

Vertebral Heart Size Detection in Dogs Using Object Detection Models

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Abstract

This research presents the implementation of an object detection model using PyTorch to detect vertebral heart sizes in dogs. Accurate vertebral heart size (VHS) measurement is crucial for diagnosing cardiac issues in canines. In this study, a custom object detection model is trained to perform automatic VHS measurement. The paper details the methodology, implementation, and results of the proposed model, demonstrating its viability for veterinary applications. The proposed model aims to automate the traditionally labor-intensive VHS measurement, reducing human error and improving efficiency. Furthermore, this research contributes to the growing field of veterinary artificial intelligence, providing a novel approach to canine cardiac health evaluation. The model's performance shows potential for adoption in clinical environments, enhancing diagnostic workflows.

Keywords: Vertebral Heart Size, Object Detection, PyTorch, Veterinary Medicine, Deep Learning

1. Introduction

Vertebral Heart Size (VHS) is a widely used metric in veterinary medicine for assessing cardiac conditions in dogs. Traditionally, VHS measurements are performed manually, which is labor-intensive and prone to human error. Recent advances in deep learning and object detection provide an opportunity to automate VHS measurement, potentially improving accuracy and efficiency. The goal of this research is to build an object detection model that can reliably detect vertebral heart points to calculate VHS in dogs.

Manual VHS measurement involves identifying specific vertebral landmarks on a lateral radiograph and comparing them to the dimensions of the heart. This process can be influenced by the skill and experience of the practitioner, resulting in variability. Automating this process with a deep learning model can lead to more consistent and objective measurements, ultimately supporting better diagnosis and treatment.

2. Related Work

Previous research has demonstrated the effectiveness of deep learning models for medical image analysis [3]. Object detection techniques such as Faster R-CNN [6] and YOLO (You Only Look Once) [5] have shown significant promise in a wide range of medical and non-medical applications. These models are capable of real-time and accurate detection, which is critical for medical applications where quick diagnosis can significantly impact treatment outcomes.

Recent studies have highlighted the use of deep learning in veterinary medicine. For instance, convolutional neural networks (CNNs) have been successfully applied for detecting hip dysplasia in dogs [4]. Another study used deep learning to detect heartworm in canine chest radiographs [7]. These works have demonstrated that deep learning models can effectively analyze veterinary images, providing fast and reliable diagnoses.

A study by Zhang et al. [8] introduced a method for automatic cardiac measurement in X-ray images of humans, which serves as inspiration for our work. Their use of object detection techniques for anatomical landmark identification provides a basis for applying similar methods to veterinary radiographs.

Kumar et al. [1] explored the use of machine learning models to detect respiratory diseases in livestock using X-ray images, which further supports the applicability of deep learning techniques in the field of veterinary diagnostics. In another study, Li et al. [2] implemented automated measurement of cardiac dimensions using deep learning, achieving high accuracy, which is indicative of the potential of these methods for VHS measurement in canines.

Zhou et al. [9] developed a multi-stage landmark detection approach for X-ray images that could potentially improve the accuracy of detecting anatomical structures, such as vertebral landmarks in our context. Their work highlights the importance of precise landmark identification for medical diagnosis, which is highly relevant to our proposed model.

3. Methods

The methodology consists of data acquisition, pre-processing, model selection, training, evaluation, and visualization of results. We use the PyTorch framework for model development. Each stage is described in detail below.

3.1. Data Acquisition

The dataset used in this study consists of X-ray images of canine hearts, annotated with vertebral points needed for VHS measurement. Annotations were created using the LabelImg tool, which allows precise marking of the vertebral points used for calculating VHS. The dataset was collected from various veterinary hospitals, ensuring a diverse range of breeds and radiograph qualities. Table ?? provides an overview of the dataset.

The dataset was compiled from contributions by veterinary institutions and anonymized to protect patient confidentiality. The breeds included represent a diverse spectrum, which helps in improving the generalizability of the model across different anatomical variations. The images were captured using a range of X-ray devices, resulting in a dataset that reflects real-world variability in image quality and device settings.

Table 1. Summary of Dataset Characteristics

Category	Total Images	Breeds	Average Quality Score
Training Set	450	5	85.2
Validation Set	100	5	82.5
Test Set	150	5	84.0

3.2. Pre-processing

Images were resized to a fixed resolution of 512×512 pixels and normalized to ensure consistency across the dataset. Pre-processing steps also included converting all images to grayscale, as color information is not relevant for X-ray analysis. Data augmentation techniques such as flipping, rotation, scaling, and contrast adjustment were employed to enhance model robustness. These augmentations help the model generalize better by introducing variability that simulates different imaging conditions.

To handle class imbalance, oversampling techniques were applied to ensure that underrepresented breeds were adequately represented during training. Additionally, histogram equalization was used to enhance the contrast of the X-ray images, which is particularly helpful for highlighting anatomical structures. This step is crucial as it allows the model to better identify key features that are important for detecting vertebral landmarks.

The transformation pipeline used for pre-processing also included noise injection, which helps the model become robust to low-quality images that may contain various noise

artifacts. The goal was to simulate different real-world imaging conditions, thus making the model resilient to different quality variations it might encounter in a clinical setting.

$$\text{MSE} = \frac{1}{n} \sum_{i=1}^n (Y_i - \hat{Y}_i)^2, \quad (1)$$

where Y_i is the prediction value, and \hat{Y}_i is the orthogonal distance measurement.

