




Marshall and Olkin-G and Gamma-G family of distribution: properties and applications

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2 Abstract:

- 3 • This article introduces a new family by combining the Marshall and Olkin-G and
4 Gamma-G classes. The family has only two extra shape parameters and can be a
5 better model than other existing classes of distributions. Simulations are performed
6 to verify the consistency of the estimators. Its flexibility is shown using two real data
7 sets.

8 Key-Words:

- 9 • *Distribution family; mathematical properties; simulations; applications.*

10 AMS Subject Classification:

- 11 • 49A05, 78B26.

1. Introduction

12 The mechanism by adding shape parameters to a baseline distribution has
13 proved to be useful to make the generated distributions more flexible especially

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1 for studying tail properties than existing distributions and for improving their
 2 goodness-of-fit statistics to the data under study. Many special distributions in
 3 these families are discussed by Tahir and Nadarajah (2015).

4 Let $G(x)$ be the cumulative distribution function (CDF) of a baseline dis-
 5 tribution and $g(x) = dG(x)/dx$ be the corresponding probability density function
 6 (PDF) depending on a parameter vectot η . A generalized family are presented
 7 with two additional shape parameters by transforming the CDF $G(x)$ according to
 8 two sequential important generators. These families are important for modeling
 9 data in several engineering areas.

10 The CDF of the Marshall and Olkin's (1997) (MO-G) family (for $\theta > 0$) is

$$(1.1) \quad F_{\text{MO-G}}(x) = \frac{G(x)}{\theta + (1 - \theta)G(x)} = \frac{G(x)}{1 - (1 - \theta)[1 - G(x)]}, \quad x \in \mathbb{R}.$$

11 The density function corresponding to (1.1) has the form

$$(1.2) \quad f_{\text{MO-G}}(x) = \frac{\theta g(x)}{[\theta + (1 - \theta)G(x)]^2}.$$

12 For $\theta = 1$, $f_{\text{MO-G}}(x)$ is equal to $g(x)$. Equation (1.2) represents the PDF
 13 of the minimum of n iid random variables having density $g(x)$, say T_1, \dots, T_N ,
 14 where N has a geometric distribution with probability parameters θ and θ^{-1} if
 15 $0 < \theta < 1$ and $\theta > 1$, respectively.

16 Tahir and Nadarajah (2015, Table 2) presented thirty distributions belong-
 17 ing to this family. It is easily generated from the baseline quantile function (QF)
 18 by $Q_{\text{MO-G}}(u) = Q_G(\theta u [\theta u + 1 - u])$ for $u \in (0, 1)$.

19 Marshall and Olkin considered the exponential and Weibull distributions
 20 for the baseline G and derived some structural properties of the generated dis-
 21 tributions. The special case that G is an exponential distribution refers to a
 22 two-parameter competitive model to the Weibull and gamma distributions.

23 The CDF of the gamma-G (Γ -G) family (Zografos and Balakrishnan, 2009)
 24 is

$$(1.3) \quad F_{\Gamma\text{-G}}(x) = \gamma_1(a, -\log[1 - G(x)]), \quad x \in \mathbb{R},$$

25 where $a > 0$ is an extra shape parameter, $\gamma_1(a, z) = \gamma(a, z)/\Gamma(a)$ is the incomplete
 26 gamma function ratio and $\gamma(a, z) = \int_0^z t^{a-1} e^{-t} dt$.

27 Then, the PDF of the Γ -G family can be expressed as

$$(1.4) \quad f_{\Gamma\text{-G}}(x) = \frac{1}{\Gamma(a)} \{-\log[1 - G(x)]\}^{a-1} g(x).$$

28 Each new Γ -G distribution follows from a given baseline G. For $a = 1$,
 29 the Γ -G family reduces to G. If Z is a gamma random variable with unit scale

1 parameter and shape parameter $a > 0$, then $W = Q_G(1 - e^Z)$ has density (1.4).
 2 So, the Γ -G distribution is easily generated from the gamma distribution and the
 3 QF of G.

4 The remaining of the paper is addressed as follows. Section 2 introduces
 5 the *Marshall and Olkin-Gamma-G* (MO- Γ -G) family and presents some special
 6 models. The maximum likelihood estimates (MLEs) of the parameters of the
 7 new family is addressed in Section 3. Some simulations ate performed in Section
 8 4 to estimate the biases of the MLEs. Two empirical applications illustrate the
 9 potentiality of the proposed family in Section 5. A variety of theoretical properties
 10 are derived in Section 6. Some conclusions remarks are offered in Section 7.

