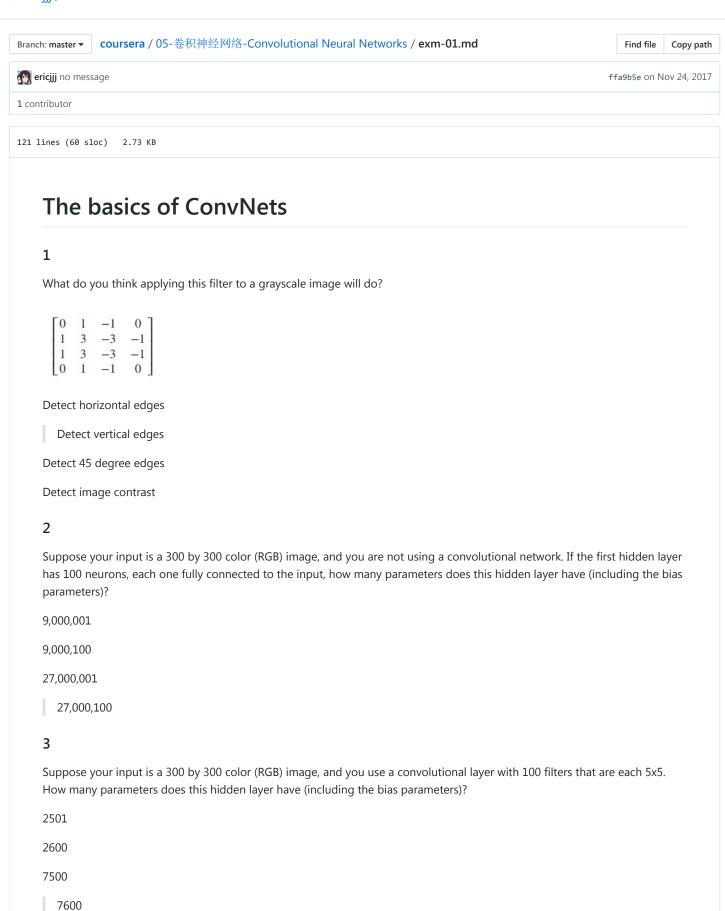
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You have an input volume that is $63x63x16$, and convolve it with 32 filters that are each $7x7$, using a stride of 2 and no padding. What is the output volume?
16x16x32
29x29x16
29x29x32
16x16x16
5
You have an input volume that is 15x15x8, and pad it using "pad=2." What is the dimension of the resulting volume (after padding)?
19x19x12
17x17x10
19x19x8
17x17x8
6
You have an input volume that is 63x63x16, and convolve it with 32 filters that are each 7x7, and stride of 1. You want to use a "same" convolution. What is the padding?
1
2
3
7
7
You have an input volume that is 32x32x16, and apply max pooling with a stride of 2 and a filter size of 2. What is the output volume?
15x15x16
16x16x16
32x32x8
16x16x8
8
Because pooling layers do not have parameters, they do not affect the backpropagation (derivatives) calculation.
True
False
9
In lecture we talked about "parameter sharing" as a benefit of using convolutional networks. Which of the following statements about parameter sharing in ConvNets are true? (Check all that apply.)

 $https://github.com/ericjjj/coursera/blob/master/05-\%E5\%8D\%B7\%E7\%A7\%AF\%E7\%A5\%9E\%E7\%BB\%8F\%E7\%BD\%91\%E7\%BB\%9C-Convolutional... \ 2/3$

It allows parameters learned for one task to be shared even for a different task (transfer learning).

It reduces the total number of parameters, thus reducing overfitting. It allows gradient descent to set many of the parameters to zero, thus making the connections sparse. It allows a feature detector to be used in multiple locations throughout the whole input image/input volume.

10

In lecture we talked about "sparsity of connections" as a benefit of using convolutional layers. What does this mean?

Each filter is connected to every channel in the previous layer.

Each activation in the next layer depends on only a small number of activations from the previous layer.

Each layer in a convolutional network is connected only to two other layers

Regularization causes gradient descent to set many of the parameters to zero.