

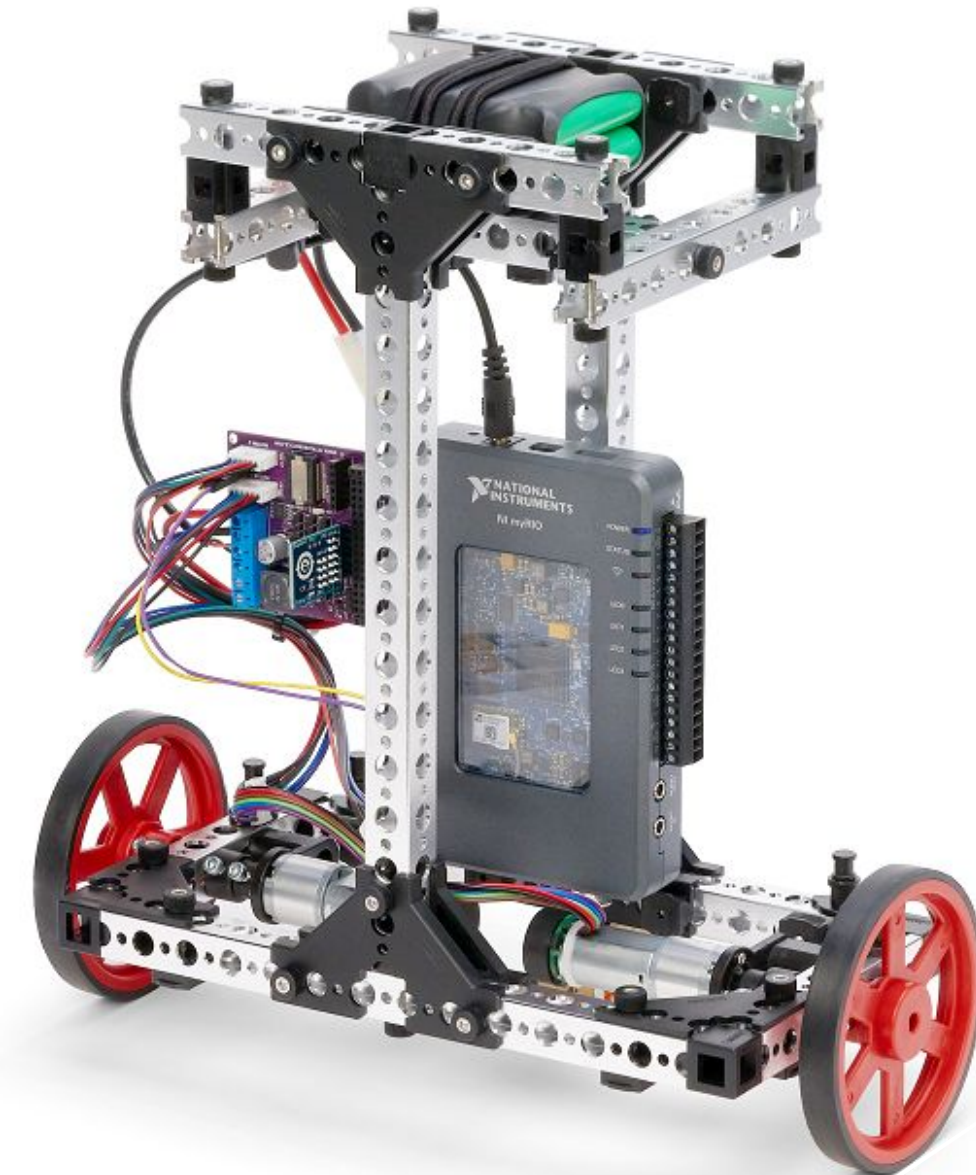
MICROPROCESSOR AND  
MICROCONTROLLER

# ASSIGNMENT PRESENTATION

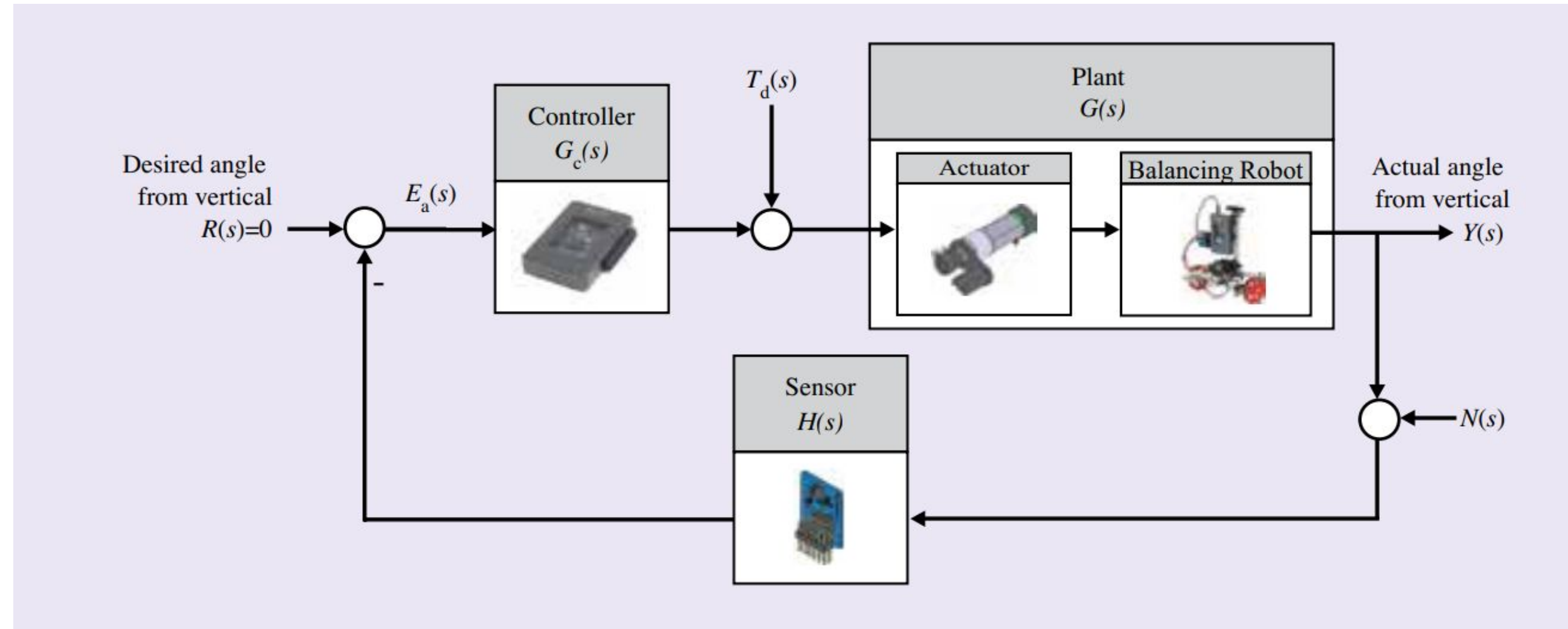


# SELF BALANCING

## ROBOT



# Working



|                   |  |
|-------------------|--|
| Plant             | Self-balancing robot   |
| Sensor            | Accelerometer, gyroscope, and encoder sensors  |
| Actuator          | DC servo motors  |
| Performance       | Robust stability, disturbance rejection, and measurement noise attenuation                   |
| Design objectives | Tune the control system by adjusting PD gain constants & stabilize the robot at the vertical |
| Reference inputs  | Regulation to zero angle (vertical pose)   |

