Chapter 6. Classification and Prediction

- What is classification? What is prediction?
- Issues regarding classification and prediction
- Classification by decision tree induction
- Bayesian classification
- Rule-based classification

- Prediction
- Accuracy and error measures
- Summary

Classification vs. Prediction

Classification

- predicts categorical class labels (discrete or nominal)
- classifies data (constructs a model) based on the training set and the values (class labels) in a classifying attribute and uses it in classifying new data

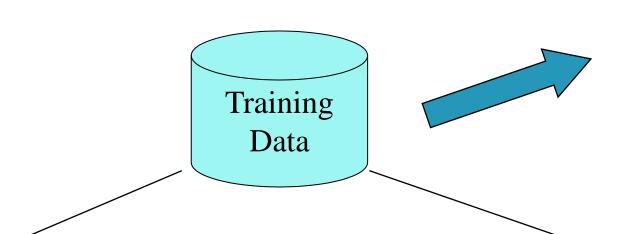
Prediction

- models continuous-valued functions, i.e., predicts unknown or missing values
- Typical applications
 - Credit approval
 - Target marketing
 - Medical diagnosis
 - Fraud detection

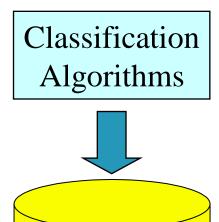
Classification—A Two-Step Process

- Model construction: describing a set of predetermined classes
 - Each tuple/sample is assumed to belong to a predefined class, as determined by the class label attribute
 - The set of tuples used for model construction is training set
 - The model is represented as classification rules, decision trees, or mathematical formulae
- Model usage: for classifying future or unknown objects
 - Estimate accuracy of the model
 - The known label of test sample is compared with the classified result from the model
 - Accuracy rate is the percentage of test set samples that are correctly classified by the model
 - Test set is independent of training set, otherwise over-fitting will occur
 - If the accuracy is acceptable, use the model to classify data tuples whose class labels are not known

Process (1): Model Construction



NAME	RANK	YEARS	TENURED
Mike	Assistant Prof	3	no
Mary	Assistant Prof	7	yes
Bill	Professor	2	yes
Jim	Associate Prof	7	yes
Dave	Assistant Prof	6	no
Anne	Associate Prof	3	no

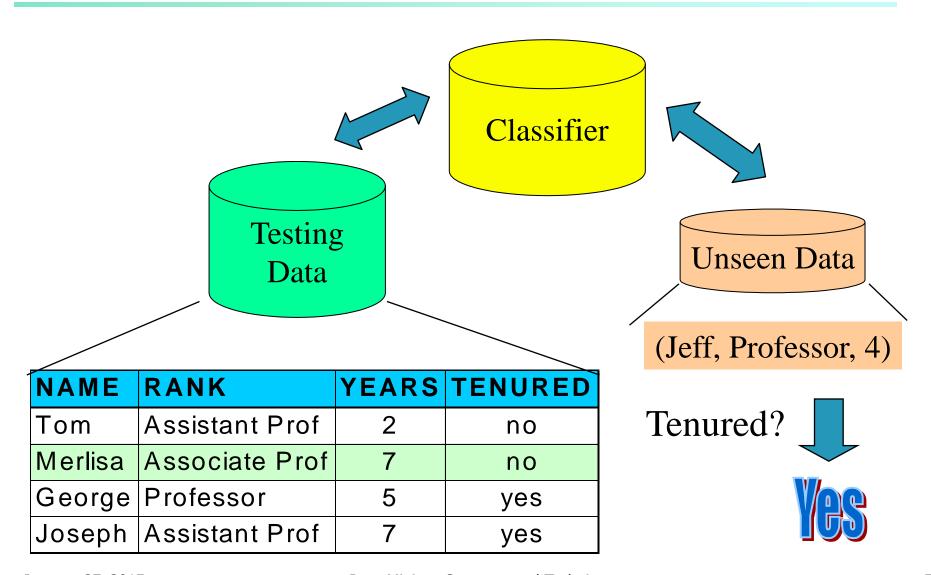


Classifier

(Model)

IF rank = 'professor'
OR years > 6
THEN tenured = 'yes'

Process (2): Using the Model in Prediction



Supervised vs. Unsupervised Learning

- Supervised learning (classification)
 - Supervision: The training data (observations, measurements, etc.) are accompanied by labels indicating the class of the observations
 - New data is classified based on the training set
- Unsupervised learning (clustering)
 - The class labels of training data is unknown
 - Given a set of measurements, observations, etc. with the aim of establishing the existence of classes or clusters in the data

