

Charotar University of Science and Technology
Devang Patel Institute of Advance Technology and Research
Department of Computer Science & Engineering
Subject: CS341 Artificial Intelligence
Unit Test - 1

Semester: 5th (B. Tech.)
Date: 26/8/2021, Thursday

Maximum Marks: 30
Time: 03:30 pm to 04:30 pm

Instructions:

- (i) Attempt *all* the questions.
- (ii) Figures to the right indicate *full* marks.
- (iii) Make suitable assumptions and draw neat figures wherever required.

Section : 1

Sr. No	Questions	Marks	CO	BL
1	Select the most appropriate situation for that a blind search can be used. A. Real-life situation B. Small Search Space C. Complex game D. All of the above	1	1	U
2	Among the given options, which search algorithm requires less memory? A. Optimal Search B. Depth First Search C. Breadth-First Search D. Linear Search	1	1	U
3	If a robot is able to change its own trajectory as per the external conditions, then the robot is considered as the____ A. Mobile B. Non-Servo C. Open Loop D. Intelligent	1	1	A

4	<p>In state-space, the set of actions for a given problem is expressed by the ____.</p> <p>A. Intermediate States</p> <p>B. Successor function that takes current action and returns next state</p> <p>C. Initial States</p> <p>D. None of the above</p>	1	2	R
5	<p>What is state space?</p> <p>A. The whole problem</p> <p>B. Your Definition to a problem</p> <p>C. Problem you design</p> <p>D. Representing your problem with variable and parameter</p>	1	2	U
6	<p>What is the major component/components for measuring the performance of problem solving?</p> <p>A. Completeness</p> <p>B. Optimality</p> <p>C. Time and Space complexity</p> <p>D. All of the mentioned</p>	1	2	U
7	<p>A production rule consists of _____</p> <p>A. A set of Rule</p> <p>B. A sequence of steps</p> <p>C. Set of Rule & sequence of steps</p> <p>D. Arbitrary representation to problem</p>	1	2	A
8	<p>In a rule-based system, procedural domain knowledge is in the form of:</p> <p>A. Production rules</p> <p>B. Rule interpreters</p> <p>C. Meta-rules</p> <p>D. Control rules</p>	1	2	U

9	<p>What is the term used for describing the judgmental or commonsense part of problem solving?</p> <p>A. Heuristic</p> <p>B. Critical</p> <p>C. Value based</p> <p>D. Analytical</p>	1	2	R
10	<p>Artificial intelligence is</p> <p>A. The embodiment of human intellectual capabilities within a computer</p> <p>B. A set of computer programs that produce output that would be considered to reflect intelligence if it were generated by humans</p> <p>C. The study of mental faculties through the use of mental models implemented on a computer</p> <p>D. All of the above</p>	1	1	U
11	<p>A strong AI is labeled as _____.</p> <p>A. Artificial general intelligence</p> <p>B. Artificial generate intelligence</p> <p>C. Artificial general intro</p> <p>D. Art general intelligence</p>	1	1	R
12	<p>Weak AI is</p> <p>A. The embodiment of human intellectual capabilities within a computer</p> <p>B. A set of computer programs that produce output that would be considered to reflect intelligence if it were generated by humans</p> <p>C. The study of mental faculties through the use of mental models implemented on a computer</p> <p>D. None of the above</p>	1	1	U
13	<p>The area of AI that investigates methods of facilitating communication between people and computers is:</p> <p>A. Natural language processing</p> <p>B. Symbolic processing</p> <p>C. Decision support</p> <p>D. Robotics</p>	1	1	A

14	<p>The time and space complexity of BFS is (For time and space complexity problems consider b as branching factor and d as depth of the search tree.)</p> <p>A. $O(bd+1)$ and $O(bd+1)$</p> <p>B. $O(b^2)$ and $O(d^2)$</p> <p>C. $O(d^2)$ and $O(b^2)$</p> <p>D. $O(d^2)$ and $O(d^2)$</p>	1	2	E
15	<p>A heuristic is a way of trying</p> <p>A. To discover something or an idea embedded in a program</p> <p>B. To search and measure how far a node in a search tree seems to be from a goal</p> <p>C. To compare two nodes in a search tree to see if one is better than the other is</p> <p>D. All of the mentioned</p>	1	2	R
16	<p>Hidden layer is use to add non – linearity in the Artificial Neural Network.</p> <p>A. True</p> <p>B. False</p>	1	3	R
17	<p>If I have Input image of size $7*7$ and filter size is $3*3$ what v resultant matrix size?</p> <p>A. $5*5$</p> <p>B. $6*6$</p> <p>C. $7*7$</p> <p>D. $8*8$</p>	1	3	E
18	<p>If we add 10 or more hidden layer in artificial neural Network then Vanishing Gradient problem occur.</p> <p>A. True</p> <p>B. False</p>	1	3	A

19	<p>Amongst this which is not the Learning type</p> <p>A. Semi Supervised Learning B. Supervised Learning C. Reinforcement Learning D. Unsupervised Learning E. None of the Above</p>	1	3	R
20	<p>Perceptron is used to classify the non- linearly separable pa</p> <p>A. True B. False</p>	1	3	U
21	<p>Which is not Activation function?</p> <p>A. Step B. Linear C. Sigmoid D. Non-Linear</p>	1	3	U
22	<p>Full form of RELU</p> <p>A. Rectified Linear Unit B. Recurrent Linear Unit C. Recursive Linear Unit</p>	1	4	R
23	<p>In convolution process Padding is use to retain the size of origina</p> <p>A. True B. False</p>	1	4	U
24	<p>If Learning rate in neural network is too high then neural network will reach to minima very quickly.</p> <p>A. True B. False</p>	1	4	U

25	<p>If learning rate is too low then neural network will reach to the minima very quickly.</p> <p>A. True B. False</p>	1	3	U
26	<p>Full form of BPNN</p> <p>A. Bidirectional Neural Network B. Backpropagation Neural Network C. Bipolar Neural Network</p>	1	4	R
27	<p>Which is the correct equation to update the weight</p> <p>A. $W_{new} = W_{old} + \Delta(E) * \text{learning rate}$ B. $W_{new} = W_{old} - \Delta(E) * \text{learning rate}$</p>	1	3	E
28	<p>In CNN we can only use 2 Fully connected layer</p> <p>A. True B. False</p>	1	3	U
29	<p>Convolution Neural Network have combination of Concolutional layer, Pooling layer and Fully Connected Layer</p> <p>A. True B. False</p>	1	3	U
30	<p>Which is not the pooling method</p> <p>A. Max B. Average C. Standard Deviation</p>	1	3	A

Note:

CO – Course Outcomes

BL – Bloom's Taxonomy Level