

# VOID Granularity Framework

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## 1 Introduction

In delving into the foundations of mathematics and physics, we often confront the limits of our understanding, particularly when grappling with concepts like infinity and the infinitesimally small. One such instance is the indeterminate expression  $0 \times \infty$ , which arises in geometric contexts and challenges our conventional notions of measurement and distinction. This indeterminacy hints that at the very smallest scales, distinctions between points become meaningless—a void where our traditional tools falter.

From this realization emerges the VOID Granularity Framework (VGF), an attempt to acknowledge and formalize the idea that there exists a minimal scale beyond which distinctions are not just impractical but fundamentally indeterminate. In classical geometry, space is often considered continuous and infinitely divisible. However, within our framework, we posit that there is a smallest discernible unit—the void—below which differentiation loses meaning. This concept is crucial because it suggests that mathematical fields cannot commence from a single point or number. Starting with zero alone is insufficient; we require at least one additional distinct entity to give rise to meaningful mathematics. This observation resonates with historical perspectives on counting and the development of number systems, which we'll explore further in subsequent chapters.

By introducing the concept of a VOID threshold ( $\delta_{\text{VOID}}$ ), we aim to provide a mathematical framework that accounts for the inherent limitations in measurement, computation, and perception. This threshold is adaptable, reflecting the specific granularity relevant to different fields—be it physics, mathematics, computation, or cognitive sciences. It's not a fixed constant but a context-dependent parameter that embodies the smallest meaningful distinction within a given system.

## 2 Primitive Terms and Definitions

### 2.1 System (S)

A finite set of elements with defined relationships and operations pertinent to a specific domain (physical, mathematical, computational, cognitive, biological, etc.).

This definition lays the groundwork for our framework. By considering systems as finite, we acknowledge practical limitations and focus on contexts where the VOID threshold has meaningful implications. This approach is extendable to various disciplines where mathematical modeling within finite systems is essential.

### 2.2 VOID Threshold ( $\delta_{\text{VOID}}$ )

A positive rational number representing the smallest meaningful distinction within the system  $S$ , beyond which distinctions become probabilistically indistinct due to the inherent indeterminacy of the void.

The VOID threshold is central to our framework. It encapsulates the minimal scale at which differences can be meaningfully recognized within a given system. By treating it as adaptable rather than a fixed constant, we allow the framework to be applicable across various disciplines, each with their own scales of granularity. For instance, in number theory, the smallest unit between 0 and 1 may be defined by our computational power and available memory.

### 2.3 Distance Function ( $d_S(x, y)$ )

A function  $d_S : S \times S \rightarrow \mathbb{Q}_{\geq 0}$  measuring the difference between elements  $x$  and  $y$  within  $S$ .

This function provides a quantitative measure of how distinct two elements are within the system. It's a fundamental tool that, when combined with the VOID threshold, allows us to assess distinguishability probabilistically.

### 2.4 Distinguishability Function ( $\mu_S(x, y)$ )

A function  $\mu_S : S \times S \rightarrow [0, 1]$  indicating the probability that two elements  $x$  and  $y$  are distinguishable based on the VOID threshold.

Formula:

$$\mu_S(x, y) = \frac{1}{1 + \frac{E[d_S(x, y)]}{\delta_{\text{VOID}}}}$$

where  $E[d_S(x, y)]$  is the expected value of the distance between  $x$  and  $y$ .

This function introduces a probabilistic aspect to distinguishability, acknowledging that as differences between elements approach the VOID threshold, our certainty in distinguishing them diminishes. It reflects a more nuanced understanding compared to classical binary distinctions.

### 3 Foundational Axioms

#### 3.1 Axiom 1.1: Universal VOID Granularity

For all  $x, y \in S$ :

$$\mu_S(x, y) = \frac{1}{1 + \frac{|x-y|}{\delta_{\text{VOID}}}}$$

**Explanation:**

This axiom establishes that the probability of distinguishing between any two elements in a system is governed by the ratio of their difference to the VOID threshold. As the difference  $|x-y|$  becomes much smaller than  $\delta_{\text{VOID}}$ , the probability  $\mu_S(x, y)$  approaches zero, indicating indistinguishability. Conversely, when the difference is much larger than the VOID threshold, the probability approaches one, indicating clear distinguishability.

**Role in the Theory:**

Axiom 1 serves as the foundational principle that quantifies how the VOID threshold affects our ability to distinguish between elements. It introduces a probabilistic framework that replaces classical deterministic distinctions, acknowledging the limitations imposed by the minimal unit of indeterminacy.

**Difference from Classical Mathematics:**

In classical mathematics, distinctions between elements are often considered absolute; two different elements are always distinguishable. However, this axiom introduces a probabilistic element, suggesting that distinguishability is not always guaranteed and depends on the scale relative to  $\delta_{\text{VOID}}$ . This offers a more realistic approach in situations where measurement precision is limited.

