

School of Advanced Sciences Digital Assignment-I, AUGUST 2020 B.Tech., Fall-2020-2021

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COURSE CODE	MAT3004
COURSE NAME	APPLIED LINEAR ALGEBRA
SLOT	A2+TA2+TAA2+V3
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MODULE -1 9.1 Which of the following equations are linear? SYSTEM OF LINEAR EQUATION (V) -34, 1 243 + AN3 = A (B) J24, -J27, 105x3=5 (C) 13x1 -31x2 + 3x3 = -1 (D) 22 x, + sin (x2) + 5 x3 = 17 A1 (B) W In (A) degree of x, & x3 is 2 & x2 is 3. In (C) degree of No is 0.5 In (D) sin(x2) is present, hence degree of M2 is not 1. .. A, C, D are not linear .. by process of elimination (B) is core (B) all N1, N2, N3 are of degree 1. in it is linear 9.2 Which system corresponds to the augmented matrix [9 4 0-2] (A) $x_1 - x_2 = -3$ $9x_1 + 4x_2 = -2$ (B) $x_1 - x_2 + 6x_3 = 3$ $9x_1 + 4x_2 = -2$ (C) $\frac{x_1 - x_2 + 6x_3 + 3x_4 = 0}{9x_1 + 4x_2 - 2x_4 = 0}$ (D) $-x_1 + 4x_2 = 0$ $6x_1 = 0$ $3x_1 - 2x_2 = 0$ A.2 (B) Only option (B) matches the system represented in augmented matrix In option (C) the elements of 4th column are coefficients & in the. question we are given augmented matrix, not coefficient matrix 9.3 which of the following statements best describes the following 100237 augmented matrix (A) A is consistent with a unique solution (B) A is inconsistent (E) A is consistent with infinitely many solutions (D) Mone of the above The system has 4 variables x, y, z, w=t (free variable A3 (C) 4 1=0; x=2-x=(3-2t, 4-t, 0, t); so for any value of t, we have infinitely many solutions n+z=3 Q.4 What is the first row of the augmented matrix for the system 9=4 (A) 0,0,2,6 (B) 0,1,0,4 (c) 1,1,1,3 (D) 1,0,1,3 A4 (D) 5 The augmented matrix of given system: [0104] matches (D) I'm which of the following matrices is in reduced now echelon form? A.4 (D) ~ (B), (C) are not in now exhelon forms, so they can't be reduced REF. A) is in new REF but not reduced since hading coefficient in now 213 is not 1. so by method of elimination, we have (D) \$.5 which of the following matrices is not investible (A)(6) (B)(36) (C)(12) (D)(36)4.2 (D) 0 since bottom now has all zero's, their matrix is not invertible 2.6 which of the following is not an elementary matrix? (A)(10) (B)(11) (C)(10) (D)(62) A.6 (B) ~ (A) is already identity matrix In (() Roths - R1 COREs leads to identity matrix leads to identify matrix. m (D) R2 -> R2/2 So A, C, D become identity matrix by single row operation, ... they are elementary. (B) single son operation cannot make it identity matrix & also its determinant is O. 9.7 What value of b makes the system xx+y=0 inconsistent? (A) b=0 (B) b = 0 (C) b=0.5 (D) b=1 A.7 (B) 5.4 $\begin{pmatrix} 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & b \end{pmatrix}$ $R_2 \rightarrow R_2 - R_1 \sim \begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 & b \end{pmatrix}$ So if b = 0, the system will be consistent with infinitely many solutions Hence b \$0 makes the system inconsistent. Q.8 The matrix A = [-3 2 000 1 0 79] (A) upper Frangular (B) Lower Triangular (() Both (A) and (B) (D) Neither (A) & (B) A.8 (A) V P. 7.0

9.9 If a system of equations has no solution, what does the graph look like

(A) intersecting thus (B) parallel lines (C) skew lines (D) intersecting lines

A-9 (B) If a system has no solution the the lines representing the equations

will never meet on the graph. Therefore parallel lines.

9.10 Let A be a nxn matrixed A is non-singular. Then which of the following is Konnect,

(B) A has a right inverse (A) A is a product of elementary matrices (D) A has a left inverse (c) AX = O has non-trivial solutions

A.10 (C) V of A is a nxn non-singular matrix, then the homogeneous system AX=0 has only the trivial solution X = 0.