# Robot assembling

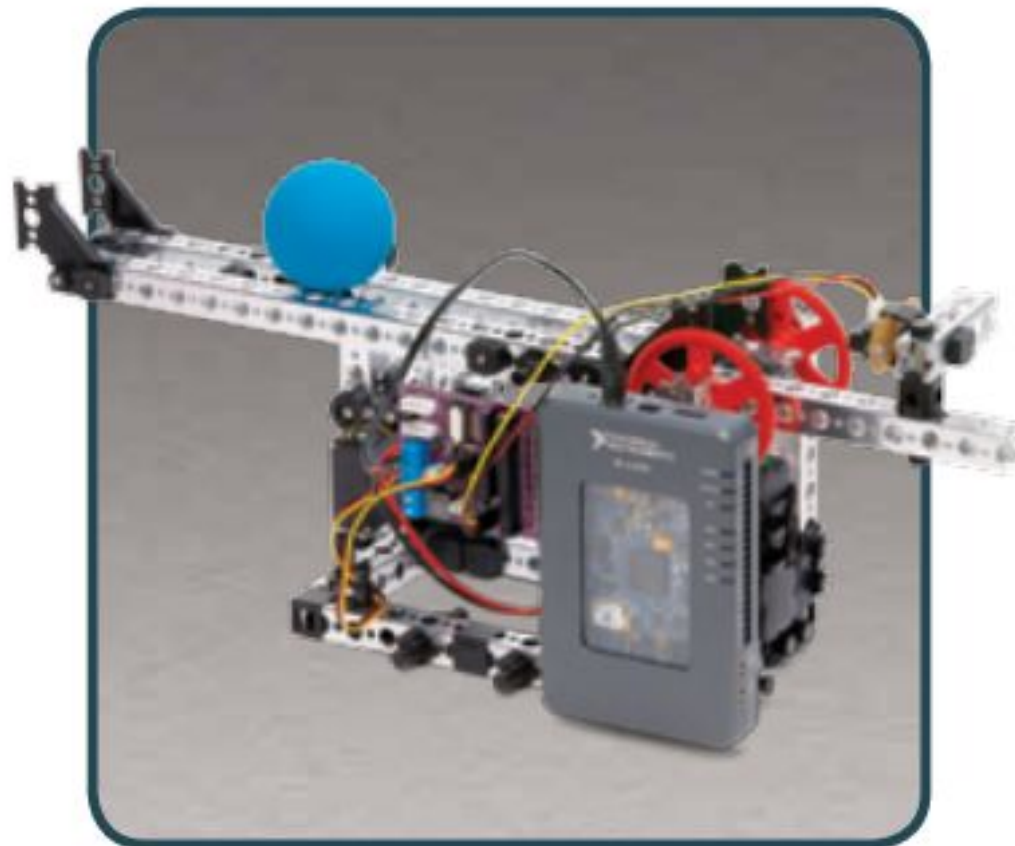
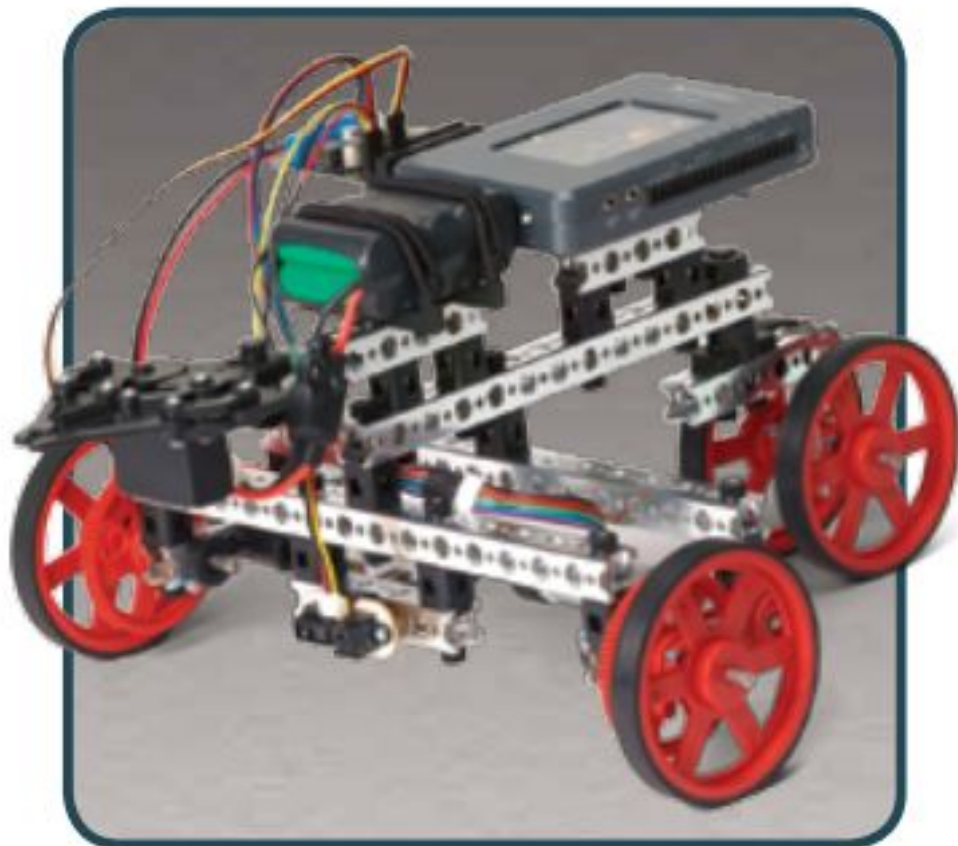






