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```
In [1]: import cv2
import numpy as np
import matplotlib.pyplot as plt
```

```
In [2]: def processImage(image):
        image = cv2.imread(image)
        image = cv2.cvtColor(src=image, code=cv2.COLOR_BGR2GRAY)
        return image
```

```

In [3]: def convolve2D(image, kernel, padding=0, strides=1):
    # Cross Correlation
    kernel = np.flipud(np.fliplr(kernel))

    # Gather Shapes of Kernel + Image + Padding
    xKernShape = kernel.shape[0]
    yKernShape = kernel.shape[1]
    xImgShape = image.shape[0]
    yImgShape = image.shape[1]

    # Shape of Output Convolution
    xOutput = int(((xImgShape - xKernShape + 2 * padding) / strides) + 1)
    yOutput = int(((yImgShape - yKernShape + 2 * padding) / strides) + 1)
    output = np.zeros((xOutput, yOutput))

    # Apply Equal Padding to All Sides
    if padding != 0:
        imagePadded = np.zeros((image.shape[0] + padding*2, image.shape[1] + padding*2))
        imagePadded[int(padding):int(-1 * padding), int(padding):int(-1 * padding)] = image
        print(imagePadded)
    else:
        imagePadded = image

    # Iterate through image
    for y in range(image.shape[1]):
        # Exit Convolution
        if y > image.shape[1] - yKernShape:
            break
        # Only Convolve if y has gone down by the specified Strides
        if y % strides == 0:
            for x in range(image.shape[0]):
                # Go to next row once kernel is out of bounds
                if x > image.shape[0] - xKernShape:
                    break
                try:
                    # Only Convolve if x has moved by the specified Strides
                    if x % strides == 0:
                        output[x, y] = (kernel * imagePadded[x: x + xKernShape, y: y + yKernShape]).sum()
                except:
                    break

    return output

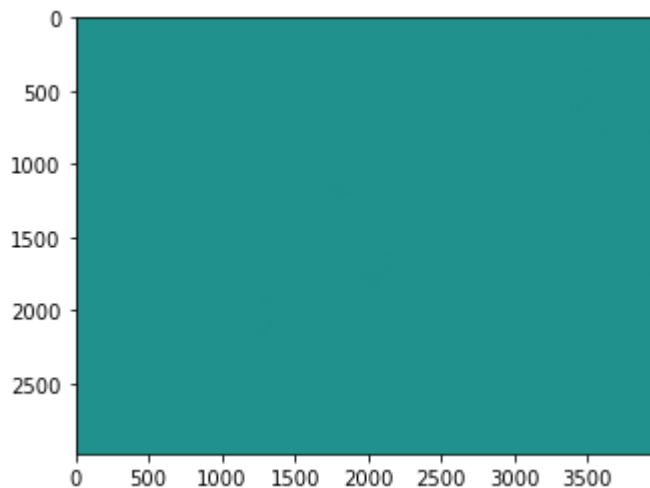
```

```
In [4]: if __name__ == '__main__':
# Grayscale Image
image = processImage('guillaume-baudusseau-2ZMjnR2d3qk-unsplash.jpg')

# Edge Detection Kernel
kernel = np.array([[ -1,  -1,  -1], [ -1,  8,  -1], [ -1,  -1,  -1]])

output = convolve2D(image, kernel, padding=2)
plt.imshow(output)
plt.show()
```

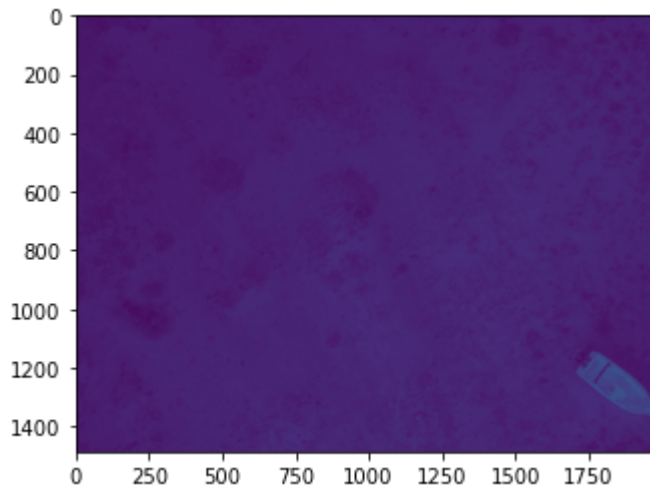
```
[[ 0.  0.  0. ...  0.  0.  0.]
 [ 0.  0.  0. ...  0.  0.  0.]
 [ 0.  0. 69. ... 101.  0.  0.]
 ...
 [ 0.  0. 63. ... 106.  0.  0.]
 [ 0.  0.  0. ...  0.  0.  0.]
 [ 0.  0.  0. ...  0.  0.  0.]]
```



Taking stride as 2 and kernel size as 5*5

```
In [5]: stride=2
filter_size=5
```

```
In [6]: kernel = np.array([[1, 1, 1,1,1], [1, 1, 1,1,1], [1, 1, 1,1,1],[1, 1, 1,1,1], [1,
# Convolve and Save Output
output2 = convolve2D(image, kernel,strides=2)
plt.imshow(output2)
plt.show()
```



