# Multiagent Systems: Intro to Game Theory

CS 486/686: Introduction to Artificial Intelligence

Are you thinking of going to graduate school?

2nd, 3rd, and 4th year undergraduates are invited to a graduate information session.

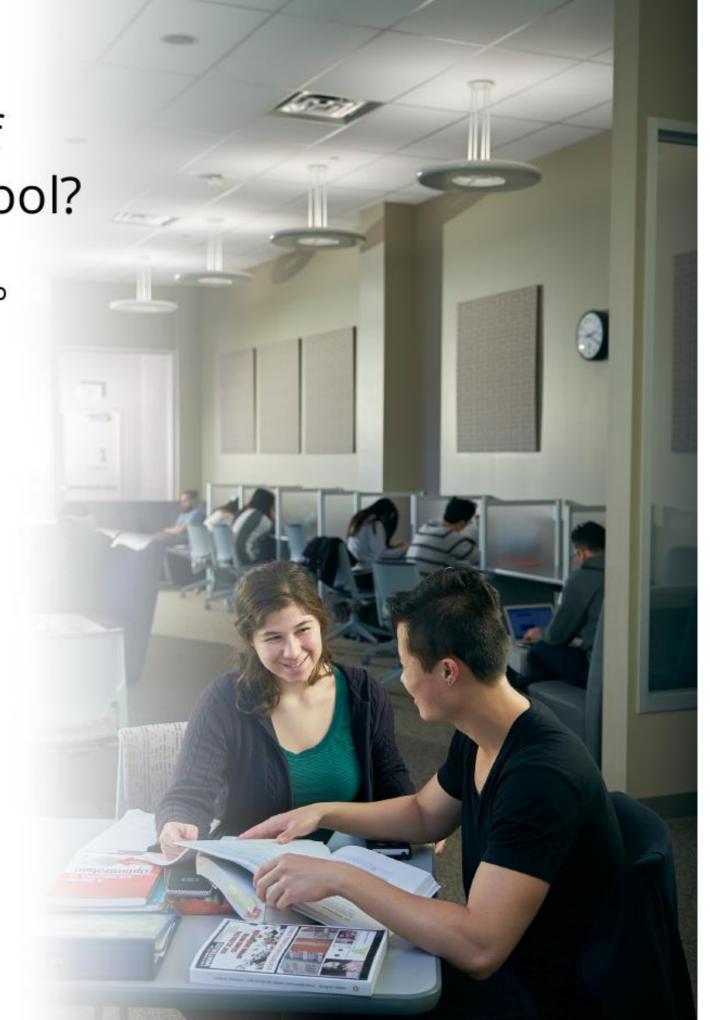
You will get an overview of Graduate Studies, including a brief description from:

Applied Mathematics
Combinatorics & Optimization
Computational Mathematics
Computer Science
Pure Mathematics
Statistics & Actuarial Science

You will have the chance to speak with department representatives and ask questions.

Refreshments will be served.

Wednesday, November 8, 2017 DC 1301 (The "fishbowl") 4:30 - 6pm



#### Introduction

- So far almost everything we have looked at has been in a single-agent setting
  - Today Multiagent Decision Making!
- For participants to act optimally, they must account for how others are going to act
- We want to
  - Understand the ways in which agents interact and behave
  - Design systems so that agents behave the way we would like them to

**Hint for the final exam**: MAS is my main research area. I like MAS problems. I even enjoy marking MAS questions. Two of the TAs do MAS research. They also like marking MAS questions. There *will* be a MAS question on the exam.