Short-descorptive II Find the relationship between a 2 b such that the following system

has infinitely many solutions. -x+2y = a -3x+6y=b At Augmented matrix $A = \begin{pmatrix} -1 & 2 & a \\ -3 & 6 & b \end{pmatrix} \times -1 \times \begin{pmatrix} 1 & -2 & -a \\ -3 & 6 & b \end{pmatrix} \times 1$

 $Am\begin{pmatrix}1&-2&-a\\0&0&b-3a\end{pmatrix}$ For the system to have infinitely many solutions b-3a=0

:. |b=3a 9.2 Determine whether the following system has no solution, exactly one solution, or infinitely many solutions. 2n+2y=2

n+4 =4 A-2 Augmented matrix: A = (2 2 2) == 2 (1 1 4) x-11+ An (1 1 1) so bottom row => 0 ox +0y=3 which is not possible.

. System has no solution.

Q3 Find the value of k that makes the cyclem [15 -3 6] inconsistent?

A:3
$$A = \begin{pmatrix} 15 & -3 & 6 \\ -10 & k & q \end{pmatrix} \rightarrow 15 \quad (1 & -1/5 & 2/5) \times 10, \quad (1 & -0.2 & 0.4)$$
For the system to be inconsistent $k-2=0$: $k=2$

1.4 For which values of x the system $2n+y-3z=1$ is soconsistent?

A:4 Augmented matrix:
$$A:4 \quad \text{Augmented} \quad \text{matrix}$$

A.4 Augmented matrix:
$$A = \begin{pmatrix} 1 & 1 & -1 & 1 \\ 2 & 1 & -3 & 1 \\ -1 & 1 & -1 & \alpha \end{pmatrix}$$

R2 -R1 +R2

A \(\begin{pmatrix} 1 & 0.5 & -1.5 & 0.5 \\ -1 & 1 & -1 & \alpha \end{pmatrix} \)

A \(\begin{pmatrix} 1 & 0.5 & -1.5 & 0.5 \\ 0 & 1.5 & -2.5 & \alpha + 0.5 \end{pmatrix} \)

\[
\begin{pmatrix} 1 & 0.5 & -1.5 & 0.5 \\ 0 & 1 & -5/3 & 2\alpha + 1 \end{pmatrix} \]

$$A = \begin{pmatrix} 1 & 1 & -1 & 1 \\ 2 & 1 & -3 & 1 \\ -1 & 1 & -1 & \alpha \end{pmatrix} \times \begin{pmatrix} 1 & 1 & -1 & 1 \\ 0 & -1 & -1 & 1 \\ -1 & 1 & -1 & \alpha \end{pmatrix} + \begin{pmatrix} 1 & 1 & -1 & 1 \\ 0 & 1 & 1 & 1 \\ 0 & 2 & -2 & \alpha + 1 \end{pmatrix} \times \begin{pmatrix} 2 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 0 & 2 & -2 & \alpha + 1 \end{pmatrix} \times \begin{pmatrix} 2 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 0 & 2 & -2 & \alpha + 1 \end{pmatrix}$$

For $[\alpha \neq 1]$, the system is consistent.

Q:5 Find the inverse by Gaus-Jordan method
$$\begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix}$$
.
A:5 $A = \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix}$; $I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

$$[A|I] = \begin{bmatrix} 1 & 2 & | & 1 & 0 \\ 2 & 3 & | & 0 & | \end{bmatrix} x^{-2} \times \begin{bmatrix} 1 & 2 & | & 1 & 0 \\ 0 & -1 & | & -2 & | \end{bmatrix} x^{-1} \times \begin{bmatrix} 1 & 2 & | & 1 & 0 \\ 0 & 1 & 2 & -1 \end{bmatrix} x^{-1}$$

$$\begin{bmatrix} A | I \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 & -3 & 2 \\ 0 & 1 & 2 & -1 \end{bmatrix}$$

$$\begin{bmatrix} A | I \end{bmatrix} = \begin{bmatrix} I & A^{-1} \end{bmatrix}$$

$$A^{-1} = \begin{bmatrix} -3 & 2 \\ 2 & -1 \end{bmatrix}$$

Q'6 Express A = [0 2] as a product of elementary matrices.

