

This handout includes space for every question that requires a written response. Please feel free to use it to handwrite your solutions (legibly, please). If you choose to typeset your solutions, the `README.md` for this assignment includes instructions to regenerate this handout with your typeset \LaTeX solutions.

4.a

Question: Suppose we have a matrix $A \in \mathbb{R}^{n \times d}$ with SVD $A = UDV^T$, where $U \in \mathbb{R}^{n \times r}$, $D \in \mathbb{R}^{r \times r}$ and $V \in \mathbb{R}^{d \times r}$

Show that

$$A = \sum_{i=1}^r \sigma_i u_i v_i^T$$

ANSWER:

u_i is the i^{th} column of matrix U where $i = [1 \dots r]$ and r represents the rank of matrix A .

D is the diagonal matrix with the values σ_i representing the non zero value of the i^{th} column.

$$UD = [\sigma_1 u_1 \sigma_2 u_2 \dots \sigma_r u_r]$$

$V = [v_1 v_2 \dots v_r]$ where v_i is the i^{th} column vector

$$UDV^T = [\sigma_1 u_1 \sigma_2 u_2 \dots \sigma_r u_r][v_1 v_2 \dots v_r]^T$$

$$UDV^T = \sum_i^r \sigma_i u_i v_i^T$$

Substituting A

$$A = \sum_i^r \sigma_i u_i v_i^T$$

$$\begin{matrix}
 u_i \rightarrow & \begin{bmatrix} u_1 & u_2 & u_3 \\ u_{11} & u_{12} & u_{13} \\ u_{21} & u_{22} & u_{23} \end{bmatrix} & \begin{bmatrix} \sigma_1 & 0 & 0 \\ 0 & \sigma_2 & 0 \\ 0 & 0 & \sigma_3 \end{bmatrix} = \begin{bmatrix} u_{11}\sigma_1 & u_{12}\sigma_2 & u_{13}\sigma_3 \\ u_{21}\sigma_1 & u_{22}\sigma_2 & u_{23}\sigma_3 \end{bmatrix}
 \end{matrix}$$

$U \text{ is } 2 \times 3$
 $D \text{ is } 3 \times 3$

Figure 1: UD multiplication illustration

4.b

Question: Show that

$$u_i = \frac{1}{\sigma_i} Av_i$$

In particular, the components u_i represent the size of the projection of the rows of A onto v_i scaled by σ_i

$$V^T V = I$$

$$[v_1 v_2 \dots v_r]^T [v_1 v_2 \dots v_r] = I$$

$$A = U D V^T$$

Multiplying both sides by v_i $Av_i = U D V^T v_i$

$$Av_i = U D (V^T v_i)$$

$V^T v_i = i^{th}$ column of vector I represented as e_i

$$e_i = \begin{bmatrix} 0 \\ 0 \\ \dots \\ 1 \\ 0 \end{bmatrix}$$

$$Av_i = U D V^T v_i$$

$$Av_i = U D e_i$$

$$Av_i = U (D e_i)$$

D is the diagonal matrix with

$$D = \begin{bmatrix} \sigma_1 & 0 & \dots & 0 \\ 0 & \sigma_2 & \dots & 0 \\ 0 & 0 & \dots & \sigma_r \end{bmatrix}$$

$$Av_i = U (\sigma_i e_i)$$

$$Av_i = \sigma_i (U e_i)$$

$$Av_i = \sigma_i u_i$$

$$u_i = \frac{1}{\sigma_i} Av_i$$

4.c

One way of finding a reduced rank approximation of A is by hard-setting all but the k largest σ_i to 0. This approximation is called truncated SVD, and by (a) we see it can be written as

$$A_k = \sum_{i=1}^k \sigma_i u_i v_i^T$$

From (a) we see the truncated SVD can also be written as $A_k = U_k D_k V_k^T$, where $U_k \in \mathbb{R}^{n \times k}$ and $V \in \mathbb{R}^{d \times k}$ are the first k columns of U , V and $D \in \mathbb{R}^{k \times k}$ has the first k singular values.

Show the the rows of A_k are the projections of the rows A onto the subspace V_k spanned by the first k right singular vectors.

Hint: Recall that the projection of a vector a onto a subspace spanned by v_1, \dots, v_k where the v_i are pairwise orthogonal is given by the sum of projections of a onto the individual v_i .

$$A = U D V^T \dots \quad (1)$$

$$A V_k = U D V^T V_k \dots \quad (2)$$

$$A V_k = U D (V^T V_k) \dots \quad (3)$$

$$V^T \in \mathbb{R}^{k \times d} \quad V_k \in \mathbb{R}^{d \times k}$$

$$V^T V_k = \begin{bmatrix} I_k \\ 0 \end{bmatrix}$$

$$A V_k = U_k D_k$$

Now,

$$A_k = U_k D_k V_k^T \text{ Substituting } U_k D_k \text{ with } A V_k.$$

$$A_k = A (V_k V_k^T) \dots \quad (4)$$

this proves that each row of A_k is a projection of the corresponding row of A onto the v_1, \dots, v_k

4.d

The Frobenium norm of a matrix $M \in \mathbb{R}^{m \times n}$ is defined as

$$\|M\|_F = \sqrt{\sum_{i=1}^n \sum_{j=1}^m M_{ij}^2}$$

Show that

$$A_k = \operatorname{argmin}_{\operatorname{rank}(B)=k} \|A - B\|_F$$

where the arg min is taken over matrices of rank k. Hint: Use the fact that V_k is the best-fit k-dimensional subspace for the rows of A .

Rank of matrix = Number of independent direction the matrix has.

Lets assume A is a 10×8 matrix. There are 8 columns but the rows truly depend on 3 underlying directions / patterns i.e. 3 columns. That is the Rank / True Rank / Actual Rank. We determined that the $r = \operatorname{rank}(A)$ by counting the number of non-zero σ_i values in the following equation:

$$A = UDV^T = \sum_{i=1}^r \sigma_i u_i v_i^T$$

$$A = \sigma_1 u_1 v_1^T + \sigma_2 u_2 v_2^T + \dots + \sigma_r u_r v_r^T$$

$$r = \operatorname{rank}(A)$$

$$\sigma_1 > \sigma_2 \dots \sigma_r > 0$$

Low Rank Matrix has few main directions that are most important.

In low Rank approximation (Truncated SVD), we keep only the top k columns such that $k < r$

$$A_k = \sigma_1 u_1 v_1^T + \sigma_2 u_2 v_2^T + \dots + \sigma_k u_k v_k^T$$

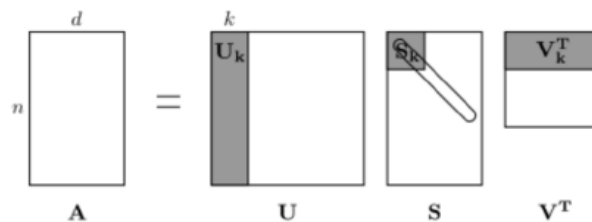


Figure 1: Dimensionality reduction by truncated SVD

Figure 2: From Assignment A1

$$A_k = U_k D_k V_k^T$$

Using Frobenium norm

$$A_F^2 = \sum_{i=1}^r \sigma_i^2$$

$$A_k^2_F = \sum_{i=1}^k \sigma_i^2$$

$$A - A_k^2_F = \sum_{i=k+1}^r \sigma_i^2$$

Given $\sigma_1 > \sigma_2 \dots \sigma_r > 0$, the norm will be smallest if the top k eigen values are chosen and hence satisfies the equation:

$$A_k = \operatorname{argmin}_{\operatorname{rank}(B)=k} \|A - B\|_F$$