#### Short title

Pritam Dey Ayan Paul

Introduction

Some Useful Definitions

Froblem

Time complexity

Ciura's sequential

Comparing Efficiency

Comparison of different

Conclusion

# Project on Introductory Computer Programming

Introduction to Shell Sort

Pritam Dey, Ayan Paul

May 4, 2020

#### What is Shell Sort

Short title

Pritam Dey Ayan Paul

Introduction

Some Usefu Definitions

Frobenius Problem

Time complexity

Ciura's sequentia analysis

Comparing Efficiency

Comparison of different

Conclusion

Shell sort is mainly a variation of Insertion sort. In insertion sort, we move elements only one position ahead. When an element has to be moved far ahead, many movements are involved.

The idea of Shell sort is to allow exchange of far items. In Shell sort, we make the array h-sorted for a large value of h. We keep reducing the value of h until it becomes 1. An array is said to be h-sorted if all sublists of every  $h^{th}$  element is sorted.

#### Visualisation

#### Short title

Pritam Dey Ayan Paul

#### Introduction

Some Usefu Definitions

Frobenius Problem

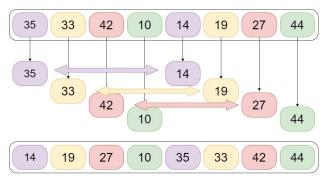
Time complexity

Ciura's sequentia analysis

Comparing Efficiency

Comparison of different

Figure: Sorting sub-arrays of gap 4



#### Visualisation

Short title

Pritam Dey Ayan Paul

#### Introduction

Some Usefu Definitions

Frobenius Problem

Time complexity

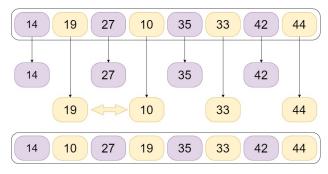
Ciura's sequentia analysis

Comparing Efficiency

Comparison o different

Conclusion

#### Figure: Sorting sub-arrays of gap 2



#### Visualisation

Short title

Pritam Dey Ayan Paul

#### Introduction

Some Usefu Definitions

Froblem

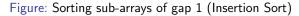
Time

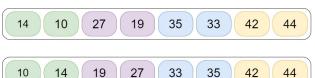
complexity

Ciura's sequential analysis

Comparing Efficiency

Comparison o different





#### **Pass**

Short title

Pritam Dey Ayan Paul

Introductio

Some Useful Definitions

Frobenius Problem

Time complexity

Ciura's sequential analysis

Comparing Efficiency

Comparison of different methods

Conclusio

Each trial of the Shellsort algorithm where every possible lists(sub-arrays) of gap h between any two elements of the list is called a **Pass**.

**E.g.**: Referring to the example shown in the **Visualisation** section, sorting sub-arrays of gap 4, gap 2 and gap 1 are the first, second and third passes of the Shellsort algorithm respectively.

#### h Sort

Short title

Pritam Dey Ayan Paul

Introductio

Some Useful Definitions

Frobenius Problem

Time complexity

Ciura's sequentia analysis

Comparing Efficiency

Comparison o different methods

Conclusion

At every pass, the Shellsort algorithm sorts every sub array or list of elements having gap h between any two of them in the original array. So after each pass, the algorithm yields some h interleaved lists, each individually sorted. This process is called **h-sorting**. Beginning with large values of h, this rearrangement allows elements to move long distances in the original list, reducing large amounts of disorder quickly and leaving less work for smaller h-sort steps to do. If the list is then k-sorted for some smaller integer k, then the list remains h-sorted.

Some Useful Definitions

Frobenius Problem

Time complexity

Ciura's sequential analysis

Comparing Efficiency

Comparison of different methods

Conclusio

Following this idea for a decreasing sequence of h values ending in 1 is guaranteed to leave a sorted list in the end. Also there is a nice property that if an array is k-sorted for some k < h, then it is  $\alpha h + \beta k$  sorted for any non negative integers  $\alpha$  and  $\beta$ .