Issues: Data Preparation

- Data cleaning
 - Preprocess data in order to reduce noise and handle missing values
- Relevance analysis (feature selection)
 - Remove the irrelevant or redundant attributes
- Data transformation
 - Generalize and/or normalize data

Issues: Evaluating Classification Methods

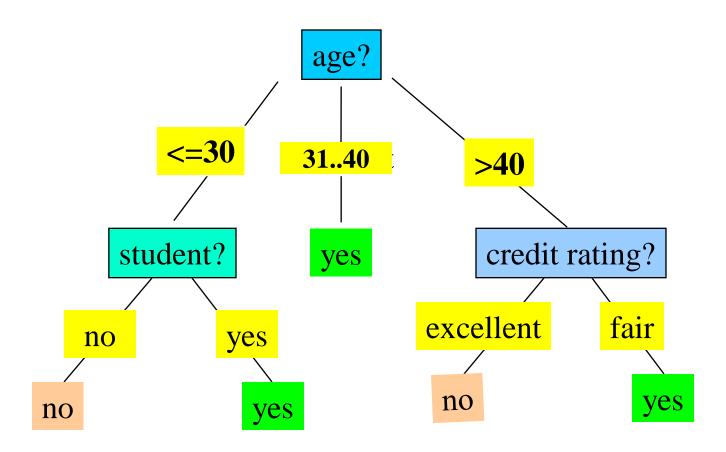
- Accuracy
 - classifier accuracy: predicting class label
 - predictor accuracy: guessing value of predicted attributes
- Speed
 - time to construct the model (training time)
 - time to use the model (classification/prediction time)
- Robustness: handling noise and missing values
- Scalability: efficiency in disk-resident databases
- Interpretability
 - understanding and insight provided by the model
- Other measures, e.g., goodness of rules, such as decision tree size or compactness of classification rules

Decision Tree Induction: Training Dataset

This follows an example of Quinlan's ID3

age	income	student	credit_rating	buys_computer
<=30	high	no	fair	no
<=30	high	no	excellent	no
3140	high	no	fair	yes
>40	medium	no	fair	yes
>40	low	yes	fair	yes
>40	low	yes	excellent	no
3140	low	yes	excellent	yes
<=30	medium	no	fair	no
<=30	low	yes	fair	yes
>40	medium	yes	fair	yes
<=30	medium	yes	excellent	yes
3140	medium	no	excellent	yes
3140	high	yes	fair	yes
>40	medium	no	excellent	no

Output: A Decision Tree for "buys_computer"

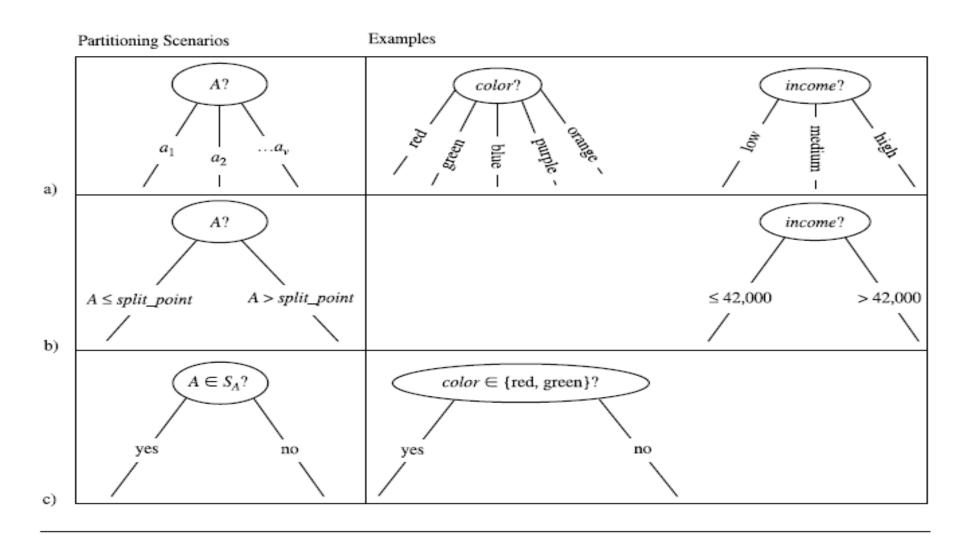


- Basic algorithm (a greedy algorithm)
 - Tree is constructed in a top-down recursive divide-and-conquer manner
 - At start, all the training examples are at the root
 - Attributes are categorical (if continuous-valued, they are discretized in advance)
 - Examples are partitioned recursively based on selected attributes
 - Test attributes are selected on the basis of a heuristic or statistical measure (e.g., information gain)
- Conditions for stopping partitioning
 - All samples for a given node belong to the same class
 - There are no remaining attributes for further partitioning –
 majority voting is employed for classifying the leaf
 - There are no samples left