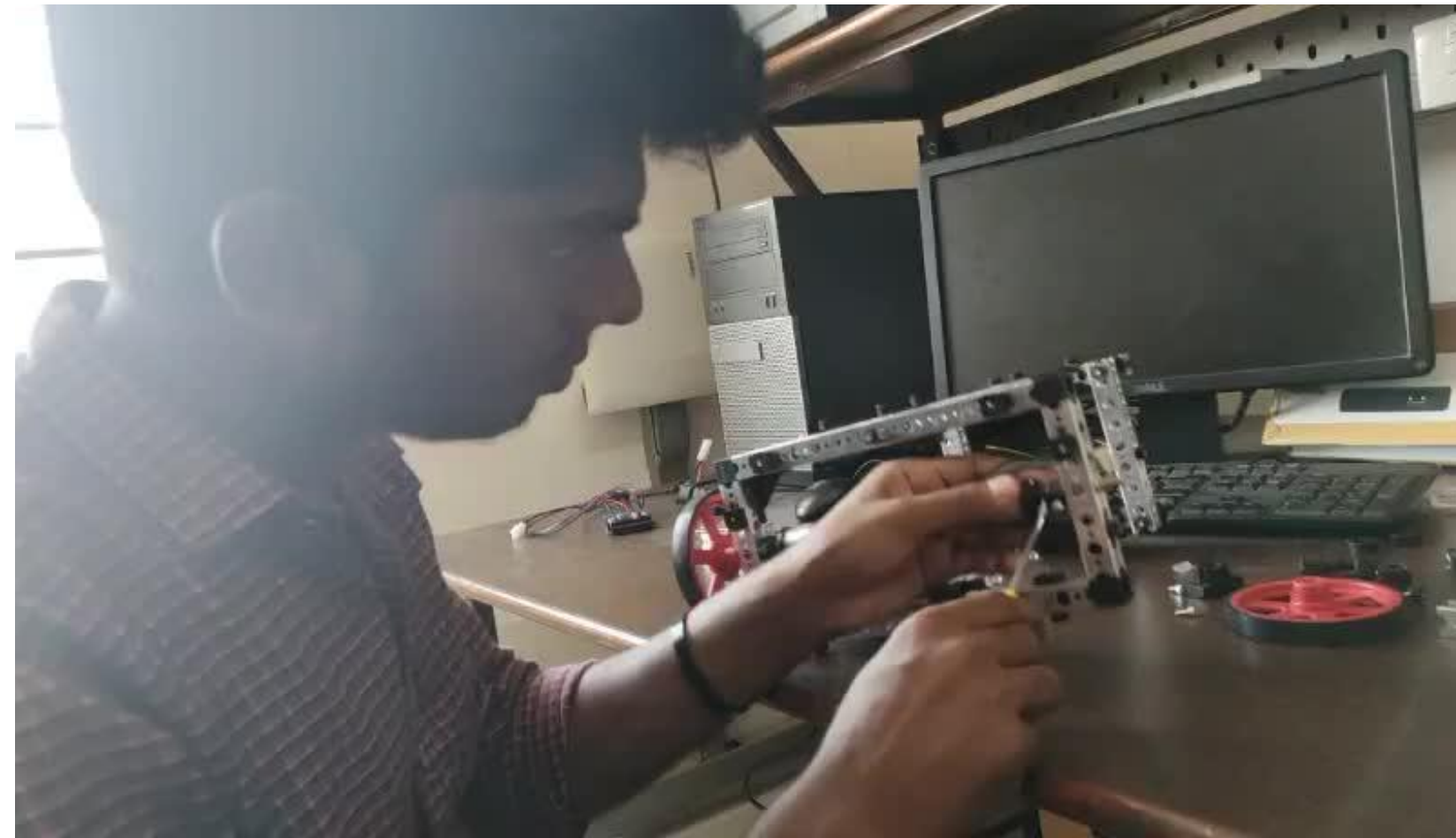
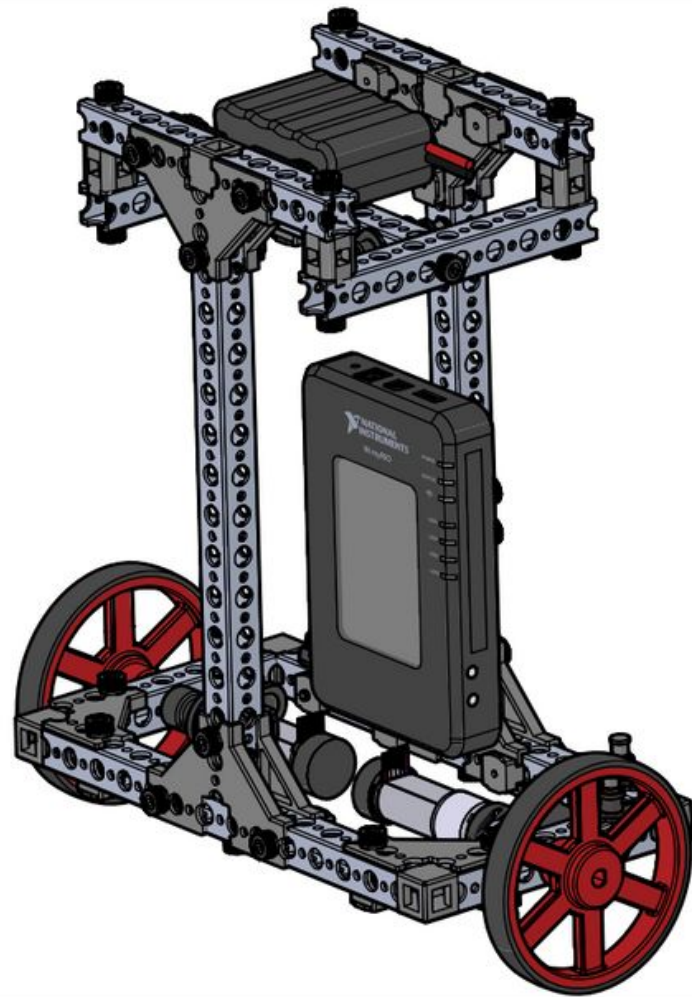
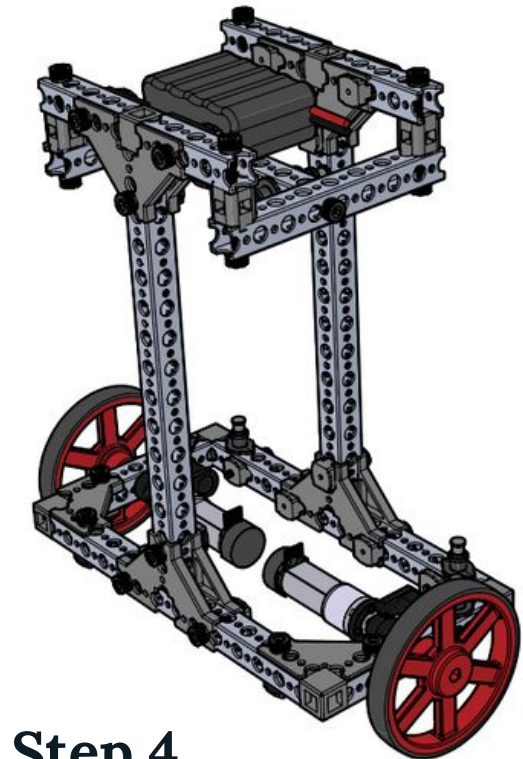
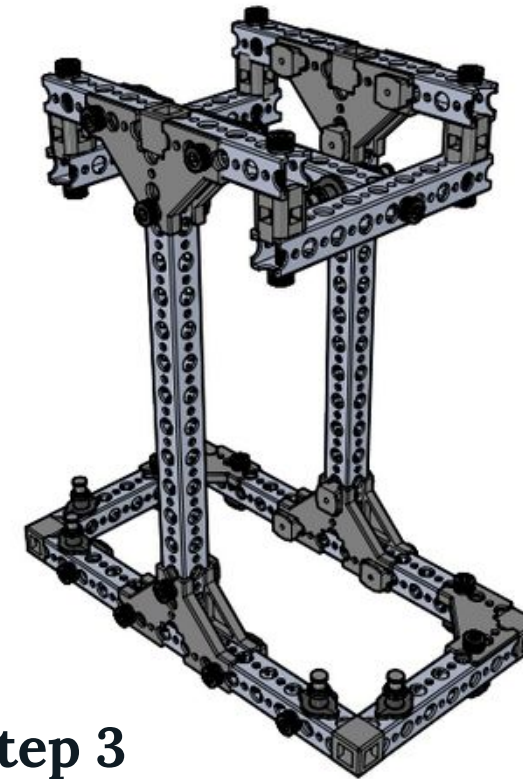
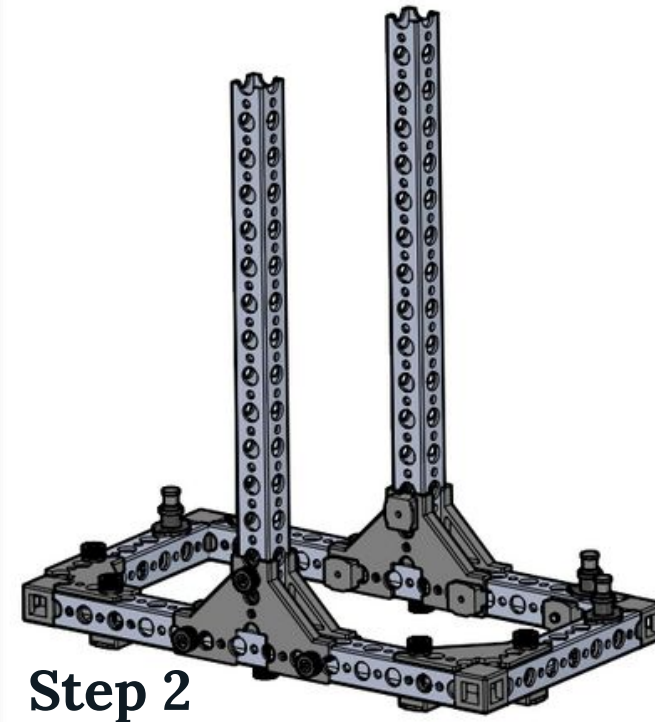
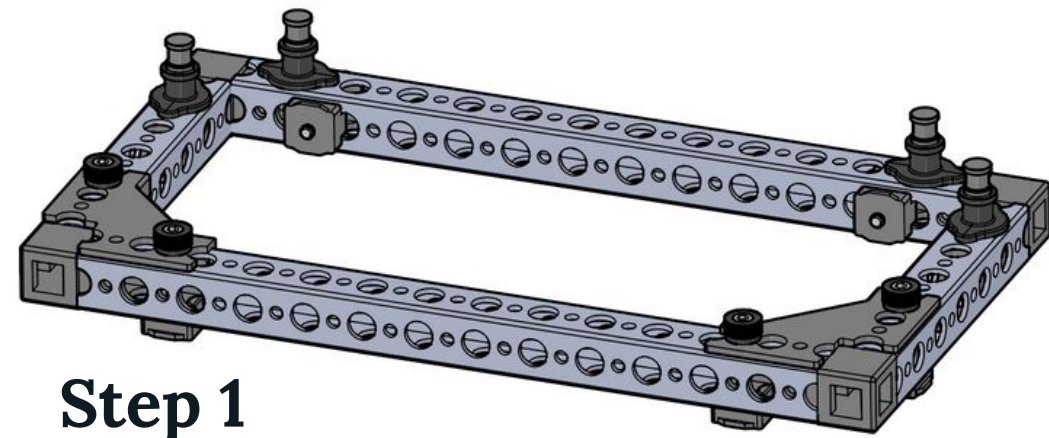
***Robot Builder's Guide***