2. The New Family

11 By combining Equations (1.1) and (1.3), the CDF of the random variable
 12 $X \sim \text{MO-}\Gamma\text{-G}$ representing the new family is defined by

$$(2.1) \quad F_X(x) = \frac{\gamma_1(a, -\log[1 - G(x)])}{\theta + (1 - \theta)\gamma_1(a, -\log[1 - G(x)])}, \quad x \in \mathbb{R}.$$

13 By differentiating (2.1), the PDF of X follows as

$$(2.2) \quad f_X(x) = \frac{\theta \{-\log[1 - G(x)]\}^{a-1} g(x)}{\Gamma(a) \{\theta + (1 - \theta)\gamma_1(a, -\log[1 - G(x)])\}^2}.$$

14 The density (2.2) can be interpreted from a sequence of N iid random vari-
 15 ables, say Z_1, \dots, Z_N , each one having a gamma density unit scale and shape
 16 $a > 0$, assuming that N (is not fixed) has a geometric distribution with probab-
 17 ities θ and θ^{-1} for $0 < \theta < 1$ and $\theta > 1$, respectively. By transforming the Z_i 's
 18 via the baseline QF by $W_i = Q_G(1 - e^{Z_i})$ (for $i = 1, \dots, N$), Equation (1.2) is
 19 defines the PDF of the minimum W_1, \dots, W_n . Making this double composition
 20 of the two generators, the proposed family absorbs the impacts of two different
 21 flexibilities on applications.

22 Table 2 provides some special cases of (2.2), where $\Phi(x)$ and $\phi(x)$ are
 23 the CDF and PDF of the standard normal distribution. The density and haz-
 24 ard functions of the Marshall-Olkin- Γ -Weibull (MO- Γ -W) defined by $h(x) =$
 25 $f(x)/(1 - F(x))$ are displayed in Figure 1, which provide more flexibility for
 26 these functions in relation to the baseline ones.

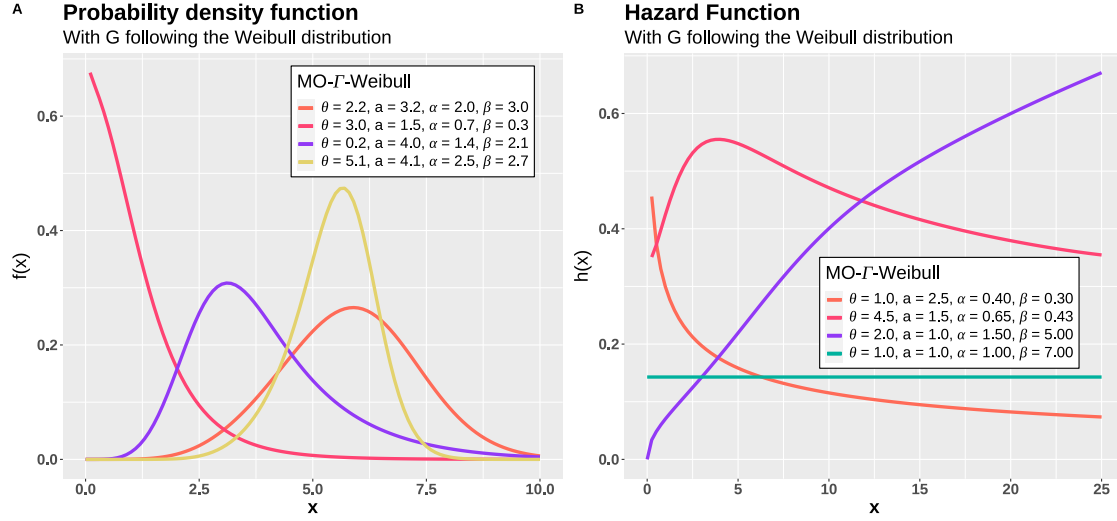


Figure 1: (A) MO- Γ -W density. (B) MO- Γ -W hazard.

