

# Assignment 9: RBF Kernels and the 3D Error Surface

Data Science and Machine Learning Module

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## 1 Introduction

Linear boundaries are insufficient for real-world manifolds. In this assignment, you will implement the **RBF (Gaussian) Kernel** to classify concentric and interlocking datasets. You will also learn to perform a **Grid Search** to find the optimal balance between model complexity ( $\gamma$ ) and error tolerance ( $C$ ).

## 2 The RBF Kernel Logic

Unlike the dot product, the RBF kernel measures similarity based on distance:

$$K(x_i, x_j) = \exp(-\gamma \|x_i - x_j\|^2)$$

To access this, you can write "rbf" in the SVM function.

## 3 Task 1: The 2D Visual Experiment

Using the two\_moons.csv and the concentric\_circles.csv dataset:

1. Fix  $C = 10$  and train your SVM with  $\gamma = 0.01$ ,  $\gamma = 1$ , and  $\gamma = 50$ .
2. Plot the decision boundaries. Observe how high  $\gamma$  creates "islands" of influence around individual points.

## 4 Task 2: 3D Hyperparameter Grid Search

To find the best model, we must sweep across two dimensions.

1. Create a grid of  $C \in \{0.1, 1, 10, 100\}$  and  $\gamma \in \{0.01, 0.1, 1, 10\}$ .
2. For each pair  $(C, \gamma)$ , calculate the **Validation Error** ( $1 - \text{Accuracy}$ ) on the validation set.
3. **3D Plotting:** Use `plotly.graph_objects.Surface` to plot:
  - X-axis:  $\log(C)$
  - Y-axis:  $\log(\gamma)$
  - Z-axis: Validation Error