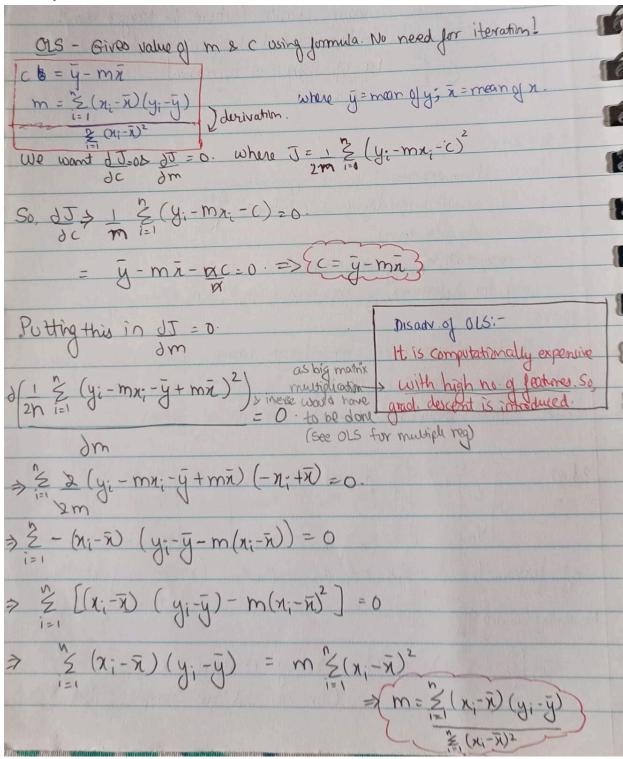
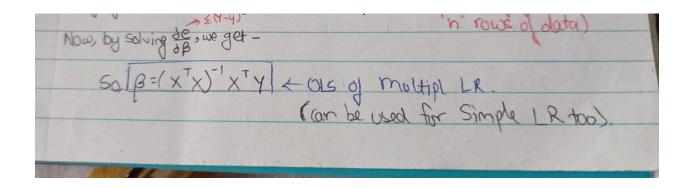
Gradient Descent

Prerequisite - OLS, differentiation



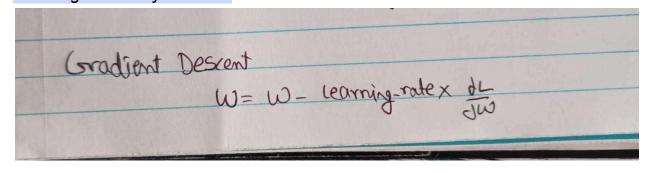


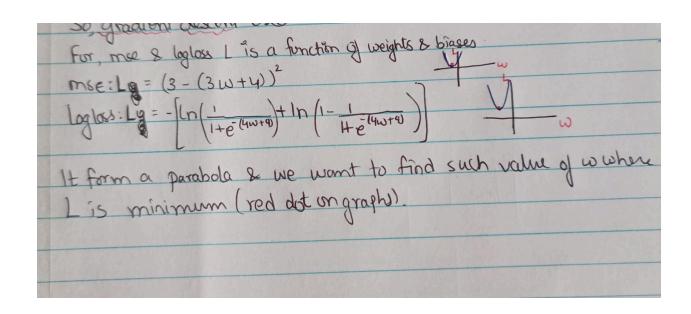
Problem with OLS (Ordinary least squares) - OLS is computationally expensive when high number of features due to more matrix inverse calculation and matrix multiplication involved.

So, Gradient Descent introduced.

Formula -

(how it works? +ve an -ve slope) Learning rate - why? what?



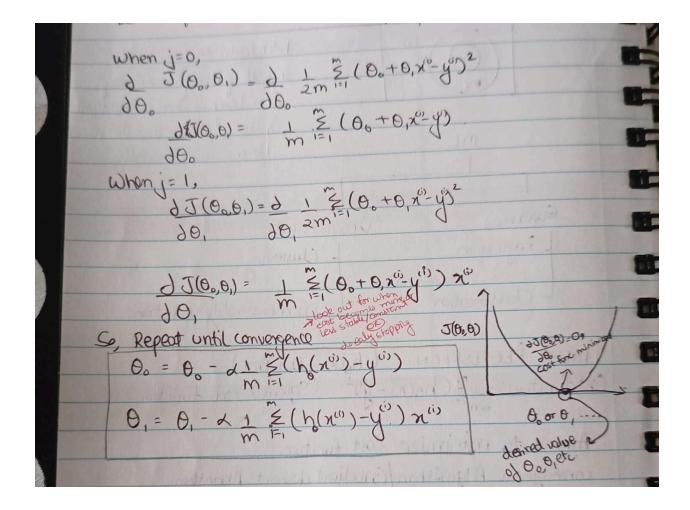


Cost function (MSE)

$$\frac{\partial}{\partial \theta} \int (\theta_0, \theta_1) = \frac{\partial}{\partial \theta} \int \frac{\tilde{z}}{\tilde{z}} (h_0(x)^2 - y^{(1)})^2$$

$$\frac{\partial}{\partial \theta} \int \theta_1 d\theta_2 d\theta_3$$

Differentiation -



When to stop?

- When the weights becomes more or less constant(doesn't change with more iterations)
- When total number of iterations decided is reached

Vizualizations - <u>link</u> @58:00 - gradient descent

<u>Link</u> @1:37:00 - visualization (look at the code then watch this)

Link @1:44:00 - effect of learning rate

Types of gradient descents -

Case of Local minima - IN case of non convex functions, Batch gradient descent gets stuck in local minima. So stochastic and mini batch gradient descent used. These are used when the data is 'big' (as it converges faster with less no. of epochs)

Doradient descent (Batch) = Entire data for updation in one exact @ Stochastic GD - wt. uplace for each data row in each egent ro. g eg. L'n' update in 1 epoch. @ niebotch GD - Make small botches, Eth say 4 botches, So for each epoch, 4 updation would take place SGD. Batch. @ Time-faster @ Time-Slower @ For agual epoch, this will @ For agual epoch, this will converge to proper Glas Converge slower Solution Jastes - more updates O can move in local minime. O Helps in moving out of local minimes 1 Exact solution not found, due to bewde 3 Exact sol, behaviour.