**E.g.**: Referring to the example shown in the **Visualisation** section, in the first pass h is 4, in the second pass h equals to 2 and in the third pass h equals to 1.

# Gap Sequence

Short title

Pritam Dey Ayan Paul

Introductio

Some Useful Definitions

Frobenius Problem

Time complexity

Ciura's sequentia analysis

Comparing Efficiency

Comparison of different methods

Conclusio

It is a proposed sequence of integers which determines which h-sortings will be done by the algorithm to sort the whole array. These are mostly random or experimentally generated integers. Use of a good gap sequence reduces the time complexity of the algorithm.

**E.g.**: Referring to the example shown in the **Visualisation** section, the gap sequence used is  $\{4, 2, 1\}$ .

#### Shell Sort and Frobenius Problem

Short title

Pritam Dey Ayan Paul

Introduction

Some Usefu Definitions

Frobenius Problem

Time complexit

Ciura's sequentia analysis

Comparing Efficiency

Comparison o different methods

Conclusion

There is a nice relation between Shell Sort, its gap sequences and a renowned problem in Number Theory, **The Frobenius Coin Problem**. The worst case time complexity of Shellsort can be analysed using the concept of this problem.

The problem asks for the largest monetary amount that cannot be obtained using only coins of specified denominations. For example, the largest amount that cannot be obtained using only coins of 3 and 5 units is 7 units. The solution to this problem for a given set of coin denominations is called the **Frobenius Number** of the set.

The Frobenius number exists as long as the set of coin denominations are co-primes.

#### Mathematical Statement of the Problem

Short title

Pritam Dey Ayan Paul

Introductio

Some Usefu Definitions

Frobenius Problem

Time complexity

Ciura's sequential analysis

Comparing Efficiency

Comparison o different methods

Conclusion

In mathematical terms the problem can be stated as: Given positive integers  $a_1, a_2, \ldots, a_n$  such that  $\gcd(a_1, a_2, \ldots, a_n) = 1$ , find the largest integer that cannot be expressed as an integer conical combination of these numbers, i.e., as a sum  $k_1 a_1 + k_2 a_2 + \ldots + k_n a_n$ , where  $k_1, k_2, \ldots, k_n$  are non-negative integers.

This largest integer is called the **Frobenius Number** of the set  $a_1, a_2, ..., a_n$ , and is usually denoted by  $g(a_1, a_2, ..., a_n)$ .

# Frobenius Number for Small Set (of size n) of Integers

Short title

Pritam Dey Ayan Paul

Introductio

Some Usefu Definitions

Frobenius Problem

Time complexity

Ciura's sequentia analysis

= n=2

Comparing Efficiency

Comparison of different methods

Conclusion

A closed-form solution exists for **The Coin Problem** only where n = 1 or 2. No closed-form solution is known for n > 2.

- n=1
  If n = 1, then a<sub>1</sub> = 1 so that all natural numbers can be formed. Hence no **Frobenius number** in one variable exists.
  - If n = 2, the **Frobenius number** can be found from the formula  $g(a_1, a_2) = a_1 a_2 a_1 a_2$ . This formula was discovered by **James Joseph Sylvester** in 1882.

Comparison of different methods

Conclusion

**Sylvester** also demonstrated for this case that there are a total of  $N(a_1,a_2)=(a_1-1)(a_2-1)/2$  non-representable (non-negative) integers.

#### ■ n=3

Formulae and fast algorithms are known for three numbers though the calculations can be very tedious if done by hand.

Simpler lower and upper bounds for **Frobenius numbers** for n = 3 can been also determined.

