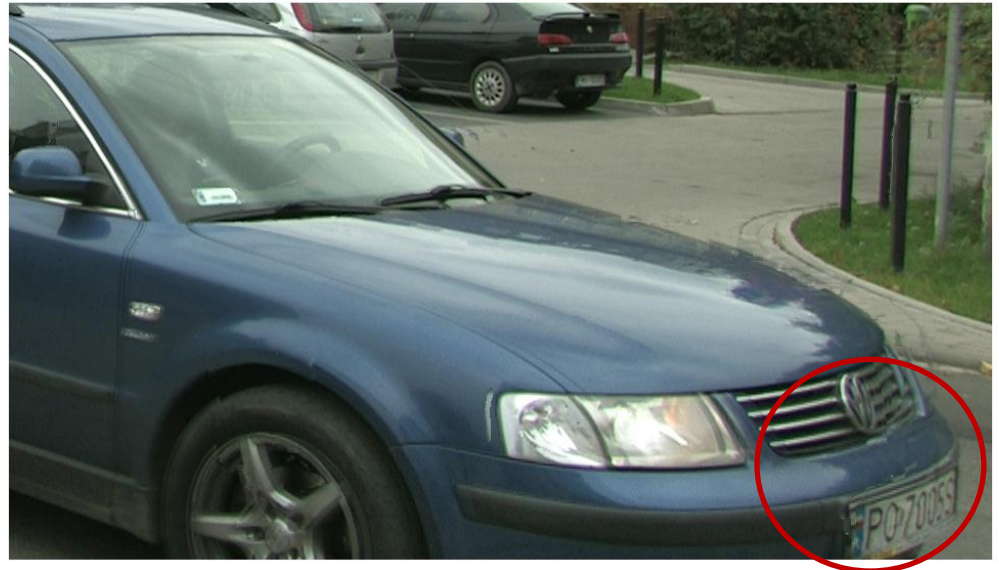
# Subjective Results



Poznan Street  
Frame 250

MPEG/D  $\rightarrow$  S/D  $\rightarrow$  VSRS+

MPEG/D  $\rightarrow$  VSRS 3.5



# Subjective Results



Original



MPEG/D  $\rightarrow$  VSRS 3.5



MPEG/D  $\rightarrow$  S/D  $\rightarrow$  VSRS 3.5

# Subjective Results



Original

Kendo 4  
Frame 202



MPEG/D  $\rightarrow$  VSRS 3.5



MPEG/D  $\rightarrow$  S/D  $\rightarrow$  VSRS 3.5

# Subjective Results



Original

Kendo 4  
Frame 204



MPEG/D  $\rightarrow$  VSRS 3.5



MPEG/D  $\rightarrow$  S/D  $\rightarrow$  VSRS 3.5



# Subjective Results



Original

