trick to method: The Jactorisation lemma

let I(x,t) be a polynomial mt with

coefficients in  $\mathbb{R}[x,\overline{x}]$  and assume J(x,0)=1.  $(\overline{x}=\frac{1}{x})$ 

There exist a unique triple  $(D(t), \Delta(x,t), \overline{\Delta}(\overline{x},t))$  of FPS int satisfying

- $\int (x,t) = \mathcal{D}(t) \cdot \Delta(x,t) \cdot \overline{\Delta}(x,t)$
- · coeffs of D(t) belong to VR
- · " (x) " | [x]
- $\mathcal{D}(0) = \Delta(0,t) = \overline{\Delta}(0,t) = \Delta(s,0) = \overline{\Delta}(s,0) = 1$

Morcoro, these three series are algebraic, and  $\Delta(x)$  is a polink  $(\overline{\Delta}(\overline{x}))$ 

Change sleps:

 $\left[1-t\left(\frac{x}{7}+\frac{y}{x}+xy+\frac{1}{xy}\right)\right]H(x,y,t)=1+t\left(xy+\frac{y}{x}-\frac{x}{7}-\frac{1}{xy}\right)G_{o}(x,t)$   $-U\left(\frac{1}{x},t\right)$ 

Exercise: find of (x,t), compute factorisation

$$G(x,y,t) = 1 + t(x + y + \frac{1}{x} + \frac{1}{y}) G(x,y,t)$$

$$- t + \frac{1}{x} G(0,y,t) - t + \frac{1}{y} G(x,0,t)$$

$$\to K(x,y,t) = xy - t \times G(x,0,t) + ty G(0,y,t)$$

Note that  $K(x_{17,1}t) = 1 - t(x + \frac{1}{x} + y + \frac{1}{y})$  has symmetries  $x = \frac{1}{x}$ ,  $y = \frac{1}{y}$ 

(i) 
$$K(x_{|Y|,E}) = 0 \rightarrow Y_1 = \int_{E}^{1} (x_{|X|}) \sim E \qquad Y_0 = \frac{1}{Y_1} - \frac{1}{E}$$

ideals: 
$$(x, y_1) \rightarrow (\frac{1}{x}, y_1) \rightarrow (\frac{1}{x}, \frac{1}{y_1}) \rightarrow (x_1 y_1) \rightarrow (x_1$$

no powerscies int: not admissible

$$K(x,y_i)=0$$
  $\Rightarrow$   $xy_i=t\times 6(x,o_i+)$   $-ty_i$   $6(o_i,y_i,t)$ 

$$K(\frac{1}{2}, \frac{1}{2}) = 0 \Rightarrow \frac{1}{2} \frac{1}{2} = t = \frac{1}{2} 6(\frac{1}{2}, 0, t) - t = \frac{1}{2} 6(0, \frac{1}{2}, \frac{1}{2})$$

so that 
$$t \times 6(x,0,t) - \frac{1}{x} 6(\frac{1}{x},0,t) = (x-\frac{1}{x}) y_1$$

$$G(x,0,t) = \frac{1}{tx} \left[ \left( x - \frac{1}{x} \right) y_{1} \right]_{x}$$

$$= \frac{1}{t} \frac{1}{2\pi i} \left[ \left( \frac{z - \frac{1}{x}}{z} \right) \frac{dz}{dz} \right]_{z(z-x)}$$

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$$K(x_{1},t) \times G(x_{1},t) = \times Y - t \times G(x_{1},t) - t + G(0,Y,t)$$

$$x \rightarrow \frac{1}{x}$$
:  $K(x_{17},t) \stackrel{!}{\times} y 6(t,y,t) = \frac{1}{x}y - t \stackrel{!}{\times} 6(t,o,t) - ty 6(o,y,t)$ 

$$K(x_{11}) \stackrel{!}{=} 6(\frac{1}{2},\frac{1}{4},t) = \frac{1}{4} - \frac{1}{2}6(\frac{1}{2},\frac{1}{4}) - \frac{1}{4}6(\frac{1}{4},t)$$

$$K(x_{1},t) \left[ x_{1} 6(x_{1},t) - \frac{1}{x_{1}} 6(\frac{1}{x_{1}},t) - x_{1} 6(\frac{1}{x_{1}},t) - x_{2} 6(\frac{1}{x_{1}},t) + \frac{1}{x_{2}} 6(\frac{1}{x_{1}},t) \right]$$

$$= x_{1} - \frac{1}{x_{1}} x_{1} - \frac{1}{x_{2}} = (x - \frac{1}{x_{1}})(x - \frac{1}{x_{2}})$$

so that 
$$G(x_1y_1t) = \frac{1}{xy} \left[ \frac{(x-\frac{1}{2})(y-\frac{1}{4})}{K(x_1y_1t)} \right]_{(x,y)}^{2}$$

$$= \left(\frac{1}{2\pi i}\right)^2 \oint \oint \frac{\left(\frac{z-i}{z}\right)\left(\omega-\frac{i}{\omega}\right)}{k\left(\frac{z}{z},\omega,t\right)} \frac{dz}{2(z-x)} \frac{d\omega}{\omega}$$

exercise: show that

$$G(x, o, t) = \left(\frac{1}{2\pi}\right)^2 \int \int \frac{(z-t)(\omega-\omega)}{(z-\omega)^2} \frac{dz}{z(z-x)} \frac{d\omega}{\omega^2}$$

reduces to the precious result

$$[1-t\left(\frac{1}{x}+\frac{1}{y}+xy\right)] \times y \cdot 6(x_1y_1t) = xy - t \times 6(x_1y_1t)$$