- Algorithm: Generate_decision_tree.Generate a decision tree from the given data
- Input: The training samples, represented by discrete valued attributes, the set of candidate attributes, attribute_list.
- Output: A decision tree.
- Method:
 - (1) create a node N;
 - (2) if samples are all of the same class, C then
 - (3) return N as a leaf node labelled with the class C;

- (4) if attribute_list is empty then
- (5) return N as a leaf node labelled with the most common class in samples;// majority voting
- (6) select test_attribute , the attribute among attribute_list with the highest information gain;
- (7) label node N with the test_attribute;
- (8) **for each** known value a_i of test attribute // partition the samples
- (9) Grow a branch from node N for the condition test_attribute = a_i (10) let s_i be the set of samples in *samples* for which test attribute = a_i

(11) if s_i is empty then
 (12) attach a leaf labelled with the most common class in samples;
 (13) else attach a node returned by Generate_decision_tree
 (s_i,attribute list,test attribute)



4 Three possibilities for partitioning tuples based on the splitting criterion, shown with examples. Let *A* be the splitting attribute. (a) If *A* is discrete-valued, then one branch is grown for each known value of *A*. (b) If *A* is continuous-valued, then two branches are grown, corresponding to *A* ≤ *split_point* and *A* > *split_point*. (c) If *A* is discrete-valued and a binary tree must be produced, then the test is of the form *A* ∈ *S_A*, where *S_A* is the splitting subset for *A*.

Attribute Selection Measure: Information Gain (ID3/C4.5)

- Select the attribute with the highest information gain
- Let p_i be the probability that an arbitrary tuple in D belongs to class C_i , estimated by $|C_{i,D}|/|D|$
- Expected information (entropy) needed to classify a tuple in D: $Info(D) = -\sum_{i=1}^{m} p_i \log_2(p_i)$
- Information needed (after using A to split D into v partitions) to classify D: $Info_A(D) = \sum_{j=1}^{\nu} \frac{|D_j|}{|D|} \times I(D_j)$
- Information gained by branching on attribute A

$$Gain(A) = Info(D) - Info_A(D)$$

Attribute Selection: Information Gain

- Class P: buys_computer = "yes"
- Class N: buys_computer = "no"

$$Info(D) = I(9,5) = -\frac{9}{14}\log_2(\frac{9}{14}) - \frac{5}{14}\log_2(\frac{5}{14}) = 0.940$$

age	p _i	n _i	I(p _i , n _i)
<=30	2	3	0.971
3140	4	0	0
>40	3	2	0.971

age	income	student	credit_rating	buys_computer
<=30	high	no	fair	no
<=30	high	no	excellent	no
3140	high	no	fair	yes
>40	medium	no	fair	yes
>40	low	yes	fair	yes
>40	low	yes	excellent	no
3140	low	yes	excellent	yes
<=30	medium	no	fair	no
<=30	low	yes	fair	yes
>40	medium	yes	fair	yes
<=30	medium	yes	excellent	yes
3140	medium	no	excellent	yes
3140	high	yes	fair	yes
>40	medium	no	excellent	no

$$\begin{split} \mathit{Info}_{age}(D) &= \frac{5}{14} \times (-\frac{2}{5} \log_2 \frac{2}{5} - \frac{3}{5} \log_2 \frac{3}{5}) \\ &+ \frac{4}{14} \times (-\frac{4}{4} \log_2 \frac{4}{4} - \frac{0}{4} \log_2 \frac{0}{4}) \\ &+ \frac{5}{14} \times (-\frac{3}{5} \log_2 \frac{3}{5} - \frac{2}{5} \log_2 \frac{2}{5}) \\ &= 0.694 \text{ bits.} \end{split}$$

$$Gain(age) = Info(D) - Info_{age}(D) = 0.246$$

$$Gain(income) = 0.029$$

$$Gain(student) = 0.151$$

$$Gain(credit_rating) = 0.048$$

Gini index (CART, IBM IntelligentMiner)

