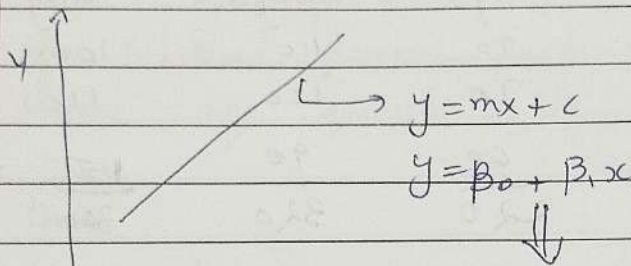


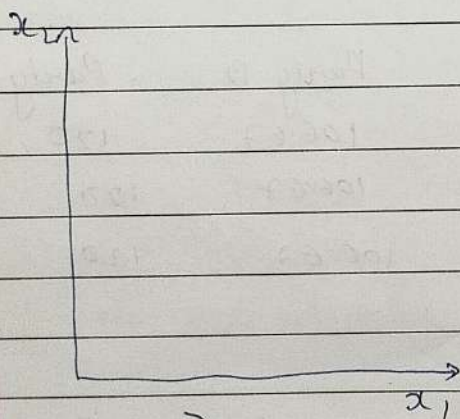
SUPPORT VECTOR MACHINES (SVM)

SVM can solve both Classification & Regression Problems.

- ① Classification } \rightarrow SVC \rightarrow Support Vector Classification
- ② Regression } \rightarrow SVR \rightarrow Support Vector Regression



$$ax + by + c = 0 \Rightarrow y = \underbrace{\left[\frac{-a}{b} \right]}_{\text{coefficient}} x - \underbrace{\left[\frac{c}{b} \right]}_{\text{intercept}}$$



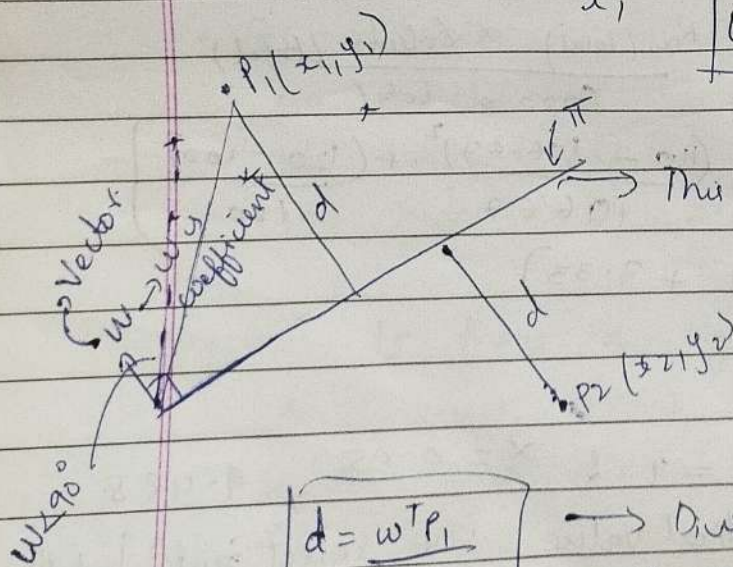
$$\begin{aligned} ax_1 + bx_2 + c &= 0 \\ w_1 x_1 + w_2 x_2 + b &= 0 \\ w^T x + b &= 0 \end{aligned}$$

Multiplication

$$\begin{bmatrix} w_1 \\ w_2 \end{bmatrix} \begin{bmatrix} x_1 & x_2 \end{bmatrix}$$

$w^T \rightarrow$ Transpose

$$w^T x = 0 \Rightarrow \text{Eqn. of line passing through origin}$$

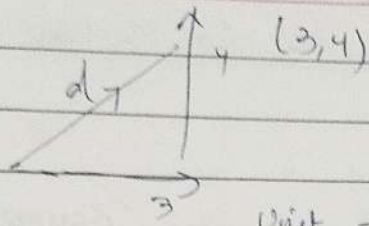


This can be plane or a line.

$$d = \frac{w^T P_1}{\|w\|}$$

\rightarrow Dividing by $\|w\|$ to get unit vector.
Unit vector \rightarrow Vector which has magnitude of 1.

