UNIVERSITÄT DES SAARLANDES Prof. Dr. Dietrich Klakow Lehrstuhl für Signalverarbeitung NNTI Winter Term 2020/2021



# Exercise Sheet 7

Regularization for Deep Learning

Deadline: 12.01.2021, 23:59

### Exercise 7.1 - $L_1$ and $L_2$ Regularization

(0.25+0.25+0.25+0.25+1+1 points)

In the lecture, you were introduced to different regularization methods such as  $L_1$  and  $L_2$  Regularization. Please answer the following questions.

- a) Sketch the contour plot of  $L_1$  and  $L_2$  norms.
- b) Why would one prefer to use  $L_1$  regularization instead of  $L_2$  regularization?
- c) Is it possible to use a new regularization method that makes use of both of  $L_1$  and  $L_2$ ? Motivate your answer and if yes what it would be beneficial for?
- d) Regularization is defined as any modification that we make to a learning algorithm that is intended to reduce its generalization error as well as its training error. Is this true? Motivate your answer.
- e) Why doesn't  $L_2$  -Regularization set variables to 0? Consider the case with  $L_2$  -regularized least squares problem with 1 feature. Note that you should give mathematical justification.
- f) Why does  $L_1$  -Regularization set variables to 0? Consider the case with  $L_1$  -regularized least squares problem with 1 feature. Note that you should give mathematical justification.

### Exercise 7.2 - Multi-Task Learning and Data Augmentation (1.5 +1 points)

Multi-Task Learning and Data Augmentation are two important concepts in Deep Learning.

- a) Read the following paper on Multi-Task Learning. Explicitly state **3 problems** and **3 solutions/methods** that the author pose related to information transfer in Multi-Task Learning. Your answer should not exceed more than 6-7 sentences. Reading the introduction (go simply through conceptually without focusing too much on the exact details) should be more than enough to give a clear view of the topic.
- b) In the previous lecture you were shown a Pytorch sample code on the MNIST dataset. We have attached it again named as "multilayer\_perceptron.py" file. Using that code please do the following data augmentation techniques.

- Add random noise (or any distribution that you think might be useful). Comment on the amount of noise and how it affects the results.
- Shift the images in all four directions by the given. Comment on the amount of shift that there is an improvement in accuracy (if there is an improvement).
- Pick another augmentation technique on your own and comment on how changing it can improve the results.

•

Please copy the code from the .py file given, edit it, and upload the solution as a Jupiter Notebook (It will not be graded if you simply give a .py file because it will give us difficulty in grading).

#### Exercise 7.3 - Early Stopping

(1+1+1 points)

Consider a quadratic error function of the form

$$E = E_0 + \frac{1}{2}(w - w^*)^T H(w - w^*)$$

where  $w^*$  represents the minimum, and the Hessian matrix H is positive definite and constant. Suppose the initial weight vector  $w^{(0)}$  is chosen to be at the origin and is updated using simple gradient descent

$$w^{\tau} = w^{\tau - 1} - \epsilon \nabla E$$

where  $\tau$  denotes the step number, and  $\epsilon$  is the learning rate (which is assumed to be small). After  $\tau$  steps, the components of the weight vector parallel to the eigenvectors of H can be written

$$w_j^{\tau} = \{1 - (1 - \epsilon \lambda_j)^{\tau}\} w_j^*$$

where  $w_j = w^T v_j$  and  $v_j$  and  $\lambda_j$  are the eigenvectors and eigenvalues, respectively, of H.

- a) Show that as  $\tau \to \infty$ , this gives  $w_{\tau} \to w^*$  as expected, provided  $|1 \epsilon \lambda_j| < 1$ .
- b) Now suppose that training is halted after a finite number of  $\tau$  steps. Show that the components of the weight vector parallel to the eigenvectors of the Hessian satisfy

$$w_j^{\tau} \simeq w_j^* \text{ when } \lambda_j \gg (\epsilon \tau)^{-1}$$
  
 $|w_j^{\tau}| \ll |w_j^*| \text{ when } \lambda_j \ll (\epsilon \tau)^{-1}$ 

c) Show that  $(\epsilon \tau)^{-1}$  is analogous to the regularization parameter  $\alpha$  in  $L_2$  Parameter Regularization.

#### Exercise 7.4 - Universal Approximation Theorem

(0.5+0.5+0.5 points)

- a) Please take a look at the Universal Approximation Theorem paper. Please concisely cite the main contribution/idea of the paper.
- b) Indeed there is a previous work related to the representation capacity of neural networks. Why is this result weaker than the paper in Part a? What is the main idea of the paper?
- c) State a reason and explain why, in practice, you would use deeper networks.

## Submission instructions

The following instructions are mandatory. If you are not following them, tutors can decide to not correct your exercise.

- Make sure to write the Microsoft Teams user name, student id and the name of each member of your team on your submission.
- Your assignment solution must be uploaded by only **one** of your team members to the 'Assignments' tab of the tutorial team (in **Microsoft Teams**).
- Upload the solution as a zip file which contains the solution to the theoretical and programming part.
- If you have any trouble with the submission, contact your tutor **before** the deadline.