**Example – Addressing the Sorites Paradox:**

Consider the Sorites Paradox, also known as the Paradox of the Heap. The paradox arises from the vague predicate “heap” and questions when a collection of grains of sand becomes a heap. Traditional logic struggles with such paradoxes due to the lack of clear boundaries.

By applying the VOID Granularity Framework, we can model this scenario:

1. Defining the Minimal Unit:

$$\delta_{\text{VOID}} = 1 \text{ grain of sand}$$

2. Heap Membership Function:

$$\mu_{\mathcal{H}}(n) = \frac{n}{N} \quad \text{for } 0 \leq n \leq N$$

where:

- $n$  is the number of grains.
- $N$  is the number at which a collection is definitely considered a heap.

3. Probabilistic Indistinctness:

- Threshold Condition:

$$\mu_{\mathcal{H}}(n) \geq \delta_{\text{VOID}} \implies \text{Collection is likely a heap}$$

- Transition Zone: When  $n \approx \frac{N}{2}$ :

$$\mu_{\mathcal{H}}(n) \approx 0.5$$

This reflects uncertainty in classifying the collection as a heap.

**Expanding the Description:**

By applying our framework, we acknowledge that the concept of a “heap” does not have a sharp boundary but rather a probabilistic transition. This approach can resolve similar problems involving vague predicates, such as:

- The Bald Man Paradox: At what point does a person become bald?
- The Ship of Theseus: How many components can be replaced before an object loses its identity?
- Color Gradation Problems: When does red become orange?

In each case, the VOID Granularity Framework allows us to model the transition probabilistically, accepting that there are thresholds below which distinctions become indistinct.

### 3.2 Axiom 1.2: Onto-Epistemological Granularity

The VOID imposes limits on both ontological (what exists) and epistemological (what we can know) distinctions within system  $S$ .

Let  $K(x, y)$  represent the epistemic difference between  $x$  and  $y$ . Then:

$$\mu_S(x, y) = \mu_{\text{ont}}(x, y) = \mu_{\text{epist}}(x, y) = \frac{1}{1 + \frac{|x-y|}{\delta_{\text{VOID}}}}$$

**Simplification:**

We define  $K(x, y) = d_S(x, y)$ , aligning the epistemic difference with the actual distance between elements.

**Explanation:**

This axiom asserts that the limitations in our ability to distinguish between elements are not merely due to deficiencies in measurement or perception but are inherent to the elements themselves within the system. By equating the ontological and epistemological probabilities of distinguishability, we acknowledge that what exists and what we can know are constrained by the same fundamental threshold.

**Role in the Theory:**

Axiom 2 ensures coherence between the nature of reality and our knowledge of it within the framework. It reinforces the idea that indeterminacy at the smallest scales is an intrinsic property, not just a limitation of our instruments or

understanding. This aligns with perspectives like the Copenhagen interpretation in quantum mechanics, where the act of measurement affects the system, and the line between reality and observation becomes blurred.

**Difference from Classical Mathematics:**

Classically, a distinction is made between the objective properties of elements and our knowledge of them. This axiom bridges that gap, suggesting that at certain scales, the distinction between ontology and epistemology blurs due to inherent indeterminacy. It challenges the notion that we can separate what is from what we can know, especially when limitations are fundamental.

**Additional Note:**

This concept resonates with philosophical ideas that our understanding of reality is inevitably linked to our means of observing it. In practice, our instruments and computational tools have physical limits, so epistemological limits become ontological, and vice versa.

### 3.3 Axiom 1.3: Domain-Specific Granularity

The VOID threshold  $\delta_{\text{VOID}}$  is adaptable and may have specific values in different domains but adheres to the universal principle of VOID Granularity.

**Explanation:**

This axiom acknowledges that the minimal meaningful distinction varies across different fields due to their unique scales and limitations. By allowing  $\delta_{\text{VOID}}$  to adapt, we ensure the framework remains relevant and practical in diverse contexts. An attempt at formalizing this adaptability is discussed in the chapter on Artificial Intelligence Systems (AIS).

**Role in the Theory:**

Axiom 3 provides the flexibility necessary for the framework to be applied universally. It allows each discipline to define its own VOID threshold based on inherent limitations, whether they stem from physical laws, computational constraints, or perceptual capabilities.

**Difference from Classical Mathematics:**

Traditional mathematical frameworks often rely on fixed constants or assume infinite precision. By introducing an adaptable  $\delta_{\text{VOID}}$ , we depart from this assumption, embracing the practical realities of different domains. This approach is made with full awareness that certain mathematical structures, like category theory, were built to support established axioms, such as Peano's axioms, which may have limitations in addressing the finite and the infinitesimal.

**Examples in Different Domains:**

- **Physics:** In quantum mechanics,  $\delta_{\text{VOID}}^{\text{phys}}$  might correspond to the Planck length ( $1.616 \times 10^{-35}$  meters), below which the concept of space becomes meaningless.
- **Computation:** In computational systems,  $\delta_{\text{VOID}}^{\text{comp}}$  could represent the machine epsilon—the smallest difference recognizable by the hardware—acknowledging limitations in digital precision.