Eg:-



Hypotenuse = $\sqrt{9+16} = \sqrt{25}$
 $d = 5$

Unit Vector $\rightarrow \hat{d} = \frac{d}{|d|}$

to make it unit vector $= \left(\frac{3}{5}, \frac{4}{5} \right)$

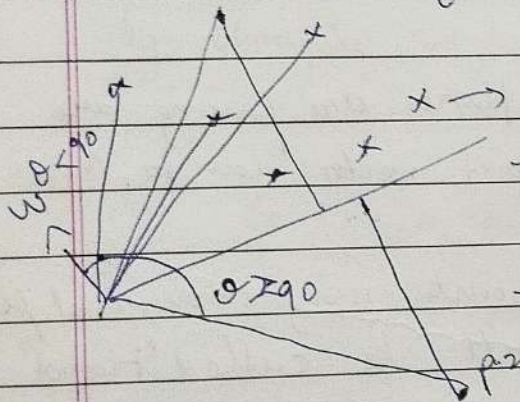
$= \sqrt{\frac{9}{25} + \frac{16}{25}}$

$= \sqrt{1} = 1$

$$\frac{d = w^T P}{|w|} \Rightarrow |w| |P| \cos \theta$$

Magnitude of w ($|w|$)

If $\theta < 90^\circ$ value will be +ve.



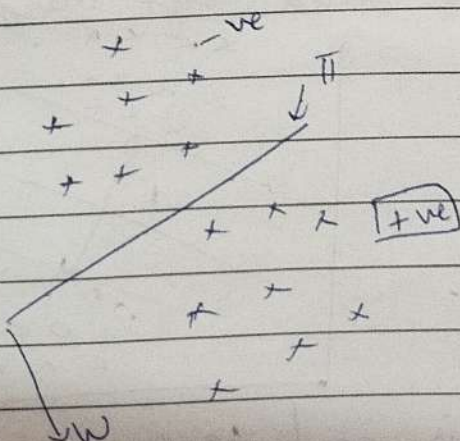
\rightarrow If points are above the plane distance is +ve.

\rightarrow For points below the plane distance value is -ve.

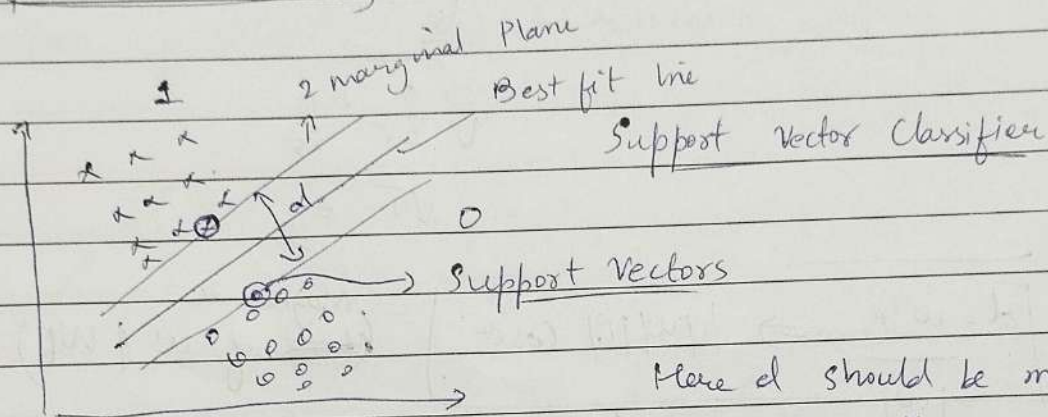
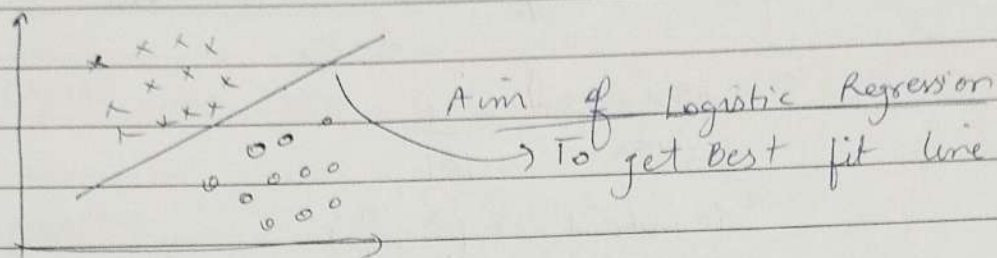
$d = \frac{w^T P_2}{|w|} = |w| |P_2| \cos \theta \Rightarrow \boxed{-ve}$

