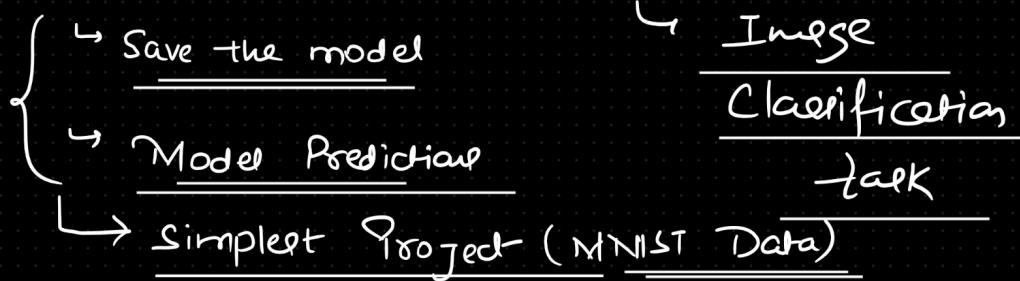
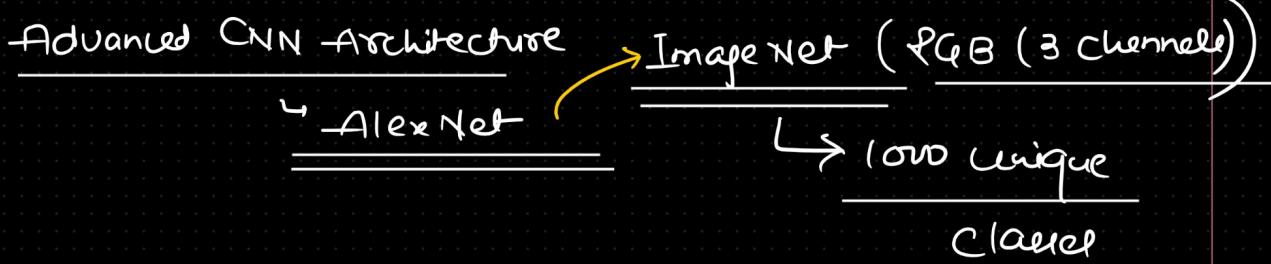


Advanced CNN - Architecture



Advanced CNN - Architecture



```
## Layer 1: Conv + MaxPooling
model_alexnet.add(layers.Conv2D(96, (11, 11), strides=(4,4), activation='relu',
input_shape=input_shape))
model_alexnet.add(layers.MaxPooling2D(pool_size=(3, 3), strides=(2, 2)))
```

```
## Layer 2: Conv + MaxPooling
model_alexnet.add(layers.Conv2D(256, (5,5), padding='same', activation='relu'))
model_alexnet.add(layers.MaxPooling2D(pool_size=(3, 3), strides=(2, 2)))
```

```
## Layer 3: Conv
model_alexnet.add(layers.Conv2D(384, (3,3), padding='same', activation='relu'))
```

```
## Layer 4: Conv
model_alexnet.add(layers.Conv2D(384, (3,3), padding='same', activation='relu'))
```

```
## Layer 5: Conv + MaxPooling
model_alexnet.add(layers.Conv2D(256, (3,3), padding='same', activation='relu'))
model_alexnet.add(layers.MaxPooling2D(pool_size=(3, 3), strides=(2, 2)))
```

Conv +
Maxpooling

Conv

Conv + Maxpooling

Neural Network - Architecture

```
## Flatten and Dense Layers
```

```
model_alexnet.add(layers.Flatten())
```

```
model_alexnet.add(layers.Dense(4096, activation='relu'))
```

to avoid overfitting

```
model_alexnet.add(layers.Dropout(0.5))
```

```
model_alexnet.add(layers.Dense(4096, activation='relu'))
```

to avoid overfitting

```
model_alexnet.add(layers.Dropout(0.5))
```

Input layer

Hidden layer

Dropout

→ Reduce

overfitting

$\text{Error} = \text{Bias} + \text{Variance}$

Low Bias &

High Variance

{ What might be the possible
reasons of overfitting ??
(DL context)

Validation set → stops the training when early stopping

① Too much training

Performance → stops improving

② Insufficient training data

flipping, augmentation

rotation, (Healthcare)

Cropping of

Domain)

similar original

images)

