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Title:	Binary Search Algorithm
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Experiment No. 4

Title: Binary Search Algorithm

Aim: To study and implement Binary Search Algorithm

Objective: To introduce Divide and Conquer based algorithms

Theory:

Search a sorted array by repeatedly dividing the search interval in half. Begin with an interval covering the whole array. If the value of the search key is less than the item in the middle of the interval, narrow the interval to the lower half. Otherwise, narrow it to the upper half. Repeatedly check until the value is found or the interval is empty

- Binary search is efficient than linear search. For binary search, the array must be sorted, which is not required in case of linear search.
- It is divide and conquer based search technique.
- In each step the algorithms divides the list into two halves and check if the element to be searched is on upper or lower half the array
- If the element is found, algorithm returns.





The idea of binary search is to use the information that the array is sorted and reduce the time complexity to $O(Log\ n)$.

Compare x with the middle element.	
If x matches with the middle element, we return the mid index.	
Else If x is greater than the mid element, then x can only lie in the right half subarray	
after the mid element. So we recur for the right half.	
Else (x is smaller) recur for the left half.	
Binary Search reduces search space by half in every iterations. In a linear search, search	
space was reduced by one only.	
n=elements in the array	
Binary Search would hit the bottom very quickly.	

	Linear Search	Binary Search
2 nd iteration	n-1	n/2
3 rd iteration	n-2	n/4



Example:

```
Algorithm BINARY_SEARCH(A, Key)
     11 Description: Perform Bs on ornay A

11 Ilp: away A of size n & key element

11 olp: Success/facilure.

15 11,22,33,
     10w -1
                                              key= 33
     high - n
   while low < high do
                                            1000 = 1
                                            Myn = 8
    mid = (10w + high)/2

if A [mid] = = key-then

return mid
                                            mid = 1+8/2
                                              = 4
                                             A[+) == 33 X
                                             A[4] < 33 x
     else if Armid] < key then
                                            high = 4-1
              10w ← mid+1
                                             My5 =3
     else high + mid-1
                                            511,22,333
     end
                                                123
end
                                            100=1
return 0
                                            high = 3 -
                                            mid = 1+3/2
                                                = 2
                                            A[2] == 33 X
                                             22 < 33
                                             100=3 -
                                             {333} mid = 3+3/2 = 3
                                             A[3] = 33
                                            Atmid ] = 33
                                            key = AES]
```



Algorithm and Complexity:

The binary search

Algorithm 3: the binary search algorithm

```
Procedure binary search (x: integer, a<sub>1</sub>, a<sub>2</sub>, ...,a<sub>n</sub>: increasing integers)
    i :=1 { i is left endpoint of search interval}
    j :=n { j is right endpoint of search interval}

While i < j

begin
    m := \[ (i + j) / 2 \]
    if x > a<sub>m</sub> then i := m+1
    else j := m

end

If x = a<sub>i</sub> then location := i
else location :=0
{location is the subscript of the term equal to x, or 0 if x is not found}
```

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BINARY SEARCH Array шш Best Average Worst Divide and Conquer 0(1) O (log n) O (log n) search (A, t) search (A, 11) low ix high low = 0first pass 1 8 9 11 15 17 2. high = n-13. while (low \leq high) do low ix high 4. ix = (low + high)/2second pass 1 4 8 9 11 15 17 5. if (t = A[ix]) then low ix 6. return true high 7. else if (t < A[ix]) then third pass 1 4 8. high = ix - 19. else low = ix + 1explored elements 10. return false end



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Best Case:

Key is first compared with the middle element of the array.

The key is in the middle position of the array, the algorithm does only one comparison, irrespective of the size of the array.

T(n)=1

Worst Case:

In each iteration search space of BS is reduced by half, Maximum log n(base 2) array divisions are possible.

Recurrence relation is

T(n)=T(n/2)+1

Running Time is O(logn).

Average Case:

Key element neither is in the middle nor at the leaf level of the search tree.

It does half of the log n(base 2).

Base case=O(1)

Average and worst case=O(logn)

Implementation:

```
#include <stdlib.h>
#include <conio.h>
#include <stdio.h>
int main(){
  int key, low, high, mid, n, i, A[100];
  clrscr();
  printf("Enter the size of array;");
  scanf("%d",&n);
  printf("\nEnter the array elements : \n");
  for(i=0;i<n;i++){
    scanf("%d",&A[i]);
}</pre>
```



```
}
printf("\nEnter the key : ");
scanf("%d",&key);
low=1;
high=n;
while(low<=high){</pre>
 mid=(low+high)/2;
 if(A[mid]==key){
  printf("\nKey found at: %d ",mid);
  break;
 else if(A[mid]<key){
  low=mid+1;
  }
 else{
  high=mid-1;
  }
 }
return 0;
}
```

Output:

```
Enter the size of array ;5

Enter the array elements :
2 4 1 0 22

Enter the key : 0

Key found at: 3
```



Conclusion: the experimental deployment of binary search has validated its prowess in swiftly locating target elements within sorted arrays. Leveraging its logarithmic time complexity, binary search stands as a formidable algorithm, offering optimal performance and scalability in diverse computational contexts. This empirical confirmation underscores its indispensable role in efficient data retrieval and underscores its status as a cornerstone technique in algorithmic design and analysis.