Ex. D has 9 tuples in buys_computer = "yes" and 5 in "no"

$$gini(D) = 1 - \left(\frac{9}{14}\right)^2 - \left(\frac{5}{14}\right)^2 = 0.459$$

Suppose the attribute income partitions D into 10 in D_1 : {low, medium} and 4 in D₂ $gini_{income \in \{low, medium\}}(D) = \left(\frac{10}{14}\right)Gini(D_1) + \left(\frac{4}{14}\right)Gini(D_1)$

$$= \frac{10}{14} \left(1 - \left(\frac{6}{10}\right)^2 - \left(\frac{4}{10}\right)^2\right) + \frac{4}{14} \left(1 - \left(\frac{1}{4}\right)^2 - \left(\frac{3}{4}\right)^2\right)$$
$$= 0.450$$

$$= Gini_{income \in \{high\}}(D)$$

but gini{medium,high} is 0.30 and thus the best since it is the lowest

- All attributes are assumed continuous-valued
- May need other tools, e.g., clustering, to get the possible split values
- Can be modified for categorical attributes

Overfitting and Tree Pruning

Overfitting:

- Overfitting results in decision trees that are more complex than necessary
- An induced tree may overfit the training data
 - Too many branches, some may reflect anomalies due to noise or outliers
 - Poor accuracy for unseen samples
- Two approaches to avoid overfitting
 - Prepruning: Halt tree construction early—do not split a node if this would result in the goodness measure falling below a threshold
 - Difficult to choose an appropriate threshold

Post pruning

- Trim the nodes of the decision tree in a bottom-up fashion
- If generalization error improves after trimming, replace sub-tree by a leaf node.
- Class label of leaf node is determined from majority class of instances in the sub-tree

Classification in Large Databases

- Classification—a classical problem extensively studied by statisticians and machine learning researchers
- Scalability: Classifying data sets with millions of examples and hundreds of attributes with reasonable speed
- Why decision tree induction in data mining?
 - relatively faster learning speed (than other classification methods)
 - convertible to simple and easy to understand classification rules
 - can use SQL queries for accessing databases
 - comparable classification accuracy with other methods

Induction Methods in Data Mining Studies

SLIQ

- builds an index for each attribute and only class list and the current attribute list reside in memory.
- Handles disk resident data sets using disk resident attribute list and memory resident class list.
- Memory restriction is there when the training set is tool large.
- When a class list becomes too large performance of SLIQ decreases.

SPRINT

- constructs an attribute list data structure.
- SPRINT removes all memory restrictions.
- Designed to be easily parallelized.

Scalable Decision Tree Induction Methods in Data Mining Studies

PUBLIC

integrates tree splitting and tree pruning: stop growing the tree earlier

RainForest

- separates the scalability aspects from the criteria that determine the quality of the tree
- builds an AVC-list (attribute, value, class label)
- Rain forest report a speed up over SPRINT.

Bayesian Classification: Why?

- A statistical classifier: performs probabilistic prediction, i.e., predicts class membership probabilities
- Foundation: Based on Bayes' Theorem.
- <u>Performance:</u> A simple Bayesian classifier, naïve Bayesian classifier, has comparable performance with decision tree and selected neural network classifiers
- <u>Incremental</u>: Each training example can incrementally increase/decrease the probability that a hypothesis is correct — prior knowledge can be combined with observed data
- Standard: Even when Bayesian methods are computationally intractable, they can provide a standard of optimal decision making against which other methods can be measured

Bayesian Theorem: Basics

- Let X be a data sample ("evidence"): class label is unknown
- Let H be a hypothesis that X belongs to class C
- Classification is to determine P(H|X), the probability that the hypothesis holds given the observed data sample X
- P(H) (prior probability), the initial probability
 - E.g., X will buy computer, regardless of age, income, ...
- P(X): probability that sample data is observed
- P(X|H) (posteriori probability), the probability of observing the sample X, given that the hypothesis holds
 - E.g., Given that X will buy computer, the prob. that X is 31..40, medium income

Bayesian Theorem

 Given training data X, posteriori probability of a hypothesis H, P(H|X), follows the Bayes theorem

$$P(H|\mathbf{X}) = \frac{P(\mathbf{X}|H)P(H)}{P(\mathbf{X})}$$

- Informally, this can be written as posteriori = likelihood x prior/evidence
- Predicts **X** belongs to C_i iff the probability $P(C_i|\mathbf{X})$ is the highest among all the $P(C_k|X)$ for all the k classes
- Practical difficulty: require initial knowledge of many probabilities, significant computational cost