The CDF (2.1) can be easily inverted to calculate the QF of the MO- Γ -G distribution, say $x = Q_X(u) = F_X^{-1}(u)$ for $u \in (0, 10$, in terms of the baseline QF $Q_G(\cdot)$. The inverse of $F_X(x) = u$, where u is a uniform number in $(0, 1)$ is easily obtained. By combining the inverses of Equations (1.1) and (2.1), $F_X(x) = u$ leads to $z = z(u) = \theta u / [1 - (1 - \theta)u]$ and $\gamma_1(a, -\log[1 - G(x)]) = z(u)$. Then, the QF of X can be expressed as

$$x = Q_G(v(u)),$$

where

$$v(u) = 1 - \exp[-\gamma_1^{-1}(a, z(u))],$$

- 1 and $\gamma_1^{-1}(a, w) = Q^{-1}(a, 1 - w)$ is the inverse function of $\gamma_1(a, w)$. Some formulae
- 2 for $Q^{-1}(a, 1 - w)$ are given in [http://functions.wolfram.com/GammaBetaErf/](http://functions.wolfram.com/GammaBetaErf/InverseGammaRegularized/)
- 3 [InverseGammaRegularized/](http://functions.wolfram.com/GammaBetaErf/InverseGammaRegularized/).

Distribution	Baseline CDF	Generated PDF
Normal	$G(x) = \Phi(x)$	$f_X(x) = \frac{\theta \{-\log[1-\Phi(x)]\}^{a-1} \phi(x)}{\Gamma(a) \{\theta + (1-\theta)\gamma_1(a, -\log[1-\Phi(x)])\}^2}$
Logistic	$G(x) = \frac{1}{1+e^{-x}}$	$f_X(x) = \frac{\theta e^{-x} \{-\log[1-(1+e^{-x})^{-1}]\}^{a-1}}{\Gamma(a) (1+e^{-x})^2 \{\theta + (1-\theta)\gamma_1(a, -\log[1-(1+e^{-x})^{-1}])\}^2}$
Gumbel	$G(x) = 1 - \exp(-e^x)$	$f_X(x) = \frac{\theta \exp(ax - e^x)}{\Gamma(a) \{\theta + (1-\theta)\gamma_1(a, e^x)\}^2}$
Log-Normal	$G(x) = \Phi(\log x)$	$f_X(x) = \frac{\theta \phi(\log x) \{-\log[1-\Phi(\log x)]\}^{a-1}}{\Gamma(a) x \{\theta + (1-\theta)\gamma_1(a, -\log[1-\Phi(\log x)])\}^2}$
Exponential	$G(x) = 1 - \exp(-\lambda x), \lambda > 0$	$f_X(x) = \frac{\theta \lambda^a x^{(a-1)}}{\Gamma(a) \{\theta + (1-\theta)\gamma_1(a, \lambda x)\}^2}$
Weibull	$G(x) = 1 - \exp(-(\lambda x)^\gamma), \lambda, \gamma > 0$	$f_X(x) = \frac{\theta \gamma \lambda^a \gamma x^{a\gamma-1} \exp\{-(\lambda x)^\gamma\}}{\Gamma(a) \{\theta + (1-\theta)\gamma_1[a, (\lambda x)^\gamma]\}^2}$
Gamma	$G(x) = \gamma_1(\alpha, \beta x), \alpha, \beta > 0$	$f_X(x) = \frac{\theta \beta^\alpha x^{\alpha-1} e^{-\beta x} \{-\log[1-\gamma_1(\alpha, \beta x)]\}^{a-1}}{\Gamma(a) \{\theta + (1-\theta)\gamma_1(a, -\log[1-\gamma_1(\alpha, \beta x)])\}^2}$
Pareto	$G(x) = 1 - \frac{1}{(1+x)^\nu}, \nu > 0$	$f_X(x) = \frac{\theta e^{-x} [\nu \log(1+x)]^{a-1} g(x)}{\Gamma(a) (1+e^{-x})^2 \{\theta + (1-\theta)\gamma_1(a, \nu \log[1+x])\}^2}$

Table 1:

Special Distributions in the MO-Γ-G family.

3. Estimation

1 The MO- Γ -G family can be fitted to real data using the **AdequacyModel**
 2 package in the R software. This package does not require to define the log-
 3 likelihood function and it computes the MLEs, their standard errors (SEs) and
 4 the formal statistics defined in Section 5. It is necessary to provide the PDF and
 5 CDF of the distribution to be fitted to a data set.

