

Model 8530/31/32/33/34

DUSTTRAK™ II and DRX Aerosol Monitors

Communication Manual

P/N 6002481, Revision A
January 2009



TRUST. SCIENCE. INNOVATION.

Copyright ©

TSI Incorporated / 2009 / All rights reserved.

Address

TSI Incorporated / 500 Cardigan Road / Shoreview, MN 55126 / USA

Fax No.

(651) 490-3824

Limitation of Warranty and Liability (effective July 2000)

Seller warrants the goods sold hereunder, under normal use and service as described in the operator's manual, shall be free from defects in workmanship and material for twenty-four (24) months, or the length of time specified in the operator's manual, from the date of shipment to the customer. This warranty period is inclusive of any statutory warranty. This limited warranty is subject to the following exclusions:

- a. Hot-wire or hot-film sensors used with research anemometers, and certain other components when indicated in specifications, are warranted for 90 days from the date of shipment.
- b. Parts repaired or replaced as a result of repair services are warranted to be free from defects in workmanship and material, under normal use, for 90 days from the date of shipment.
- c. Seller does not provide any warranty on finished goods manufactured by others or on any fuses, batteries or other consumable materials. Only the original manufacturer's warranty applies.
- d. Unless specifically authorized in a separate writing by Seller, Seller makes no warranty with respect to, and shall have no liability in connection with, goods which are incorporated into other products or equipment, or which are modified by any person other than Seller.

The foregoing is IN LIEU OF all other warranties and is subject to the LIMITATIONS stated herein. **NO OTHER EXPRESS OR IMPLIED WARRANTY OF FITNESS FOR PARTICULAR PURPOSE OR MERCHANTABILITY IS MADE.**

TO THE EXTENT PERMITTED BY LAW, THE EXCLUSIVE REMEDY OF THE USER OR BUYER, AND THE LIMIT OF SELLER'S LIABILITY FOR ANY AND ALL LOSSES, INJURIES, OR DAMAGES CONCERNING THE GOODS (INCLUDING CLAIMS BASED ON CONTRACT, NEGLIGENCE, TORT, STRICT LIABILITY OR OTHERWISE) SHALL BE THE RETURN OF GOODS TO SELLER AND THE REFUND OF THE PURCHASE PRICE, OR, AT THE OPTION OF SELLER, THE REPAIR OR REPLACEMENT OF THE GOODS. IN NO EVENT SHALL SELLER BE LIABLE FOR ANY SPECIAL, CONSEQUENTIAL OR INCIDENTAL DAMAGES. SELLER SHALL NOT BE RESPONSIBLE FOR INSTALLATION, DISMANTLING OR REINSTALLATION COSTS OR CHARGES. No Action, regardless of form, may be brought against Seller more than 12 months after a cause of action has accrued. The goods returned under warranty to Seller's factory shall be at Buyer's risk of loss, and will be returned, if at all, at Seller's risk of loss.

Buyer and all users are deemed to have accepted this LIMITATION OF WARRANTY AND LIABILITY, which contains the complete and exclusive limited warranty of Seller. This LIMITATION OF WARRANTY AND LIABILITY may not be amended, modified or its terms waived, except by writing signed by an Officer of Seller.

Service Policy

Knowing that inoperative or defective instruments are as detrimental to TSI as they are to our customers, our service policy is designed to give prompt attention to any problems. If any malfunction is discovered, please contact your nearest sales office or representative, or call TSI at (800) 874-2811 (USA) or (001 651) 490-2811 (International).

CONTENTS

CHAPTER 1 INSTRUMENT COMMUNICATION METHODS	1
Connecting to the Instrument	1
NIDS Communication Method.....	1
RS-232 Serial Communication Method	1
RS-232 Method Supports TSI Radio Accessory	1
CHAPTER 2 INSTRUMENT COMMAND SET	3
Read the Model of the Instrument	3
Read the Serial Number of the Instrument.....	3
Read the Firmware Version of the Instrument	4
Read the Current User Polling Status of the Instrument.....	4
Start the Instrument Measurement.....	4
Stop the Instrument Measurement.....	5
Update INSTRUMENT RAM	5
Read the Current Measurements of the Instrument.....	6
Read the Current Measurements and Statistics of the Instrument	6
Read the Fault Messages of the Instrument	8
Read the State of Data Logging	10
Read Instrument Logging Mode	11
Write Instrument Logging Mode	12
Read the Current Instrument Logging Mode.....	14
Set the Current Instrument Logging Mode	14
Read Instrument Alarm Settings	15
Set Instrument Alarm Settings.....	16
Read Instrument Analog Output Settings.....	17
Set Instrument Analog Output Settings.....	18
Read the Current Instrument User Calibration.....	19
Set the Current Instrument User Calibration	20
Read Instrument User Calibration Data	20
Set Instrument User Calibration Data	21
Read the Instrument Date And Time.....	22
Set the Current Instrument User Calibration	22
Read the Filter Change Date.....	23
Read the Calibration Date:	23

Chapter 1

Instrument Communication Methods

Desktop Basic Models	8530, 8531
Handheld Basic Model	8532
Desktop DRX Model	8533
Handheld DRX Model	8534

Connecting to the Instrument

USB and Ethernet instrument connections use the NDIS communication method.