#### Self-Interest

- We will focus on self-interested MAS
- Self-interested does not necessarily mean
  - Agents want to harm others
  - Agents only care about things that benefit themselves
- Self-interested means
  - Agents have their own description of states of the world
  - Agents take actions based on these descriptions

#### What is Game Theory?

- The study of games!
  - Bluffing in poker
  - What move to make in chess
  - How to play Rock-Paper-Scissors

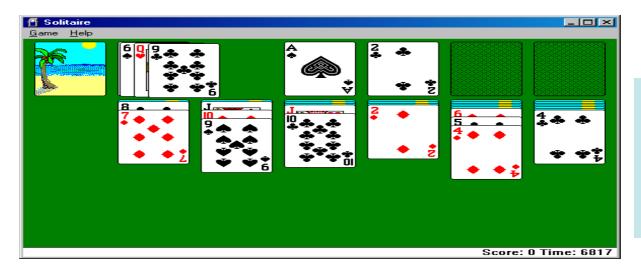


#### But also

- auction design
- strategic deterrence
- election laws
- coaching decisions
- routing protocols
- •

#### What is Game Theory?

- Game theory is a formal way to analyze interactions among a group of rational agents that behave strategically
  - Group: Must have more than 1 decision maker
    - Otherwise, you have a decision problem, not a game



Solitaire is not a game!

#### What is Game Theory?

- Game theory is a formal way to analyze interactions among a group of rational agents that behave strategically
  - Interaction: What one agent does directly affects at least one other
  - Strategic: Agents take into account that their actions influence the game
  - Rational: Agents chose their best actions

## Example



- Decision Problem
  - Everyone pays their own bill
- Game
  - Before the meal, everyone decides to split the bill evenly

# Strategic Game (Matrix Game, Normal Form Game)

- Set of agents: I={1,2,..,,N}
- Set of actions:  $A_i = \{a_i^1, ..., a_i^m\}$
- Outcome of a game is defined by a profile a=(a<sub>1</sub>,...,a<sub>n</sub>)
- Agents have preferences over outcomes
  - Utility functions u<sub>i</sub>:A->R

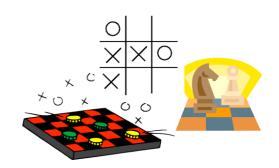
## Examples

Agent 2

		One	Two
	One	2,-2	-3,3
Agent 1	Two	-3,3	4,-4

I={1,2}  $A_i$ ={One,Two}  $A_n$  outcome is (One, Two)  $U_1$ ((One,Two))=-3 and  $U_2$ ((One,Two))=3 Zero-sum game.

 $\sum_{i=1}^{n} u_i(o)=0$ 



# Examples

**BoS** 

B S

B 2,1 0,0 S 0,0 1,2





**Coordination Game** 

#### Chicken

· (

T -1,-1 10,0 C 0,10 5,5





**Anti-Coordination Game** 

#### Example: Prisoners' Dilemma







Confess

**Don't Confess** 

Confess

Don't Confess

-5,-5	0,-10
-10,0	-1,-1

## Playing a Game

- Agents are rational
  - Let p<sub>i</sub> be agent i's belief about what its opponents will do
  - Best response: a<sub>i</sub>=argmax∑<sub>a-i</sub> u<sub>i</sub>(a<sub>i</sub>,a<sub>-i</sub>)p<sub>i</sub>(a<sub>-i</sub>)

Notation Break:  $a_{-i} = (a_1, ..., a_{i-1}, a_{i+1}, ..., a_n)$ 

## Dominated Strategies

a'i strictly dominates strategy ai if

$$u_i(a_i', a_{-i}) > u_i(a_i, a_{-i}) \forall a_{-i}$$

 A rational agent will never play a dominated strategy!