Elementary Matrix Inverse of Elementary Matrix Reduction to Row Echlon Form

$$E = \begin{bmatrix} 1 & 1 \\ 0 & 2 \end{bmatrix} \times \frac{1}{2}$$

$$E_1^{-1} = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}.$$

$$\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \times -1$$

$$E_2 = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$$

$$E_2^{-1} = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$$

$$E = E_1^{-1} E_2^{-1} \qquad E = E_1^{-1} E_2^{-1} \dots E_k^{-1}$$

A.7 Augmented matrix!
$$A = \begin{pmatrix} 1 & 0 & 2 & \times & 2 & \times & 2 \\ 2 & 1 & 5 & \beta & 2 & 2 \end{pmatrix}$$
 in $\begin{pmatrix} 0 & 1 & 31 & \beta & -2\alpha \\ 0 & -1 & 3 & -1 & 2 & 2 \end{pmatrix}$

$$A = \begin{pmatrix} 1 & 0 & 1 & \alpha \\ 0 & 1 & 21 & \beta - 2\alpha \\ 0 & -1 & 9 & 8 - \alpha \end{pmatrix} 2 + \begin{pmatrix} 1 & 0 & 1 & \alpha \\ 0 & 1 & 3 & \beta - 2\alpha \\ 0 & 0 & 20 & \beta + 8 - 3\alpha \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & 0 & 1 & \alpha \\ 0 & 1 & 3 & \beta - 2\alpha \\ 0 & 0 & 20 & \beta + 8 - 3\alpha \end{pmatrix}$$

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$$A = \begin{pmatrix} 1 & 0 & 1 & \alpha \\ 0 & 0 & 2 & 1 \end{pmatrix}$$

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$$A = \begin{pmatrix} 1 & 0 & 1 & \alpha \\ 0 & 0 & 1 \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & 0 & 1 & \alpha$$

Q: Verify whether
$$AB = BA$$
 where $A = \begin{bmatrix} 1 & 0 \\ -1 & 2 \end{bmatrix}$, $B = \begin{bmatrix} 1 & 1 \\ 0 & 2 \end{bmatrix}$
A: B $AB = \begin{bmatrix} D & 1 \\ 0 & 2 \end{bmatrix}$, $BA = \begin{bmatrix} 0 & -1 & 2 \\ 0 & 2 \end{bmatrix}$

AB + BA Q.9 Find LU decomposition for -2x+y=-1

$$A \cdot 9$$
 $Ax = b$: $\begin{bmatrix} -2 \\ 4 \end{bmatrix} \begin{bmatrix} 1 \\ y \end{bmatrix} = \begin{bmatrix} -1 \\ 5 \end{bmatrix}$ $A = \begin{bmatrix} -2 \\ 4 \end{bmatrix} ; B = \begin{bmatrix} -15 \\ 5 \end{bmatrix}$

Reduction to Eumentary Inverse of REF

Matrix

$$\begin{bmatrix} -2 & 1 \\ 4 & -1 \end{bmatrix} \times -\frac{1}{2} = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_1 = \begin{bmatrix} -\frac{2}{2} & 0 \\ 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -\frac{1}{2} \\ 4 & -1 \end{bmatrix} \times -\frac{1}{2} = \begin{bmatrix} 1 & 0 \\ -\frac{1}{4} & 1 \end{bmatrix} \qquad E_2 = \begin{bmatrix} 1 & 0 \\ -\frac{1}{4} & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} 1 & \frac{1}{2} \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} 1 & -\frac{1}{2} \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} 1 & -\frac{1}{2} \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} 1 & -\frac{1}{2} \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} 1 & -\frac{1}{2} \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} 1 & -\frac{1}{2} \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} 1 & -\frac{1}{2} \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} 1 & -\frac{1}{2} \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} 1 & -\frac{1}{2} \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} 1 & -\frac{1}{2} \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} 1 & -\frac{1}{2} \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} 1 & -\frac{1}{2} \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} -\frac{1}{2} & 0 \\$$

$$A = \begin{bmatrix} 1 & 2 & 1 \\ 1 & 3 & 0 \\ 1 & 1 & 2 \end{bmatrix} x^{-1} \times \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & -1 \\ 0 & -1 & 1 \end{bmatrix} 2 + 1 \begin{bmatrix} 1 & 2 & 1 \\ 0 & 0 & 1 \end{bmatrix} x^{-2} \times \begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$x + 3z = 0 \qquad \text{(Since 3rd row has no pivot; z is free variable)}$$