Remote radio communications use the RS-232 serial communication method.

NIDS Communication Method

This method communicates with the DUSTTRAK™ II and DUSTTRAK™ DRX instruments via USB and Ethernet connections. This method uses windows sockets.

RS-232 Serial Communication Method

This method communicates with the DUSTTRAK™ II and DUSTTRAK™ DRX instruments via host to remote radio communication.

RS-232 Method Supports TSI Radio Accessory

801820	920 MHz modem with antenna mount kit for enclosure
801821	920 MHz modem
801825	2.4 GHz modem with antenna mount kit for enclosure
801826	2.4 GHz modem

The serial settings are as follows:

Baud Rate:	9600
Flow Control:	NONE
Data Bits:	8
Parity:	NONE
Stop Bits:	1

Chapter 2

Instrument Command Set

Read the Model of the Instrument

Command: **RDMN**

Return value: a string containing the model of the instrument.

Code Example:

```
// "RDMN" is the DustTrak command to read the model of the instrument.  
// The command must be followed by a CR.  
iRet = m_pSocket->Send( "RDMN\r", 5);  
  
// Reply  
// buff = a string containing the model of the instrument (i.e. 8530).  
iRet = m_pSocket->Receive( buff, PACKET_SIZE, 0);
```

Read the Serial Number of the Instrument

Command: **RDSN**

Return value: a string containing the serial number of the instrument.

Code Example:

```
// "RDSN" is the DustTrak command to read the serial number of the instrument.  
// The command must be followed by a CR.  
iRet = m_pSocket->Send( "RDSN\r", 5);  
  
// The returned value is a string containing the serial number of the  
// instrument (i.e. 8530083001).  
iRet = m_pSocket->Receive( buff, PACKET_SIZE, 0);
```

Read the Firmware Version of the Instrument

Command: **RDBS**

Return value: a string containing the firmware version of the instrument.

Code Example:

```
// "RDBS" is the DustTrak command to read the firmware version of the
// instrument.
// The command must be followed by a CR.
m_pSocket->Send( "RDBS\r", 5);

// The returned value is a string containing the firmware version of
// the instrument (i.e. 1.0).
m_pSocket->Receive( buff, PACKET_SIZE, 0);
```

Read the Current User Polling Status of the Instrument

Command: **MSTATUS**

Return value: a string containing the user polling status of the instrument.

Code Example:

```
// "MSTATUS" is the DustTrak command to read the current user polling
// status of the instrument.
// The command must be followed by a CR.
iRet = m_pSocket->Send( "MSTATUS\r", 8);

// The returned value is a string containing the user polling status of
// the instrument (i.e. Idle, Waiting, Running, etc.).
iRet = m_pSocket->Receive( buff, PACKET_SIZE, 0);
```

Start the Instrument Measurement

Command: **MSTART**

Return value: a response OK indicating that the instrument started, or FAIL indicating an error starting the measurement.

Code Example:

```
// "MSTART" is the DustTrak command to start the instrument measurement.
// The command must be followed by a CR.
iRet = m_pSocket->Send( "MSTART\r", 7);

// The returned value is a string containing status
// of the command (i.e. OK or FAIL).
iRet = m_pSocket->Receive( buff, PACKET_SIZE, 0);
```

Stop the Instrument Measurement

Command: **MSTOP**

Return value: a string response OK indicating that the instrument started, or FAIL indicating an error starting the measurement.

Code Example:

```
// "MSTOP" is the DustTrak command to stop the instrument measurement.  
// The command must be followed by a CR.  
iRet = m_pSocket->Send( "MSTOP\r", 6);  
  
// The returned value is a string containing status  
// of the command (i.e. OK or FAIL).  
iRet = m_pSocket->Receive( buff, PACKET_SIZE, 0);
```

Update INSTRUMENT RAM

Command: **MUPDATE**

Return value: a string response OK indicating that the instrument RAM was updated, or FAIL indicating an error during the RAM update.

Code Example:

```
// "MUPDATE" is the DustTrak command to update the instrument RAM.  
// The command must be followed by a CR.  
iRet = m_pSocket->Send( "MUPDATE\r", 8);  
  
// The returned value is a string containing status  
// of the command (i.e. OK or FAIL).  
iRet = m_pSocket->Receive( buff, PACKET_SIZE, 0);
```

Read the Current Measurements of the Instrument

Command: **RMMEAS**

Return value: a comma separated string containing the following data format based on the instrument model.