Towards Naïve Bayesian Classifier

- Let D be a training set of tuples and their associated class labels, and each tuple is represented by an n-D attribute vector $\mathbf{X} = (x_1, x_2, ..., x_n)$
- Suppose there are m classes C₁, C₂, ..., C_m.
- Classification is to derive the maximum posteriori, i.e., the maximal P(C_i|X)
- This can be derived from Bayes' theorem

$$P(C_i|\mathbf{X}) = \frac{P(\mathbf{X}|C_i)P(C_i)}{P(\mathbf{X})}$$

Since P(X) is constant for all classes, only

$$P(C_i|\mathbf{X}) = P(\mathbf{X}|C_i)P(C_i)$$

needs to be maximized

Derivation of Naïve Bayes Classifier

A simplified assumption: attributes are conditionally independent (i.e., no dependence relation between attributes):

 $P(\mathbf{X} \mid C_i) = \prod_{k=1}^{n} P(x_k \mid C_i) = P(x_1 \mid C_i) \times P(x_2 \mid C_i) \times ... \times P(x_n \mid C_i)$

- This greatly reduces the computation cost: Only counts the class distribution
- If A_k is categorical, $P(x_k|C_i)$ is the # of tuples in C_i having value x_k for A_k divided by $|C_{i,D}|$ (# of tuples of C_i in D)
- If A_k is continous-valued, $P(x_k|C_i)$ is usually computed based on Gaussian distribution with a mean μ and standard deviation σ $g(x,\mu,\sigma) = \frac{1}{\sqrt{2\pi}\sigma}e^{-\frac{(x-\mu)^2}{2\sigma^2}}$

and
$$P(x_k|C_i)$$
 is

$$P(\mathbf{X} \mid C_i) = g(x_k, \mu_{C_i}, \sigma_{C_i})$$

Naïve Bayesian Classifier: Training Dataset

Class:

C1:buys_computer = 'yes'

C2:buys_computer = 'no'

Data sample

X = (age <=30,

Income = medium,

Student = yes

Credit_rating = Fair)

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age	income	studeni	credit_rating	_com
<=30	high	no	fair	no
<=30	high	no	excellent	no
3140	high	no	fair	yes
>40	medium	no	fair	yes
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>40	medium	yes	fair	yes
<=30	medium	yes	excellent	yes
3140	medium	no	excellent	yes
3140	high	yes	fair	yes
>40	medium	no	excellent	no

Naïve Bayesian Classifier: An Example

- $P(C_i)$: P(buys_computer = "yes") = 9/14 = 0.643 P(buys_computer = "no") = 5/14= 0.357
- Compute P(X|C_i) for each class

```
P(age = "<=30" | buys_computer = "yes") = 2/9 = 0.222

P(age = "<= 30" | buys_computer = "no") = 3/5 = 0.6

P(income = "medium" | buys_computer = "yes") = 4/9 = 0.444

P(income = "medium" | buys_computer = "no") = 2/5 = 0.4

P(student = "yes" | buys_computer = "yes) = 6/9 = 0.667

P(student = "yes" | buys_computer = "no") = 1/5 = 0.2

P(credit_rating = "fair" | buys_computer = "yes") = 6/9 = 0.667

P(credit_rating = "fair" | buys_computer = "no") = 2/5 = 0.4
```

X = (age <= 30, income = medium, student = yes, credit_rating = fair)</p>

```
P(X|C_i): P(X|buys\_computer = "yes") = 0.222 x 0.444 x 0.667 x 0.667 = 0.044 P(X|buys\_computer = "no") = 0.6 x 0.4 x 0.2 x 0.4 = 0.019 <math>P(X|C_i)* P(C_i): P(X|buys\_computer = "yes") * P(buys\_computer = "yes") = 0.028 P(X|buys\_computer = "no") * P(buys\_computer = "no") = 0.007
```

Therefore, X belongs to class ("buys_computer = yes")

Example - 2

Outlook	Temperature	Humidity	Windy	Class
sunny	hot	high	false	N
sunny	hot	high	true	N
overcast	hot	high	false	Р
rain	mild	high	false	Р
rain	cool	normal	false	Р
rain	cool	normal	true	N
overcast	cool	normal	true	Р
sunny	mild	high	false	N
sunny	cool	normal	false	Р
rain	mild	normal	false	Р
sunny	mild	normal	true	Р
overcast	mild	high	true	Р
overcast	hot	normal	false	Р
rain	mild	high	true	N