Since 3rd row has no pivot; z is

$$y-z=0$$

Since 3rd row has no pivot; z is

 $y-z=0$

Let $z=t$; $y=z=t$; $x=-3z=-3t$

$$y-z=0$$

Let $z=t$; $y=z=t$; $x=-3z=-3t$
 $[-3t]$ Taking $t=1$ $x=(-3,1,1)$

Let
$$z=t$$
; $y=z=t$; $x=-5z=-5t$

$$x = \begin{bmatrix} -3t \\ t \end{bmatrix}$$
 Taking $t=1$ $x=(-3 \ 1 \ 1)$

$$\chi = \begin{bmatrix} -3t \\ t \end{bmatrix}$$
 Taking $t = 1$ $\chi = \begin{pmatrix} -3 \\ t \end{pmatrix}$

[X= (-3t + t)] for any values of t

Module-2 multiple Choice Questions
9.1 Which set is not a vector space
i) The span of the set of rows in A (ii) The span of the set of codumns in A
in) The set & x: Ax=03 (iv) The set & x: Ax=e,3 where e,= (1,00)
A:1 (iv)
(i) & (ii) are now & column vector spaces respectively
(iii) is subspace of R? I : a vector space
So by method of elimination, answer is (iv)
9.2 Which one is not a vector space?
(i) The kernel of a matrix A (ii) The set of all sequences (x1, x2 x34)
(11) The span of a set of vectors in a vector space
(iv) The set of all discontinuous functions defined on the interval (0,1).
A-2 (iv) ~
set of all "continuous" functions defined on the interval (0,1) is a vector
space, since sum & scalar multiples of continuous functions are also continuous (& addition is commutative)
9.3 For what value of is the vector (2, 3, -5) in the linear span of
(1,3, -1) & (-5, -8,2)?
(i) 3 (ii) -6 (iii)-13 (iv) none of these
$\frac{A\cdot 3}{2} (3,3,-5) = \chi(1,3,-1) + y(-5,-8,2) \qquad \text{a.y.} \in \mathbb{R}$
$2x - 5y = 3$ $\therefore 17 - 5(4) = 3$
3x - 8y = 3 $3 = 3$
$(iii) \checkmark $

1.4 which of these assertions is not logically equivalent to all the others? The matrix A is nxn).

(i) The row vectors in A span R" (ii) The column vectors in A span R" (iii) For each be R", the equation Ax=b has a solution (iv) A has a pivot position in each row-

A.4 (i)

Row vectors do not span R" in A

9.5 Which is not a vector space? (1) The set of all polynomials that satisfy p(0)=0 (ii) The set of all polynomials of the form p(t) = a+b++c+2++3. (iii) The set of all vectors of the form [atb, 6+3a, -a-46] (iv) The set of all vectors [a+b3, a-b3] AS (IV) Polynomial of degree 3 is not vector space. The set doesn't contain O-element. gis Which set is not a subspace of R3? (1) } (x,y,z) = 3(x+) +2(y+1)+2=5} (ii) {(wy, 2): x(y+1)-y(x-2)=25 (iii) { try, z) T: 3(x+1)+2(y+1)+z=6 (iv) {(n,y,z) T: x(y+2+3) = z(x+y)+y(x-z+1)} A-6 (iv) 5 x(y+z+3) = z(x+y) + y(x-z+1) = xz+yz+xy-yz+yxy+ xz+3x = xy+ xz+ y => 3x=y: they are linearly dependent :. (11) is not subspace. 0.7 Let u=(1,2,3), v=(0,-1,2) + w=(2,2,0). Which assertion is true? (1) 4 Espan(v, w) + w Espan (4, v) (iii) y Espan (u, w) + u & span (y, w) (it) u E span (v, w) & w E span (u,v) (iv) we span (y,v) & v Espan (u, w) A:7 (ii) \(\sqrt{1} \) 4=1.5 v + 0.500 (u 6 span (v, w) w= 24 7 3V :. w Espan (u, v) 9:3 Let 5 be a linearly independent set of 4 polynomials in P3. What conclusion can be drawn? (ii) One member of Scan be discarded to obtain basis of B (i) S spans P3 (IV) S does not span P3 (iii) The set S can be extended to obtain the bask of P3. <u>A</u>: (i) , Ky> ✓ 5 - linearly independent; has 4 polynomials ... spans P3 P3 requires min 3 polynomials : I can be discarded. 9.9 What is the dimension of the space of vectors in RS having the form (a-3b, b-a, a+2b, a, b)? (i) 2 (ii) 3 (iii) 4 (iv) 5 A.9 (1) W (a-3b, b-a, a+2b, a,b)= a(1,-1,1,1,0) +b(-3,1,2,0,1) . . dim = 2