All Basic Models:

Current second of test, Aerosol measurement,

All DRX Models:

Current second of test, PM₁ channel measurement, PM_{2.5} channel measurement, PM₄ (*RESP*) channel measurement, PM₁₀ channel measurement, Total channel measurement,

Code Example:

```
// "RMMEAS" is the DustTrak command to read the current measurements
//   of the instrument.
// The command must be followed by a CR.
iRet = m_pSocket->Send( "RMMEAS\r", 7);

iRet = m_pSocket->Receive( buff, PACKET_SIZE, 0);
// DRX Reply
// buff = "10,0.023,0.024,0.123,0.156,0.179,"
// 10 = Current second of the sample time
// 0.023 = PM1 measurement
// 0.024 = PM2.5 measurement
// 0.123 = Resp (PM4) measurement
// 0.156 = PM10 measurement
// 0.179 = Total measurement
// All measurements in mg/m3

// DTII Reply
// buff = "10,0.024,"
// 10 = Current second of the sample time
// 0.024 = Mass measurement in mg/m3
```

Read the Current Measurements and Statistics of the Instrument

Command: **RMMEASSTATS**

Return value: a comma separated string containing the following data format based on the instrument model.

All Basic Models:

Current second of test, Aerosol measurement, Aerosol minimum, Aerosol maximum, Aerosol average, Aerosol TWA (*time weighted average*),

All DRX Models:

Current second of test, PM₁ channel measurement, PM₁ channel minimum, PM₁ channel maximum, PM₁ channel average, PM₁ channel TWA (*time weighted average*), PM_{2.5} channel measurement, PM_{2.5} channel minimum, PM_{2.5} channel maximum, PM_{2.5} channel average, PM_{2.5} channel TWA (*time weighted average*), PM₄ (RESP) channel measurement, PM₄ (RESP) channel minimum, PM₄ (RESP) channel maximum, PM₄ (RESP) channel average, PM₄ (RESP) channel TWA (*time weighted average*), PM₁₀ channel measurement, PM₁₀ channel minimum, PM₁₀ channel maximum, PM₁₀ channel average, PM₁₀ channel TWA (*time weighted average*), Total channel measurement, Total channel minimum, Total channel maximum, Total channel average, Total channel TWA (*time weighted average*),

Code Example:

```
// "RMMEASSTATS" is the DustTrak command to read the current
// measurements of the instrument.
// The command must be followed by a CR.
iRet = m_pSocket->Send( "RMMEASSTATS\r", 12);

iRet = m_pSocket->Receive( buff, PACKET_SIZE, 0);
// DRX Reply
// buff = "10,0.023,0.012,0.028,0.022,0.000,
//        0.024,0.016,0.027,0.025,0.000,
//        0.123,0.120,0.153,0.145,0.000,
//        0.156,0.125,0.187,0.166,0.000,
//        0.179,0.120,0.190,0.180,0.000,"
// 10 = Current second of the sample time
// 0.023 = PM1 current measurement
// 0.012 = PM1 Minimum measurement
// 0.028 = PM1 Maximum measurement
// 0.022 = PM1 Avg calculation
// 0.000 = PM1 TWA calculation
// 0.024 = PM2.5 measurement
// 0.016 = PM2.5 Minimum measurement
// 0.027 = PM2.5 Maximum measurement
// 0.025 = PM2.5 Avg calculation
// 0.000 = PM2.5 TWA calculation
// 0.123 = Resp (PM4) measurement
// 0.120 = Resp (PM4) Minimum measurement
// 0.153 = Resp (PM4) Maximum measurement
// 0.145 = Resp (PM4) Avg calculation
// 0.000 = Resp (PM4) TWA calculation
// 0.156 = PM10 measurement
// 0.125 = PM10 Minimum measurement
// 0.187 = PM10 Maximum measurement
// 0.166 = PM10 Avg calculation
// 0.000 = PM10 TWA calculation
// 0.179 = Total measurement
// 0.120 = Total Minimum measurement
```

```
// 0.190 = Total Maximum measurement
// 0.180 = Total Avg calculation
// 0.000 = Total TWA calculation
// All measurements in mg/m3

// DTII Reply
// buff = "10,0.179,0.120,0.190,0.180,0.000,"
// 10 = Current second of the sample time
// 0.179 = Mass measurement
// 0.120 = Mass Minimum measurement
// 0.190 = Mass Maximum measurement
// 0.180 = Mass Avg calculation
// 0.000 = Mass TWA calculation
// All measurements in mg/m3
```

Read the Fault Messages of the Instrument

Command: **RMMESSAGES**

Return value: a comma separated string containing the following integer data format based on the instrument model.