S	A
+	-

Scenario:



Geometric Intuition Behind Support Vector Machine



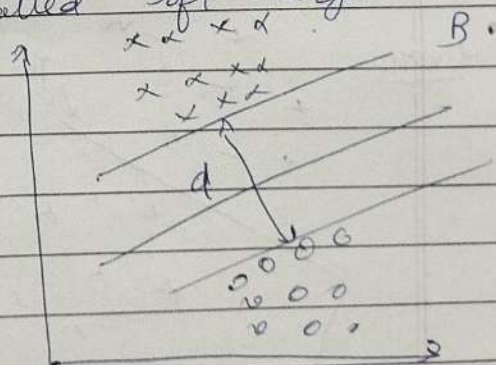
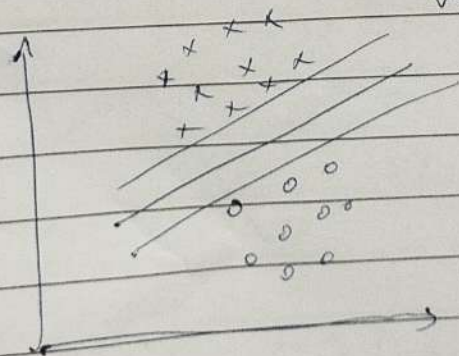
Aim -> Along with the best fit line there are 2 marginal planes where d would be maximum.

-> Point through which 2 marginal planes are passing are support vectors. More than 1 support vector can be there.

-> Marginal planes are equidistant.

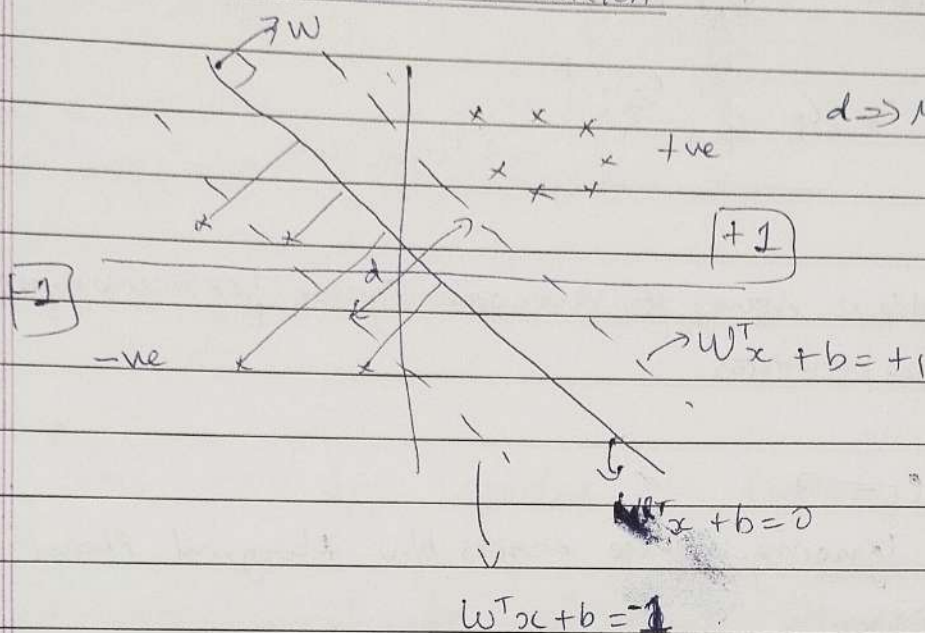
-> If we clearly separate all the points using marginal planes, best fit line and there are no errors it will be called 'Hard Margin'.

-> If there are some errors b/w marginal planes & best fit lines ~~then~~ it will be called 'Soft Margin'.



B is good because d is greater.

