

Principal component analysis in treespace

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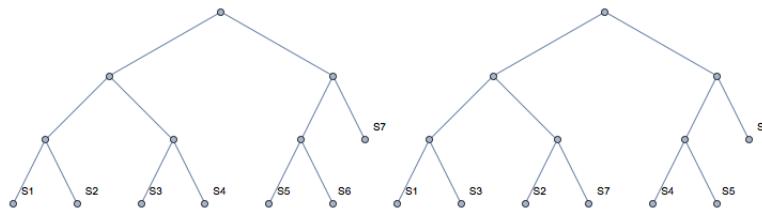
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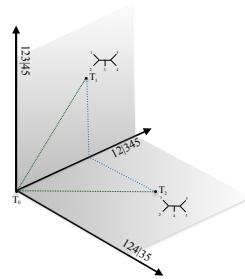
Distances between phylogenetic trees

- ▶ Given two trees (rooted or unrooted) on the same set of leaves (taxa), to what extent do they differ?



- ▶ Metrics on trees: Nearest Neighbor Interchange (NNI), Robinson-Foulds (RF) Δ , Subtree-Prune-Regraft (SPR), Tree Bisection and Reconnection (TBR), Billera-Holmes-Vogtmann (BHV), ...

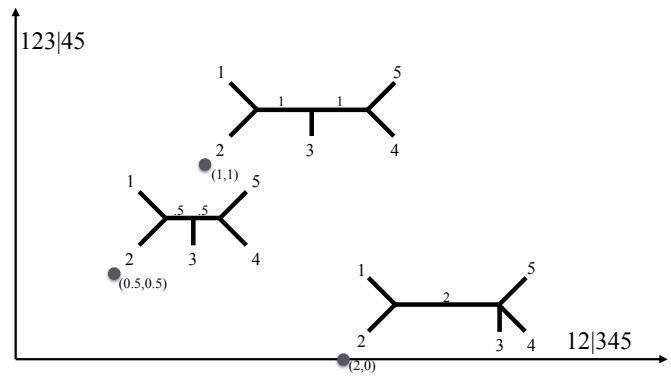
Trees as Vectors



	1 2345 2 1345 3 1245 4 1235 5 1234 12 345 13 245 14 235 15 234 23 145 24 135 25 134 34 125 35 124 45 123
$T_0 = (1, 2, 3, 4, 5)$	1 1 1 1 1 0
$T_1 = ((1, 2), (3, (4, 5)))$	1 1 1 1 1 1 0 1
$T_2 = ((1, 2), (4, (3, 5)))$	1 1 1 1 1 1 0

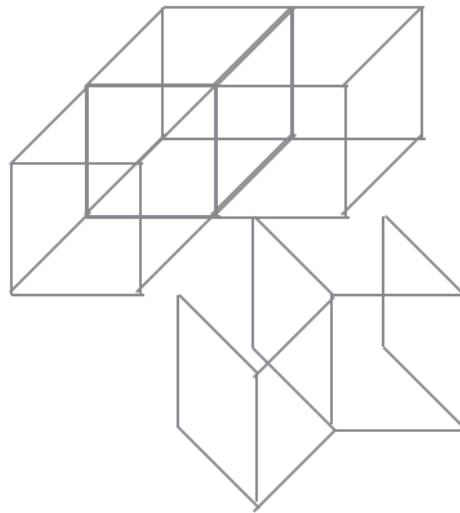
Billeara-Holmes-Vogtmann space

- ▶ Trees on fixed n taxa, edge lengths positive reals
- ▶ Edges to leaves have fixed length 1
- ▶ Form a space with a metric which is locally Euclidean



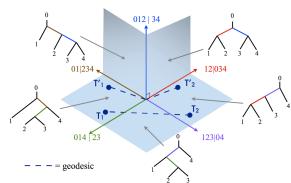
Billera-Holmes-Vogtmann treespace

- ▶ Adjacency of orthants: two orthants of dimension k share a face of dimension l if they have l edges in common.
- ▶ Gives gluing of orthants to obtain space



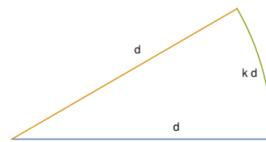
Finding geodesics in treespace

- ▶ Piecewise Euclidean segments in a sequence of orthants
- ▶ Many cells to consider
- ▶ First algorithms exponential
- ▶ Polynomial-time algorithm of order $O(n^4)$ of Owen-Provan (2011) uses incompatibility graph of edges to compute which edges to drop and introduce successively.
- ▶ Owen-Provan algorithm foundational for computing means, interpolations, variances, principal components, ...