Basic Desktop Model:

System Error, Laser Error, Flow Error, Flow Blocked, Max Concentration Total, STEL Alarmed, Filter Concentration Error, Battery Installed , Battery Charging, Battery Percentage available, Battery Low Error, Memory Percentage available, Memory Low Error,

Basic Handheld Model:

System Error, Laser Error, Flow Error, Flow Blocked, Max Concentration Total, Filter Concentration Error, Battery Installed , Battery Charging, Battery Percentage available, Battery Low Error, Memory Percentage available, Memory Low Error,

DRX Desktop Model:

System Error, Laser Error, Flow Error, Flow Blocked, Max Concentration PM₁, Max Concentration PM_{2.5}, Max Concentration PM₄ (RESP), Max Concentration PM₁₀, Max Concentration Total, STEL Alarmed, Filter Concentration Error, Battery Installed , Battery Charging, Battery Percentage available, Battery Low Error, Memory Percentage available, Memory Low Error,

DRX Handheld Model:

System Error, Laser Error, Flow Error, Flow Blocked, Max Concentration PM₁, Max Concentration PM_{2.5}, Max Concentration PM₄ (RESP), Max Concentration PM₁₀, Max Concentration Total, Filter Concentration Error, Battery Installed , Battery Charging, Battery Percentage available, Battery Low Error, Memory Percentage available, Memory Low Error,

Code Example:

```
// "RMMEASSAGES" is the DustTrak command to read the fault messages
// of the instrument.
// The command must be followed by a CR.
iRet = m_pSocket->Send( "RMMESSAGES\r", 11);

iRet = m_pSocket->Receive( buff, PACKET_SIZE, 0);
// DRX Desktop Reply
// buff = "0,1,1,0,1,0,1,0,1,0,0,1,0,80,0,90,0,"
// 0 = No System Error
// 1 = Laser Error
// 1 = Flow Error
// 0 = No Flow Blocked error
// 1 = Maximum Concentration PM1
// 0 = No Maximum Concentration PM2.5
// 1 = Maximum Concentration Resp
// 0 = No Maximum Concentration PM10
// 1 = Maximum Concentration Total
// 0 = No STEL Alarmed
// 0 = Filter Concentration error
// 1 = Battery Installed
// 0 = Battery Not Charging
// 80 = Battery Percentage Available
// 0 = No Battery Low error
// 90 = Memory Percentage Available
// 0 = No Memory Low error

// DRX Handheld Reply
// buff = "0,1,1,0,1,0,1,0,1,0,1,0,80,0,90,0,"
// 0 = No System Error
// 1 = Laser Error
// 1 = Flow Error
// 0 = No Flow Blocked error
// 1 = Maximum Concentration PM1
// 0 = No Maximum Concentration PM2.5
// 1 = Maximum Concentration Resp
// 0 = No Maximum Concentration PM10
// 1 = Maximum Concentration Total
// 0 = Filter Concentration error
// 1 = Battery Installed
// 0 = Battery Not Charging
// 80 = Battery Percentage Available
// 0 = No Battery Low error
// 90 = Memory Percentage Available
// 0 = No Memory Low error

// DTII Desktop Reply
// buff = "0,1,1,0,1,0,0,1,0,80,0,90,0,"
// 0 = No System Error
// 1 = Laser Error
```

```
// 1 = Flow Error
// 0 = No Flow Blocked error
// 1 = Maximum Concentration
// 0 = No STEL Alarmed
// 0 = Filter Concentration error
// 1 = Battery Installed
// 0 = Battery Not Charging
// 80 = Battery Percentage Available
// 0 = No Battery Low error
// 90 = Memory Percentage Available
// 0 = No Memory Low error

// DTII Handheld Reply
// buff = "0,1,1,0,1,0,0,1,0,80,0,90,0,"
// 0 = No System Error
// 1 = Laser Error
// 1 = Flow Error
// 0 = No Flow Blocked error
// 1 = Maximum Concentration
// 0 = Filter Concentration error
// 1 = Battery Installed
// 0 = Battery Not Charging
// 80 = Battery Percentage Available
// 0 = No Battery Low error
// 90 = Memory Percentage Available
// 0 = No Memory Low error
```

Read the State of Data Logging

Command: **RMLOGINFO**

Return value: a comma separated string containing the following data format.

Log Name, Log Error, Total Time, Time Elapsed, Time Remaining, Current Test, Total Tests,

Value formats:

Log Name:	String; Logging test name
Log Error:	Integer; indicates logging error
Total Time:	Integer; in seconds
Time Elapsed:	Integer; in seconds
Time Remaining:	Integer; in seconds
Current Test:	Integer; the number of the test that is running
Total Tests:	Integer; the total number of tests being executed.

The following logging error corresponds to the following integers:

OK:	0
Number of tests is greater than max allowed:	1
Start Time for test has elapsed:	2
Number of data points is greater than max allowed:	3
Logging Interval is to short:	4

Code Example:

```
// "RMLOGINFO" is the DustTrak command to read the state of data logging.
// The command must be followed by a CR.
iRet = m_pSocket->Send( "RMLOGINFO\r", 10);

iRet = m_pSocket->Receive( buff, PACKET_SIZE, 0);
// Reply
// buff = "LOG MODE 1_001,0,60,50,10,2,3"
// LOG MODE 1_001 = Log Mode Name and current run number
// 0 = Log Error
// 60 = Total Time in seconds
// 50 = Time Elapsed
// 10 = Time Remaining
// 2 = Current Test
// 3 = Total Tests
```

Read Instrument Logging Mode

Command: **RMODELOG<<#>>**

is a value 0-6 corresponding to the logging program number.