For example, if x_i is one observation from (2.2) and $\boldsymbol{\eta}$ is a q -parameter vector specifying $G(\cdot)$, the log-likelihood function for $\boldsymbol{\theta}^\top = (a, \theta, \boldsymbol{\eta}^\top)$ from n observations is

$$\begin{aligned} \ell(\boldsymbol{\theta}) = & n \log(\theta) + n \log(\gamma) + n a \gamma \log(\lambda) + (a\gamma - 1) \sum_{i=1}^n \log(x_i) - \lambda^\gamma \sum_{i=1}^n \log(x_i) \\ (3.1) \quad & - n \log[\Gamma(a)] - 2 \sum_{i=1}^n \log\{\theta + (1 - \theta)\gamma_1[a, (\lambda x_i)^\gamma]\}. \end{aligned}$$

6 Due to the impossibility of obtaining the MLEs in closed form, numerical
 7 methods to obtain the estimates that maximize $\ell(\cdot)$ are necessary. Several pro-
 8 gramming languages and statistical software distributes functions and routines
 9 that make it easy to obtain numerical estimates by various interactive methods.
 10 In practice, obtaining the MLEs for the parameters that index a probability distri-
 11 bution are commonly obtained in this way, since the Newton and quasi-Newton
 12 methods produce satisfactory results under reasonable conditions of the object
 13 function, that is, when they do not impose conditions that disturb the conver-
 14 gence of the algorithms.

15 To obtain the MLEs, the package **AdequacyModel** of the programming
 16 language R was used, see R Core Team (2020). This library, created and main-
 17 tained by one of the authors of this paper, is widely cited by several papers in the
 18 field of statistics and serves as a basis for other library implementations available
 19 on the Comprehensive R Archive Network - CRAN. With it, in particular using
 20 the goodness.fit function, it is possible to provide an implementation R of (2.2),
 21 being in charge of this function, obtain $\ell(\cdot)$ by returning several measures of fit
 22 adequacy as well as the MLEs. Further details regarding this package can be
 23 obtained from Marinho et al. (2019).

4. Simulations

24 Due to the probable absence of MLEs in closed-form for distributions be-
 25 longing to the MO- Γ -G family, it is necessary to examine the precision of the
 26 estimates calculated numerically. For doing that, the biases of the estimators of

1 the parameters of the MO- Γ -Dagum($\theta, a, \alpha, \beta, p$) distribution are determined,
 2 where $G \sim \text{Dagum}(\alpha, \beta, p)$ is the baseline distribution. All parameters are taken
 3 equal to one for different sample sizes reported in Table 2.

4 Ten thousand Monte Carlo simulations are performed for each sample size
 5 to examine the numerical estimates calculated by the BFGS method. The figures
 6 in Table 2 indicate that this method behaves well when the sample size increases.
 7 This is theoretically expected. However, in practice, difficulties can be faced in
 8 other families of distributions due to the flatness of the log-likelihood function.

9 All simulations can be reproduced using the script in Appendix A. The
 10 simulations are parallelized and able to use all threads available by a multicore
 11 processor, thus making them more computationally efficient and consequently
 12 requiring less time to complete. The simulations are performed on a computer
 13 with an Intel Core i5-8265U processor with 8 threads working at a maximum
 14 frequency of 3.90 GHz, requiring, on these hardware, a time of 14.36 hours to
 15 perform all simulations. The figures in Table 2 reveal that the average biases of
 16 the MLEs could be very reduced only for $n > 2,000$.

17 To generate observations from the random variable X with density f , the
 18 well-known Acceptance-Rejection Algorithm for continuous random variables, which
 19 is very useful when the quantile function involves complex functions that can lead
 20 to some numerical inaccuracies. For doing this, another random variable Y is chosen
 21 such that it can generate observations from a PDF h with the same support
 22 as f . Then, the acceptance and rejection algorithm is defined by the following
 23 steps:

- 24 1. Generate an outcome y from Y ;
- 25 2. Generate an observation u from a random variable $U \sim \mathcal{U}(0, 1)$;
- 26 3. If $u < \frac{f(y)}{c g(y)}$, where c is a real constant, accept $x = y$; otherwise reject y as
 27 an outcome from X and return to 1.

28 The constant c must be chosen in such a way that $\frac{f(y)}{c g(y)} \leq 1$. Thus, to
 29 minimize the computational cost of generating observations from X through the
 30 generated observations from Y , c is chosen as the lowest possible value to maximize
 31 the likelihood of acceptance. Further details of this method can be found in Rizzo
 32 (2019).

