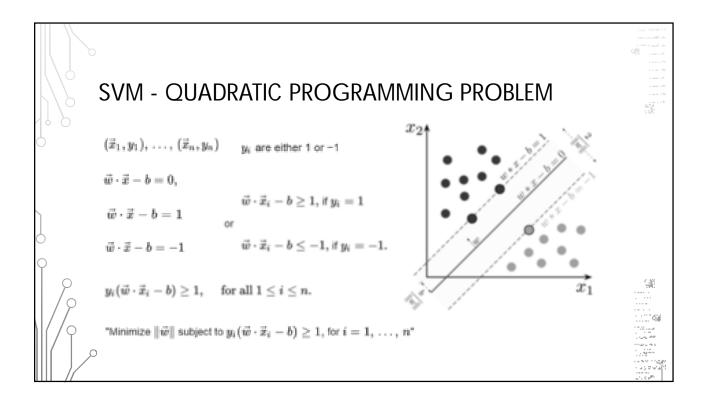


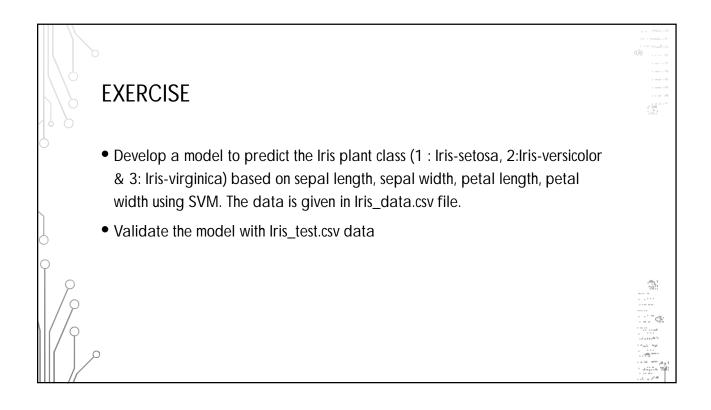


Suppose for $X = X_1$, X_2 , X_3 X_p

- If $w_0 + w_1 X_1 + w_2 X_2 + w_3 X_3 + \dots + w_p X_p > 0$ Then the X lies in one side of the hyperplane
- If $w_0 + w_1 X_1 + w_2 X_2 + w_3 X_3 + \dots + w_p X_p < 0$ Then the X lies in one the other side of the hyperplane
- Hyperplane divide p dimensional space into 2 halves
- A value close to the line returns a value close to zero and the point may be difficult to classify
- If the magnitude of the value is large, the model may have more confidence in the prediction

CONTD.. • Distance between the line and the closest data points is referred to as the margin • Best or optimal line that can separate the two classes is the line that has the largest margin. This is called Maximal-Margin hyperplane.





```
PYTHON CODE:
                                         np. random. seed(0)
import numpy as np
                                         order = np.random.permutation(n_sample)
import matplotlib.pyplot as plt
                                         X = X[order]
from sklearn import datasets, svm
                                         y = y[order].astype(np.float)
iris = datasets.load_iris()
                                         X_{train} = X[:int(.9 * n_sample)]
X = iris. data
                                         y_{train} = y[:int(.9 * n_sample)]
print(X)
                                         X_{\text{test}} = X[int(.9 * n_{\text{sample}}):]
y = iris.target
                                         y_{test} = y[int(.9 * n_{sample}):]
print(y)
X = X[y != 0, :2]
y = y[y != 0]
n_{sample} = len(X)
```

```
CONTD..
                                                     y_min = X[:, 1].min()
                                                     y_max = X[:, 1].max()
  classifier = svm. SVC(kernel='linear',
                                                     XX, YY = np. mgrid[x_min: x_max: 200j,
  gamma=10)
                                                     y_mi n: y_max: 200j ]
  classifier.fit(X_train, y_train)
                                                     Z = classifier.decision_function(np.c_[XX.ravel(),
  plt.figure()
                                                     YY. ravel ()])
  plt.clf()
                                                     # Put the result into a color plot
  plt.scatter(X[:, 0], X[:, 1], c=y, zorder=10,
                                                     Z = Z. reshape(XX. shape)
  cmap=plt.cm.Paired, edgecolor='k', s=20)
                                                     plt.pcolormesh(XX, YY, Z > 0, cmap=plt.cm.Paired)
  # Circle out the test data
                                                     plt.contour(XX, YY, Z, colors=['k', 'k', 'k'],
  plt.scatter(X_test[:, 0], X_test[:, 1], s=80,
                                                                    linestyles=['--', '-', '--'],
facecolors='none', zorder=10, edgecolor='k')
                                                     level s=[-.5, 0, .5])
  plt.axis('tight')
                                                     plt.title('linear')
   x_min = X[:, 0].min() 
                                                     plt.show()
  x_max = X[:, 0].max()
```