(0 = Survey, 1 = Manual, 2-6 = Program 1-5)

Return value: a comma separated string containing the following data format.

Start Time, Start Date, Interval, Test Length, Number of Test, Time Between Tests, Time Constant, Use Start Time, Use Start Date, Auto Zero Interval, Auto Zero Enable, Program Name

Return value formats:

Start Time: Hour:Minute:Second

Start Date: Month/Day/Year

Interval: Minute:Second

Test Length: Day:Hour:Minute

Number of Test: Integer

Time Between Tests: Day:Hour:Minute

Time Constant: Integer

Use Start Time: Integer; 1 to use the start time, 0 to not use the start time

Use Start Date	Integer; 1 to use the start date, 0 to not use the start date
Auto Zero Interval	Hour:Minute
Auto Zero Enabled	Integer; 1 enabled, 0 disabled
Program Name	char [12]

Code Example:

```
// "RMODELOG#" is the DustTrak command to read an instrument logging
// mode.
// The command must be followed by a CR.
// Command
// buff = "RMODELOG2"
// 2 = Log Mode index
iRet = m_pSocket->Send( "RMODELOG2\r", 10);

iRet = m_pSocket->Receive( buff, PACKET_SIZE, 0);
// Reply
// buff = "12:15:0,09/30/2008,0:1,0:2:0,3,0:0:1,5,0,0,0:15,0,LOG MODE 1"
// 12:15:0 = Start Time
// 09/30/2008 = Start Date
// 0:1 = Interval
// 0:2:0 = Test Length
// 3 = Number of Tests
// 0:0:1 = Time Between Tests
// 5 = Time Constant
// 0 = Use Start Time
// 0 = Use Start Date
// 0:15 = Auto Zero Interval (unused on a Handheld model)
// 0 = Auto Zero Enable (unused on a handheld model)
// LOG MODE 1 = Log Mode Name
```

Write Instrument Logging Mode

Command: **WMODELOG<<#>> <<Start Time, Start Date, Interval, Test Length, Number of test, Time Between tests, Time Constant, Use Start Time, Use Start Date, Auto Zero Interval, Auto Zero Enable, Test Name>>**

Where # is a value 0–6 corresponding to the logging program number.
(0 = Survey, 1 = Manual, 2-6 = Program 1–5)

Value formats:

Start Time:	Hour:Minute:Second
Start Date:	Month/Day/Year
Interval:	Minute:Second
Test Length:	Day:Hour:Minute
Number of Test:	Integer
Time Between Tests:	Day:Hour:Minute

Time Constant	Integer
Use Start Time	Integer; 1 to use the start time, 0 to not use the start time
Use Start Date	Integer; 1 to use the start date, 0 to not use the start date
Auto Zero Interval	Hour:Minute
Auto Zero Enabled	Integer; 1 enabled, 0 disabled
Program Name	char[12]
Return value:	a string response OK indicating that the logging program was written to the instrument, or FAIL indicating an error during the write of the logging program.

Note: *This command requires the MUPDATE command to be sent to update the instrument RAM.*

Survey Mode: Only Time Constant will change

Manual Mode: Only Interval, Test Length, and Time Constant will change

Code Example:

```
// "WMODELOG#" is the DustTrak command to write the instrument logging
// mode.
// The command must be followed by a CR.
// Command
// buff= "WMODELOG2 12:15:0,09/30/2008,0:1,0:2:0,3,0:0:1,5,0,0,0:15,0,LOG
MODE 1"
// 2 = Log Mode index (2 is the first log mode)
// 12:15:0 = Start Time
// 09/30/2008 = Start Date
// 0:1 = Interval
// 0:2:0 = Test Length
// 3 = Number of Tests
// 0:0:1 = Time Between Tests
// 5 = Time Constant
// 0 = Use Start Time
// 0 = Use Start Date
// 0:15 = Auto Zero Interval (unused on a Handheld model)
// 0 = Auto Zero Enable (unused on a handheld model)
// LOG MODE 1 = Log Mode Name
iRet = m_pSocket->Send( "WMODELOG2
12:15:0,09/30/2008,0:1,0:2:0,3,0:0:1,5,0,0,0:15,0,LOG MODE 1\r", 71);

// The returned value is a string containing status
// of the command (i.e. OK or FAIL).
iRet = m_pSocket->Receive( buff, PACKET_SIZE, 0);
```

Read the Current Instrument Logging Mode

Command: **RMODECURLOG**

Return value: an integer that corresponds to a logging program.