Table 2: Mean biases of the MLEs obtained using the BFGS method calculated from the Monte-Carlo simulation.

n	$B(\hat{\theta})$	$B(\hat{a})$	$B(\hat{\alpha})$	$B(\hat{\beta})$	$B(\hat{p})$	Time (mins)
10	0.2376	2.1635	2.7557	1.6282	1.3057	1.1430
20	0.4154	2.4639	1.5728	1.8082	0.7383	1.6248
60	0.7214	2.2432	0.5667	1.8815	0.2872	3.3954
100	0.6146	1.9579	0.3253	1.6148	0.2651	4.9628
200	0.3838	1.3894	0.1827	1.1773	0.3701	8.1457
400	0.2166	0.9635	0.1076	0.6181	0.3957	13.7370
600	0.1269	0.7242	0.0772	0.3968	0.3637	17.9310
1,000	0.0553	0.4885	0.0521	0.2328	0.2636	22.8784
2,000	0.0456	0.3087	0.0334	0.0990	0.1722	38.4593
5,000	-0.0058	0.1307	0.0146	0.0117	0.0171	52.8098
10,000	-0.0146	0.0842	0.0095	0.0095	0.0031	95.8380
20,000	-0.0090	0.0330	0.0038	0.0005	-0.0099	126.4260
30,000	-0.0028	0.0183	0.0012	-0.0036	-0.0029	182.0760
50,000	-0.0057	0.0124	0.0015	0.0016	-0.0021	291.9300

5. Applications

Consider the Weibull baseline. Two applications are provided to compare the new generated model with seven extended Weibull distributions, namely the beta-Weibull (β -W) (Famoye *et al.*, 2005), Kumaraswamy Weibull (Kw-W) (Cordeiro and Nadarajah, 2010), Marshall-Olkin Weibull (MO-W) (Ahmed *et al.*, 2017), Marshall-Olkin Extended Weibull (MOE-W) (Cordeiro *et al.*, 2019), exponentiated Weibull (exp-W) (Mudholkar and Srivastava, 1993), gamma Weibull (Γ -W) Cordeiro *et al.*, 2016) and exponentiated generalized Weibull (EG-W) (Oguntunde *et al.*, 2015) (with $a = 1$). Some of these distributions are widely used in practice.

The log-likelihood for the Marshall-Olkin-Gamma-Weibull (MO- Γ -W) from one observation is

$$\begin{aligned} \ell(\boldsymbol{\theta}) = & \log(\theta) + \log(\gamma) + (a\gamma)\log(\lambda) + (a\gamma - 1)\log(x) - (\gamma x)^\gamma - \log[\Gamma(a)] \\ (5.1) \quad & - 2\log\{\theta + (1 - \theta)\gamma_1[a, (\lambda x)^\gamma]\}, \end{aligned}$$

where $\boldsymbol{\theta} = (a, \theta, \lambda, \gamma)^\top$. The components of the score function are

$$U_a(\boldsymbol{\theta}) = \gamma \log(\lambda) + \gamma \log(x) - \psi^{(0)}(a) - \frac{2\{(1 - \theta)A - (1 - \theta)\psi^{(0)}(a)\gamma_1[a, (x\lambda)^\gamma]\}}{\theta\Gamma(a) + (1 - \theta)\gamma_1[a, (x\lambda)^\gamma]},$$

$$U_\theta(\boldsymbol{\theta}) = \frac{1}{\theta} - \frac{2\{\Gamma(a) - \gamma_1[a, (\lambda x)^\gamma]\}}{\theta\Gamma(a) + (1 - \theta)\gamma_1[a, (\lambda x)^\gamma]},$$

$$U_\lambda(\boldsymbol{\theta}) = \frac{\gamma}{\lambda} [a - (\lambda x)^\gamma] + \frac{2\gamma \lambda^{-1} (\lambda x)^{a\gamma} (1 - \theta) \exp\{-(\lambda x)^\gamma\}}{\theta \Gamma(a) + (1 - \theta) \gamma_1 [a, (x\lambda)^\gamma]}$$

and

$$U_\gamma \boldsymbol{\theta} = \frac{1}{\gamma} + a \log(\lambda) + a \log(x) - (\lambda x)^\gamma \log(\lambda x) + \frac{2(1 - \theta) (\lambda x)^{\gamma a} \log(\lambda x) \exp\{-(\lambda x)^\gamma\}}{\theta \Gamma(a) + (1 - \theta) \gamma_1 [a, (x\lambda)^\gamma]},$$

where

$$A = G_{2,3}^{3,0} \left[(x\lambda)^\gamma \middle| \begin{matrix} 1, 1 \\ 0, 0, a \end{matrix} \right] + \log [(\lambda x)^\gamma] \gamma_1 [a, (x\lambda)^\gamma],$$

1 $\psi^{(n)}(x)$ is the n -th derivative of the digamma function,

$$A = \psi^{(0)}(a) - \log [(\lambda x)^\gamma] - G_{2,3}^{3,0} \left((\lambda x)^\gamma \middle| \begin{matrix} 1, 1 \\ 0, 0, a \end{matrix} \right),$$

2 and $G_{p,q}^{m,n} \left(z \middle| \begin{matrix} a_1, \dots, a_p \\ b_1, \dots, b_q \end{matrix} \right)$ is the Meijer G function.