An unseen sample

X = <rain, hot, high, false>

Play-tennis example: estimating

Temperature	Humidity	Windy	Class
hot	high	false	N
hot	high	true	N
hot	high	false	Р
mild	high	false	Р
cool	normal	false	Р
cool	normal	true	N
cool	normal	true	Р
mild	high	false	N
cool	normal	false	Р
mild	normal	false	Р
mild	normal	true	Р
mild	high	true	Р
hot	normal	false	Р
mild	high	true	N
	hot hot hot cool cool mild cool mild mild mild hot	hot high hot high hot high mild high cool normal cool normal mild high cool normal mild high mild normal mild normal mild normal mild normal mild normal	hot high true hot high false mild high false cool normal false cool normal true cool normal true mild high false cool normal true mild high false mild normal false mild normal true high false false mild normal false mild normal true high true hot normal false

	P(p) = 9/14
	P(n) = 5/14
January	27, 2015

P	P(x: C)					
SS	outlook					
	P(sunny p) = 2/9	P(sunny n) = 3/5				
	P(overcast p) = 4/9	P(overcast n) = 0				
	P(rain p) = 3/9	P(rain n) = 2/5				
	temperature					
	P(hot p) = 2/9	P(hot n) = 2/5				
	P(mild p) = 4/9	P(mild n) = 2/5				
	P(cool p) = 3/9	P(cool n) = 1/5				
	humidity					
	P(high p) = 3/9	P(high n) = 4/5				
	P(normal p) = 6/9	P(normal n) = 2/5				
	windy					
1 8/	P(true p) = 3/9	P(true n) = 3/5				

Data Mining: Concepts and Techniques $D(f_{-}|_{-}|_{-})$ $O(f_{-}|_{-})$

Play-tennis example: classifying X

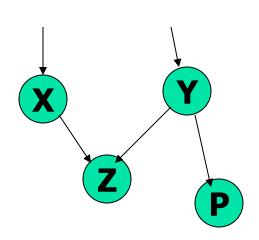
- An unseen sample X = <rain, hot, high, false>
- P(X|p)'P(p) = P(rain|p)'P(hot|p)'P(high|p)'P(false|p)'P(p) = 3/9'2/9'3/9'6/9'9/14 = 0.010582
- P(X|n)·P(n) = P(rain|n)·P(hot|n)·P(high|n)·P(false|n)·P(n) = 2/5·2/5·4/5·2/5·5/14 = 0.018286
- Sample X is classified in class n (don't play)

Naïve Bayesian Classifier: Comments

- Advantages
 - Easy to implement
 - Good results obtained in most of the cases
- Disadvantages
 - Assumption: class conditional independence, therefore loss of accuracy
 - Practically, dependencies exist among variables
 - E.g., hospitals: patients: Profile: age, family history, etc. Symptoms: fever, cough etc., Disease: lung cancer, diabetes, etc.
 - Dependencies among these cannot be modeled by Naïve Bayesian Classifier
- How to deal with these dependencies?
 - Bayesian Belief Networks

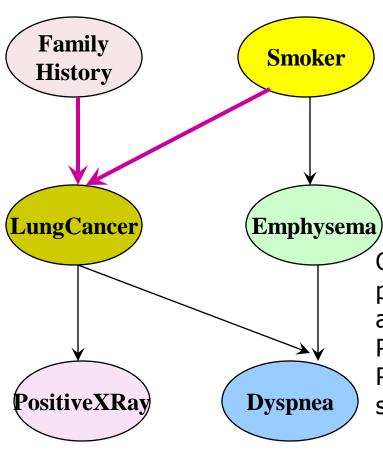
Bayesian Belief Networks

- Bayesian belief network allows a subset of the variables conditionally independent
- A graphical model of casual relationships
 - Represents <u>dependency</u> among the variables
 - Gives a specification of joint probability distribution



- Nodes: random variables
- ☐ Links: dependency
- ☐ X and Y are the parents of Z, and Y is the parent of P
- No dependency between Z and P
- ☐ Has no loops or cycles

Bayesian Belief Network: An Example



The **conditional probability table** (**CPT**) for variable LungCancer:

	(FH, S)	$(FH, \sim S)$	(~FH, S)	(~FH, ~S)
LC	0.8	0.5	0.7	0.1
~LC	0.2	0.5	0.3	0.9

CPT shows the conditional probability for each possible combination of its parents. The CPT for a variable Z specifies the conditional distribution P(Z/Parents(Z)).

