

view_frames Result
Recorded at time: 93.571

odom

Broadcaster: /gazebo
Average rate: 40.207 Hz
Most recent transform: 93.551 (0.020 sec old)
Buffer length: 4.825 sec

ebot_base

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (93.571 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (93.571 sec old)
Buffer length: 0.000 sec

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Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10.213 Hz
Most recent transform: 93.500 (0.071 sec old)
Buffer length: 4.700 sec

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Most recent transform: 93.500 (0.071 sec old)
Buffer length: 4.700 sec

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Most recent transform: 93.500 (0.071 sec old)
Buffer length: 4.700 sec

FUS1

FUS2

FUS3

FUS4

LHUS10

LHUS9

RHUS7

RHUS9

RUS5

RUS6

base_link

camera_link

imu_link

laser

FWL

FWR

RWL

RWR

base

shoulder_link

camera_depth_frame

camera_rgb_frame

upper_arm_link

forearm_link

wrist_1_link

wrist_2_link

wrist_3_link

camera_link2

ce_link

gripper_base_link

tool0

camera_depth_frame2

camera_rgb_frame2

gripper_finger1_knuckle_link

gripper_finger2_knuckle_link

gripper_finger1_inner_knuckle_link

gripper_finger2_inner_knuckle_link

object_66

gripper_finger1_finger_link

gripper_finger2_finger_link

gripper_finger1_finger_tip_link

gripper_finger2_finger_tip_link