3 The **AdequacyModel** is used to fit the distributions cited before to two
 4 real data sets. The SANN method, which is a variant of simulated annealing
 5 (Belisle, 1992), is considered. The distributions are compared via the Anderson
 6 Darling (A*) and Cramér Von Mises (W*) statistics reported in the **goodness.fit**
 7 function.

8 For the first data set, a modification of the “FoodExpenditure” data from the
 9 **betareg** package is considered, which refers to the proportions of income spent
 10 on food for a random sample of 38 households in a large US city (according to the
 11 package information). Here, the household expenditures for food are considered
 12 and is given by

$$data = FoodExpenditure_{food} / \#(FoodExpenditure_{food}),$$

13 where $FoodExpenditure_{food}$ is the random variable corresponding to the house-
 14 hold expenditures for food and $\#(\cdot)$ indicates the number of observations on this
 15 variable. The MLEs and their standard errors (SEs) (in parentheses) are listed
 16 in Table 3. The statistics W* and A* are also given in this table. The results
 17 indicate that the proposed model has better performance than the other seven
 18 fitted models.

19 As a second application, consider a data set collected in a pilot study about
 20 hypertension in the Dominican Republic in 1997 found in <http://biostat.mc.vanderbilt.edu/wiki/Main/DataSets>. The observations are the systolic blood
 21 pressure of persons who came to medical clinics in several villages for a variety
 22 of complaints. The MLEs of the parameters, their SEs and the values of the
 23 statistics are listed in Table 4 for the previous distributions. By comparing the
 24 measures of these formal statistics, we conclude that the proposed distribution
 25 outperforms the rest of them.
 26

Table 3: Application 1

Model	a	θ	λ	γ	W^*	A^*
MO- Γ -W($a, \theta, \lambda, \gamma$)	0.926134 (0.02626926)	1.379664 (0.22381086)	33.323073 (0.28530971)	25.398809 (0.08259864)	0.0339	0.2376
β -W($a, \theta, \lambda, \gamma$)	9.92882 (0.02908181)	0.1700880 (0.02049663)	9.759469 (<0.0001)	1.530541 (<0.0001)	0.043567	0.2594618
KW-W($a, \theta, \lambda, \gamma$)	0.04987575 (0.008090352)	99.99989793 (16.225905058)	1.07602954 (0.003156126)	23.40287099 (0.014646102)	1.330915	6.742609
MOE-W($a, \theta, \lambda, \gamma$)	0.1366666 (0.1599182)	2.020436 (<0.0001)	62.72201 (<0.0001)	4.2956659 (0.7365535)	0.03541554	0.2579222
EGW(a, b, λ, γ)	5.6189861421 (0.0028147823)	6.1833138579 (0.0009807091)	1.2870816760 (0.1159810838)	1.3798562942 (0.1480747352)	0.03715255	0.2518879
MO-W(a, λ, γ)	0.15920715 (0.07170351)	- (-)	1.58609458 (0.13353716)	4.26713785 (0.16650667)	0.03456333	0.257339
exp-W(a, λ, γ)	6.1102948 (0.4222173)	- (-)	4.4680469 (0.3175876)	1.3858740 (0.1677722)	0.03726684	0.2523749
γ -W(a, λ, γ)	5.751546 (0.0015006)	- (-)	10.0000 (0.0001163185)	1.208773 (0.00822782)	0.0879	0.6599

Table 4: Application 2

Model	a	θ	λ	γ	W^*	A^*
MO- Γ -W($a, \theta, \lambda, \gamma$)	9.629304 (0.006217876)	3.640779 (0.182495785)	6.260826 (0.024446563)	12.823429 (0.007965221)	0.5093	2.8076
β -W($a, \theta, \lambda, \gamma$)	31.08471 (0.01279570)	47.14636 (<0.0001)	0.01698383 (0.00014535)	2.054037 (<0.0001)	0.7540428	4.279418
KW-W($a, \theta, \lambda, \gamma$)	7363.281 (0.04194304)	0.03925762 (0.0004194304)	1.467640 (<0.0001)	0.6146940 (<0.0001)	0.5351	2.9617
MOE-W($a, \theta, \lambda, \gamma$)	101.13471834 (46.782882038)	0.42386507 (0.100832102)	0.03095935 (0.003644092)	1.70240332 (0.168142275)	1.14418	6.644617
EGW(a, b, λ, γ)	0.2351691 (0.002540837)	140.0000 (3.278565)	0.4576370 (<0.0001)	0.7425738 (<0.0001)	0.8925	5.3338
MO-W(a, λ, γ)	173.2139 (0.00016394)	- (-)	0.02125455 (0.000212794)	1.601970 (0.0001398109)	1.476088	8.58705
exp-W(a, λ, γ)	69.02916 (0.08389090)	- (-)	0.02405120 (0.0002249256)	1.345536 (<0.0001)	0.8899261	5.094141
Γ -W(a, λ, γ)	9.11229459 (0.96330688)	- (-)	0.02617729 (0.00291875)	1.74641178 (0.08030313)	0.6227098	3.488268