Q.10 Which set is a bashs of R3? (1) {(1,2,3), (4,5,6), (5,7,5)] (1) {(1,2,3), (4,5,6), (5,7,9)} (iii) {(1,2,3) [, (4,5,6) [, (4,8,9) [} (iv) {(1,2,3) [, (4,5,1)], (3,8,15) [] A.10 (1) W (ii) (5,7,9) = (1,2,3) + (4,5,6) unearly dependent & (iii) 2x (4,5,6) = 20 (7,8,9) + (1,2,3) do not form basis (iv) 2x(4,5,1) = (7,8,15) +(1,2,3) 9.11 what is the dimension of the space of polynomials spanned by 4 function u,(t)=t+t2, u,(t)=t3+t4, u,(t)=t5-t2-t4, u4(t)=t+t3++5? (i) 1 (i) 2 (iii) 3 (iv) 4 A·)I (M) u3(t) = u1(t) - u1(t) - u3(t) or u4(t) = u1(t) + u2(t) + u3(t) :. dim = 43 }(n-1)=5-129) Q-12 What is the dimension of space of matrices spanned by ?[1, o], [1], [0], 4(1) i) 1 (ii) 2 (iii) 3 [91] 4? A-12 2×[1] = [10] + [00] + [01] : only [10], [10], [10] are linearly independent. dim=4 (iv) 9.13 which of these statements are false? (i) Dim (Pn) = n+i) (ii) Dim (Rmxn) = mxn (iii) Dim (Pn)=n (iv) Dim (Rm)=m+i) A-13 (iii) (iv) Properties of basis & dimensions for general cases 9.14 What is the dimension of the space of all matrices [a b] for which 2a=3d? (i) 1 (ii) 2 (iii) 3 (iv) 4 since 2a=3d, only a, b,c or b, c,d are linearly independent A.14 (iii) Q.15 A Unearly adependent set can contain a linearly dependent subset - FALSE 0.16 If a set of vectors is linearly dependent, then we can add vectors to the set & make it linearly independent - FALSE 9.17 The set of all polynomials p of degree at most 7 sit p(7)=0 is a vector space - TRUE

Q-18 The set of all vectors x=(x1, x2) such that x,201 x20 is a subspace of R2-FALSE FALSE

Q.19 Every subspace in a vector space V is the span of some vectors in V-TRUE

9.20 of His a linearly independent set of vectors in some vector space, then His a basis for the span of H - TRUE FALSE TRUE

Short Answer Questions:

91 Consider {P1, P2, P3, P4} where p1(t)=1, P2(t)=t, P3(t)=4-t, P4(t)=t3. Determine whether this set of polynomials is linearly independent or linearly dependent.

api(+) + bp=(+) + cp=(+) + dp4(+) = 0 a + bt + 4c-c++ at3 = 0 0 1-100 Linearly dependent

Is the following an example of vector space? X=R, X\(\mathbb{B}\)y = \(\chi + y + 1\); \(\alpha\)X=

(ii) ~ (B(B) ×) = (KB) (B) × A:2 i) x By = y Bx all (Bx+B) = aBx + aB x+y+1 = y+x+1 ~ x(Bx+B) + x = xBx+xB «BN +KB+X + XBN+XB

(iii) REX :. - NEX such that NA(-N)=0 Let y = -n EX n () (-x) = m+(-x)+1

: . inverse does not exist.

X is not a vector space.

