# Bordism Homology and Cohomology

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## 0 Introduction/Motivation

Recall the definition of homotopy groups  $\pi_n(X)$  as the set of homotopy classes of maps from the *n*-sphere  $S^n$  to a space X. The problem with these groups is that they are generally hard to compute, even for simple spaces. For example, the homotopy groups of spheres are not known in general. The general idea of bordism is to replace the *n*-sphere with a manifold of dimension n and to consider the homotopy classes of maps from this manifold to a space X.

Testing citations: [Ati61], [BD70], [Tho54], [Lee13], [Hat02], [Die08]

#### 1 Basic Definitions

Here, Examples still need to be added.

**Definition 1.1** (Topological manifold). An n-dimensional <u>topological manifold</u> is a topological space M such that:

- M is Hausdorff, (i.e. any two distinct points can be separated by disjoint open sets),
- M is second countable, (i.e. there exists a countable basis for the topology of M),
- M is locally Euclidean (i.e. every point in M has a neighbourhood homeomorphic to an open subspace of  $\mathbb{R}^n$ ).

We will often write  $M^n$  for an n-dimensional manifold.

[Lee13]

**Remark.** One could replace the condition of being second countable with the condition of being paracompact (i.e. every open cover of M admits a locally finite refinement). The following equivalence holds:

M is second countable  $\iff M$  is paracompact and countably many connected components

This is shown in [Lee13].

**Definition 1.2** ((Smooth) Atlas). Let M be a topological manifold. A (smooth) atlas A on M is a collection of smooth charts  $(U_{\alpha}, \varphi_{\alpha})$  such that:

- the  $\{U_{\alpha}\}$  cover M,
- the charts are pairwise smoothly compatible (i.e. the transition functions  $\varphi_j \circ \varphi_i^{-1} : \varphi_i(U_i \cap U_j) \to \varphi_j(U_i \cap U_j)$  are smooth)

[Lee13]

**Definition 1.3.** Two atlases A and A' (on a fixed topological manifold) are said to be <u>equivalent</u>, if their union is still on atlas.

[Lee13]

This is an equivalence relation. [Lee 13]

**Definition 1.4** (Smooth manifold). A smooth manifold M = (M, [A]) consists of

- a topological manifold M,
- an equivalence class [A] of smooth atlases on M.

[Lee 13]

**Remark.** While being a topological manifold is just a property of the topological space M, begin a smooth manifold gives the manifold extra structure.

**Definition 1.5** (Manifold with boundary). To get a definition of a (smooth or topological) manifold with boundary, replace the condition of the manifold being locally Euclidean with the condition that every point has a neighbourhood homeomorphic to an open subspace of  $\mathbb{H}^n := \{(x_1, \ldots, x_n) \in \mathbb{R} \mid x_1 \geq 0\}$  (the half space).

[Lee 13]

Remark. In this thesis, with manifold we will always mean a smooth manifold with boundary.

**Definition 1.6.** A point  $x \in M^n$  is called a <u>interior point</u> if it admits a neighbourhood homeomorphic to  $\mathbb{R}^n$ . Otherwise, it is called a <u>boundary point</u>. The <u>set of boundary points</u> is denoted by  $\partial M$  and is called the <u>boundary</u> of M.

If a manifold is compact and has empty boundary, it is called a closed manifold.

[Lee13]

**Example** (Standard n-disk). The <u>standard n-disk</u> is the set of points in  $\mathbb{R}^n$  such that  $|x| \leq 1$ . The boundary of the standard n-disk is the standard (n-1)-sphere. The standard n-disk is denoted by  $D^n$  and the standard (n-1)-sphere is denoted by  $S^{n-1}$ .

**Remark.** The boundary of an n-dimensional manifold is an (n-1)-dimensional submanifold.

Maybe I will make a theorem out of this and add a proof.

Non-example. Line with two origins

#### 2 Bordism

The problem with working with manifolds is that they are hard to classify up to homeomorphism or diffeomorphism. Bordism is a way to classify manifolds up to a weaker equivalence relation, which is easier to work with.

#### 2.1 unoriented bordism

**Definition 2.1** (Singular manifold). Let X be a topological space. An n-dimensional <u>singular manifold</u> in X is a pair M, f of a compact manifold  $M^n$  and a continuous map  $f: M \to X$ .

The <u>boundary</u> of a singular manifold is  $\partial(M, f) := (\partial M, f_{|\partial M})$ .

[BD70]

**Definition 2.2** (Nullbordant). Let (M, f) be a singular manifold in X. We say that (M, f) is <u>nullbordant</u>, if there exists a singular manifold (B, F), such that  $\partial(B, F) = (M, f)$ . B, F is then called a <u>nullbordism</u> of (M, f).