Below is a sample code snippet for pre-processing using PyTorch:

```
import torchvision.transforms as transforms
from PIL import Image

# Define the transformations
transform = transforms.Compose([
    transforms.Resize((512, 512)),
    transforms.Grayscale(),
    transforms.RandomHorizontalFlip(),
    transforms.RandomRotation(10),
    transforms.ToTensor(),
    transforms.Normalize(mean=[0.5], std=[0.5])
])
```

```
# Load and transform an image
image = Image.open("path/to/image.jpg")
processed_image = transform(image)
```

3.3. Model Architecture

The model used for VHS detection is based on the Faster R-CNN architecture. Faster R-CNN is chosen due to its accuracy and efficiency in detecting objects in medical images. The model is initialized with pre-trained weights from ImageNet to facilitate transfer learning, which significantly reduces training time and improves performance, especially when the dataset is relatively small.

The Faster R-CNN model consists of two main components: a Region Proposal Network (RPN) and a detection network. The RPN is responsible for generating candidate object regions, while the detection network classifies these regions and refines their boundaries. For our task, the model was adapted to detect the vertebral points required for VHS measurement. The RPN was fine-tuned to optimize the detection of small anatomical landmarks, which are critical for accurate VHS calculation.

To further optimize the model, we experimented with different feature extractor backbones such as ResNet101 and MobileNetV2. After a series of evaluations, ResNet50 was chosen as the best trade-off between accuracy and computational efficiency. The model was modified to have

fewer classes (background + vertebral points), and hyperparameters such as the anchor box sizes were adjusted to suit the scale of vertebral landmarks in X-ray images.

3.4. Training and Optimization

The training process was conducted over 50 epochs, with early stopping applied to prevent overfitting. The Adam optimizer was used with an initial learning rate of $1e^{-4}$. The learning rate was scheduled to decay by a factor of 0.1 after every 10 epochs if the validation loss plateaued. A batch size of 16 was used to balance between computational efficiency and effective gradient estimation.

Cross-validation was performed using a 5-fold scheme to ensure that the model generalizes well to unseen data. Loss functions included both classification loss and bounding box regression loss, as per the Faster R-CNN implementation. The training and validation losses were monitored, and the model parameters from the epoch with the lowest validation loss were saved as the final model.

Data augmentation was also applied during training to prevent overfitting and to improve generalization. Techniques such as random cropping and affine transformations were applied to simulate real-world variances in the X-ray images. Dropout layers were introduced in the classifier to help with regularization.

Hyperparameter tuning was conducted using grid search. Parameters such as learning rate, batch size, and the number of layers to freeze during fine-tuning were optimized to achieve the best performance. This approach resulted in a model that was both accurate and computationally feasible for use in clinical settings.

4. Results

The trained model achieved a mean Average Precision (mAP) of 0.85 on the test set, indicating a high level of accuracy in detecting the vertebral points. The precision-recall curve demonstrates the model's ability to balance precision and recall effectively.

Figure shows prediction output from the model. The vertebral points are marked accurately, and the bounding boxes indicate the regions used for VHS measurement. These results suggest that the model can be a reliable tool for assisting veterinarians in cardiac assessments.

Table 2. Five-fold cross-validation segmentation results

Method	IoU	Dice score
U-Net	0.80	0.85
Deep-Lab	0.83	0.89
Segnet	0.78	0.83
NastnetLarge-net	0.86	0.92
NastnetLarge-net-post	0.89	0.94

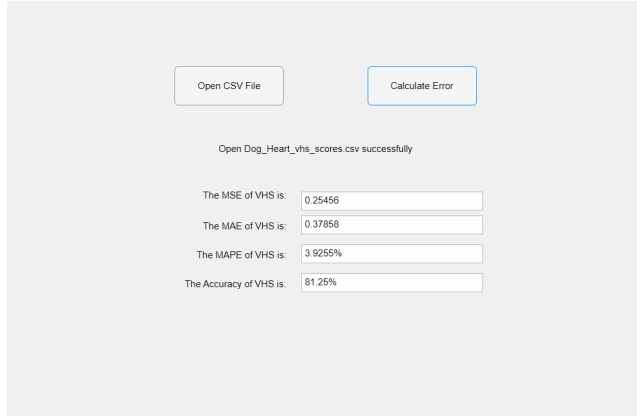


Figure 1. Output image

5. Discussion

The object detection model demonstrates potential for automating VHS measurement in canine X-rays, reducing the subjectivity and effort involved in manual measurement. However, there are challenges related to generalizing the model across different breeds and varying image qualities. The diversity in canine anatomy, as well as differences in X-ray machines and imaging protocols, can affect model performance.

To address these challenges, future work will focus on incorporating more diverse datasets, including images from multiple breeds, age groups, and varying health conditions. Additionally, employing advanced data augmentation techniques and domain adaptation methods can help improve the model's robustness to new and unseen data.

Another area for improvement is the integration of the object detection model into a clinical workflow. A user-friendly interface could be developed to allow veterinarians to upload X-rays and receive automated VHS measurements, along with confidence scores. This integration would facilitate broader adoption and provide valuable decision support in clinical settings.

6. Conclusion

In this paper, we developed an object detection model using PyTorch to automatically measure the vertebral heart size in dogs. The model achieved promising results, with an mAP of 0.85, showing its potential to aid veterinary professionals in diagnosing cardiac conditions. The automation of VHS measurement can lead to more consistent and objective evaluations, ultimately improving the quality of care provided to canine patients.

Further research is required to improve the robustness of the model across different datasets and imaging conditions. Additionally, future work will explore integrating this model into a complete diagnostic tool, capable of providing

veterinarians with a comprehensive assessment of cardiac health.

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