$$-ty \cdot 6(y_1t)$$

$$= xy - R(x) - R(y)$$

Symmetry: 
$$K(x,y,t) = K(\frac{1}{xy},y,t) = K(\frac{1}{xy},x,t) = \dots$$

[xery symmety]  $\begin{pmatrix} (x,y) & (\frac{1}{xy},y) & (\frac{1}{xy},x) \\ (x,\frac{1}{xy}) & (y,\frac{1}{xy}) & (y,x) \end{pmatrix}$ 

$$y^2 - \frac{1}{x} \left( \frac{1}{t} - \frac{1}{x} \right) y + \frac{1}{x} = 0$$

$$\gamma_{\delta\gamma} = \frac{1}{x} \left( \frac{1}{x} - \frac{1}{x} \right), \gamma_{\delta\gamma} = \frac{1}{x}$$

$$Y_{0}(x,t) = t + \frac{1}{x}t^{2} + O(t^{3})$$
,  $Y_{1}(x,t) = \frac{1}{xt} - \frac{1}{x^{2}} - t - \frac{1}{x^{2}}t^{2} + O(t^{3})$ 

in iteration cycle, pick y= Yo(x,t):

$$R(x) + R(Y_0) = xY_0 \sim xt$$

$$R(Y_1) + R(Y_0) = Y_0Y_1 = \frac{1}{x}$$

$$\left[R(Y_1) + R(x) = Y_1x = \frac{1}{y_0} \sim \frac{1}{t} \quad \text{in good}\right]$$

runik:

$$R(\gamma_0) - x \gamma_0 = -R(x)$$

$$R(\gamma_0) - x \gamma_1 = \gamma_0 \gamma_1 - R(\gamma_0) - x \gamma_1$$

$$= \frac{1}{x} + R(x) - x \gamma_0 - x \gamma_1$$

$$= \frac{1}{x} + R(x) - \left(\frac{1}{x} - \frac{1}{x}\right)$$

$$= R(x) + \frac{2}{x} - \frac{1}{x}$$

so that 
$$\frac{R(\gamma_0) - R(\gamma_1)}{\gamma_0 - \gamma_1} - x = \pm x \frac{2R(x) + \frac{2}{x} - \frac{1}{\xi}}{\sqrt{\delta(x, t)}}$$

when  $\delta(x,t)=(1-t\frac{1}{x})^2-4t^2x$ . Use the factorisation lemme to

argue that  $\Gamma(x,t) = \mathcal{D}(t) \Delta(x,t) \overline{\Delta}(\frac{1}{x},t)$ 

Thru rooh 
$$X_0, X_1, X_2$$
:  $D(t) = 4t^2 X_2, \quad \Delta(x_1 t) = 1 - \frac{x_1}{X_2}$ 

$$X_1 \wedge t \quad \times_2 \vee \frac{1}{t^2}$$

$$\overline{\Delta} \left( \frac{1}{x_1} t \right) = \left( 1 - \frac{x_0}{x} \right) \left( 1 - \frac{x_1}{x_2} \right)$$

$$\left[\frac{\overline{\Delta}(\frac{1}{x}, t)}{\overline{\Delta}(\frac{1}{x}, t)}\right] = \frac{2 \times R(x) + 2 - \frac{x}{t}}{\overline{\Delta}(x, t)}$$

extracting the positive part gives

$$-x = \frac{t}{\sqrt{2(x)}} \left[ \frac{2 \times \mathcal{C}(x) + 2 - \frac{x}{t}}{\sqrt{\Delta(x_1 t)'}} - 2 \right]$$

rewriting (exercise) gives

## Theorem

$$G(x,0,t) = \frac{1}{t\times} \left( \frac{1}{2t} - \frac{1}{x} - \left( \frac{1}{w} - \frac{1}{x} \right) \sqrt{1-xw^2} \right)$$

when 
$$W = t(2+W^3)$$
 defines the prior series  $W = W(t)$ 

some further work gives for walls returning to the origin

$$C_{3n} = \frac{4^n}{(nn)(2nn)} {3n \choose n}$$

$$\sim$$
  $\gamma_{0,1}$  satisfy  $\frac{1}{\gamma_0} + \frac{1}{\gamma_1} = \frac{1}{t} \times \sim 3$  -term recurred

iteration: 
$$K(x_n, x_{nr_i}, t) = 0$$
 gives

..., 
$$x_1 = y_0$$
,  $x_0 = x$ ,  $x_1 = y_1$ ,  $x_2 = \dots$  will  $x_n$  given by

$$\frac{1}{x_n} = \alpha \lambda^n + \beta \lambda^m, \quad \lambda + \frac{1}{\lambda} = \frac{1}{\lambda}, \quad \alpha + \beta = \frac{1}{\lambda}, \quad \alpha + \beta = \frac{1}{\lambda}$$

envise: check that 
$$x_n = xt^n + O(t^{nx_1})$$

$$K(x_{n_1}x_{nn_1}t) = 0 \implies t x_n^2 G(x_{n_1}o_1t) = x_n x_{nx_1} - t x_{nx_1}^2 G(x_{nx_1}o_1t)$$

leads to 
$$G(x,0,t) = \frac{1}{x^2t} \sum_{h=0}^{\infty} (-1)^h \times_h \times_{hx_1}$$

$$6(1,1,t) = \frac{1-2t6(1,0,t)}{1-3t}$$
exercise:  $c_n \sim (1-2\sum_{k=1}^{\infty} \frac{c_k}{f_{kn}f_{kn}}) 3^n$ 

Note: 6(x, y, t) is not differentiably finite (poles accumulate)