③ Noisy or irrelevant data

④ Lack of Regularisation

(L1, L2 (Lasso,

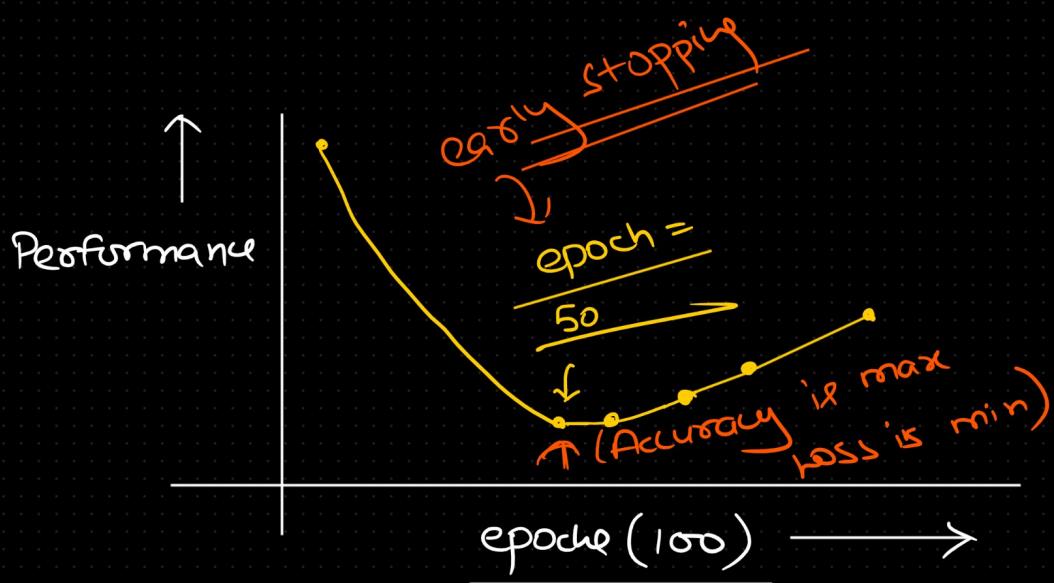
Ridge))

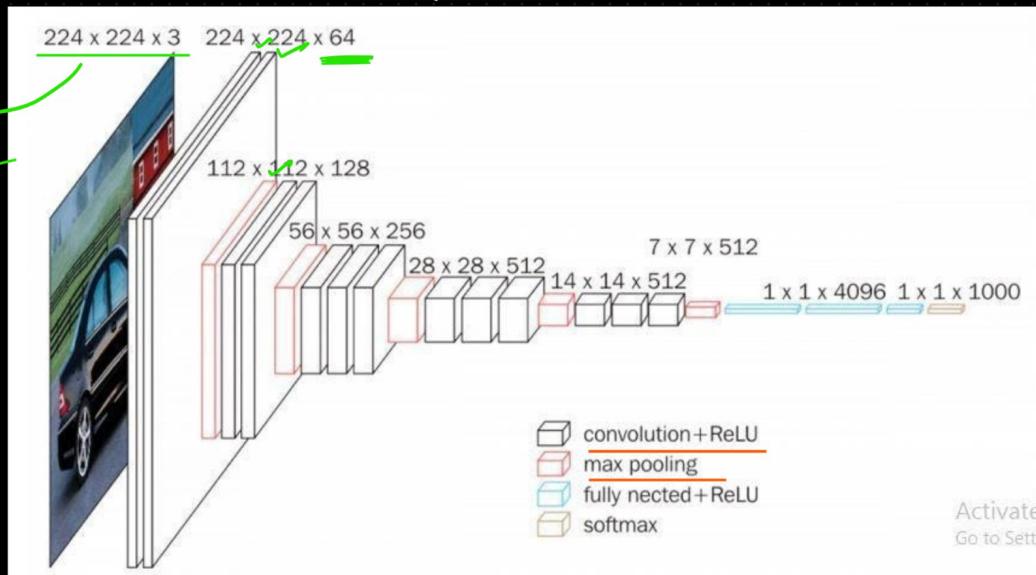
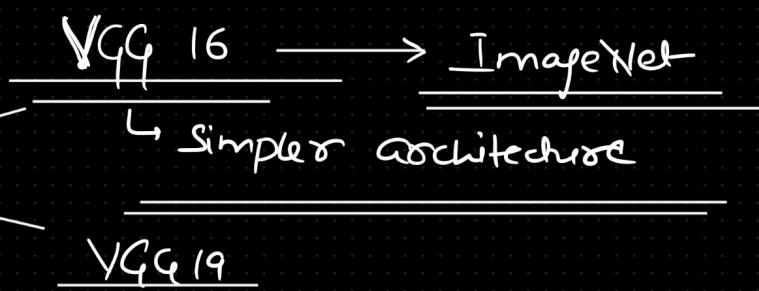
Dropout