6. Mathematical properties

In this section, some main mathematical properties are presented for the MO- Γ -G family based on a general linear representation for its density function, which are important to determine its mathematical properties from those of exponentiated-G (exp-G) distributions.

6.1. Linear Representation

For an arbitrary CDF $G(x)$, the CDF and PDF of the exponentiated-G (exp-G) distribution with power parameter $a > 0$ are

$$\Pi_a(x) = G(x)^a \quad \text{and} \quad \pi_a(x) = a g(x) G(x)^{a-1},$$

respectively. This class of distributions is quite useful in several applications. In fact, Tahir and Nadarajah (2015) cited more than seventy papers on exponentiated distributions in their Table 1.

First, the MO-G cumulative distribution (1.2) admits the linear combination (Barreto-Souza *et al.*, 2013)

$$(6.1) \quad F_{\text{MO-}\Gamma}(x) = \sum_{i=0}^{\infty} w_i^{\text{MO-G}} \Pi_{i+1}(x) = \sum_{i=0}^{\infty} w_i^{\text{MO-G}} G(x)^{i+1},$$

where the coefficients are (for $i = 0, 1, \dots$)

$$w_i^{\text{MO-}\Gamma} = w_i^{\text{MO-}\Gamma}(\theta) = \begin{cases} \frac{(-1)^i \theta}{(i+1)} \sum_{j=i}^{\infty} (j+1) \binom{j}{i} \bar{\theta}^j, & \theta \in (0, 1), \\ \theta^{-1} (1 - \theta^{-1})^i, & \theta > 1, \end{cases}$$

and $\bar{\theta} = 1 - \theta$.

Second, the linear combination for the Γ -G cumulative distribution (1.4) follows from Castellares and Lemonte (2015) as

$$(6.2) \quad F_{\Gamma\text{-G}}(x) = \sum_{j=0}^{\infty} w_j^{\Gamma\text{-G}} \Pi_{a+j}(x).$$

Here,

$$w_j^{\Gamma\text{-G}} = w_j^{\Gamma\text{-G}}(a) = \frac{\varphi_j(a)}{(a+j)},$$

$$\varphi_0(a) = \frac{1}{\Gamma(a)}, \quad \varphi_j(a) = \frac{(a-1)}{\Gamma(a)} \psi_{j-1}(j+a-2), \quad j \geq 1,$$

and

$$\begin{aligned} \psi_{n-1}(x) = \frac{(-1)^{n-1}}{(n+1)!} & \left[H_n^{n-1} - \frac{x+2}{n+2} H_n^{n-2} + \frac{(x+2)(x+3)}{(n+2)(n+3)} H_n^{n-3} - \dots \right. \\ & \left. + (-1)^{n-1} \frac{(x+2)(x+3) \cdots (x+n)}{(n+2)(n+3) \cdots (2n)} H_n^0 \right], \end{aligned}$$

- 1 is the Stirling polynomial, $H_{n+1}^m = (2n+1-m)H_n^m + (n-m+1)H_n^{m-1}$ is a
 2 positive integer, $H_0^0 = 1$, $H_{n+1}^0 = 1 \times 3 \times 5 \times \cdots \times (2n+1)$ and $H_{n+1}^n = 1$.