Q & Does the set of all vectors in R4 that have exactly 2 zero entries span R4? A.3 The basic span of R4 has vectors: (1,0,0,9), (01,0,0), (0,0,1,0), (0,0,0,0) These vectors also dire in R4 & span R4 despite not having exactly 2 set of vectors having exactly 2 zero entries in R1 ! {(1,1,0,0), (0,0,1,1), (1,0,1,0), (1,0,0,1), (0,1,0,1), (0,1,1,0)} C1V,+C2V2+C3V3+C4V4+C5V5+C6V6=d,12+d212+d312 w3=(0,0,0,0)T +d4w4 w1= (1,0,0,0)T WH = (0,0,0, D) W2 = (0,1,0,0)] 14 + 002+163+164+005+06 = 101+002+0013+0dy 14 + 0cz + ocz + ocy+lcz + 14 = od; + ldz+odz+ody Oc, + 1 c2 + 1 c3 + Oc4 + Oc5 + 1 c6 = Od, + Od2 + 1 d3 + Od4 0 c, + 1c2 + 0c3+ 1c4+1c5+ 0c = 00, + 0d2+0d3+1d4. Augmented matrix to reduced row echelon form P100011/010 0 1 0 0 1 1 -1/2 1/2 1/2 1/2 0 0 1 0 -1 0 | 1/2 - 1/2 1/2 0 0 0 1 0 -1 1 1/2 -1/2 1/2 c, + (5+ (6 = d2 62+65+66 = 1 (-d,+d2+d3+d4) This system is consisted with B (3-45 = 12 (d,-d2+d3-d4) system D for all right hand side values. !- supans V Cu - Ce = 12 (di-dz-dz+du) Any yes, all rectors in R4 that have exactly 2 zero entries span R4. Q'4 Consider S= { (1,3,2,0), (-2,0,6,7), (0,6,10,7), (2,10,-3,1)}, (2,10,-3,1)}, Find book for span(s). · all rows have pirols :. Basis of span = O signal pinot columns · Basis = 63 (1,3,2,0), (-2,0,6,7), (0,6,10,7), (2,10, 3,1)) Basis = { (1,-2,0,1) , (0,1,1,0) , (0,0,0,0) }

9.5 Is there a 2x2 matrix whose powers span R2x2? A.5 2x2 matrix should be polynomial in matrix A & would commute with A = [ab]; a,b,c,d ER : ax+by=0 1 cx+dy=0. Multiples of Iz would only commute with all 2x2 matrices. .. [KI2] I 9.6 If A \$3x4 matrix, prove that the columns of A are linearly tadependent. linearly dependent because there exists non-zero n such that 0 0 0 0 x = 0 9.7 9f A & 4x3 matrix, prove that the rows of A are linearly dependent. A.7 [0 0] -> The rows of this matrix are linearly dependent because there exists non-zero x such that the last now has all zeroes. So the matrix system will avitore ters + dry = 0 have infinite non-zero solutions. 9.8 In each case determine wis a subspace of R3. (i) W= {x: x2 == x + x23 (ii) W= {x:x1 = 2x3} A.8 (1) W= { (x1, x2, x3); x122x1+x23 where a2= a+c; u2=u+w Let x= (a,b,c); B= (u,v,w); KER for w to be subspace of R X+KB 60 = (a, b, c) + K(u,v,w) XTKB = (a+ku), b+kv, c+kw) & 0 :. (a+ Ku)2 = a+ ku + C+ kw : . Wis not subspace of R3 a + k · u + 2 auk = a + ku + C + kw (ii) W= { (x1, x2, x3) | x1=2x3} For any vectors $\alpha = (a,b,c)$; $\beta = (u,v,w)$ in W any skalar $k_1,k_2 \in \mathbb{R}$ Then k, x + k2B = k((a, b, c) + k2(u, v, w) = (k, a+k2u, k, b+k2v, k,c+k2w) a=2(=) k1a=2k1c K, a+k24 = 2K,C+2K2W u= 2w => k2u=2k2w wis a subspace of R3

If V= R" & W= ? (xi, xz -- xn); xi = xn3, find abaou & dimension of W. X V1 + XV2 + XV3 + - . . XnVn = 0 d, (1,0,0,0,...)+ x2 (0,1,0;9,...0) +x3 (0,0,1,0,0,.+0) + 4 . - - . + 40-1 (0,0,0, , 0) = 0 in does not exist : it is given x = xn => v = vn i. vn is not linearly dependent. -. Basis of w will be 2 vi, v2 --. Vny :. | dim W = n-1 9.10 can you exhibit a basis of Pn consisting of all elements of dyrec n rat All of the degree ≤ no-1? Pr &= (x, x, x, x, ... x,) C1 x2 + C2 x2 + C3 x3 + - - . C1 x2 = 0 ... CI+ G+ C3+C4 - -- + Cn = 0 So G, Cz, Cz -- . Cn can have be any values as long as they satisfy the above eq". Iff 4= c2 = - - = cn = 0 then we have a basis for Pn of all elements of degree of i.e the rector if the elements themselves. As for all elements of degree B ≤ n-1, the basis will be 1 = 3 p.(m), p2 (m) - - . Pn-1(m) & with dimension n-1