LAB ASSIGNMENT – 4

NAME	PRIYAL BHARDWAJ
REG. NO.	18BIT0272
COURSE CODE	MAT2002
COURSE NAME	APPLICATIONS OF DIFFERENTIAL AND DIFFERENCE EQUATIONS
SLOT	L1+L2
FACULTY	UMA K

EXPERIMENT 3(B):

Solution of Linear differential equations by Laplace transforms

Q. Solve
$$y''+2y'+10y=1+5$$
\$ $(t-5)$, $y(0)=1$, $y'(0)=2$.

MATLAB CODE:-

```
1 -
       clear all
 3 -
      syms t s y(t) Y
      dy(t)=diff(y(t));
      d2y(t) = diff(y(t), 2);
      F = input('Input the coefficients [a,b,c]: ');
 7 -
      a=F(1);b=F(2);c=F(3);
      nh = input('Enter the non-homogenous part f(x): ');
9 -
      eqn=a*d2y(t)+b*dy(t)+c*y(t)-nh;
10 -
      LTY=laplace(eqn,t,s);
11 -
      IC = input('Enter the initial conditions in the form [y0,Dy(0)]: ');
12 -
      y0=IC(1);dy0=IC(2);
      LTY=subs(LTY, {'laplace(y(t), t, s)', 'y(0)', 'D(y)(0)'}, {Y, y0, dy0});
13 -
14 -
      eq=collect(LTY,Y);
15 -
      Y=simplify(solve(eq,Y));
      yt=simplify(ilaplace(Y,s,t));
16 -
17 -
      disp('The solution of the differential equation y(t)=')
18 - disp(yt);
19 - ezplot(yt,[y0,y0+2]);
```

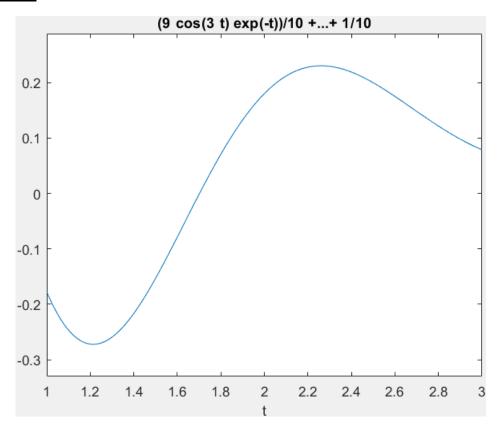
INPUT:-

```
Input the coefficients [a,b,c]: [1 2 10]
Enter the non-homogenous part f(x): 1+5*dirac(t-5)
Enter the initial conditions in the form [y0,Dy(0)]: [1,2]
```

OUTPUT:-

```
The solution of the differential equation y(t) = (9*\cos(3*t)*\exp(-t))/10 + (29*\sin(3*t)*\exp(-t))/30 + (5*heaviside(t - 5)*exp(5 - t)*sin(3*t - 15))/3 + 1/10
```

FIGURE:-



EXPERIMENT 4(A): Solution of System of 2^{nd} order differential equations of the form Y'' + AY = 0.

Q. Solve $y_1'' = -5 y_1 - 2 y_2$; $y_2'' = -2 y_1 - 2 y_2$ by Diagonalization

MATLAB CODE:-

```
1 -
       clear all
 2 -
       clc
 3 -
      syms x t
 4 -
      A=input('Enter the coefficient matrix A: ');
 5 -
       lambda=eig(A);
 6 -
      n=length(lambda);
 7 - □ for i=1:n
 8 -
           P(:,i) = \text{null}(A-\text{lambda}(i) * \text{eye}(\text{size}(A)), 'r');
 9 -
10 -
      disp('The Modal Matrix is: ');
11 -
      disp(P);
12 -
      D=inv(P)*A*P;
13 -
      sol1=dsolve(strcat('D2x=',num2str(D(1)),'*x'),'t');
       sol2=dsolve(strcat('D2x=',num2str(D(4)),'*x'),'t');
15 -
      disp('The solution of the decoupled system is: ');
16 -
      disp(sol1); disp(sol2);
17 -
       disp('The solution of the original system is: ');
18 -
      Y=P*[sol1;sol2];
```

INPUT/OUTPUT:-