**for NI myRIO**



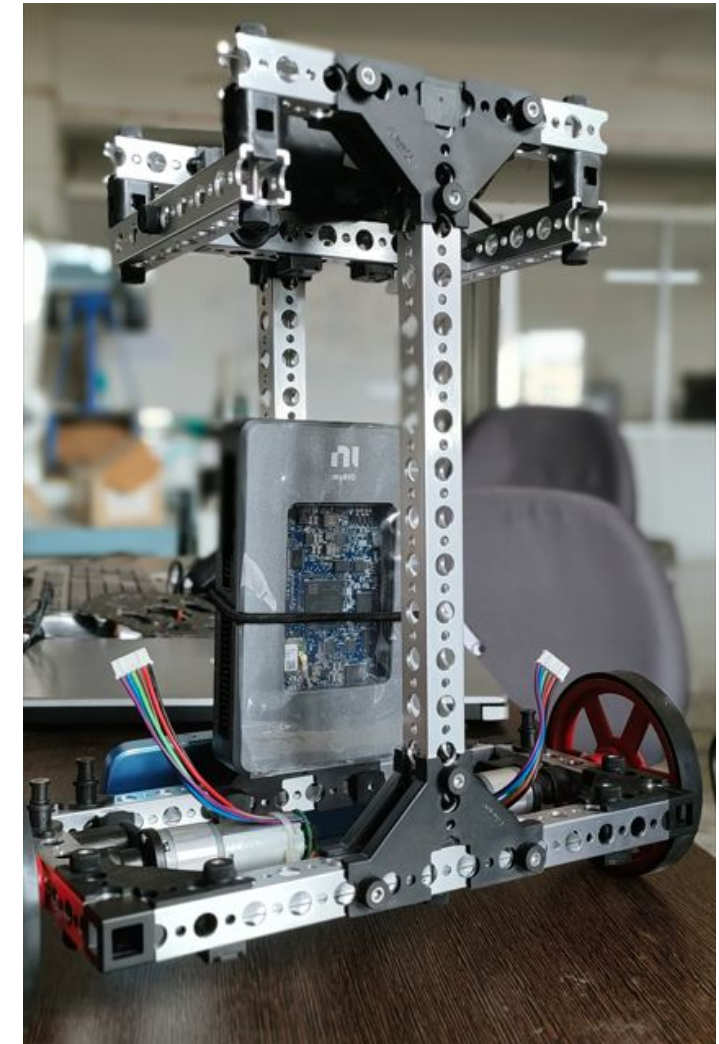
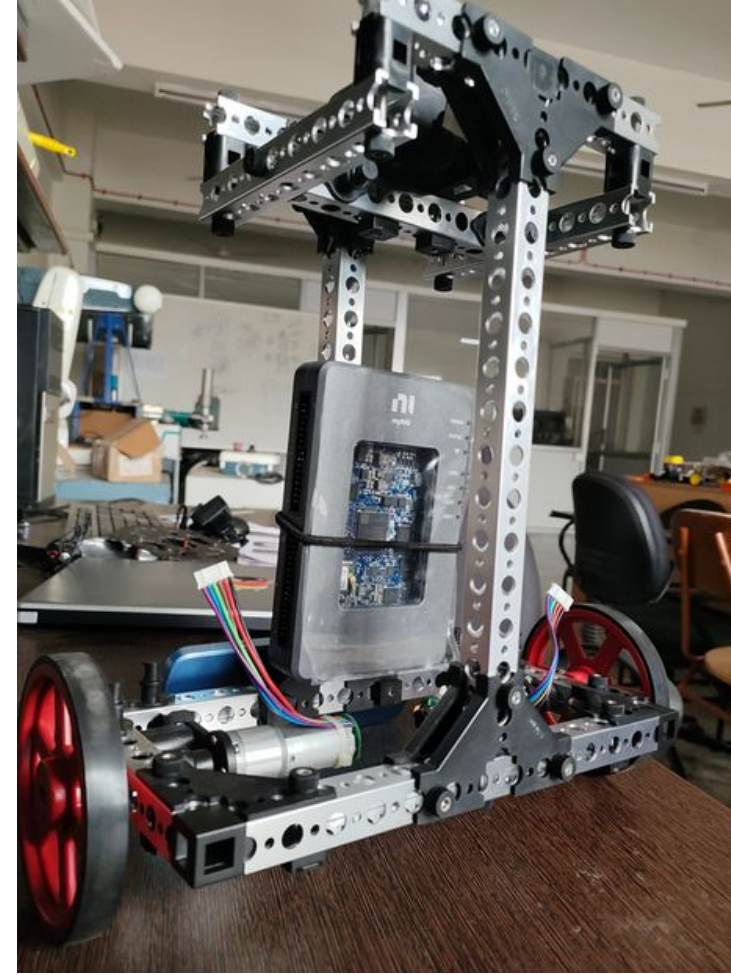
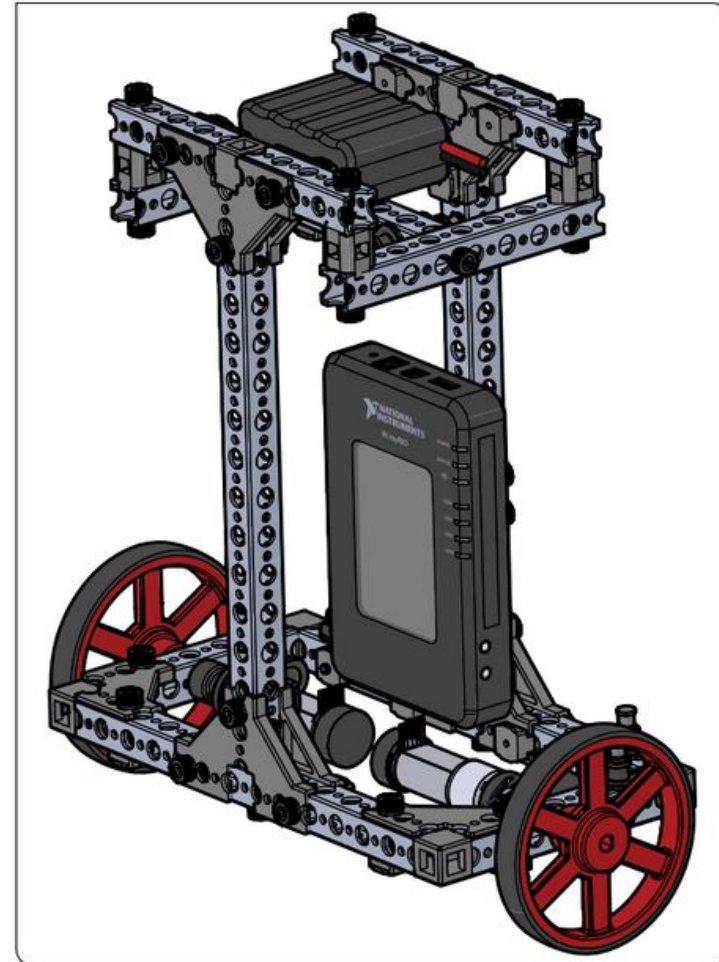


# Robot assembling

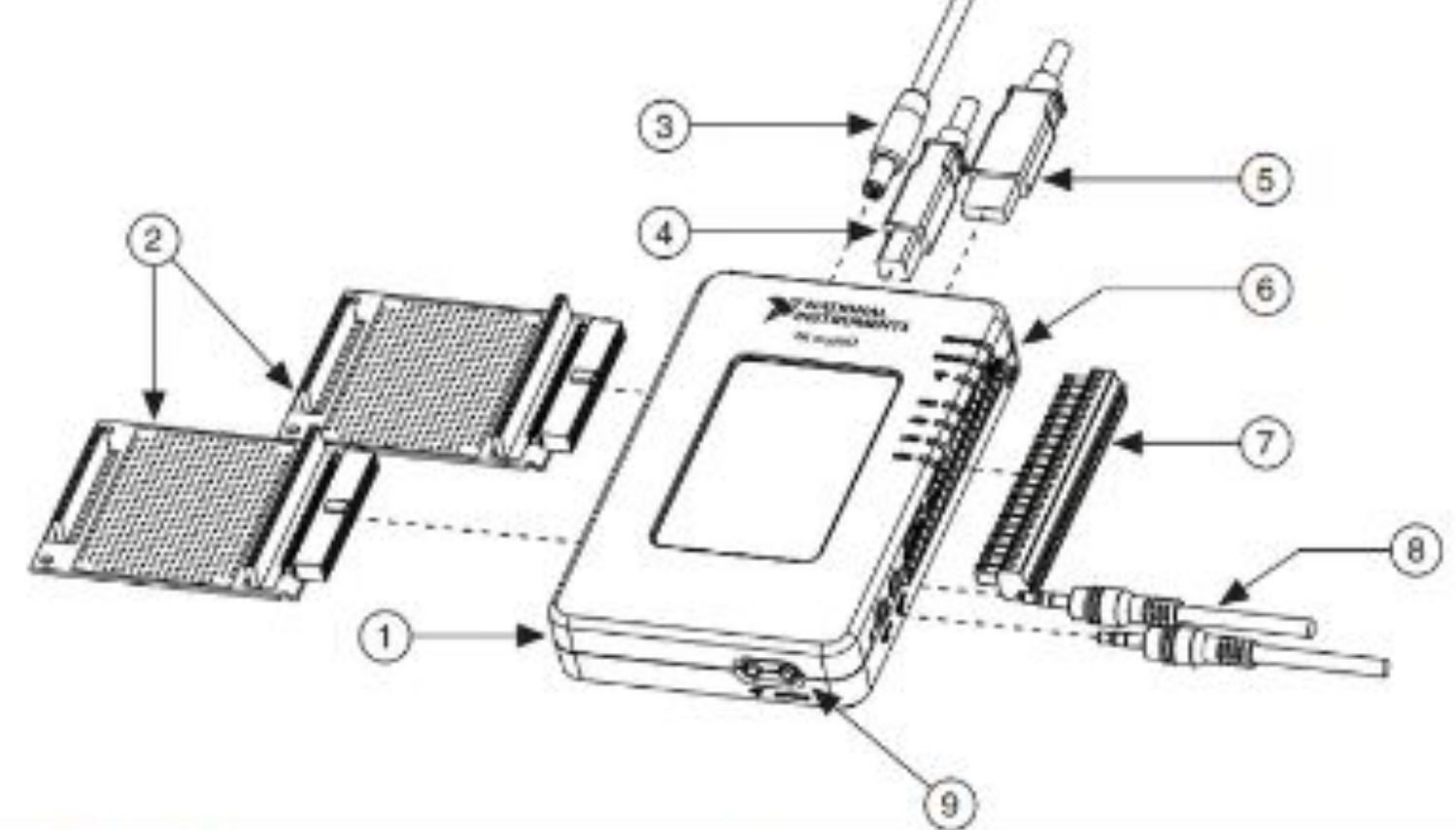
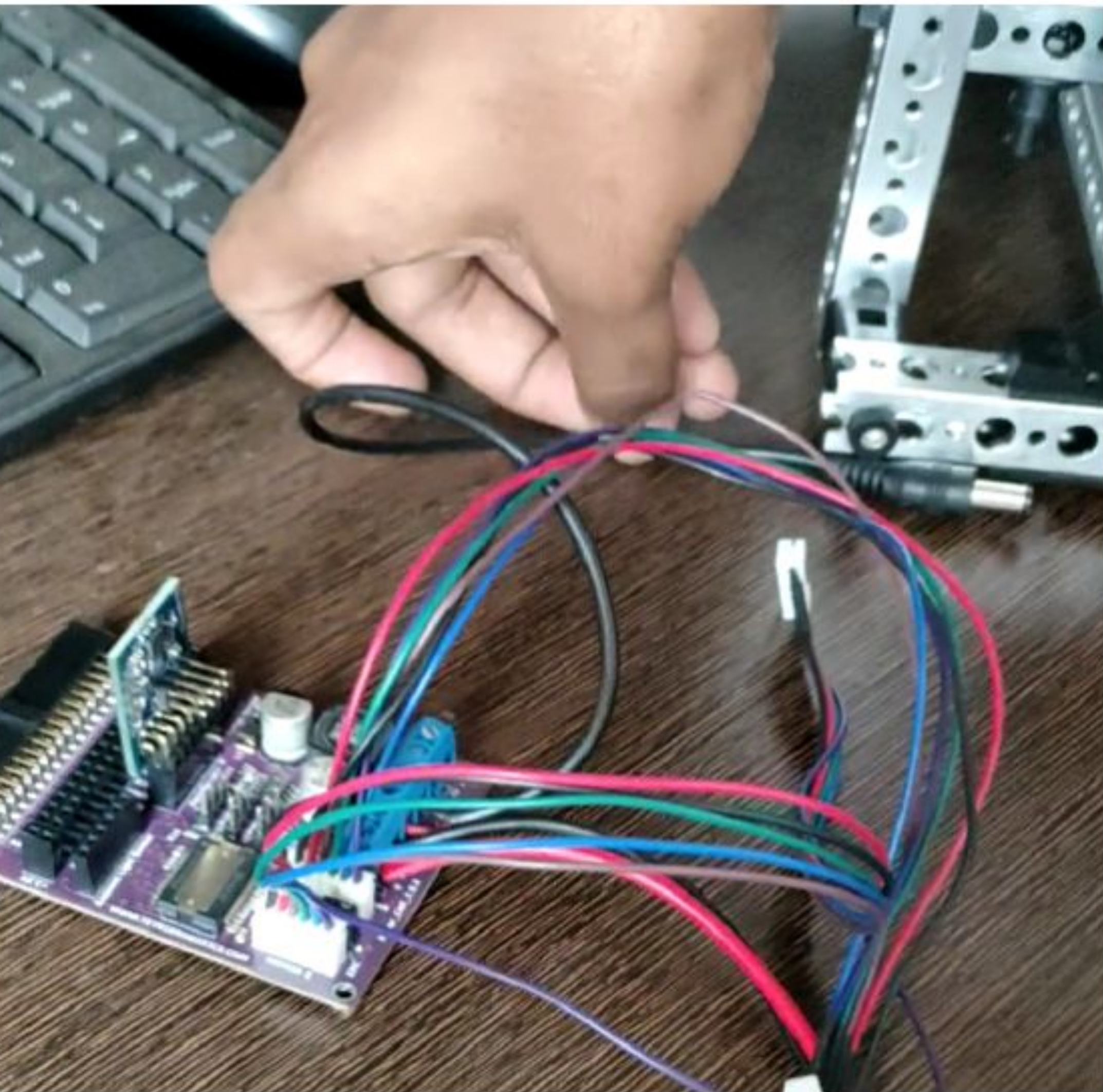