# Example

Confess

Don't Confess

Confess

Don't Confess

-5,-5	0,-10
-10,0	-1,-1



# Strict Dominance Does Not Capture the Whole Picture

	Α	В	С
Α	0,4	4,0	5,3
В	4,0	0,4	5,3
C	3,5	3,5	6,6

## Nash Equilibrium

**Key Insight**: an agent's best-response depends on the actions of other agents

An action profile a\* is a Nash equilibrium if no agent has incentive to change given that others do not change

$$\forall i u_i(a_i^*, a_{-i}^*) \ge u_i(a_i', a_{-i}^*) \forall a_i'$$

#### Nash Equilibrium

• Equivalently, a\* is a N.E. iff

$$\forall i a_i^* = \arg\max_{a_i} u_i(a_i, a_{-i}^*)$$

_	Α	В	С
A	0,4	4,0	5,3
В	4,0	0,4	5,3
C	3,5	3,5	6,6

(C,C) is a N.E. because

$$u_1(C,C) = \max \begin{bmatrix} u_1(A,C) \\ u_1(B,C) \\ u_1(C,C) \end{bmatrix}$$

$$AND$$

$$u_2(C,C) = \max \begin{bmatrix} u_2(C,A) \\ u_2(C,B) \\ u_2(C,C) \end{bmatrix}$$

## Nash Equilibrium

- If (a<sub>1</sub>\*,a<sub>2</sub>\*) is a N.E. then player 1 won't want to change its action given player 2 is playing a<sub>2</sub>\*
- If (a<sub>1</sub>\*,a<sub>2</sub>\*) is a N.E. then player 2 won't want to change its action given player 1 is playing a<sub>1</sub>\*

-5,-5	0,-10
-10,0	-1,-1

	Α	В	С
Α	0,4	4,0	5,3
В	4,0	0,4	5,3
С	3,5	3,5	6,6

#### Another Example



2 Nash Equilibria

Coordination Game

#### Yet Another Example

#### Agent 2

	One	Two
One Agent 1	2,-2	-3,3
Two	-3,3	4,-4

#### (Mixed) Nash Equilibria

- (Mixed) Strategy: si is a probability distribution over Ai
- Strategy profile: s=(s<sub>1</sub>,...,s<sub>n</sub>)
- Expected utility:  $u_i(s) = \sum_a \Pi_j s(a_j) u_i(a)$
- Nash equilibrium: s\* is a (mixed) Nash equilibrium if

$$u_i(s_i^*, s_{-i}^*) \ge u_i(s_i', s_{-i}^*) \forall s_i'$$

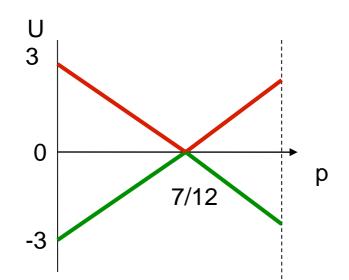
#### Yet Another Example

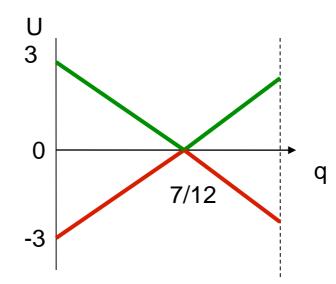
9 One Two

Done 2,-2 -3,3

Two -3,3 4,-4

How do we determine p and q?



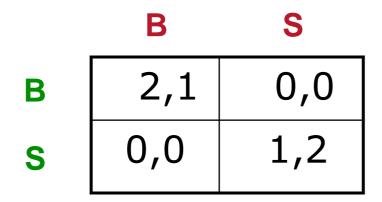


## Yet Another Example



How do we determine p and q?

#### Exercise

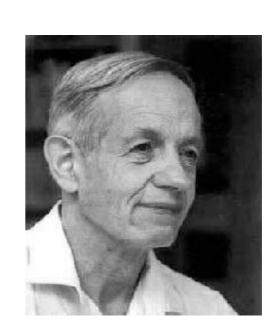


This game has 3 Nash Equilibrium (2 pure strategy NE and 1 mixed strategy NE).

#### Mixed Nash Equilibrium

 Theorem (Nash 1950): Every game in which the action sets are finite, has a mixed strategy equilibrium.