- **Cognitive Sciences:** In perception studies,  $\delta_{\text{VOID}}^{\text{cog}}$  might be the just-noticeable difference, the minimal change in a sensory stimulus that can be detected.

**Additional Note:**

In every field of study, we can find this smallest unit, although it may not always be known at the outset and must be discovered through careful analysis. Recognizing and defining this unit is crucial for applying the VOID Granularity Framework effectively.

### 3.4 Axiom 1.4: Adaptation of Dynamic Logic to VOID Theory

Actions and knowledge within systems constrained by the VOID are modeled using dynamic logic that respects the VOID threshold.

For any action  $\alpha$  and property  $\phi$ :

$$\forall s \in S : \left( \mu_S(s, s') = \frac{1}{1 + \frac{|s-s'|}{\delta_{\text{VOID}}}} \right) \implies [\alpha_{\delta_{\text{VOID}}}] \phi$$

where:

- $s'$  is the state resulting from action  $\alpha$  on state  $s$ .
- $[\alpha_{\delta_{\text{VOID}}}] \phi$  denotes that after action  $\alpha$  constrained by  $\delta_{\text{VOID}}$ , property  $\phi$  holds considering the probabilistic VOID constraints.

**Explanation:**

This axiom integrates the VOID threshold into the realm of dynamic logic, which deals with actions and their effects on system states. By incorporating  $\delta_{\text{VOID}}$  into dynamic logic, we ensure that any action's outcome respects the limitations imposed by the minimal meaningful distinction. Changes smaller than this threshold may not result in distinguishable new states.

**Role in the Theory:**

Axiom 4 extends the framework to dynamic systems, highlighting how the VOID threshold impacts not just static distinctions but also the evolution of systems over time. It's particularly relevant in fields like computer science and artificial intelligence, where system states change through actions, and precision may be limited.

**Difference from Classical Mathematics:**

In classical logic, actions and their outcomes are often considered deterministic and precise. By incorporating probabilistic constraints based on  $\delta_{\text{VOID}}$ , we acknowledge that actions may not always lead to clearly distinguishable results due to inherent limitations. This is similar to the principles of fuzzy logic, where truth values range between completely true and completely false, but our approach is grounded in the VOID threshold.

### 3.5 Axiom 1.5: Optional Temporal Dynamics of VOID Granularity

The VOID threshold  $\delta_{\text{VOID}}$  can change over time but is not required to do so.

**Temporal Dynamics:**

$$\delta_{\text{VOID}}(t+1) = \begin{cases} f_{\text{VOID}}(\delta_{\text{VOID}}(t), \theta) & \text{if } \Delta(t) = 1 \\ \delta_{\text{VOID}}(t) & \text{if } \Delta(t) = 0 \end{cases}$$

where:

- $\Delta(t) \in \{0, 1\}$  indicates whether  $\delta_{\text{VOID}}$  changes at time  $t$ .
- $f_{\text{VOID}}$  is a function defining how  $\delta_{\text{VOID}}$  changes.
- $\theta$  represents parameters influencing the change.

**Explanation:**

This axiom introduces the possibility that the minimal meaningful distinction within a system may evolve over time. This adaptability reflects situations where measurement technologies improve, systems undergo changes that alter their inherent limitations, or learning processes refine distinctions.

**Role in the Theory:**

Axiom 5 provides temporal flexibility to the framework, allowing it to model systems where the VOID threshold is not static. This is important for accurately representing evolving systems and acknowledging that our perceptions and instruments can change. In artificial intelligence, for example, a learning algorithm might improve its precision over time, effectively decreasing  $\delta_{\text{VOID}}$ .

**Difference from Classical Mathematics:**

Classical frameworks typically consider constants to be unchanging. By allowing  $\delta_{\text{VOID}}$  to be dynamic, we accommodate a more realistic portrayal of systems where conditions and limitations are not fixed. This reflects the reality of scientific progress and adaptive systems.

## 4 Conclusion

The VOID Granularity Framework offers a perspective on understanding the limitations inherent in various systems by introducing a minimal scale of indeterminacy—the VOID threshold. Through its foundational axioms, the framework integrates this concept into the assessment of distinguishability, the alignment of being and knowing, and adaptability across different domains and over time.

By addressing classical paradoxes like the Sorites Paradox within this framework, we demonstrate its applicability and potential to provide resolutions where traditional approaches struggle. The probabilistic nature of distinctions at scales approaching the void acknowledges the inherent uncertainties and limitations we face, leading to a more nuanced and realistic understanding of systems.

This framework does not aim to overturn classical mathematics but to extend and refine it, embracing the complexities and indeterminacies that are often simplified or ignored. By doing so, we hope to contribute to a deeper comprehension of the foundational aspects of mathematics, physics, computation, and cognition.

## 5 Final Remarks

In developing the VOID Granularity Framework, we recognize the importance of humility in the face of the unknown. The concept of the void reminds us that there are limits to what we can measure and know. By accepting and incorporating these limits into our theoretical constructs, we strive for models that better reflect the realities of the systems we study.