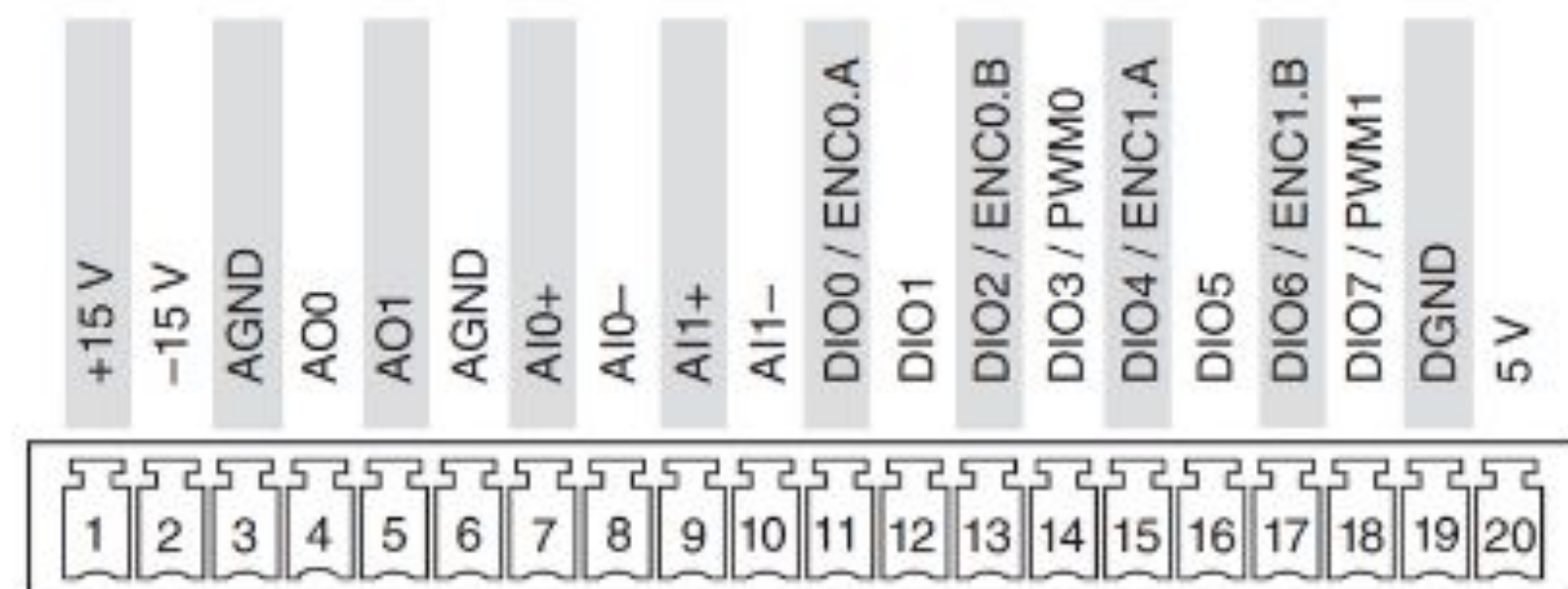
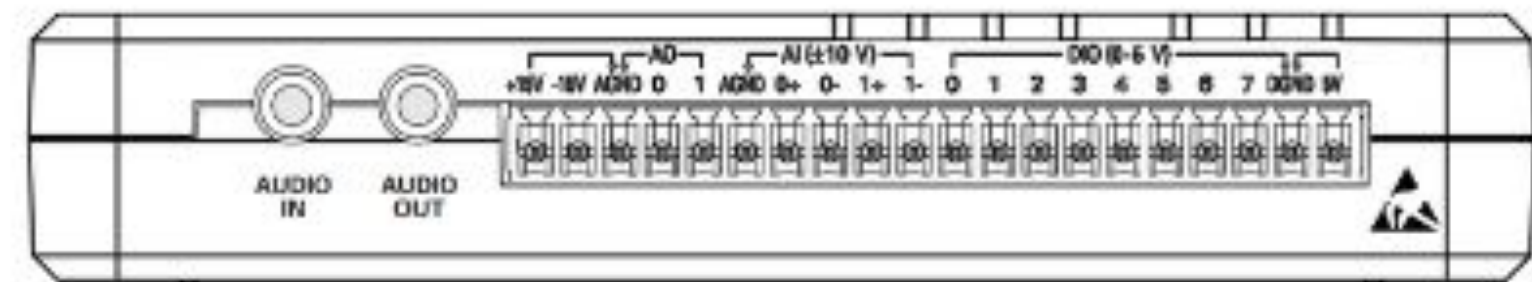
# Finished assembly







- |   |  |   |   |
|---|--|---|---|
| 1 | NI myRIO-1900  | 6 | LEDs  |
| 2 | myRIO Expansion Port (MXP) Breakouts (One Included in Kit) | 7 | Mini System Port (MSP) Screw-Terminal Connector |
| 3 | Power Input Cable  | 8 | Audio In/Out Cables (One Included in Kit)       |
| 4 | USB Device Cable   | 9 | Button0   |
| 5 | USB Host Cable (Not Included in Kit)                       |   |   |