# Time complexity

Short title

Pritam Dey Ayan Paul

Introduction

Some Usefu Definitions

Frobenius Problem

Time complexity

Ciura's sequentia analysis

Comparing Efficiency

Comparison of different

Conclusion

Time complexity of Shell Sort is directly related to the gap sequence used in the algorithm. Shell originally proposed the following gap sequence. (1959)

$$\left[\frac{N}{2}\right], \left[\frac{N}{4}\right], \dots, 1$$

# Worst case of Shell's gap sequence

Short title

Pritam Dey Ayan Paul

Introduction

Some Usefu Definitions

Frobenius Problem

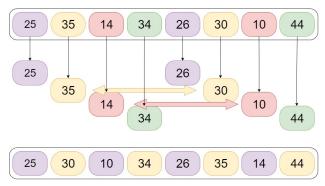
#### Time complexity

Ciura's sequential

Comparing Efficiency

Comparison of different

Figure: Sorting sub-arrays of gap 4



# Worst case of Shell's gap sequence

Short title

Pritam Dey Ayan Paul

Introduction

Some Useful Definitions

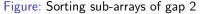
Frobenius Problem

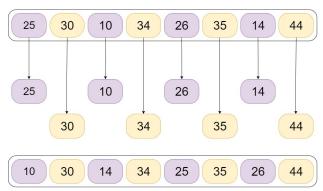
#### Time complexity

Ciura's

Comparing Efficiency

Comparison of different





# Gap sequences and Time complexity

Short title

Pritam Dey Ayan Paul

Introduction

Some Usefu Definitions

Frobenius Problem

Time complexity

Ciura's sequentia analysis

Comparing Efficiency

Comparison of different methods

Conclusion

The question of deciding which gap sequence to use is hence very important. A carefully selected gap-sequence can improve the time complexity of Shell Sort significantly.

Short title

Pritam Dey Ayan Paul

Introductio

Some Usefu Definitions

Frobenius Problem

Time complexity

Ciura's sequentia analysis

Comparing Efficiency

Comparison of different methods

- Any gap sequence that includes 1 yields a correct sort.
- Given the length of the array, the gap sequence should not be too large or too small.
- The gap sequence should have pairwise co-prime members.
- Gonnet and Baeza-Yates observed that Shell Sort makes the fewest comparisons on average when the ratios of successive gaps are roughly equal to 2.2. Whereas Tokuda suggested that gap-sequence with successive ratio 2.25 is more efficient.

Short title

Pritam Dey Ayan Paul

Introductio

Some Usefu Definitions

Frobenius Problem

Time complexity

Ciura's sequentia analysis

Comparing Efficiency

Comparison of different methods

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Short title

Pritam Dey Ayan Paul

Introductio

Some Usefu Definitions

Frobenius Problem

Time complexity

Ciura's sequentia analysis

Comparing Efficiency

Comparison of different methods

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Short title

Pritam Dey Ayan Paul

Introduction

Some Usefu Definitions

Frobenius Problem

Time complexity

Ciura's sequentia analysis

Comparing Efficiency

Comparison of different methods

Conclusion

■ The gap sequence should have pairwise co-prime members.

Sedgewick recommends to use gaps that have low greatest common divisors or are pairwise co-prime. It is quite intuitive since if we have a gap sequence like  $\{1,3,5,8\}$ . Then after 8-pass and 5-pass, 3-sorting for the array will always be efficient. Moreover, we know that after 3-sorting and 5-sorting, an array gets 8-sorted  $(1\cdot 3+1\cdot 5)$  automatically. However, the elements at gaps 2, 4 or 7 will never be compared.

So it is better to construct a gap sequence with pairwise co-prime integers

Short title

Pritam Dey Ayan Paul

Introductio

Some Usefu Definitions

Frobenius Problem

Time complexity

Ciura's sequentia analysis

Comparing Efficiency

Comparison of different methods

- Any gap sequence that includes 1 yields a correct sort.
- Given the length of the array, the gap sequence should not be too large or too small.
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Short title

Pritam Dey Ayan Paul

Introductio

Some Usefu Definitions

Frobenius Problem

Time complexity

Ciura's sequentia

Comparing Efficiency

Comparison of different methods

Conclusio

#### Shell's Sequence

**Year of Publication**: 1959

**General Term**:  $\lfloor \frac{N}{2^k} \rfloor$ 

Concrete Gaps:  $\left[\frac{N}{2}\right], \left\lfloor\frac{N}{4}\right\rfloor, ..., 1$ 