The following logging program corresponds to the following integers:

SURVEY:	0
MANUAL:	1
PROGRAM_1:	2
PROGRAM_2:	3
PROGRAM_3:	4
PROGRAM_4:	5
PROGRAM_5:	6

Code Example:

```
// "RMODECURLOG" is the DustTrak command to read the current instrument
// logging mode.
// The command must be followed by a CR.
iRet = m_pSocket->Send( "RMODECURLOG\r", 12);

//Reply
//buff = "4"
//Instrument currently in Program log #3
iRet = m_pSocket->Receive( buff, PACKET_SIZE, 0);
```

Set the Current Instrument Logging Mode

Command: **WMODECURLOG<<#>>**

Where: # is a value 0–6 corresponding to the logging program number.

The following logging program corresponds to the following integers:

SURVEY:	0
MANUAL:	1
PROGRAM_1:	2
PROGRAM_2:	3
PROGRAM_3:	4
PROGRAM_4:	5
PROGRAM_5:	6

Return value: a string response OK indicating that the logging program was set, or FAIL indicating an error during the setting of the logging program.

Note: *This command requires the MUPDATE command to be sent to update the instrument RAM.*

Code Example:

```
// "WMODECURLOG#" is the DustTrak command to write the current
// instrument logging mode.
// The command must be followed by a CR.

// Command
// buff = "WMODECURLOG"
// 0 = Log Mode index (0 is the SURVEY mode)
iRet = m_pSocket->Send( "WMODECURLOG\r", 13);

// The returned value is a string containing status
// of the command (i.e. OK or FAIL).
iRet = m_pSocket->Receive( buff, PACKET_SIZE, 0);
```

Read Instrument Alarm Settings

Command: **RMODEALARM**<<#>>
is a value 0–4 corresponding to the channel of the instrument.
The channel number is only necessary with a DUSTTRAK™ DRX model.

Return value: a comma separated string containing the following data format.

Alarm State, Alarm Value, STEL Alarm State

Return value formats:

Alarm State:	Integer; see table below
Alarm Value:	Float; value of measurement when it is to alarm
STEL Alarm State:	Integer; 1 enabled, 0 disabled

The following alarm settings correspond to the following integers:

Off	0
Audible	1
Visible	2
Audible and Visible	3
Relay	4
Audible and Relay	5
Visible and Relay	6
Audible, Visible and Relay	7

All DRX Models:

The following channels corresponds to the following integer

PM ₁	0
PM _{2.5}	1
PM ₄ (RESP)	2
PM ₁₀	3
TOTAL	4

Code Example:

```
// "RMODEALARM#" is the DustTrak command to read the instruments alarm
// settings.
// The command must be followed by a CR.
// Command
// buff= "RMODEALARM0"
// 0 = Measurement (DRX only)
iRet = m_pSocket->Send( "RMODEALARM0\r", 11);

iRet = m_pSocket->Receive( buff, PACKET_SIZE, 0);
// Reply
// buff= "3,10.0,0"
// 3 = Alarm State
// 10.0 = Alarm Value
// 0 = STEL Alarm State (Desktop models only)
```

Set Instrument Alarm Settings

Command: **WMODEALARM<<#>> <<Alarm setting, Alarm Value, STEL Alarm state>>**
is a value 0-4 corresponding to the channel of the instrument.
The channel number is only necessary with a DUSTTRAK™ DRX model.

Value formats:

Alarm State: Integer; see table below
Alarm Value: Float; value of measurement when it is to alarm
STEL Alarm State: Integer; 1 enabled, 0 disabled

The following alarm settings correspond to the following integers:

Off	0
Audible	1
Visible	2
Audible and Visible	3
Relay	4
Audible and Relay	5
Visible and Relay	6
Audible, Visible and Relay	7

All DRX Models:

The following channels corresponds to the following integer

PM ₁	0
PM _{2,5}	1
PM ₄ (RESP)	2
PM ₁₀	3
TOTAL	4

Return value: a string response OK indicating that the alarm was set, or FAIL indicating an error during the setting of the alarm.

Note: *An alarm setting is active on a single channel, for the DRX Models, which is the last channel to be set. The handheld units do not support this alarm function.*

Also, this command requires the MUPDATE command to be sent to update the instrument RAM.

Code Example:

```
// "WMODEALARM#" is the DustTrak command to write the instruments alarm
// settings.
// The command must be followed by a CR.
// Command
// buff = "WMODEALARM0 3,10.0,0"
// 0 = Measurement (DRX only)
// 3 = Alarm State
// 10.0 = Alarm Value
// 0 = STEL Alarm State (Desktop models only)
iRet = m_pSocket->Send( "WMODEALARM 3,10.0,0\r", 20);

// The returned value is a string containing status
// of the command (i.e. OK or FAIL).
iRet = m_pSocket->Receive( buff, PACKET_SIZE, 0);
```

Read Instrument Analog Output Settings

Command: **RMODEANALOG**

Return value: comma separated string containing the following data format.