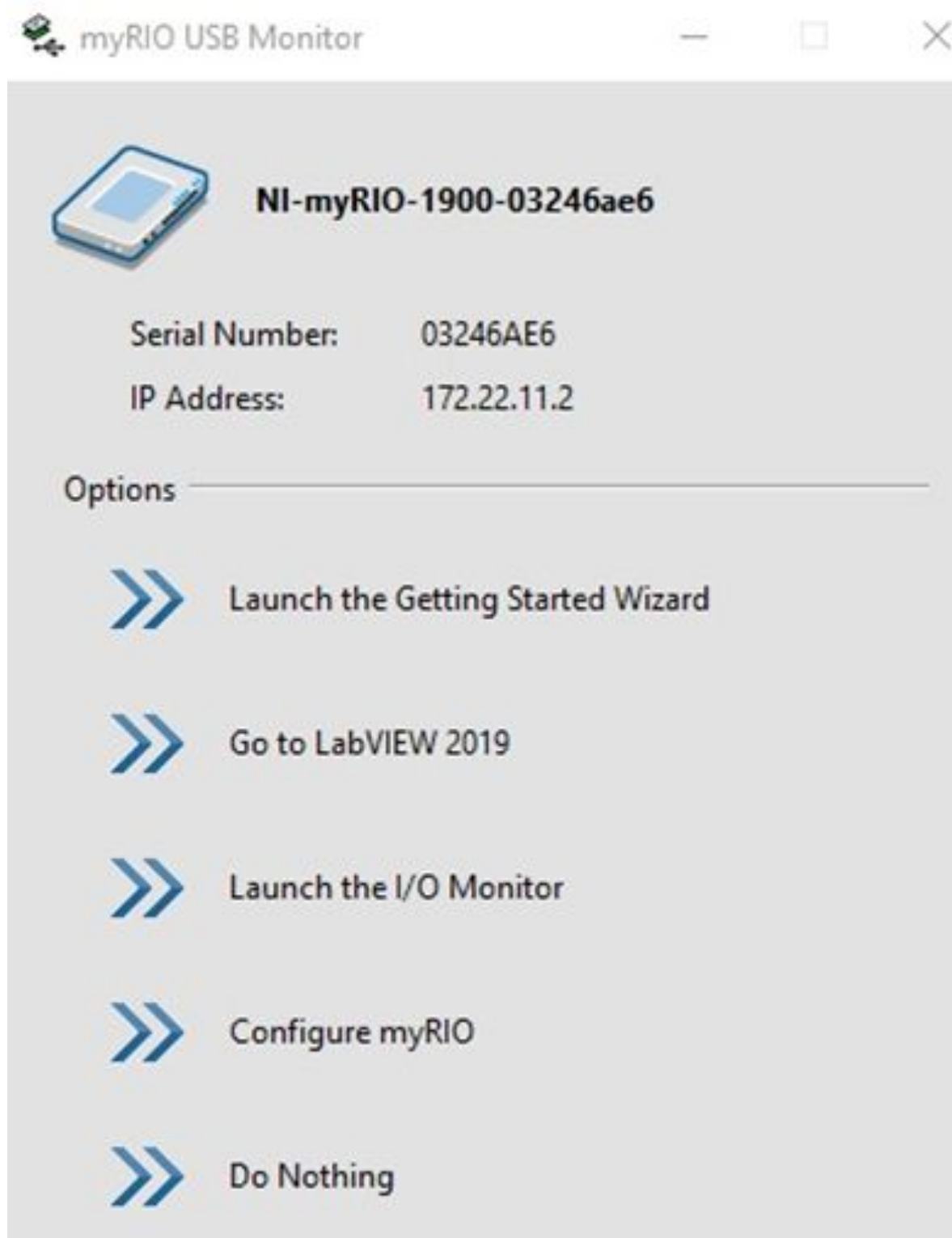




# Setting up Labview Software





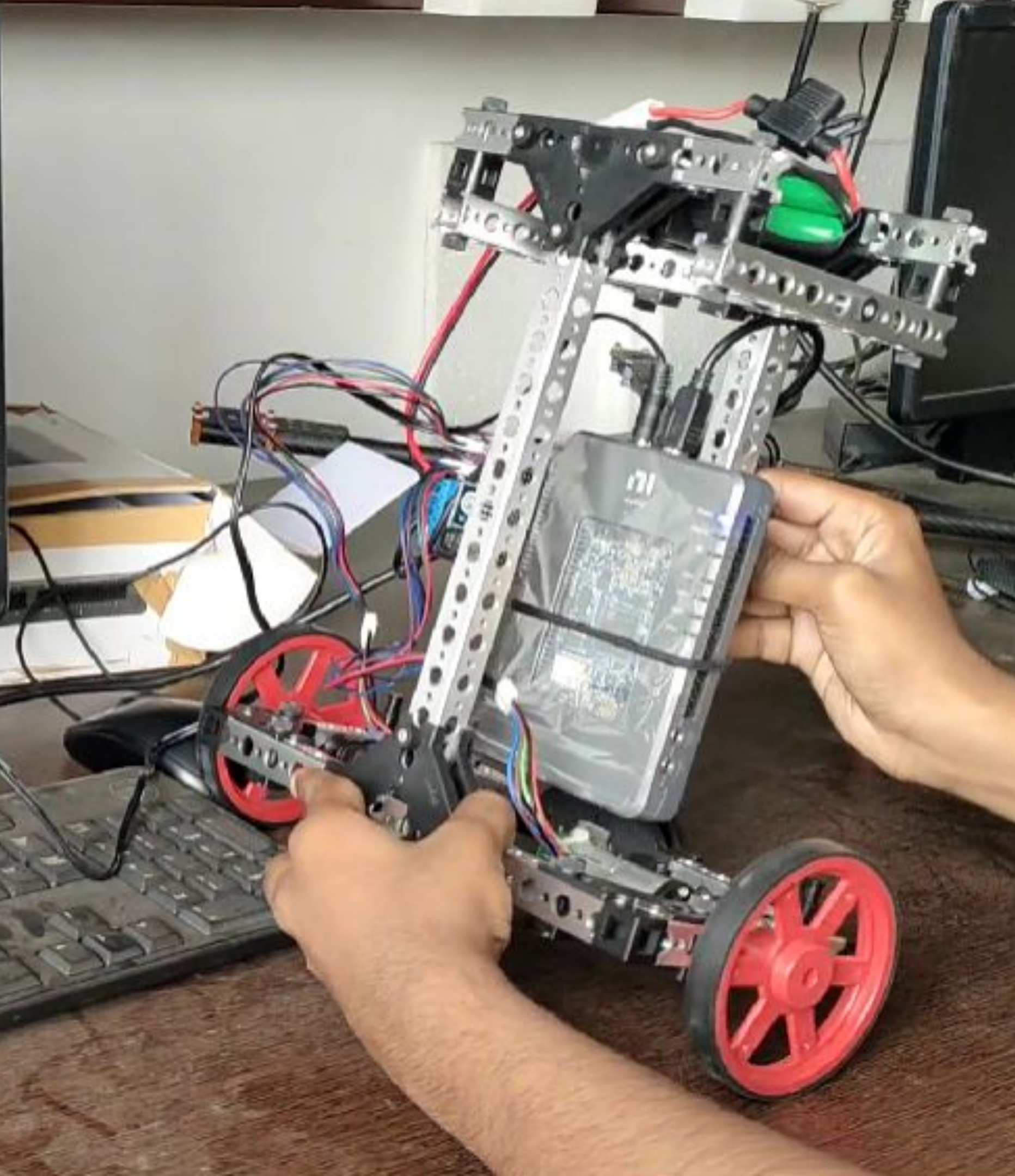
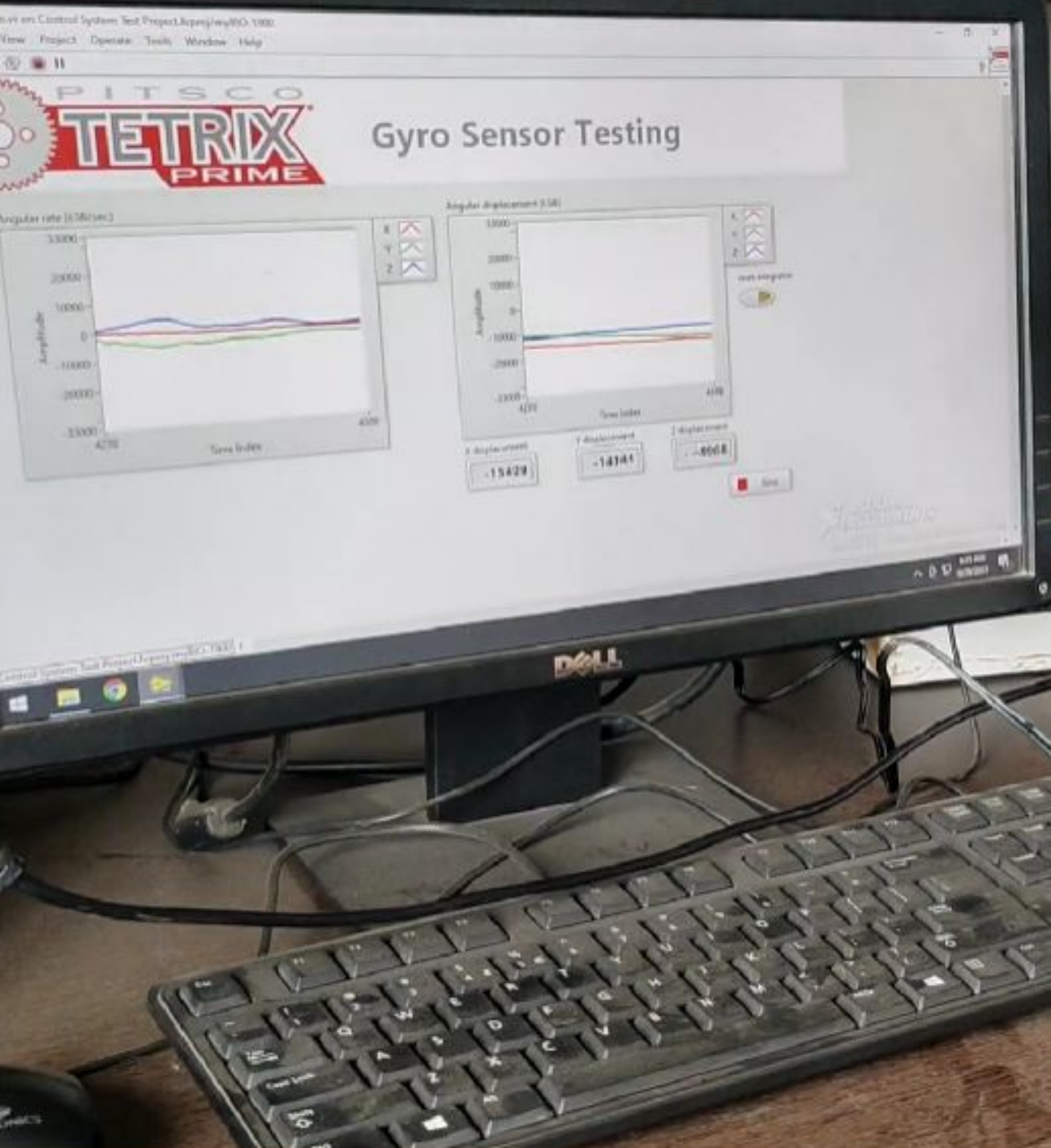