Worst Case Time Complexity:  $\Theta(N^2)$ 

#### Frank and Lazarus's Sequence

**Year of Publication**: 1960

General Term:  $2\lfloor \frac{N}{2^{2^{k+1}}} \rfloor + 1$ 

Concrete Gaps:  $2\lfloor \frac{N}{4} \rfloor + 1, ..., 3, 1$ 

Worst Case Time Complexity:  $\Theta(N^{\frac{3}{2}})$ 

Short title

Pritam Dey Ayan Paul

Introduction

Some Usefu Definitions

Frobenius Problem

Time complexity

Ciura's sequentia analysis

Comparing Efficiency

Comparison o different methods

Conclusion

#### Hibbard's Sequence

**Year of Publication**: 1963

**General Term**:  $2^k - 1$ 

**Concrete Gaps**: 1, 3, 7, 15, 31, 63, ...

Worst Case Time Complexity:  $\Theta(N^{\frac{3}{2}})$ 

#### Papernov and Stasevich's Sequence

**Year of Publication**: 1965

**General Term**:  $2^k + 1$ , prefixed with 1 **Concrete Gaps**: 1, 3, 5, 9, 17, 33, 65, ... **Worst Case Time Complexity**:  $\Theta(N^{\frac{3}{2}})$ 

Short title

Pritam Dey Ayan Paul

Introduction

Some Usefu Definitions

Frobenius Problem

Time complexity

Ciura's sequentia analysis

Comparing Efficiency

Comparison o different methods

Conclusi

#### Pratt's Sequence

**Year of Publication**: 1971

General Term:

Successive numbers of the form  $2^p3^q$  (3 – smooth Numbers)

**Concrete Gaps**: 1, 2, 3, 4, 6, 8, 9, 12, ....

Worst Case Time Complexity:  $\Theta(N \log_2 N)$ 

#### Knuth's Sequence

**Year of Publication**: 1973, based on **Pratt**'s sequence.

**General Term**:  $\frac{3^k-1}{2}$ , not greater than  $\lceil \frac{N}{3} \rceil$ 

**Concrete Gaps**: 1, 4, 13, 40, 121, ....

Worst Case Time Complexity:  $\Theta(N^{\frac{3}{2}})$ 

Short title

Pritam Dey Ayan Paul

Introduction

Some Usefu Definitions

Frobenius Problem

Time complexity

Ciura's sequentia analysis

Comparing Efficiency

Comparison o different methods

Conclusion

#### Incerpi and Sedgewick's Sequence

Year of Publication: 1985

General Term:

$$\prod_{I} a_{q}, \text{ where } a_{q} = \min\{n \in \mathbb{N} : n \geqslant (5/2)^{q+1} \ \forall p : 0 \leqslant p < q \implies \gcd(a_{p}, n) = 1\}$$

$$I = \{ 0 \leqslant q < r | \ q \neq \frac{(r^{2}+r)}{2} - k \}$$

$$r = \left\{ \begin{array}{l} 0 \leqslant q \leqslant r \mid q \neq \frac{1}{2} - k \right\} \\ r = \left| \sqrt{2k + \sqrt{2k}} \right| \end{array}$$

Worst Case Time Complexity:  $\Theta(N^{1+\sqrt{\frac{8\log(\frac{5}{2})}{\log N}}})$ 

