scanpy.tl.diffmap

scanpy.tl.diffmap(adata, n_comps=15, neighbors_key=None, random_state=0, copy=False)

Diffusion Maps [Coifman05] [Haghverdi15] [Wolf18].

Diffusion maps [Coifman05] has been proposed for visualizing single-cell data by [Haghverdi15]. The tool uses the adapted Gaussian kernel suggested by [Haghverdi16] in the implementation of [Wolf18].

The width ("sigma") of the connectivity kernel is implicitly determined by the number of neighbors used to compute the single-cell graph in <code>neighbors()</code>. To reproduce the original implementation using a Gaussian kernel, use <code>method=='gauss'</code> in <code>neighbors()</code>. To use an exponential kernel, use the default <code>method=='umap'</code>. Differences between these options shouldn't usually be dramatic.

Parameters:

adata: AnnData

Annotated data matrix.

n_comps: int (default: 15)

The number of dimensions of the representation.

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neighbors_key : Optional [ str ] (default: None )
```

If not specified, diffmap looks .uns['neighbors'] for neighbors settings and .obsp['connectivities'], .obsp['distances'] for connectivities and distances respectively (default storage places for pp.neighbors). If specified, diffmap looks .uns[neighbors_key] for neighbors settings and .obsp[.uns[neighbors_key] ['connectivities_key']], .obsp[.uns[neighbors_key]['distances_key']] for connectivities and distances respectively.

random_state : Union [None , int , RandomState] (default: 0)

A numpy random seed

copy: bool (default: False)

Return a copy instead of writing to adata.

Returns:

: Depending on copy, returns or updates adata with the following fields.

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X_diffmap : numpy.ndarray ( adata.obsm )
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Diffusion map representation of data, which is the right eigen basis of the transition matrix with eigenvectors as columns.

```
diffmap_evals : numpy.ndarray ( adata.uns )
```

Array of size (number of eigen vectors). Eigenvalues of transition matrix.

Notes

The O-th column in <code>adata.obsm["x_diffmap"]</code> is the steady-state solution, which is non-informative in diffusion maps. Therefore, the first diffusion component is at index 1, e.g. <code>adata.obsm["x_diffmap"][:,1]</code>