# GYRO SENSOR TESTING



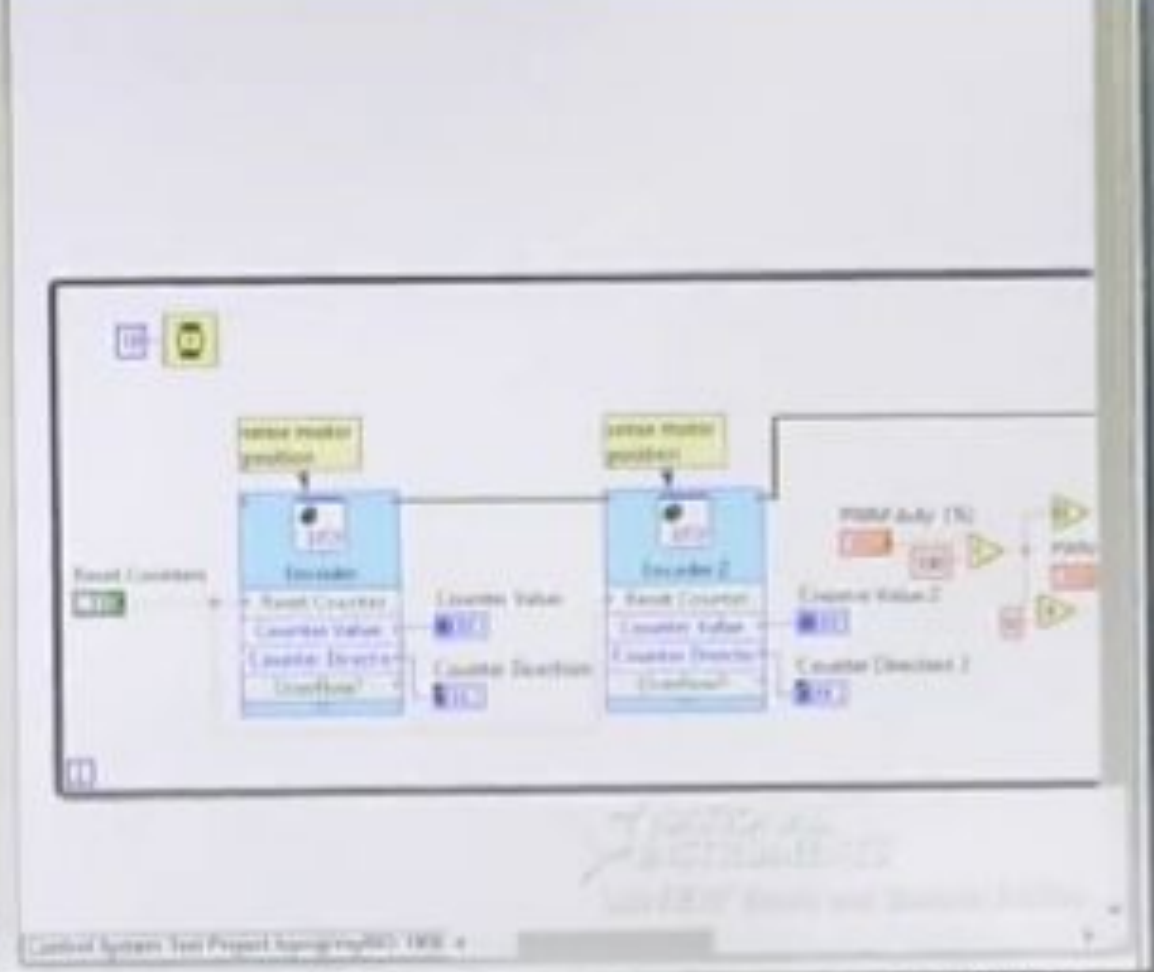
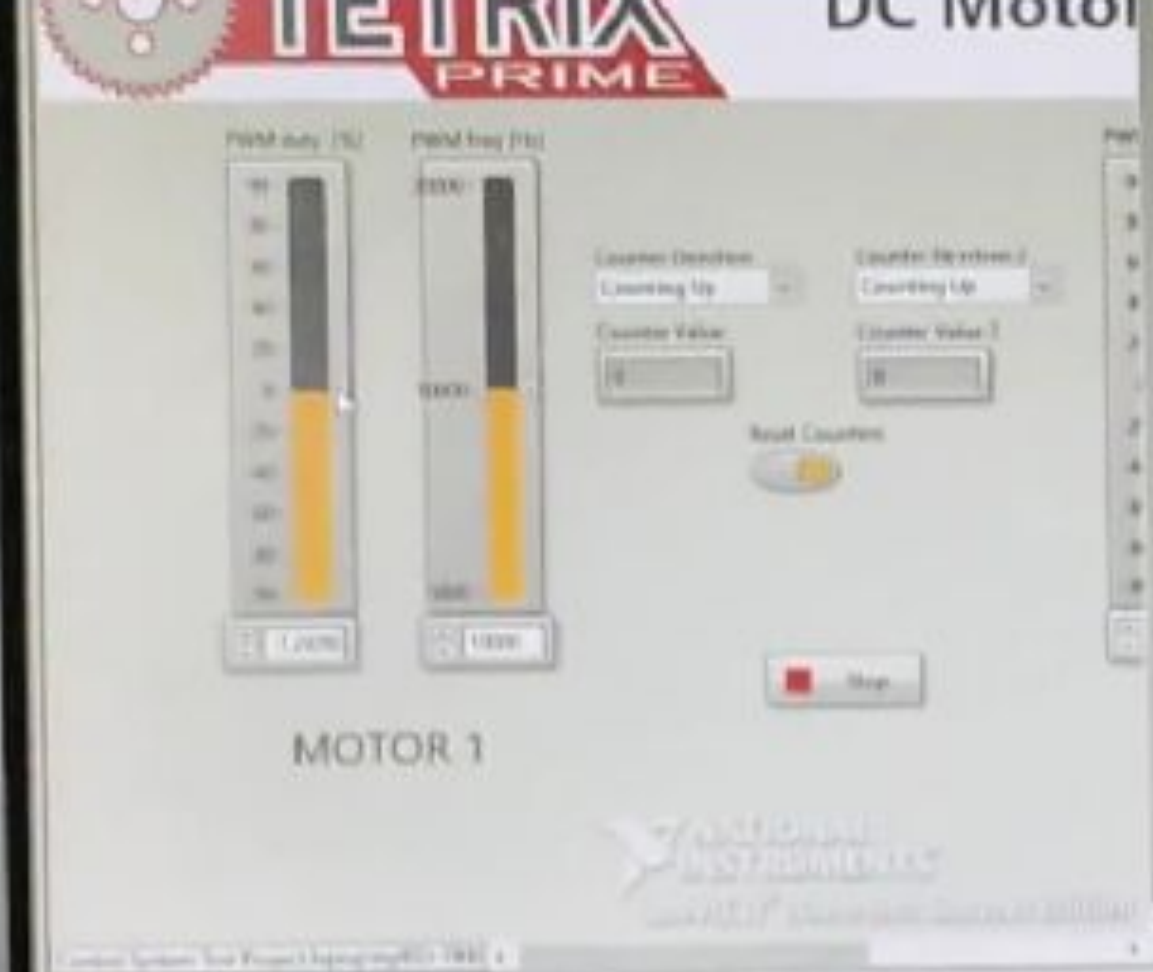