P(Lungcancer="yes" | FamilyHistory = "yes", smoker="yes")=0.8

Bayesian Belief Networks

Derivation of the probability of a particular combination of values of **X**, from CPT:

$$P(x_1,...,x_n) = \prod_{i=1}^n P(x_i \mid Parents(X_i))$$

Data Mining: Concepts and Techniques

January 27, 2015

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- Prediction <</p>
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- Summary

What Is Prediction?

- (Numerical) prediction is similar to classification
 - construct a model
 - use model to predict continuous or ordered value for a given input
- Prediction is different from classification
 - Classification refers to predict categorical class label
 - Prediction models continuous-valued functions
- Major method for prediction: regression
 - model the relationship between one or more independent or predictor variables and a dependent or response variable
- Regression analysis
 - Linear and multiple regression
 - Non-linear regression
 - Other regression methods: generalized linear model, Poisson regression, log-linear models, regression trees

Linear Regression

<u>Linear regression</u>: involves a response variable y and a single predictor variable x

$$y = W_0 + W_1 X$$

where w_0 (y-intercept) and w_1 (slope) are regression coefficients

Method of least squares: estimates the best-fitting straight line

$$w_{1} = \frac{\sum_{i=1}^{|D|} (x_{i} - \bar{x})(y_{i} - \bar{y})}{\sum_{i=1}^{|D|} (x_{i} - \bar{x})^{2}} \qquad w_{0} = \bar{y} - w_{1}\bar{x}$$

- Multiple linear regression: involves more than one predictor variable
 - Training data is of the form $(\mathbf{X_1}, y_1), (\mathbf{X_2}, y_2), ..., (\mathbf{X_{|D|}}, y_{|D|})$
 - Ex. For 2-D data, we may have: $y = w_0 + w_1 x_1 + w_2 x_2$
 - Solvable by extension of least square method
 - Many nonlinear functions can be transformed into the above

Regression - Example

- Table shows a set of paired data where X is the number of years of work experience of a college graduate and y is the corresponding salary of the graduate.
- Y = 23.6 + 3.5X
- Predict the salary for a graduate with 10 yrs of experience.

X Years Experience	Y Salary (in \$ 1000s)	
3	30	
8	57	
9	64	
13	72	
3	36	
6	43	
11	59	
21	90	
1	20	
16	83	

Y = 58.6\$

Nonlinear Regression

- Some nonlinear models can be modeled by a polynomial function
- A polynomial regression model can be transformed into linear regression model. For example,

$$y = w_0 + w_1 x + w_2 x^2 + w_3 x^3$$

convertible to linear with new variables: $x_2 = x^2$, $x_3 = x^3$
 $y = w_0 + w_1 x + w_2 x_2 + w_3 x_3$

- Other functions, such as power function, can also be transformed to linear model
- Some models are intractable nonlinear (e.g., sum of exponential terms)
 - possible to obtain least square estimates through extensive calculation on more complex formulae

Chapter 6. Classification and Prediction

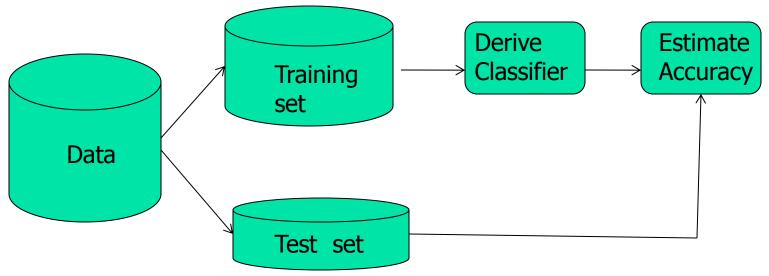
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- Prediction
- Accuracy and error measures



Evaluating the Accuracy of a Classifier or Predictor (I)

- Holdout method
 - Given data is randomly partitioned into two independent sets
 - Training set (e.g., 2/3) for model construction
 - Test set (e.g., 1/3) for accuracy estimation

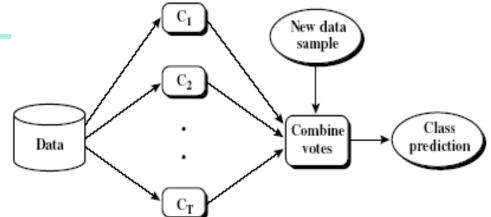


- Random sampling: a variation of holdout
 - Repeat holdout k times, accuracy = avg. of the accuracies obtained

Evaluating the Accuracy of a Classifier or **Predictor (I)**

- Cross-validation (k-fold, where k = 10 is most popular)
 - Randomly partition the data into k mutually exclusive subsets, each approximately equal size
 - At iteration, use D_i as test set and others as training set
 - The accuracy estimate =
 Overall number of correct classifications from the k iterations
 Total number of samples in the initial data
 - Leave-one-out: k folds where k = # of tuples, for small sized data
 - Stratified cross-validation: folds are stratified so that class dist. in each fold is approx. the same as that in the initial data.