Desktop Basic Models:

Analog output state, Minimum output range value, Maximum output range value,

Desktop DRX Models:

Analog output state, Analog output measurement, Minimum output range value, Maximum output range value,

The following analog output states correspond to the following values:

OFF	0
Voltage	1
Current	2

The following channels correspond to the following analog output measurement:

PM ₁	0
PM _{2.5}	1
PM ₄ (RESP)	2
PM ₁₀	3
TOTAL	4

Code Example:

```
// "RMODEANALOG" is the DustTrak command to read the instruments analog
// out settings.
// The command must be followed by a CR.
iRet = m_pSocket->Send( "RMODEANALOG\r", 12);

iRet = m_pSocket->Receive( buff, PACKET_SIZE, 0);
// DRX Reply
// buff = "2,1,0.000,150.0"
// 2   = Analog Out State
// 1   = Analog Out Measurement
// 0.000 = Lower Limit
// 150.0 = Upper Limit

// DTII Reply
// buff = "2,0.000,150.0"
// 2   = Analog Out State
// 0.000 = Lower Limit
// 150.0 = Upper Limit
```

Set Instrument Analog Output Settings

Command: **WMODEANALOG << Analog output state, Analog output measurement (*Desktop ONLY*), Minimum output range value, Maximum output range value >>**

Value formats:

Analog output state:	integer
Analog output measurement:	integer
Minimum output range value:	float
Maximum output range value:	float

The following analog output states correspond to the following values:

OFF	0
Voltage	1
Current	2

The following channels correspond to the following analog output measurement:

PM ₁	0
PM _{2,5}	1
PM ₄ (RESP)	2
PM ₁₀	3
TOTAL	4

Return value: a string response OK indicating that the instrument analog output was set, or FAIL indicating an error during the setting of the analog output.

Note: This command requires the MUPDATE command to be sent to update the instrument RAM.

Code Example:

```
// "WMODEANALOG" is the DustTrak command to write the analog out settings.
```

```
// The command must be followed by a CR.
```

```
// DRX Command
```

```
// buff = "WMODEANALOG 2,1,0.000,150.0"
```

```
// 2 = Analog Out State
```

```
// 1 = Analog Out Measurement
```

```
// 0.000 = Lower Limit
```

```
// 150.0 = Upper Limit
```

```
// DTII Command
```

```
// buff = "2,0.000,150.0"
```

```
// 2 = Analog Out State
```

```
// 0.000 = Lower Limit
```

```
// 150.0 = Upper Limit
```

```
iRet = m_pSocket->Send( "WMODEANALOG 2,0.000,150.0\r", 26);
```

```
// The returned value is a string containing status
```

```
// of the command (i.e. OK or FAIL).
```

```
iRet = m_pSocket->Receive( buff, PACKET_SIZE, 0);
```

Read the Current Instrument User Calibration

Command: **RMODECURUSERCAL**

Return value: an integer 0 – 9 that corresponds to a user calibration, 10 corresponds to factory calibration.

Code Example:

```
// "RMODECURUSERCAL" is the DustTrak command to read the current instrument user calibration.
```

```
// The command must be followed by a CR.
```

```
iRet = m_pSocket->Send( "RMODECURUSERCAL\r", 16);

//Reply
//buff = "4"
//Instrument currently using user calibration 4
iRet = m_pSocket->Receive( buff, PACKET_SIZE, 0);
```

Set the Current Instrument User Calibration

Command: **WMODECURUSERCAL <<#>>**

Where: # is a value 0-9 corresponding to a user calibration number of the instrument, 10 corresponds to factory calibration.

Return value: a string response OK indicating that the user calibration was set, or FAIL indicating an error during the setting of the user calibration.

Note: *This command requires the MUPDATE command to be sent to update the instrument RAM.*

Code Example:

```
// "WMODECURUSERCAL#" is the DustTrak command to write the current
// instrument user calibration.
// The command must be followed by a CR.
// Command
// buff = "WMODECURUSERCAL0"
// 0 = Current User Cal

iRet = m_pSocket->Send( "WMODECURUSERCAL0\r", 17);

// The returned value is a string containing status
// of the command (i.e. OK or FAIL).
iRet = m_pSocket->Receive( buff, PACKET_SIZE, 0);
```

Read Instrument User Calibration Data

Command: **RMODEUSERCAL<<#>>**

is a value 0-9 corresponding to a user calibration number of the instrument.

Return value: comma separated string containing the following data format.

User calibration number, Size correction factor,
Photometric calibration factor, User calibration name,

Code Example:

```
// "RMODEUSERCAL#" is the DustTrak command to read the instruments user
// calibration settings.
// The command must be followed by a CR.
// Command
// buff = "RMODEUSERCAL0"
```

```
// 0 = User Cal index
iRet = m_pSocket->Send( "RMODEUSERCAL0\r", 14);

iRet = m_pSocket->Receive( buff, PACKET_SIZE, 0);
// Reply
// buff = "0,1.5,0.9,USER CAL 0"
// 0 = User Cal index
// 1.5 = Size Correction Factor (DRX only)
// 0.9 = Photometric Calibration Factor
// USER CAL 0 = User Cal Name
```

Set Instrument User Calibration Data

Command: **WMODEUSERCAL <<#>><< User calibration number, Size correction factor, Photometric calibration factor, User calibration name >>**
 # is a value 0-9 corresponding to a user calibration number of the instrument.