# DC MOTOR TESTING





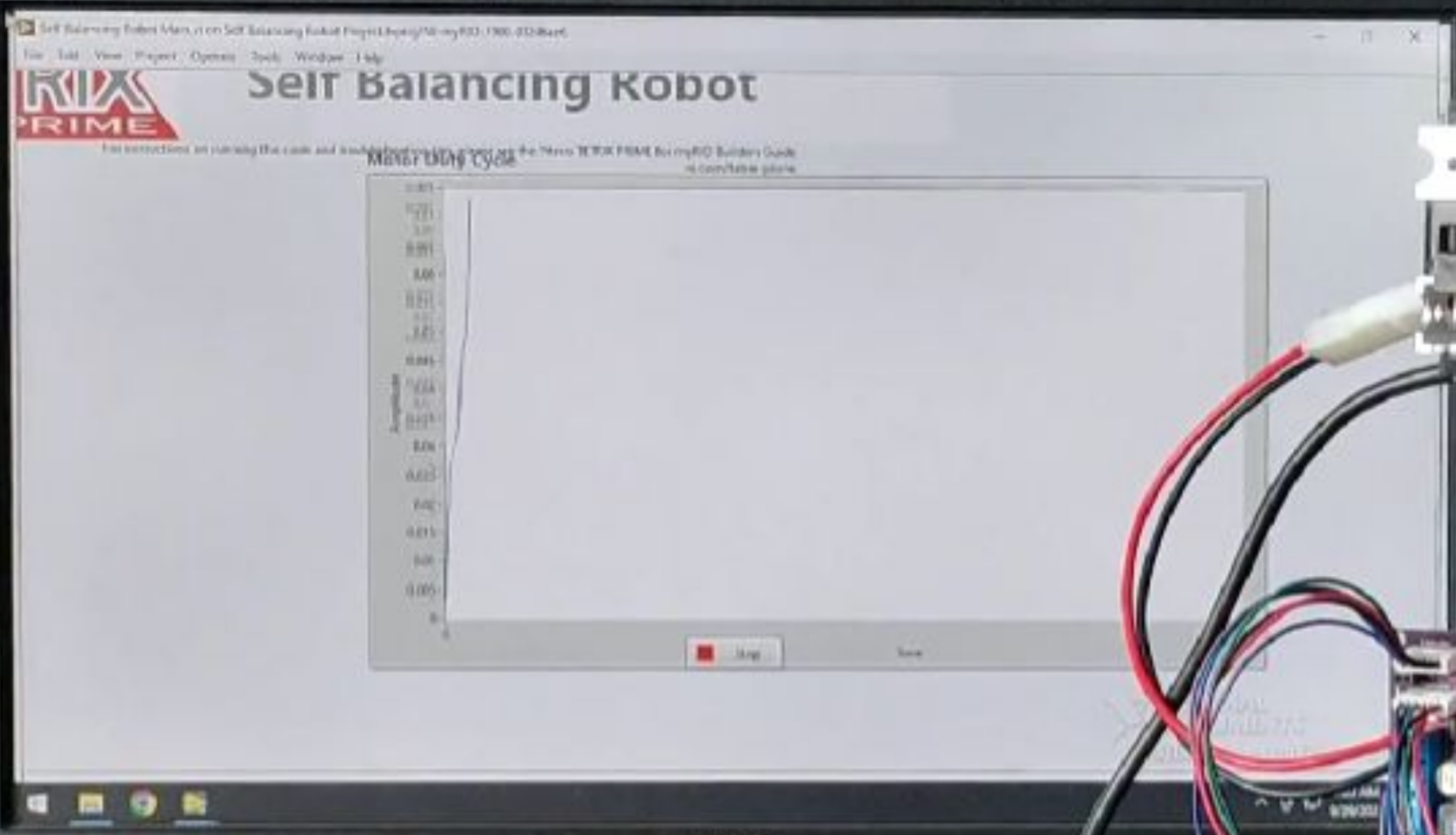
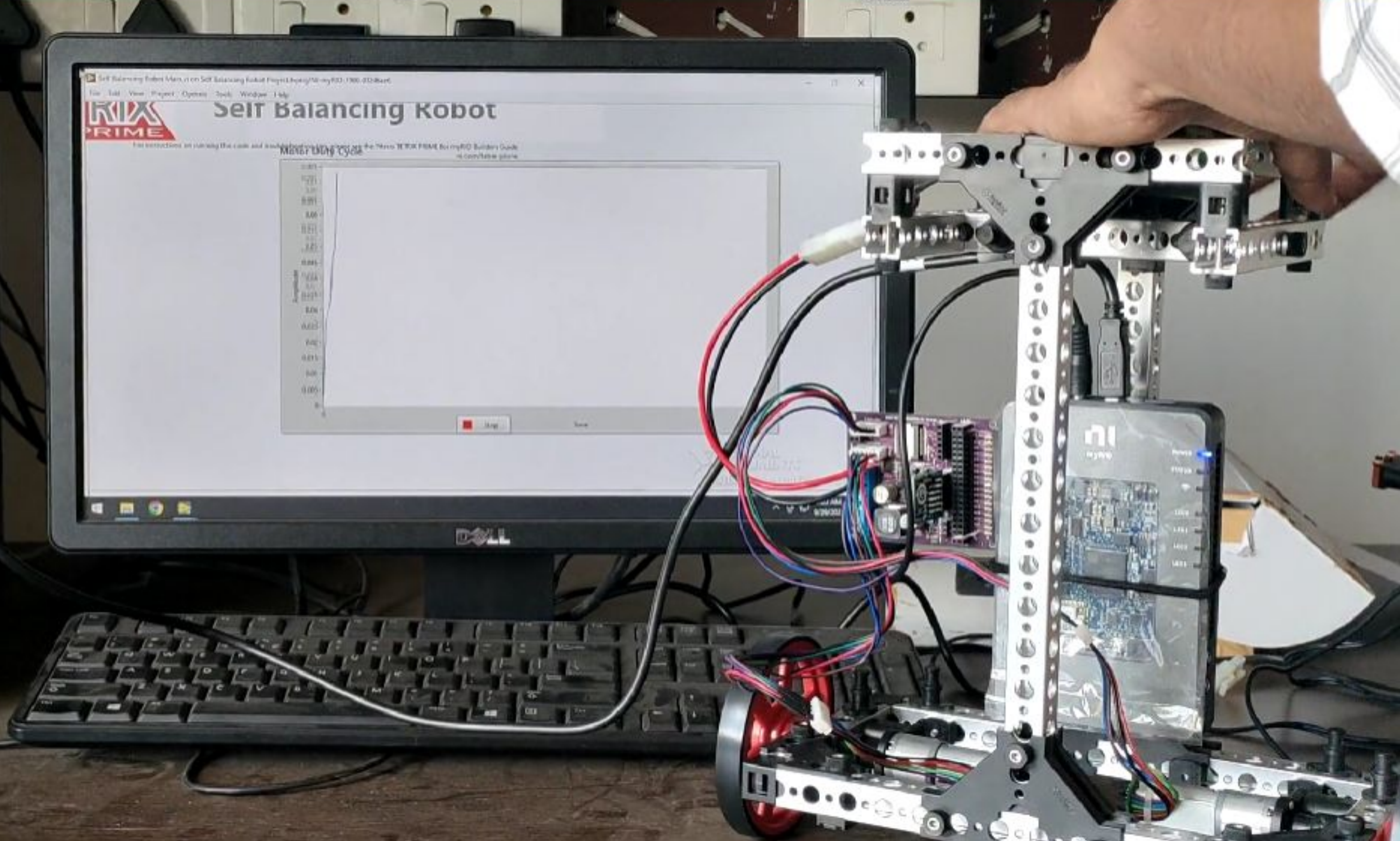


# RUNNING

## Self balancing robot MAIN VI












Recently added



Vision Assistant 2019 (32-bit)




Vision Assistant 2019 (64-bit)




Vision Texture Training

Expand


Most used




NI LabVIEW 2019 (32-bit)




Google Chrome




File Explorer




Word




NI MAX



#



3D Viewer



NI-myRIO-1900-03246ae6 - Measurement & Automation Explorer

FileEditViewToolsHelp

My System

Devices and Interfaces

Software

Remote Systems

NI-myRIO-1900-03246ae6

RestartSaveRefreshSet PermissionsLog In

Network Adapters

Ethernet Adapter usb0 (Primary)

|              |                   |
|--------------|-------------------|
| Adapter Mode | TCP/IP Network    |
| MAC Address  | 00:80:2F:34:5E:18 |

Configure IPv4 Address

DHCP Only

|              |         |
|--------------|---------|
| IPv4 Address | 0.0.0.0 |
| Subnet Mask  | 0.0.0.0 |
| Gateway      | 0.0.0.0 |
| DNS Server   | 0.0.0.0 |

More Settings

Wireless Adapter wlan0

|               |                             |
|---------------|-----------------------------|
| Wireless Mode | Connect to wireless network |
| Country       | India                       |
| MAC Address   | 00:80:2F:34:5E:19           |
| Status        | Connected to iQOO Z6 Pro.   |

Wireless Network

iQOO Z6 Pro

Network Type

Infrastructure

Security

Security settings are saved.  
Remove this network  
Enter new security settings

THank you !

Done by

21R218 - JAISURYA

21R226 - PRIYADHARSHAN

21R242 - SIVANESAN