Pseudonymly deactivate neurons

during training

- 5 Poor hyperparameter tuning
(Learning Rate
Batch Size)





→ Convolutional Layer

↳ Filter size = 3×3

Stride = 1

→ Padding = 'Same' (input &

output

image dimensions

are same)

Standardize

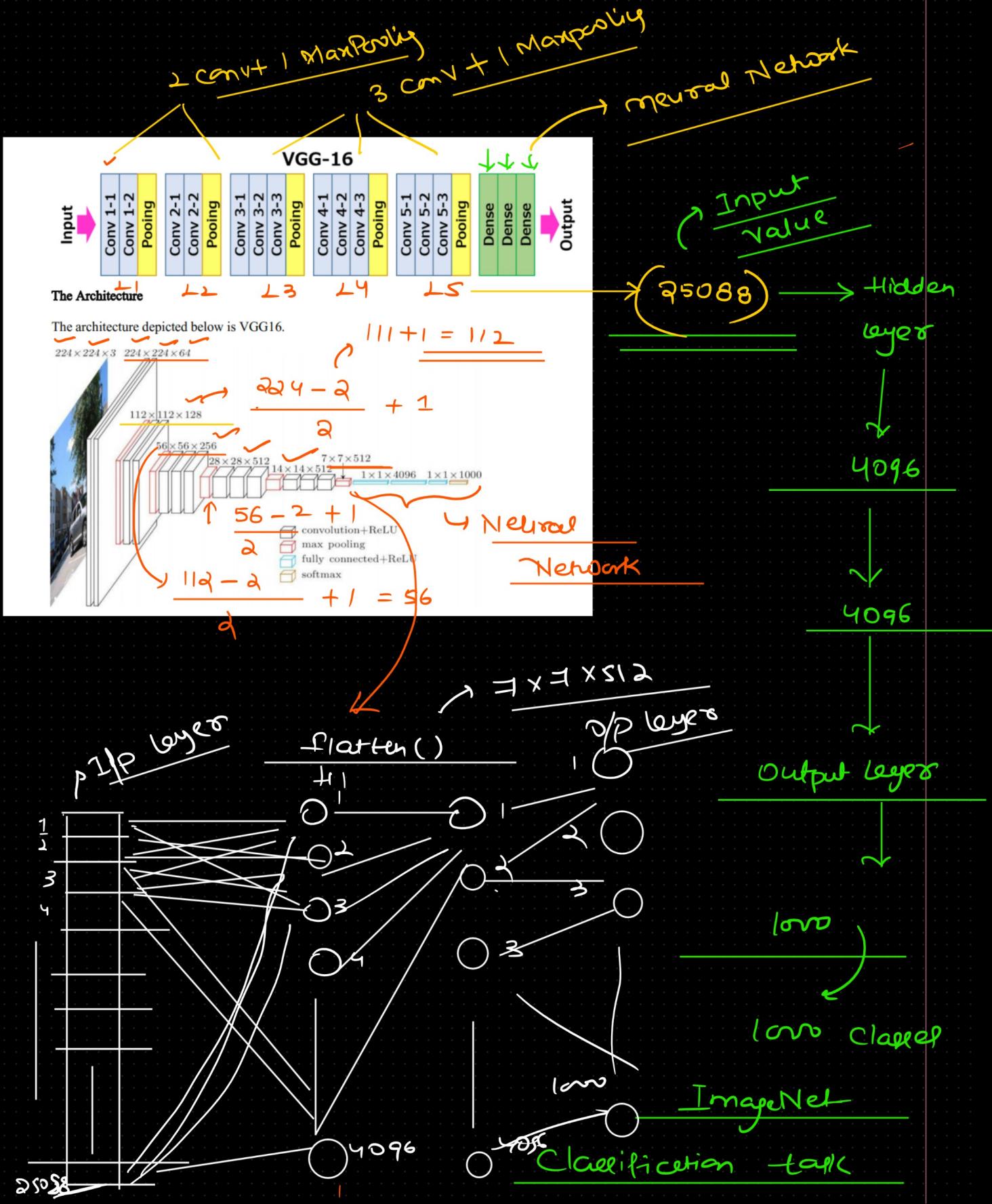
the values

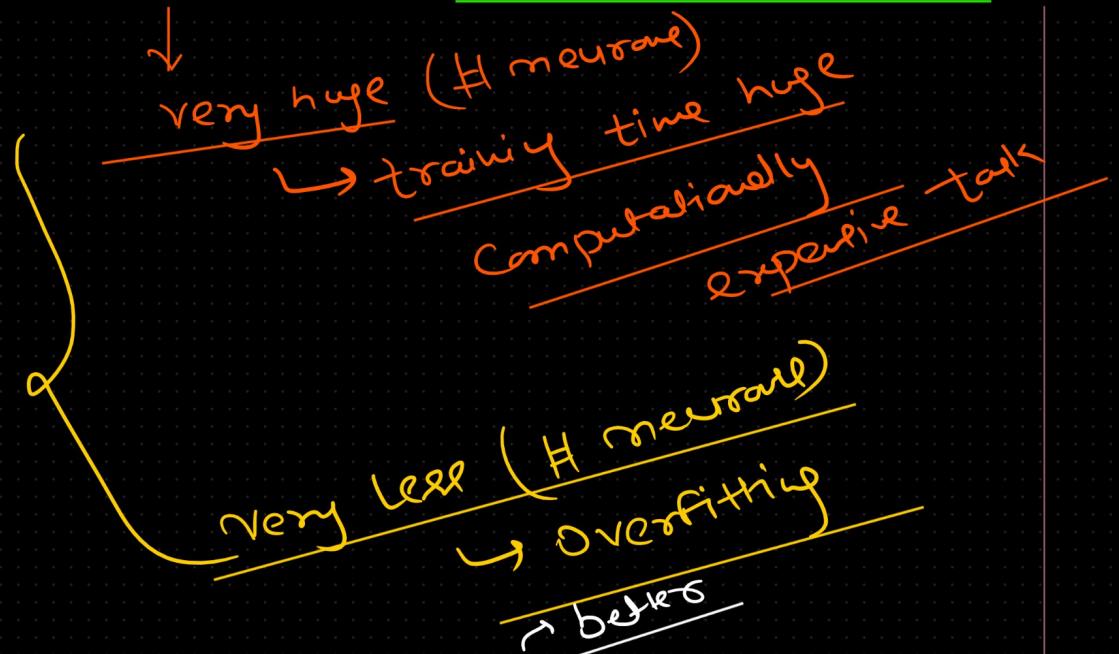
→ MaxPooling Layer

↳ Filter = 2×2

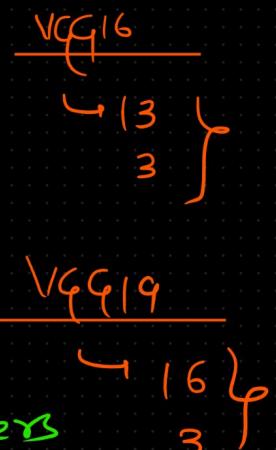
Stride = 2

$$\Rightarrow \left| \frac{\gamma - f + 2p}{s} \right| + 1$$





Feature	AlexNet (2012)	VGG16 (2014)
Total Parameters	~60M ✓	~138M ✓
Convolution Layers	5	13 (VGG16), 16 (VGG19)
Fully Connected Layers	3 ✓	3 ✓
Kernel Sizes	11x11, 5x5, 3x3	Only 3x3
Max Pooling	3x3, stride 2	2x2, stride 2
Activation Function	ReLU ✓	ReLU ✓
Dropout	Yes ✓	Yes ✓
Final Classifier	Softmax (1000 classes) ✓	Softmax (1000 classes) ✓



VGG16 better than AlexNet
easier to understand & implement

extract more complex & hierarchical features

better in terms of performance

better performance

in recognizing fine details in an image

Transfer Learning

RESNET → Task to explore & do

Some research on your

Own -