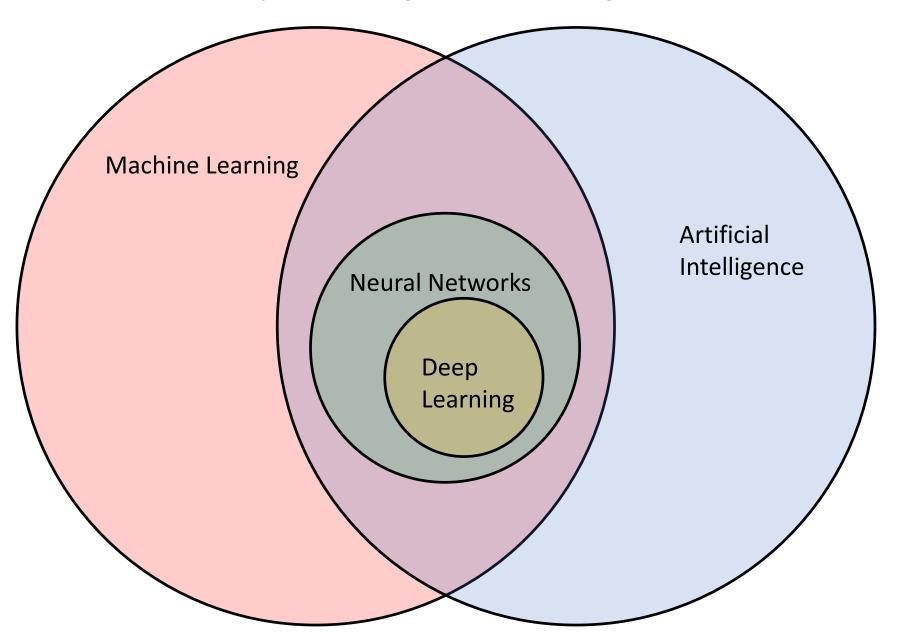
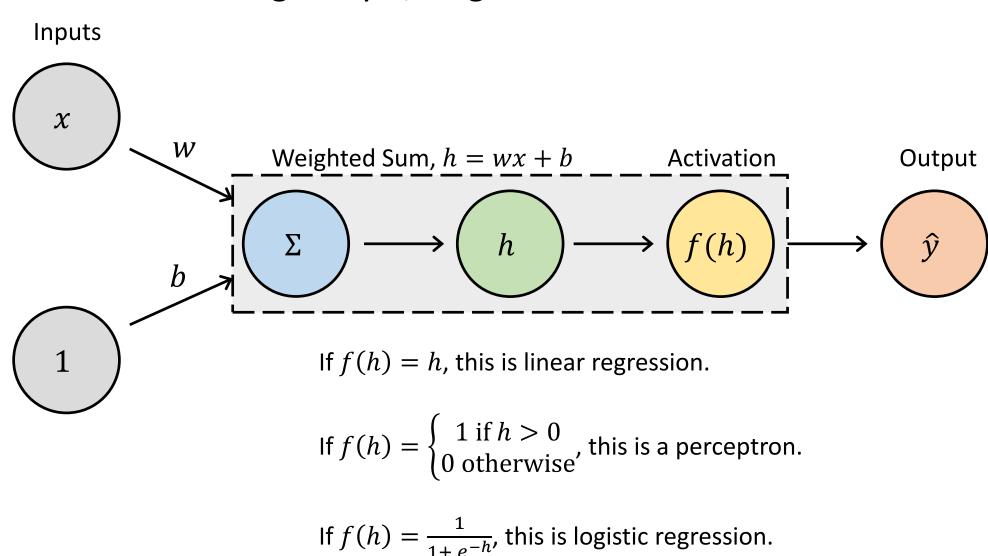
# Deep Learning: A Venn Diagram



## Single-Layer, Single-Node Neural Network



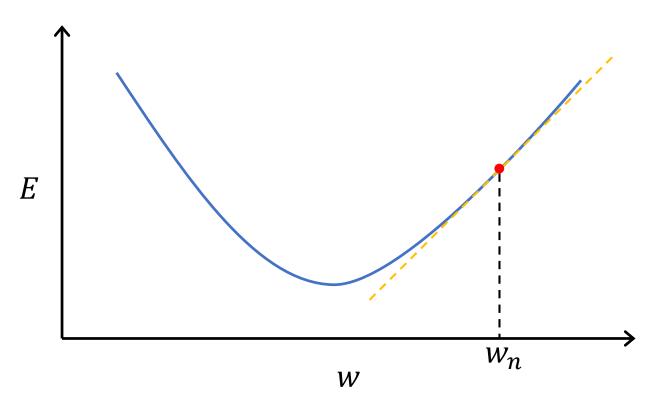
### **Gradient Descent**

Goal: Find network weights that minimize the error between the model outputs (predictions) and the actual data (targets).