(2) SVM Mathematical Intuition



$d \Rightarrow$ Maximum $w^T x_1 + b = +1$
 $-(w^T x_2 + b = -1)$

$\Rightarrow \frac{w^T (x_1 - x_2)}{|w|} = \frac{2}{|w|}$

\downarrow unit vector we divide
 To get magnitude of w

Cost function

Maximize $\frac{2}{|w|} \Rightarrow$ Distance b/w Marginal Plane

by changing w, b

Constraint such that y_i $\begin{cases} 1 & x^T x + b \geq 1 \\ -1 & x^T x + b \leq -1 \end{cases}$ \rightarrow condition for all correct classified points

* for linear algebra -1 & $+1$ fits best

For all correct points,

constraints $\rightarrow y_i \cdot x (w^T x + b) \geq 1$

$y_i \rightarrow$ Truth points

Maximize $\frac{2}{|w|} \Rightarrow$ Minimize $|w|$
 w, b 2

Because for every Cost fn. we are trying to minimize every

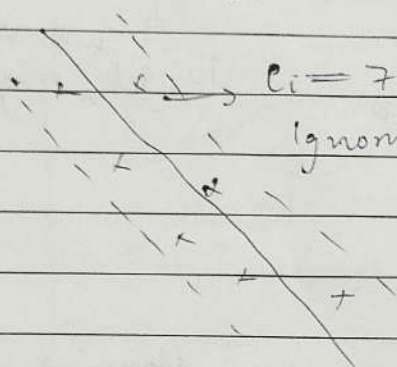
Cost function

Soft Margin

$\zeta_i \Rightarrow \epsilon_i$

$$\min_{w, b} \frac{|w|}{2} + C \sum_{i=1}^n \zeta_i \Rightarrow \text{Hinge loss}$$

$C_i \rightarrow$ how many pt. we can ignore for misclassification
It is hyperparameter.



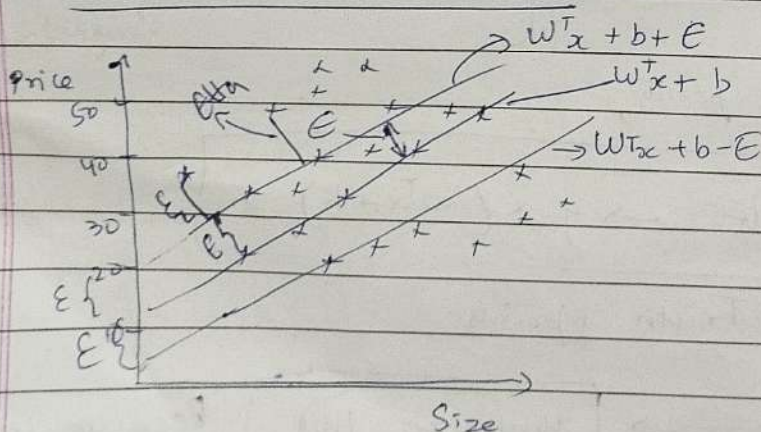
Ignoring these errors b/w Marginal Planes

$\zeta_i \rightarrow \epsilon_i$ is another hyperparameter.

Summation of the distance of incorrest data points from the marginal Plane.

② SUPPORT VECTOR REGRESSION

$\epsilon \rightarrow$ Epsilon (Marginal Error)



$$\min_{w, b} \frac{|w|}{2} + C \sum_{i=1}^n \zeta_i \Rightarrow \text{Hinge loss}$$

Constraint

$$|y_i - w_i x_i| \leq \epsilon + \sum_{i=1}^m \xi_i$$

Diff b/w Truth & Predicted Pt.

ξ_i → Distance b/w pt & marginal plane.

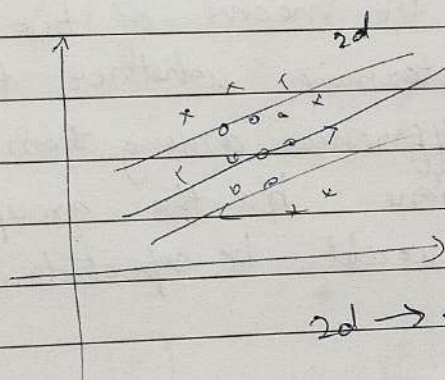
Q. Will SVM get Impacted by Outliers.

Ans Yes

Q: Do we need to normalize / Standardize data.

Ans Yes

* SVM Kernel



→ we would not be able to solve this problem using SVC or SVR.

→ Here we use SVM Kernel

2d → 3D