> John Nash Nobel Prize in Economics (1994)



# Finding NE

- Existence proof is non-constructive
- Finding equilibria?
  - 2 player zero-sum games can be represented as a linear program (polynomial)
  - For arbitrary games, the problem is in PPAD
  - Finding equilibria with certain properties is often NP-hard

Recall the Prisonner's Dilemma. What if the prisoners are habitual criminals?

-5,-5	0,-10
-10,0	-1,-1

-5,-5	0,-10
-10,0	-1,-1

-5,-5	0,-10
-10,0	-1,-1

- How do we define payoffs?
- What is the strategy space?

Recall the Prisonner's Dilemma. What if the prisoners are habitual criminals?

-5,-5	0,-10
-10,0	-1,-1

-5,-5	0,-10
-10,0	-1,-1

-5,-5	0,-10	
-10,0	-1,-1	

• •

How do we define payoffs?

- Average reward
- Discounted Awards

•

Recall the Prisonner's Dilemma. What if the prisoners are habitual criminals?

-5,-5	0,-10	
-10,0	-1,-1	

-5,-5	0,-10	
-10,0	-1,-1	

-5,-5	0,-10	
-10,0	-1,-1	•

Strategy space becomes significantly larger!

S:H→A where H is the history of play so far

Can now reward and punish past behaviour, worry about reputation, establish trust,...

Recall the Prisonner's Dilemma. What if the prisoners are habitual criminals?

-5,-5	0,-10	
-10,0	-1,-1	

-5,-5	0,-10
-10,0	-1,-1

-5,-5	0,-10	
-10,0	-1,-1	•

• •

Grim Strategy: In first step cooperate. If opponent defects at some point, then defect forever

Tit-for-Tat: In first step cooperate. Copy what ever opponent did in previous stage.

#### Extensive Form Games

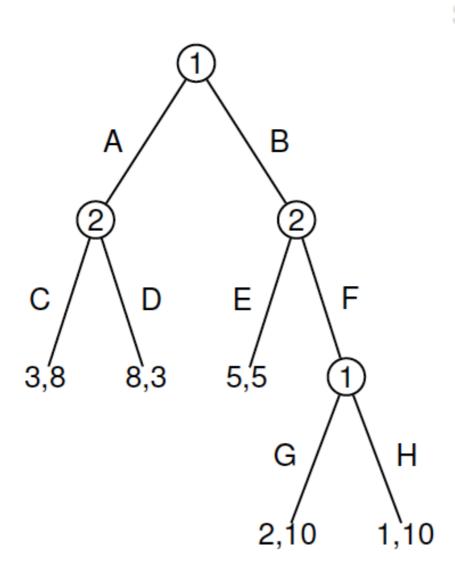
- Normal form games assume agents are playing strategies simultaneously
  - What about when agents' take turns?
    - Checkers, chess,....

# Extensive Form Games (with perfect information)

- G=(I,A,H,Z, $\alpha$ , $\rho$ , $\sigma$ ,u)
  - I: player set
  - A: action space
  - H: non-terminal choice nodes
  - Z: terminal nodes
  - $\alpha$ : action function  $\alpha$ : H $\rightarrow$ 2<sup>A</sup>
  - $\rho$ : player function  $\rho:H\rightarrow N$
  - $\sigma$ : successor function  $\sigma$ :HxA $\rightarrow$ H $\cup$ Z
  - = u=(u<sub>1</sub>,...,u<sub>n</sub>) where u<sub>i</sub> is a utility function u<sub>i</sub>:Z $\rightarrow$ R