To minimize  $E(w,b) = \frac{1}{2}(y - \hat{y}(w,b))^2$  we can iterate each weight at each time step by a value proportional to the partial derivative of the error with respect to the weight.

$$\Delta w = w_{n+1} - w_n = -\eta \frac{\partial E}{\partial w}$$

$$\Delta b = b_{n+1} - b_n = -\eta \frac{\partial E}{\partial b}$$



$$\Delta w = \frac{-\eta \sum_{\text{all data}} \frac{\partial E}{\partial w}}{\text{number of data records}}$$

#### **Gradient Descent**

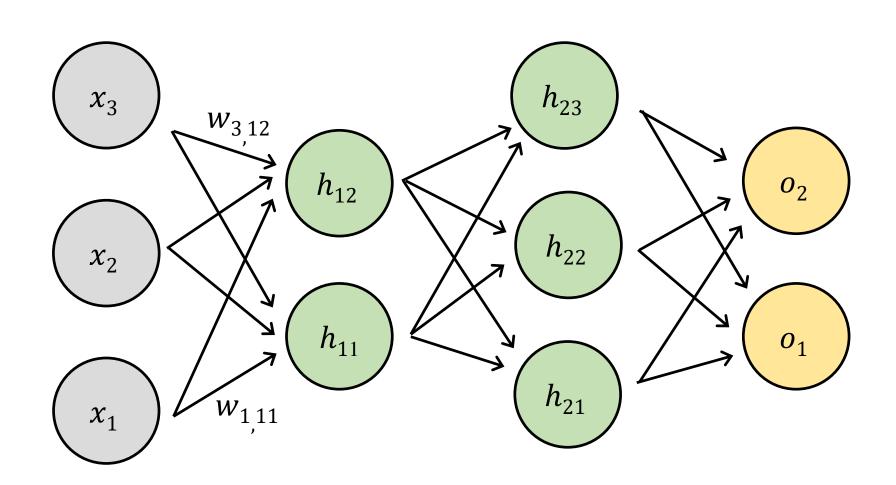
Inputs 
$$\frac{\partial E}{\partial w} = -(y - \hat{y}) \frac{\partial \hat{y}}{\partial w} = -(y - \hat{y}) f'(h) \frac{\partial h}{\partial w} = -(y - \hat{y}) f'(h) x$$

$$\frac{\partial E}{\partial b} = -(y - \hat{y}) f'(h)$$

$$\frac{\partial W}{\partial b} = -(y - \hat{y}) f'(h)$$

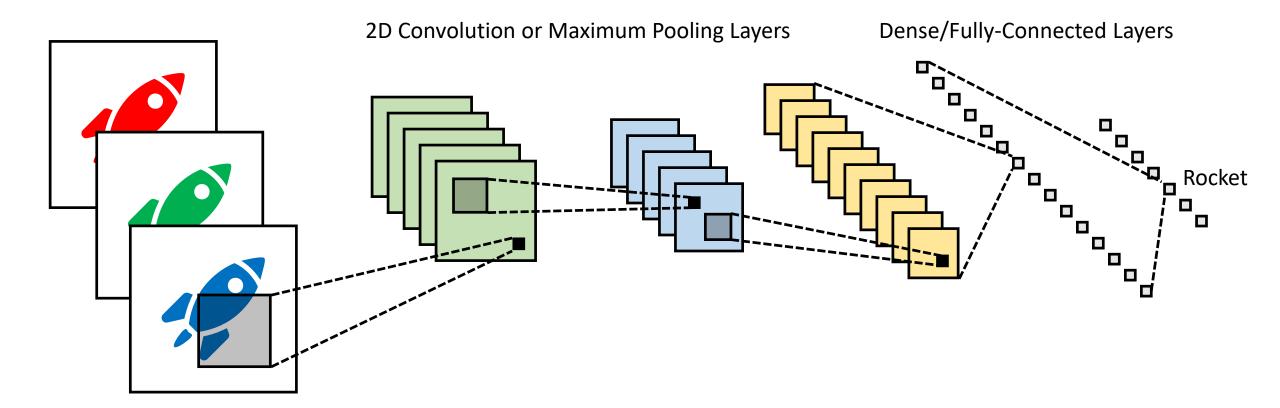
$$\frac{$$

# Multi-Node, Multi-Layer Neural Network Deep Learning Models Have Many Layers

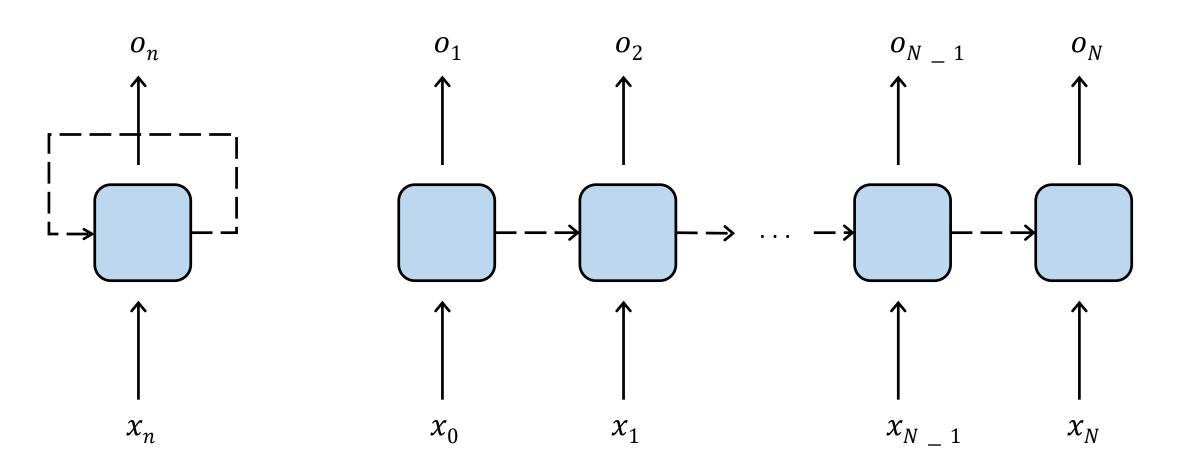


### Convolutional Neural Network

Input Layer: 3-Channel (RGB) Image Output Layer: One Node for Each Class



## Recurrent Neural Network



Unrolled