```
In [7]: output2
```

```
Out[7]: array([[1637.,    0., 1643., ...,    0., 2235.,    0.],
 [    0.,    0.,    0., ...,    0.,    0.,    0.],
 [1617.,    0., 1637., ...,    0., 2236.,    0.],
 ...,
 [    0.,    0.,    0., ...,    0.,    0.,    0.],
 [1662.,    0., 1550., ...,    0., 1613.,    0.],
 [    0.,    0.,    0., ...,    0.,    0.,    0.]])
```

Taking stride as 1 but making an image padded with 0 padding

```
In [8]: import numpy as np
import pandas as pd
from keras.models import Sequential
from keras.layers.convolutional import Conv2D
import cv2
from matplotlib import pyplot as plt
```

```
In [9]: def processImage(image):

    image = cv2.imread(image)
    image = cv2.cvtColor(src=image, code=cv2.COLOR_BGR2GRAY)
    return image
```

```

In [10]: def convolve2D(image, kernel, padding=0, strides=1):
# Cross Correlation
kernel = np.flipud(np.fliplr(kernel))

# Gather Shapes of Kernel + Image + Padding
xKernShape = kernel.shape[0]
yKernShape = kernel.shape[1]
xImgShape = image.shape[0]
yImgShape = image.shape[1]

# Shape of Output Convolution
xOutput = int(((xImgShape - xKernShape + 2 * padding) / strides) + 1)
yOutput = int(((yImgShape - yKernShape + 2 * padding) / strides) + 1)
output = np.zeros((xOutput, yOutput))

# Apply Equal Padding to All Sides
if padding != 0:
    imagePadded = np.zeros((image.shape[0] + padding*2, image.shape[1] + padding*2))
    imagePadded[int(padding):int(-1 * padding), int(padding):int(-1 * padding)] = image
    print(imagePadded)
else:
    imagePadded = image

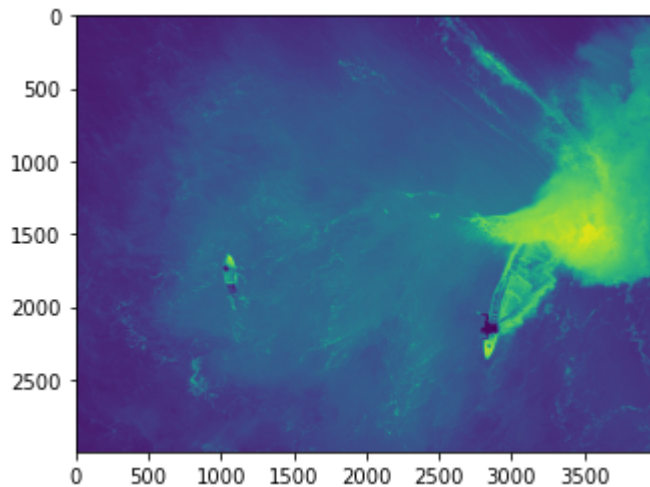
# Iterate through image
for y in range(image.shape[1]):
    # Exit Convolution
    if y > image.shape[1] - yKernShape:
        break
    # Only Convolve if y has gone down by the specified Strides
    if y % strides == 0:
        for x in range(image.shape[0]):
            # Go to next row once kernel is out of bounds
            if x > image.shape[0] - xKernShape:
                break
            try:
                # Only Convolve if x has moved by the specified Strides
                if x % strides == 0:
                    output[x, y] = (kernel * imagePadded[x: x + xKernShape, y: y + yKernShape]).sum()
            except:
                break

return output

```

```
In [11]: image = processImage('michael-olsen-xbRe2QwIi-8-unsplash.jpg')
kernel = np.array([[1, 1, 1], [1, 1, 1], [1, 1, 1]])
output3 = convolve2D(image, kernel, padding=0)
plt.imshow(output3)
```

Out[11]: <matplotlib.image.AxesImage at 0x12a219619a0>



```
In [12]: output3
```

```
Out[12]: array([[180., 170., 161., ..., 495., 487., 481.],
                [182., 174., 165., ..., 494., 488., 482.],
                [173., 169., 162., ..., 491., 488., 484.],
                ...,
                [217., 215., 208., ..., 386., 391., 391.],
                [213., 212., 204., ..., 390., 395., 390.],
                [213., 212., 204., ..., 389., 396., 388.]])
```

Calculating metrics i.e. entropy between original image and filtered image

```
In [13]: import skimage.measure
entropy_original_image = skimage.measure.shannon_entropy(image)
```

```
In [14]: print(entropy_original_image)
```

```
6.9196791409088245
```

```
In [15]: import skimage.measure  
entropy_for_1_stride = skimage.measure.shannon_entropy(output)
```

```
In [16]: print(entropy_for_1_stride)
```

```
6.9588006035582275
```

```
In [17]: import skimage.measure  
entropy_for_2_stride = skimage.measure.shannon_entropy(output2)
```

```
In [18]: print(entropy_for_2_stride)
```

```
3.491078469771006
```

```
In [19]: import skimage.measure  
entropy_for_0_padding = skimage.measure.shannon_entropy(output3)
```

```
In [20]: print(entropy_for_0_padding)
```

```
10.074482698094565
```