Kendo 4  
Frame 204



MPEG/D  $\rightarrow$  VSRS 3.5



MPEG/D  $\rightarrow$  S/D  $\rightarrow$  VSRS 3.5

# Subjective Results



Original

Kendo 4  
Frame 204



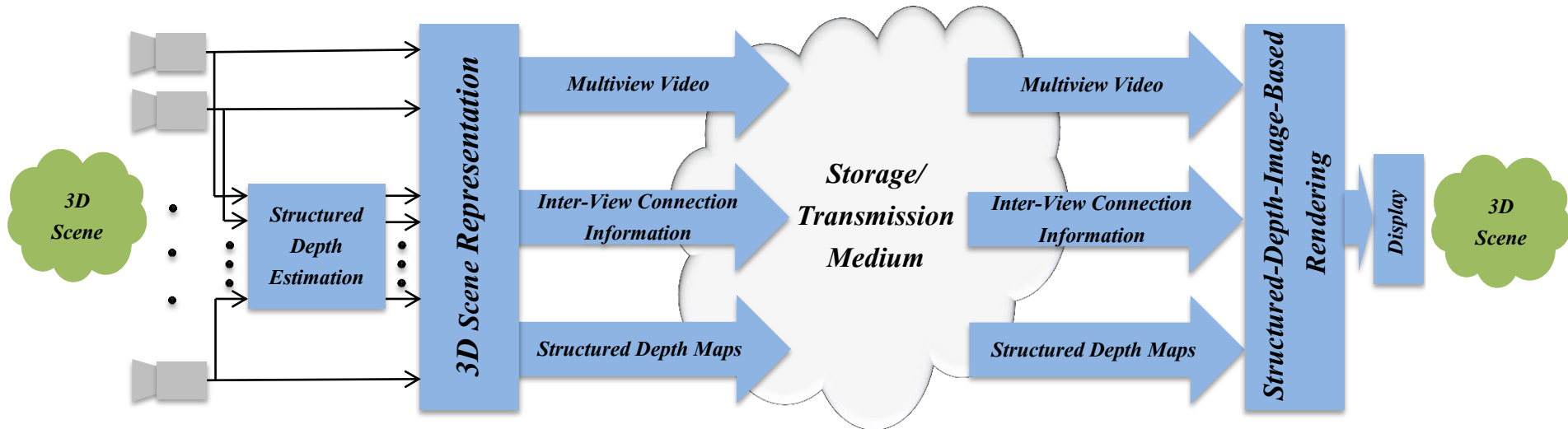
MPEG/D  $\rightarrow$  VSRS 3.5



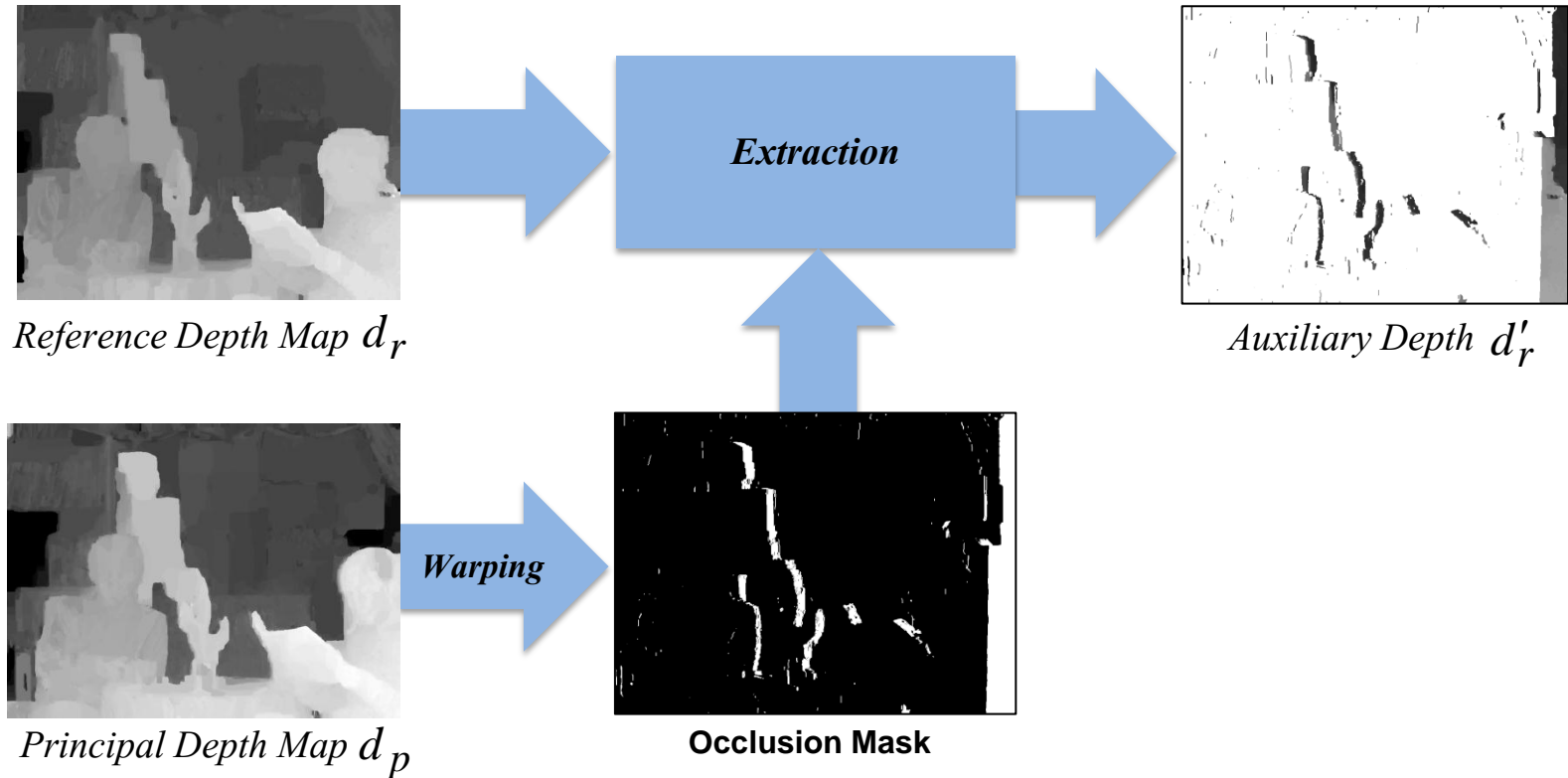
MPEG/D  $\rightarrow$  S/D  $\rightarrow$  VSRS 3.5

# Thank You

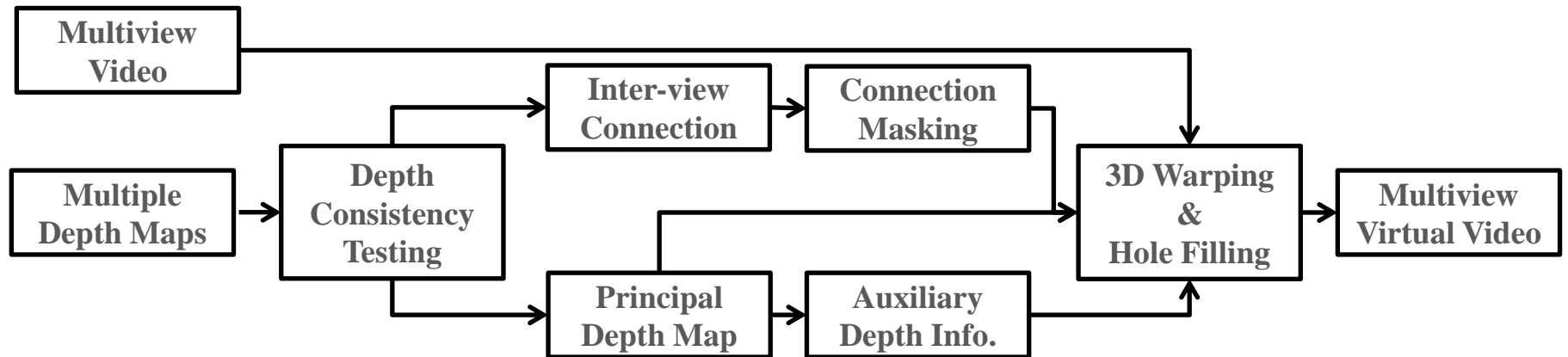
# View Synthesis Using Structured Depth Images (VSRS+)



# Extraction of Auxiliary Depth



# Experiments



# Subjective Results



Undo Dancer 3  
Frame 30

Original



MPEG/D → VSRS 3.5



MPEG/D → MDCTA/D → VSRS 3.5



MPEG/D → S/D → VSRS+