Ensemble Methods: Increasing the Accuracy



- Ensemble methods
 - Use a combination of models to increase accuracy
 - Combine a series of k learned models, M₁, M₂, ..., M_k, with the aim of creating an improved model M*
- Popular ensemble methods
 - Bagging: averaging the prediction over a collection of classifiers
 - Boosting: weighted vote with a collection of classifiers
 - Ensemble: combining a set of heterogeneous classifiers

Bagging: Boostrap Aggregation

- Analogy: Diagnosis based on multiple doctors' majority vote
- Training
 - Given a set D of d tuples, at each iteration i, a training set D_i of d tuples is sampled with replacement from D (i.e., boostrap)
 - A classifier model M_i is learned for each training set D_i
- Classification: classify an unknown sample X
 - Each classifier M_i returns its class prediction
 - The bagged classifier M* counts the votes and assigns the class with the most votes to X
- Prediction: can be applied to the prediction of continuous values by taking the average value of each prediction for a given test tuple
- Accuracy
 - Often significant better than a single classifier derived from D
 - For noise data: not considerably worse, more robust
 - Proved improved accuracy in prediction

Boosting

- Analogy: Consult several doctors, based on a combination of weighted diagnoses—weight assigned based on the previous diagnosis accuracy
- How boosting works?
 - Weights are assigned to each training tuple
 - A series of k classifiers is iteratively learned
 - After a classifier M_i is learned, the weights are updated to allow the subsequent classifier, M_{i+1}, to pay more attention to the training tuples that were misclassified by M_i
 - The final M* combines the votes of each individual classifier, where the weight of each classifier's vote is a function of its accuracy
- The boosting algorithm can be extended for the prediction of continuous values
- Comparing with bagging: boosting tends to achieve greater accuracy, but it also risks overfitting the model to misclassified data

Classifier Accuracy Measures and Confusion matrix

- t_pos (Eg "cancer samples" that were correctly classified as such)
- t_neg ("not_cancer" samples that were correctly classified as such)
- False positives ("not_cancer" samples that were incorrectly labeled as "cancer")
- False negative("cancer" samples that were incorrectly labeled as "not_cancer")
- pos is the number of positive samples
- neg is the number of negative

	C_1	C ₂
C_1	t_pos	f_neg
C ₂	f_pos	t_neg

Classifier Accuracy Measures

classes	buy_computer = yes	buy_computer = no	total	recognition(%)
buy_computer = yes	6954	46	7000	99.34
buy_computer = no	412	2588	3000	86.27
total	7366	2634	10000	95.52

- Accuracy of a classifier M, acc(M): percentage of test set tuples that are correctly classified by the model M
 - Error rate (misclassification rate) of M = 1 acc(M)
 - Given m classes, CM_{i,j}, an entry in a confusion matrix, indicates # of tuples in class i that are labeled by the classifier as class j
- Alternative accuracy measures (e.g., for cancer diagnosis)

```
sensitivity = t-pos/pos /* true positive recognition rate */
specificity = t-neg/neg /* true negative recognition rate */
precision = t-pos/(t-pos + f-pos)
accuracy = sensitivity * pos/(pos + neg) + specificity * neg/(pos + neg)
```

This model can also be used for cost-benefit analysis

Predictor Error Measures

- Measure predictor accuracy: measure how far off the predicted value is from the actual known value
- Loss function: measures the error betw. y_i and the predicted value y_i'
 - Absolute error: | y_i y_i'|
 - Squared error: $(y_i y_i')^2$
- Test error (generalization error): the average loss over the test set

 Mean absolute error: $\sum_{i=1}^{d} |y_i y_i'|$ Mean squared error: $\sum_{i=1}^{d} (y_i y_i')^2$ Relative absolute error: $\sum_{i=1}^{d} |y_i y_i'|$ Relative squared error: $\sum_{i=1}^{d} (y_i y_i')^2$ $\sum_{i=1}^{d} (y_i \overline{y})^2$

The mean squared-error exaggerates the presence of outliers

Popularly use (square) root mean-square error, similarly, root relative squared error