Short title

Pritam Dey Ayan Paul

Introduction

Some Usefu Definitions

Frobenius Problem

Time complexity

Ciura's sequential analysis

Comparing Efficiency

Comparison of different methods

Conclusion

#### Sedgewick's First Sequence

**Year of Publication**: 1982

**General Term**:  $4^k + 3.2^{k-1} + 1$ , prefixed with 1

**Concrete Gaps**: 1, 8, 23, 77, 281, ....

Worst Case Time Complexity:  $\Theta(N^{\frac{4}{3}})$ 

Short title

Pritam Dey Ayan Paul

Introductio

Some Usefu Definitions

Frobenius Problem

Time complexity

Ciura's sequentia analysis

Comparing Efficiency

Comparison of different methods

Conclus

#### Sedgewick's Second Sequence

Year of Publication: 1986

**General Term:** 

$$9(2^k - 2^{k/2}) + 1$$
; k even

 $8.2^k - 6.2^{(k+1)/2} + 1$ ; k odd

**Concrete Gaps**: 1, 5, 19, 41, 109, ...

Worst Case Time Complexity:  $\Theta(N^{\frac{4}{3}})$ 

#### Gonnet and Baeza-Yates's Sequence

Year of Publication: 1991

**General Term:** 

$$h_k = max\{\lfloor \frac{5h_{k-1}}{11} \rfloor, 1\}, h_0 = N$$

Concrete Gaps:  $\lfloor \frac{5N}{11} \rfloor$ ,  $\lfloor \frac{5}{11} \lfloor \frac{5N}{11} \rfloor \rfloor$ , ...., 1

Worst Case Time Complexity: *Unknown* 

Short title

Pritam Dey Ayan Paul

Introductior

Some Usefu Definitions

Frobenius Problem

Time complexity

Ciura's sequentia analysis

Comparing Efficiency

Comparison o different methods

Conclusion

#### Tokuda's Sequence

**Year of Publication**: 1992

**General Term**:  $\left[\frac{1}{5}(9.(\frac{9}{4})^{k-1}-4)\right]$ 

**Concrete Gaps**: 1, 4, 9, 20, 46, 103, ....

Worst Case Time Complexity: Unknown

#### Ciura's Sequence

**Year of Publication**: 2001

**General Term**: Unknown(Experimentally Derived)

**Concrete Gaps**: 1, 4, 10, 23, 57, 132, 301, 701

Worst Case Time Complexity: Unknown

Short title

Pritam Dey Ayan Paul

Introduction

Some Usefu

Froblem

Problem

Time

Ciura's sequential analysis

Comparing Efficiency

Comparison o different methods

Conclusion

Ciura showed that the number of comparisons made by Shell Sort algorithm for a particular gap sequence follows approximately a normal distribution.

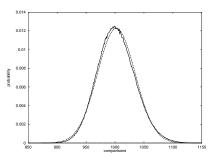


Fig. 2. Distribution of the number of comparisons in Shellsort using the sequence (1, 4, 9, 24, 85) for sorting 128 elements (solid line), and the normal distribution with the same mean and standard devistion (dashed line)

Short title

Pritam Dey Ayan Paul

Introduction

Some Usefu Definitions

Frobenius Problem

Time complexity

Ciura's sequential analysis

Comparing Efficiency

Comparison o

- For all the arrays of a particular size, Ciura based on his experience conjectured some lower and upper cut off points  $\theta_0$  and  $\theta_1$  respectively.
- setting  $\alpha=0.01$  (accidental rejection of a good sequence) and  $\beta=0.01$  (accidental acceptance of a bad sequence) he continued the test procedure for gap sequences of length  $2,3,4,\ldots$
- With each sequence probed, he performed Shell sort on randomly generated permutations and added the number of comparisons( $c_i$ ) at each trial. He performed each test as long as

Short title

Pritam Dey Ayan Paul

Introduction

Some Usefu Definitions

Frobenius Problem

Time complexity

Ciura's sequential analysis

Comparing Efficiency

Comparison o different

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Short title

Pritam Dey Ayan Paul

Introduction

Some Usefu Definitions

Frobenius Problem

Time complexity

Ciura's sequential analysis

Comparing Efficiency

Comparison o different

- For all the arrays of a particular size, Ciura based on his experience conjectured some lower and upper cut off points  $\theta_0$  and  $\theta_1$  respectively.
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# Sequential test