[BD70]

Example.

**Definition 2.3** (bordant). Let (M, f) and (N, g) be singular manifolds in X. We say that (M, f) and (N, g) are <u>bordant</u>, if their sum  $(M, f) + (N, g) = (M + N, (f, g)) := (M \coprod N, f \coprod g)$  is nullbordant. A nullbordism of (M, f) + (N, g) is called a <u>bordism</u> between (M, f) and (N, g).

[BD70]

Remark.

$$(M, f) + (\emptyset, g)$$
 are bordant  $\iff$   $(M, f)$  is nullbordant

Example.

Non-example.

**Proposition 2.4.** Being bordant is an equivalence relation on the set of singular manifolds.

Proof. [BD70]

• Symmetry: Follows from the symmetry of the disjoint union. If (M, f) and (N, g) are bordant, then there exists a nullbordism of  $(M, f) + (N, g) = (M \coprod N, f \coprod g) = (N \coprod M, g \coprod f) = (N, g) + (M, f)$ . So, a bordism between (M, f) and (N, g) is also bordism between (N, g) and (M, f).

• Reflexivity: Cylinder

• Transitivity: Draw a picture

Check smooth structure!

**Definition 2.5** (bordism group).

Observe the similarity with the definition of singular homology groups.

**Theorem 2.6.** The bordism groups are abelian groups.

**Definition 2.7** (graded bordism ring).

#### 2.2 The Eilenberg-Steenrod Axioms

The Eilenberg-Steenrod axioms are a set of axioms that characterize the homology and cohomology theories.

**Definition 2.8** (Homology theory [Lüc05]). A <u>homology theory</u>  $\mathcal{H}_* = (\mathcal{H}_*, \partial_*)$  with coefficients in R-modules is a covariant functor

$$\mathcal{H}_*: \mathrm{TOP}^2 \to \mathbb{Z}$$
-graded R-modules

together with a natural transformation

$$\partial_*: \mathcal{H}_* \to \mathcal{H}_{*-1} \circ I$$

• Homotopy invariance

Let  $f, g: (X, A) \to (Y, B)$  be homotopic maps. Then for all  $n \in \mathbb{Z}$ , we have

$$\mathcal{H}_n(f) = \mathcal{H}_n(g) : \mathcal{H}_n(X, A) \to \mathcal{H}_n(Y, B)$$

• Long exact sequence

Let (X,A) be a pair of spaces. Then for all  $n \in \mathbb{Z}$ , we have the long exact sequence of homology groups:

$$\dots \xrightarrow{\partial_{n+1}(X,A)} \mathcal{H}_n(A) \xrightarrow{\mathcal{H}_n(i)} \mathcal{H}_n(X) \xrightarrow{\mathcal{H}_n(j)} \mathcal{H}_n(X,A) \xrightarrow{\partial_n(X,A)} \mathcal{H}_{n-1}(A) \to \dots$$

• Excision

Let  $A \subset B \subset X$  be subspaces of X such that  $\overline{A} \subset B^{\circ}$ . Then the inclusion  $i: (X \setminus B, A \setminus B) \to (X, A)$  induces an isomorphism of homology groups for all  $n \in \mathbb{Z}$ :

$$\mathcal{H}_n(i): \mathcal{H}_n(X \setminus A, B \setminus A) \xrightarrow{\cong} \mathcal{H}_n(X, B)$$

Sometimes one adds the following axioms:

• Disjoin union axiom

Let  $\{X_i\}_{i\in I}$  be a family of topological spaces. Let  $j_i: X_i \to \coprod_{i\in I} X_i$  be the inclusion. Then for all  $n\in \mathbb{Z}$ , we have a bijection:

$$\bigoplus_{i \in I} \mathcal{H}_n(j_i) : \bigoplus_{i \in I} \mathcal{H}_n(X_i) \xrightarrow{\cong} \mathcal{H}_n\left(\coprod_{i \in I} X_i\right)$$

• Dimension axiom

For the point space pt, we have

$$\mathcal{H}_n(\mathrm{pt}) \cong \begin{cases} R & n=0\\ \{0\} & n \neq 0 \end{cases}$$

We will now calculate the bordism groups.

## 2.3 oriented bordism

Definition 2.9 (vector bundle).

Definition 2.10 (orientable).

Definition 2.11 (bordant).

Definition 2.12 (oriented bordism group).

# 3 Cobordism

classifying spaces, Thom spaces, Thom isomorphism, Thom class, Thom isomorphism theorem

# 4 Pontryagin-Thom Construction

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