By inserting (6.2) in Equation (6.1) and via a result for a power series raised to a positive integer (Gradshteyn and Ryzhik, 2000), the expansion for the cdf of the MO- Γ -G distribution reduces to

$$\begin{aligned} F_{\text{MO-}\Gamma\text{-G}}(x) &= \sum_{i=0}^{\infty} w_i^{\text{MO-}\Gamma} G(x)^{(i+1)a} \left[\sum_{j=0}^{\infty} w_j^{\Gamma\text{-G}} G(x)^j \right]^{i+1} \\ &= \sum_{i=0}^{\infty} w_i^{\text{MO-}\Gamma} G(x)^{(i+1)a} \sum_{j=0}^{\infty} c_{i+1,j} G(x)^j = \sum_{i,j=0}^{\infty} d_{i,j} \Pi_{(i+1)a+j}(x), \end{aligned}$$

- 3 where $d_{i,j} = d_{i,j}(a, \theta) = w_i^{\text{MO-}\Gamma} c_{i+1,j}(a)$, $c_{i+1,0}(a) = (w_0^{\Gamma\text{-G}})^{i+1}$ and, for $m \geq 1$,
 4 $c_{i+1,m}(a) = \frac{1}{mw_0^{\Gamma\text{-G}}} \sum_{r=1}^m [r(i+2) - m] w_r^{\Gamma\text{-G}} c_{i+1,m-r}(a)$.

- 5 By differentiating the last equation, the expansion for the MO- Γ -G density
 6 follows as

$$(6.3) \quad f_{\text{MO-}\Gamma\text{-G}}(x) = \sum_{i,j=0}^{\infty} d_{i,j} \pi_{(i+1)a+j}(x).$$

- 7 So, some structural properties of the proposed family can be determined
 8 from the double linear combination (6.3) and those properties of the exp-G dis-
 9 tribution. In most applications, the indices i and j can vary up to five.

6.2. Some quantities

- 10 Hereafter, let $T_{i,j} \sim \text{exp-G}[(i+1)a + j]$. The n th moment of X can be
 11 obtained from (6.3) as

$$\mu'_{n-1}(X) = \sum_{i,j=0}^{\infty} d_{i,j} E(T_{i,j}) = \sum_{i,j=0}^{\infty} [(i+1)a + j - 1] d_{i,j} \tau[n, (i+1)a + j - 1],$$

- 12 where

$$\tau(n, a) = \int_{-\infty}^{\infty} x^n G(x)^a g(x) dx = \int_0^1 Q_G(u)^n u^a du.$$

Expressions for moments of several exponentiated distributions can be found in the papers cited in Tahir and Nadarajah (2015, Table 1). We give just one example from Equation (6.4) by taking the exponential distribution with rate $\lambda > 0$ for the baseline G. It follows easily as

$$\mu'_n = n! \lambda^n \sum_{i,j,m=0}^{\infty} \frac{(-1)^{n+m} [(i+1)a+j] d_{i,j}}{(m+1)^{n+1}} \binom{(i+1)a+j-1}{m}.$$

A general expansion for the moment generating function (MGF) $M(t) = E(e^{tX})$ of X can be expressed from (6.3)

$$(6.5) M(t) = \sum_{i,j=0}^{\infty} d_{i,j} M_{i,j}(t) = \sum_{i,j=0}^{\infty} [(i+1)a+j] d_{i,j} \rho(t, (i+1)a+j-1),$$

where $M_{i,j}(t)$ is the MGF of $Y_{i,j}$ and

$$\rho(t, a) = \int_{-\infty}^{\infty} e^{tx} G(x)^a g(x) dx = \int_0^1 \exp\{t Q_G(u)\} u^a du.$$

The MGFs of many MO- Γ -G distributions can be determined from Equation (6.5). For example, the generating function of the MO- Γ -exponential with parameter λ (if $t < \lambda^{-1}$) is

$$M(t) = \sum_{i,j=0}^{\infty} [(i+1)a+j] d_{i,j} B((i+1)a+j, 1-\lambda t).$$

For empirical purposes, the shape of many distributions can be usefully described by the incomplete moments. These moments play an important role for measuring inequality. For example, the mean deviations and Lorenz and Bonferroni curves depend upon the first incomplete moment of the distribution. The n th incomplete moment of X can be expressed as

$$(6.6) m_n(y) = \int_{-\infty}^y x^n f_X(x) dx = \sum_{i,j=0}^{\infty} [(i+1)a+j] d_{i,j} \int_0^{G(y)} Q_G(u)^n u^{(i+1)a+j-1} du.$$

The definite integral in (6.6) can be evaluated for most baseline G distributions.

7. Conclusions

A new family of distributions called the Marshall and Olkin-Gamma-G family with two shape parameters is introduced. The estimation of the unknown parameters is done via the maximum likelihood method and a simulation study is conducted to verify its adequacy. Additionally, the usefulness of the proposed family is shown empirically by means of two applications to real data.

A. Appendix: Simulation code

1 The script below is used to perform the simulations whose results are given
 2 in Table 2 of Section 4. It is developed a script using the programming language
 3 R to be used in other simulations or even to check the results presented in this
 4 paper.

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