Short title

Pritam Dey Ayan Paul

Introduction

Some Useful Definitions

Frobenius Problem

Time complexity

Ciura's sequential analysis

Comparing Efficiency

Comparison o different methods

Conclusion

$$a_k = \frac{\sigma_{max}^2}{\theta_1 - \theta_0} ln \frac{\beta}{1 - \alpha} + k \frac{\theta_0 + \theta_1}{2} \le \sum_{i=1}^k c_i$$

$$r_k = \frac{\sigma_{max}^2}{\theta_1 - \theta_0} \ln \frac{1 - \beta}{\alpha} + k \frac{\theta_0 + \theta_1}{2} \ge \sum_{i=1}^k c_i$$

Here  $\theta_0$  and  $\theta_1$  are his conjectured constants for a given length of gap-sequences.

A gap sequence is considered as a good (or bad) gap sequence if average number of comparisons made by the sequence is less than  $\theta_0$  (or more than  $\theta_1$ )

# Dominant Operation in Shell sort

Short title

Pritam Dey Ayan Paul

Introduction

Some Usefu Definitions

Frobenius Problem

Time complexity

Ciura's sequential analysis

Comparing Efficiency

Comparison of different methods

Conclusion

Ciura claimed that comparisons rather than moves should be considered the dominant operation in Shellsort. And searched for a sequence which has fewer comparisons than any other sequence for arrays of size up to 8000. Here are the results of his experiment.

Table 4. The best 8-increment beginnings of 10-pass sequences for sorting 8000 elements

	Increments	Ratio passed
1 4 10	23 57 132 301 75	8 0.6798
1 4 10	23 57 132 301 70	1 - 0.6756
1 4 10	21 56 125 288 71	7 0.6607
1 4 10	23 57 132 301 72	1 - 0.6573
1 4 10	23 57 132 301 71	0.6553
14 9	24 58 129 311 73	9 0.6470
1 4 10	23 57 132 313 72	6 0.6401
1 4 10	21 56 125 288 66	1 0.6335
1 4 10	23 57 122 288 69	
		4 D > -

# Comparing efficiency of some latest gap-sequences

Short title

Pritam Dey Ayan Paul

Introduction

Some Usefu Definitions

Frobenius Problem

Time complexity

Ciura's sequentia analysis

Comparing Efficiency

Comparison of different methods

Conclusion

We have used three different plots to compare the sorting methods. We have plotted the following variables against length of array in each plot.

 $\frac{Average number of comparisons}{log_2N!}$ 

Average number of element swaps or value assignment log<sub>2</sub>N!