# Extensive Form Games (with perfect information)

The previous definition describes a tree



A strategy specifies an action to each nonterminal history at which the agent can move

$$S_1 = \{(A,G),(A,H),(B,G),(B,H)\}$$

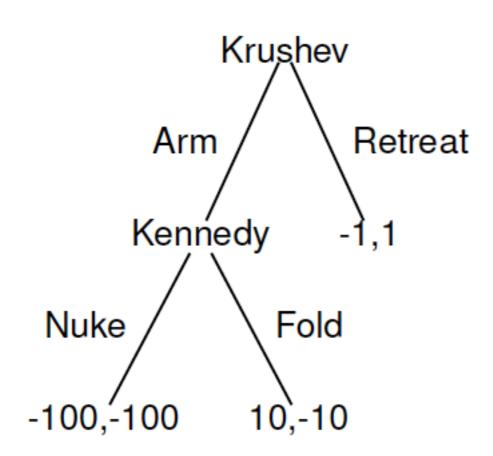
$$S_2 = \{(C,E),(C,F),(D,E),(D,F)\}$$

#### Nash Equilibria

We can transform an extensive form game into a normal form game.

	(C,E)	(C,F)	(D,E)	(D,F)
(A,G)	3,8	3,8	8,3	8,3
(A,H)	3,8	3,8	8,3	8,3
(B,G)	5,5	2,10	5,5	2, 10
(B,H)	5,5	1,0	5,5	1,0

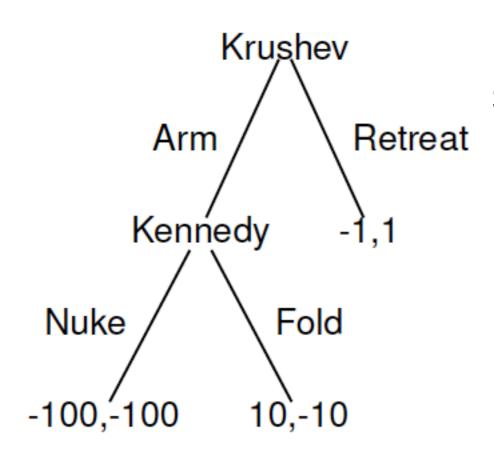
#### Subgame Perfect Equilibria



What are the NE?

#### Subgame Perfect Equilibria

#### Subgame Perfect Equilibria



s\* must be a Nash equilibrium in all subgames

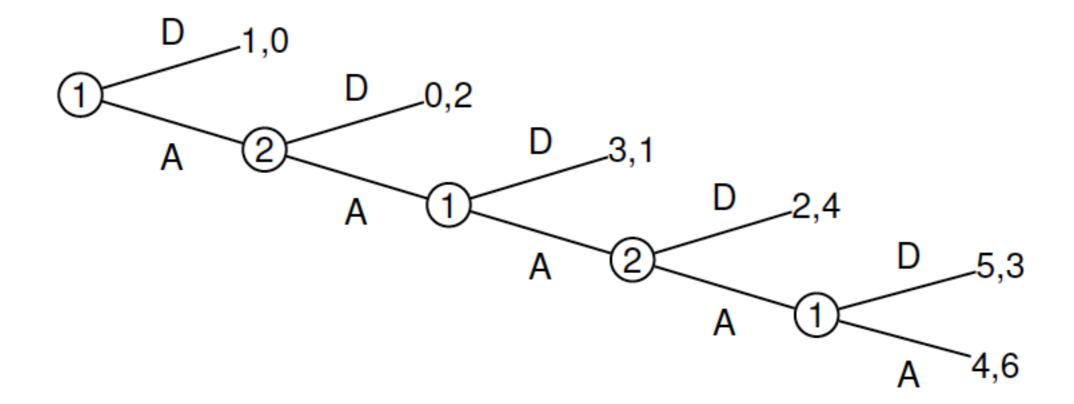
What are the SPE?

#### Existence of SPE

• Theorem (Kuhn): Every finite extensive form game has an SPE.

- Compute the SPE using backward induction
  - Identify equilibria in the bottom most subtrees
  - Work upwards

#### Example: Centipede Game



## Summary

- Definition of a Normal Form Game
- Dominant strategies
- Nash Equilibria
- Extensive Form Games with Perfect Information
- Subgame Perfect Equilibria