

# ANH (FRANK) LE

+1 701 219 5500 ◊ ducanh.le@ndsu.edu ◊ <https://www.linkedin.com/in/anhlendsu/>

## PROFESSIONAL SUMMARY

Water resources researcher specializing in physics-informed machine learning for hydraulic modeling and bathymetry inversion. Expertise in solving partial differential equations through computational methods, integrating UAV-derived data with hydrodynamic models, and developing novel measurement-free approaches for river characterization. Experienced in advancing R&D workflows with HPC acceleration, Bayesian uncertainty quantification, and AI applications in hydraulic modeling.

## EDUCATION

|   |                      |
|---|----------------------|
| <b>Ph.D. in Civil Engineering, Focus: Water Resources and AI</b>  | <i>Expected 2028</i> |
| North Dakota State University — Specialization in Physics-Informed Machine Learning, Hydraulics, and Uncertainty Quantification |                      |
| <b>M.S. in Construction Management, First Class Honors</b>  | <i>2020</i>          |
| Ho Chi Minh City University of Technology   |                      |
| <b>B.Eng. in Industrial and Civil Engineering</b>   | <i>2018</i>          |
| Ho Chi Minh City University of Technology   |                      |

## EXPERIENCE

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|--|---------------------------|
| <b>Graduate Research Assistant — Water Resources Engineering</b>   | <i>Jan 2024 — Present</i> |
| North Dakota State University  | <i>Fargo, ND</i>          |
| • Accelerated Physics-Informed Neural Network (PINN) training by 70% through GPU/CUDA optimization in JAX, enabling real-time experimentation for PDE-based hydraulic modeling |                           |
| • Developed a measurement-free bathymetry inversion framework solving Shiono-Knight Method PDEs to recover river depth profiles from UAV-derived surface velocity data         |                           |
| • Integrated UAV remote sensing data with PDE-constrained neural networks to improve non-contact bathymetry estimation for R&D applications                                    |                           |
| • Applied Bayesian uncertainty quantification and Polynomial Chaos Expansion to generate confidence intervals and quantify prediction reliability                              |                           |

## KEY RESEARCH PROJECT

|  |                     |
|--|---------------------|
| <b>Measurement-Free Bathymetry Inversion using Physics-Informed Machine Learning</b>   | <i>2024—Present</i> |
| • Developed novel PINN-based framework for non-invasive river depth recovery, solving Shiono-Knight Method PDEs to reconstruct bathymetry $H(y)$ from UAV-derived surface velocity measurements $U_d(y)$ without requiring traditional depth surveys |                     |
| • Pioneered integration of remote sensing data with PDE-constrained neural networks for hydraulic R&D, demonstrating feasibility of measurement-free river characterization for flood modeling and channel design applications                       |                     |
| • Integrated Monte Carlo simulation and Bayesian PINNs for robust uncertainty quantification, providing probabilistic depth estimates critical for risk-informed hydraulic engineering decisions   |                     |
| • Utilized HEC-RAS, Tecplot, and QGIS for validation and visualization of bathymetry reconstructions against benchmark scenarios   |                     |

## PAPERS IN PROGRESS

Le, A., Souri J., & Le, T. B. (In preparation). *Physics-Informed Neural Network for Measurement-Free Bathymetry Inversion Using the Shiono–Knight Method*. Target journal: *Water Resources Research (AGU)*.

## TECHNICAL SKILLS

**Water Resources:** Open-channel hydraulics, river bathymetry inversion, culvert/levee analysis, hydrodynamic modeling, UAV-based hydraulic measurements

**Hydraulic Software:** HEC-RAS, HY8, Tecplot, QGIS, ArcGIS

**Modeling & ML:** Physics-informed neural networks (PINNs), solving PDEs with neural networks, Bayesian inference, graph neural networks, time-series forecasting

**HPC & Computing:** MATLAB, GPU/CUDA parallelization, distributed training (JAX, PyTorch)

**Programming:** Python (scikit-learn, TensorFlow, Flax)