Average time taken by the algorithm NlogN

## Number of comparisons

Short title

Pritam Dey Ayan Paul

Introduction

Some Usefu Definitions

Froblem

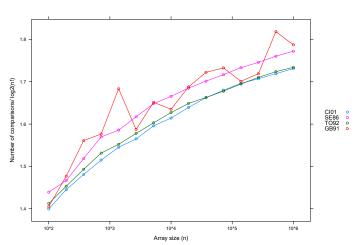
Time complexity

Ciura's sequentia analysis

Comparing Efficiency

Comparison of different methods

Figure: Number of comparisons for different gap sequences



## Number of comparisons

Short title

Pritam Dey Ayan Paul

Introduction

Some Usefu Definitions

Froblem

Time

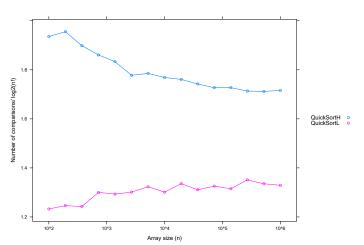
Ciura's sequentia analysis

Comparing Efficiency

Comparison of different methods

Conclusion

Figure: Number of comparisons for different partioning schemes



## Number of comparisons

Short title

Pritam Dey Ayan Paul

Introduction

Some Usefu Definitions

Froblem

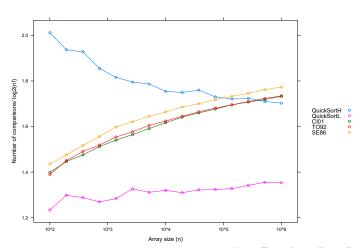
Time complexity

Ciura's sequentia analysis

Comparing Efficiency

Comparison of different methods

Figure: ShellSort vs QuickSort — Number of comparisons



# Number of Assignments/Swaps

Short title

Pritam Dey Ayan Paul

Introduction

Some Useful Definitions

Froblem

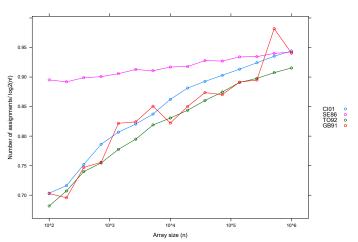
Time complexity

Ciura's sequentia analysis

Comparing Efficiency

Comparison of different methods

Figure: Number of assignments for different gap sequences



# Number of Assignments/Swaps

Short title

Pritam Dey Ayan Paul

ntroduction

Some Usefu Definitions

Froblem

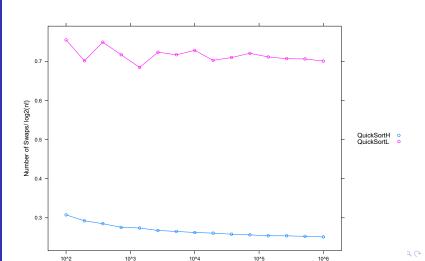
Time

Ciura's sequentia analysis

Comparing Efficiency

Comparison of different methods

Figure: Number of assignments for different gap sequences



# Number of Assignments/Swaps

Short title

Pritam Dey Ayan Paul

Introduction

Some Usefu

Froblem

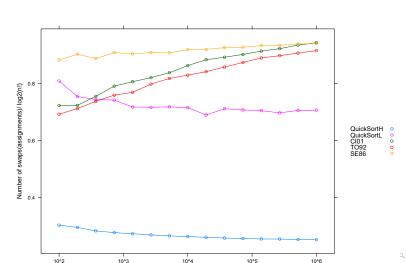
Time

Ciura's sequential analysis

Comparing Efficiency

Comparison of different methods

Figure: QuickSort vs ShellSort — Assignments/Swaps



# Running Time

Short title

Pritam Dey Ayan Paul

Introduction

Some Usefu

Froblem

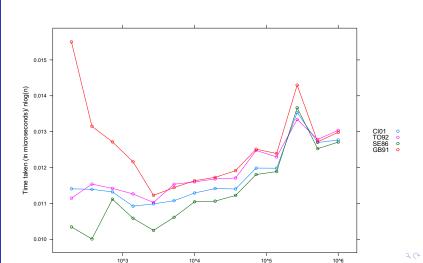
Time

Ciura's sequentia analysis

Comparing Efficiency

Comparison of different methods

Figure: Time comparison between different gap sequences



# Running Time

Short title

Pritam Dey Ayan Paul

ntroduction

Some Useful Definitions

Frobenius Problem

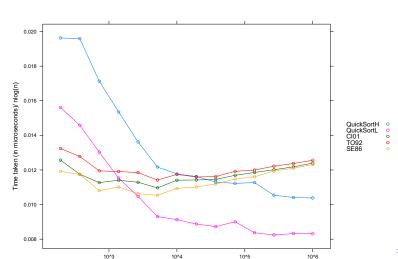
Time complexity

Ciura's sequential analysis

Comparing Efficiency

Comparison of different methods

Figure: QuickSort vs ShellSort — Time



#### **Conclusions**

Short title

Pritam Dey Ayan Paul

Introductio

Some Usefu Definitions

Frobenius Problem

Time complexity

Ciura's sequentia analysis

Comparing Efficiency

Comparison of different methods

- For smaller arrays (length  $< 10^3$ ) Shell sort performs better than Quick sort algorithms.
- When array size increases, Quick sort becomes more efficient.
- Evidently the efficiency of insertion sort for small arrays has been extended to quite large arrays. (10³)
- The partitioning scheme used in this project can be improved in different ways by choosing better algorithms for selecting the pivot.