```
robot" ><
link name ='chassis' ><
pose >
0 0.1 0 0 0 <
/pose ><
collision name ='collision' ><
geometry ><
box ><
size >
.4 .2 .1 <
/size ><
/box ><
/geometry ><
/collision >

collision' ><
pose >
-0.15 0 -0.05 0 0 0 <
/pose ><
geometry ><
sphere ><
radius >
.05 <
/radius ><
/sphere ><
/geometry >

visual' ><
pose >
-0.15 0 -0.05 0 0 0 <
/pose ><
geometry ><
sphere ><
radius >
.05 <
/radius ><
/sphere ><
/geometry ><
/visual ><
/link ><
link name = "left_wheel" ><
pose >
0.1 0.13 0.1 0 1.5707 1.5707 <
/pose ><
collision name = "collision" ><
geometry ><
cylinder ><
radius >
.1 <
/radius ><
length >
.05 <
/length ><
/cylinder ><
/geometry ><
/collision ><
visual name = "visual" ><
geometry ><
cylinder ><
radius >
.1 <
/radius ><
length >
.05 <
/length ><
/cylinder ><
/geometry ><
/visual ><
/link >
wheel" ><
pose >
0.1 -0.13 0.1 0 1.5707 1.5707 <
/pose ><
collision name = "collision" ><
geometry ><
cylinder ><
radius >
.1 <
/radius ><
length >
.05 <
/length ><
```