Value formats:

User calibration number: integer 0-9
 Size correction factor: float
 Photometric calibration factor: float
 User calibration name: char [12]

Return value: a string response OK indicating that the instrument user calibration was written to the instrument, or FAIL indicating an error during the setting of the user calibration.

Note: *This command requires the MUPDATE command to be sent to update the instrument RAM. The Size Correction factor is only used in the DRX models.*

Code Example:

```
// "WMODEUSERCAL#" is the DustTrak command to write the instruments user cal
// settings.
// The command must be followed by a CR.
// Command
// buff = "WMODEUSERCAL0 1.5,0.9,USER CAL 0"
// 0 = User Cal index
// 1.5 = Size Correction Factor (DRX only)
// 0.9 = Photometric Calibration Factor
// USER CAL 0 = User Cal Name
iRet = m_pSocket->Send( "WMODEUSERCAL0 1.5,0.9,USER CAL 0\r", 33);

// The returned value is a string containing status
// of the command (i.e. OK or FAIL).
iRet = m_pSocket->Receive( buff, PACKET_SIZE, 0);
```

Read the Instrument Date And Time

Command: **RSDATETIME**

Return value: a date time string of the format Day/Month/Year
Hour:Minute:Second.

Code Example:

```
// "RSDATETIME" is the DustTrak command to read the instruments date
// and time.
// The command must be followed by a CR.
iRet = m_pSocket->Send( "RSDATETIME\r", 11);

iRet = m_pSocket->Receive( buff, PACKET_SIZE, 0);
// Reply
// buff = "9/30/2008,13:44:5"
// 09 = Month
// 30 = Day
// 2008 = Year
// 13 = Hour
// 44 = Minute
// 05 = Second
```

Set the Current Instrument User Calibration

Command: **WSDATETIME<<Date Time>>**

Where: Date Time is a date time string of the format
Day/Month/Year Hour:Minute:Second.

Return value: a string response OK indicating that the date and time was
set, or FAIL indicating an error during the setting of the
date and time of the instrument.

Note: This command requires the MUPDATE command to be sent to
update the instrument RAM.

Code Example:

```
// "WSDATETIME" is the DustTrak command to write the instruments date
// and time.
// The command must be followed by a CR.
// Leading zeros are optional.
// Command
// buff = "WSDATETIME 09/30/2008,13:44:05"
// 09 = Month
// 30 = Day
// 2008 = Year
// 13 = Hour
// 44 = Minute
// 05 = Second
iRet = m_pSocket->Send( "WSDATETIME 09/30/2008,13:44:05\r", 31);

// The returned value is a string containing status
```

```
// of the command (i.e. OK or FAIL).  
iRet = m_pSocket->Receive( buff, PACKET_SIZE, 0);
```

Read the Filter Change Date

Command: **RSFILTERCHANGEDATE**

Return value: comma separated string containing the following data format.

Day/Month/Year, Concentration since last filter change

Code Example:

```
// "RSFILTERCHANGEDATE" is the DustTrak command to read the instruments  
// filter change date.  
// The command must be followed by a CR.  
iRet = m_pSocket->Send( "RSFILTERCHANGEDATE\r", 19);  
  
iRet = m_pSocket->Receive( buff, PACKET_SIZE, 0);  
// Reply  
// buff = "8/27/2008,456"  
// 09 = Month  
// 30 = Day  
// 2008 = Year  
// 456 = Concentration since last filter change
```

Read the Calibration Date

Command: **RSCALDATE**

Return value: comma separated string containing the following data format.

Day/Month/Year, Run time since last calibration,
Concentration since last calibration, Pump run time in
seconds

Code Example:

TSI Incorporated – 500 Cardigan Road, Shoreview, MN 55126 U.S.A

USA	Tel: +1 800 874 2811	E-mail: info@tsi.com	Website: www.tsi.com
UK	Tel: +44 149 4 459200	E-mail: tsiuk@tsi.com	Website: www.tsiinc.co.uk
France	Tel: +33 491 95 21 90	E-mail: tsifrance@tsi.com	Website: www.tsiinc.fr
Germany	Tel: +49 241 523030	E-mail: tsigmbh@tsi.com	Website: www.tsiinc.de
India	Tel: +91 80 41132470	E-mail: tsi-india@tsi.com	
China	Tel: +86 10 8260 1595	E-mail: tsibeijing@tsi.com	



Contact your local TSI Distributor or visit our website **www.tsi.com** for more detailed specifications.