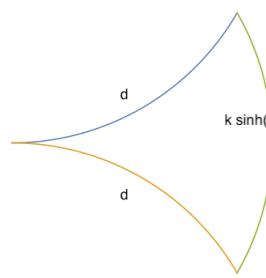


Divergence of geodesics in hyperbolic space

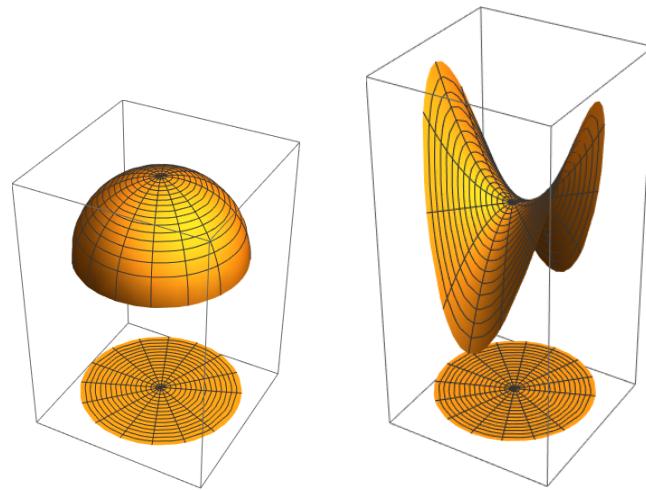
Euclidean: lengths of paths between points on two geodesic rays from X at angle θ at distance d increases linearly in d :



Hyperbolic: lengths of paths between points on two geodesic rays from X at angle θ at distance d outside the ball increases exponentially



Projections from non-positive to Euclidean have distortion



Capturing sets of trees via dimensionality reduction

Hillis, Heath, St. John (2005)

Given a set of trees T_i :

- ▶ Can construct pair-wise distance matrix wrt. preferred metric
- ▶ Embed this approximately in high-dimensional Euclidean space
- ▶ Take traditional Euclidean MDS to project to lower-dimensional space that best captures variances

Advantages: uses effective tools, gives valuable visualizations

Disadvantages: assumes a Euclidean structure

Finding geodesics capturing the first principal component

Given a set of trees $\{T_i\}$:

- ▶ Nye (2011, 2014): efficient algorithm to find endpoints of a geodesic γ where projections via BHV onto γ are maximally correlated with pairwise BHV distances
- ▶ Feragen, Owen (2013, 2015): generalized Nye's algorithm for medical imaging of airway trees in healthy and diseased lungs
- ▶ Cleary, Feragen, Owen, Vargas (2015, 2020): iterate projections onto geodesics
- ▶ Nye et. al (2017): projections onto 2-dimensional subsurfaces of BHV space.

Iterated projections

Given a set of trees $\{T_i\}$:

- ▶ Find γ the geodesic best capturing the projected distances, parameterize via $[0, 1]$.
- ▶ For each T_i , find point on γ closest, to give coordinates t_i
- ▶ Bin the trees into subsets S_j by coordinates t_i
- ▶ Repeat the analysis on the smaller subsets S_j

Lives a collection of piecewise projections

Can iterate to get subsets $S_{j,k}, \dots$

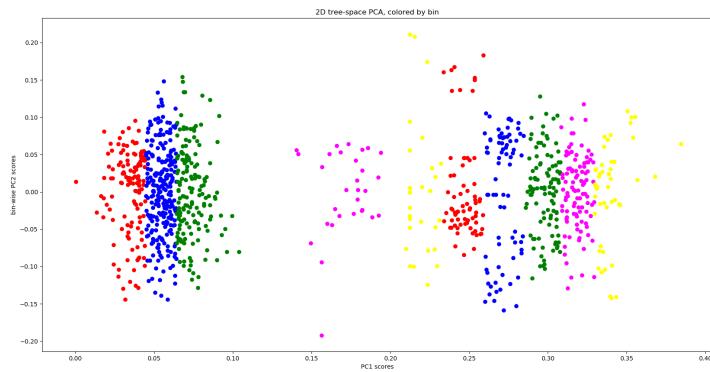
Two dimensional case

Given a set of trees $\{T_i\}$:

- ▶ Find γ , backbone of the entire collection
- ▶ Bin trees into say 10 subsets along projections onto γ
- ▶ Find γ_0 to γ_9 , geodesics for those 10 subsets
- ▶ Give coordinates (x, y) to trees based upon their projections onto γ and the relevant γ_i
- ▶ Use these coordinates to plot and visualize data

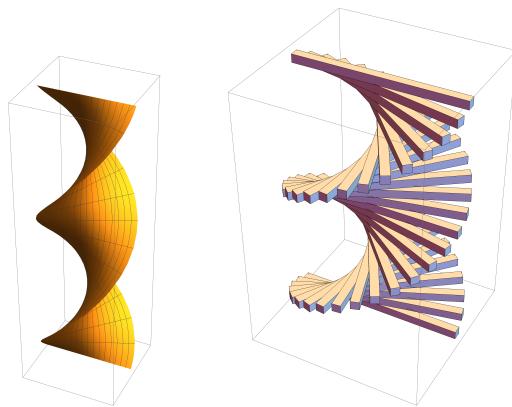
Example

VL3 dataset: 442 trees on 50 taxa, GARTFase Beiko et al. (2006), alignments bacterial and archaeal sequences of protein-coding genes



Piecewise approximation

Approximate helicoid via backbone and perpendicular parts of changing direction:

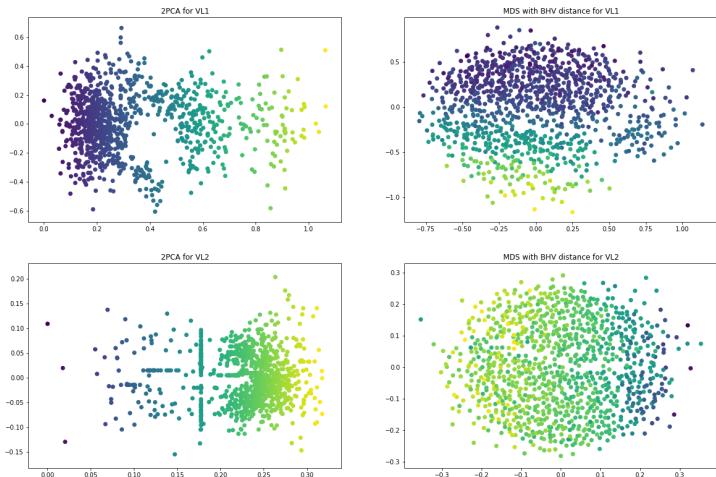


Properties

- ▶ Projections are optimized locally on subsets, more robustness with respect to far off points
- ▶ Choices about orientation made to maximize correlation
- ▶ Uses: cluster identification, visualizing distribution

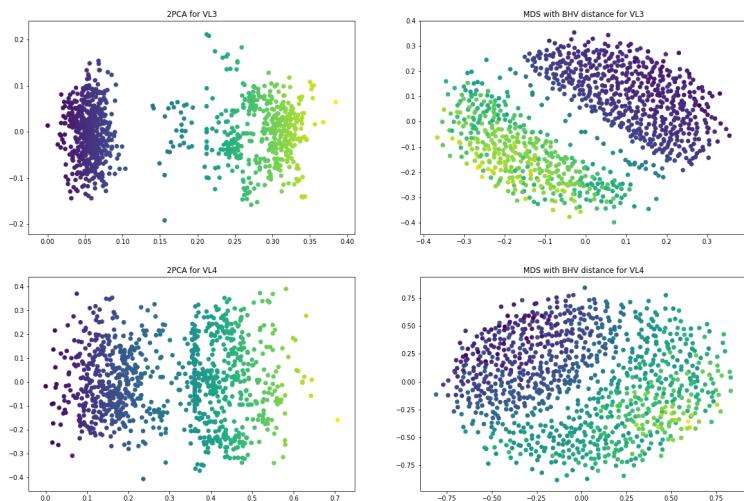
Examples

Colored by first PCA coordinates:



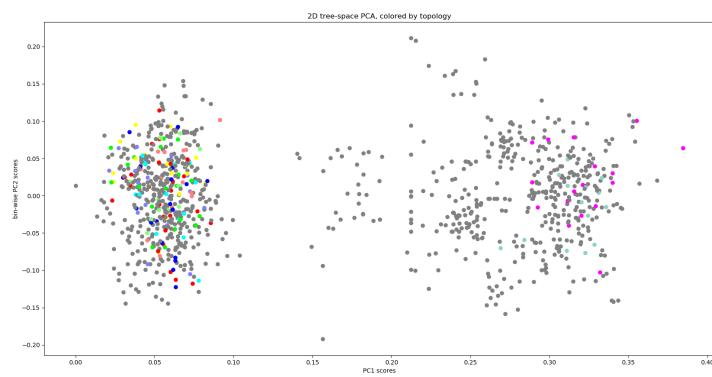
Examples

Colored by first PCA coordinates:



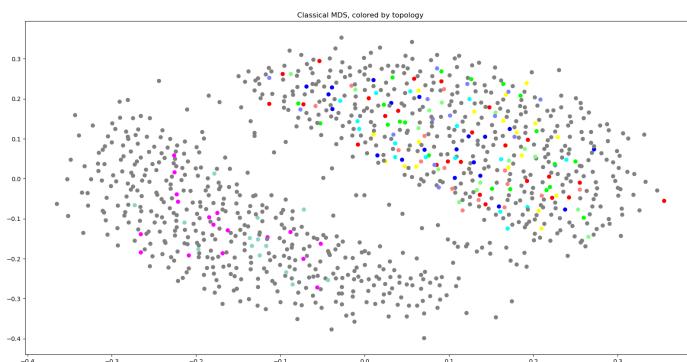
Common topologies in 2PCA

VL3 dataset, Tree PCA colored by topology:



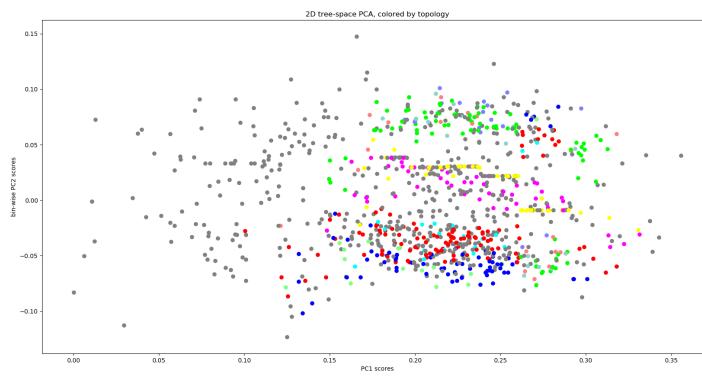
Common topologies in MDS

VL3 dataset, MDS, colored by topology:

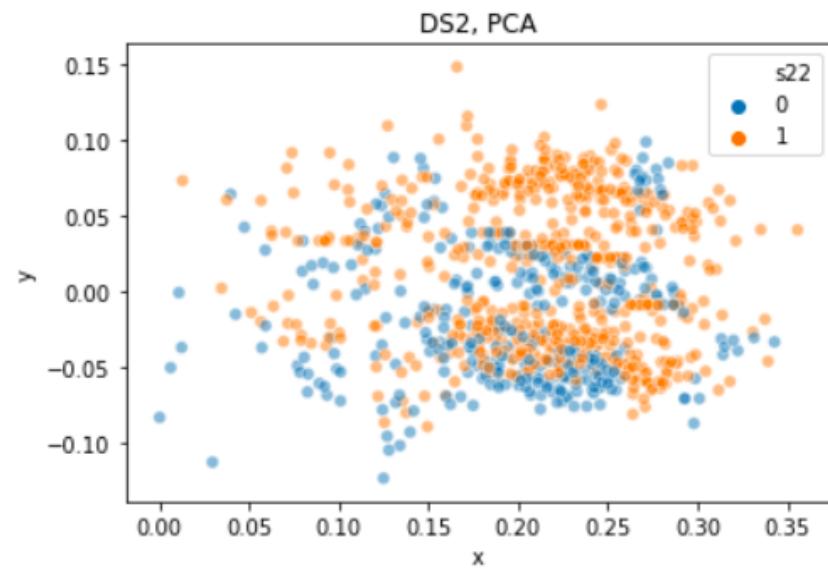


Common topologies in Tree PCA

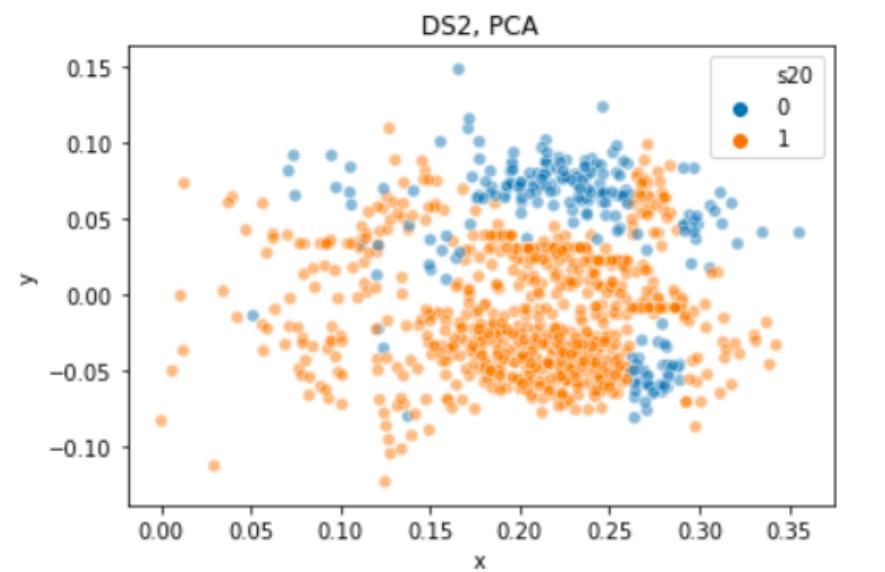
DS2 dataset: 2520 trees on 29 taxa, rDNA; 18s Garey et al. (2012) , sequences from eukaryote species, colored by topology:



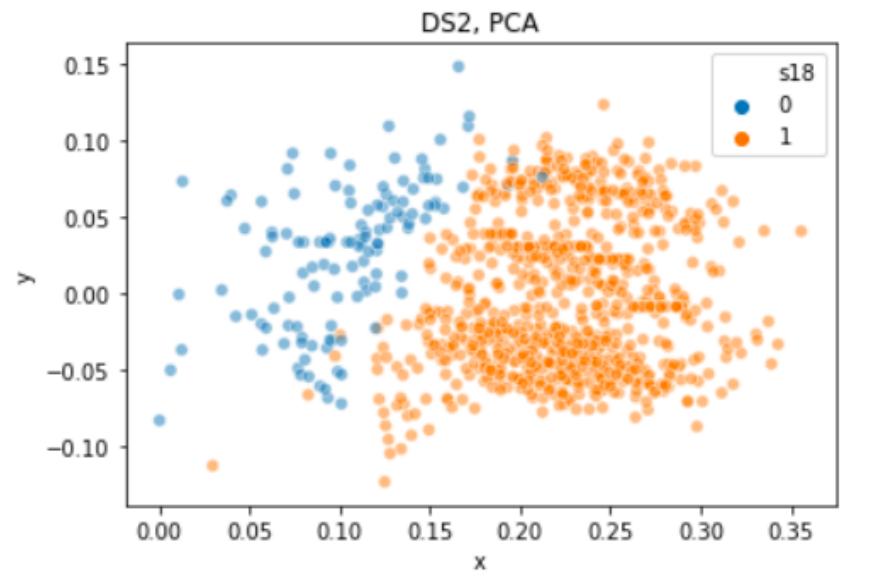
Specific splits: edge 22 present



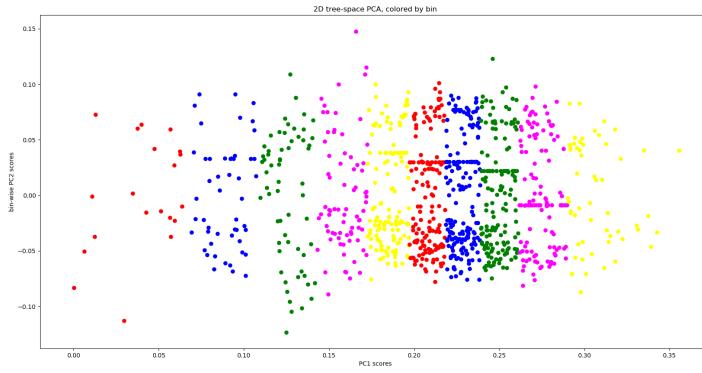
Specific splits: edge 20 present



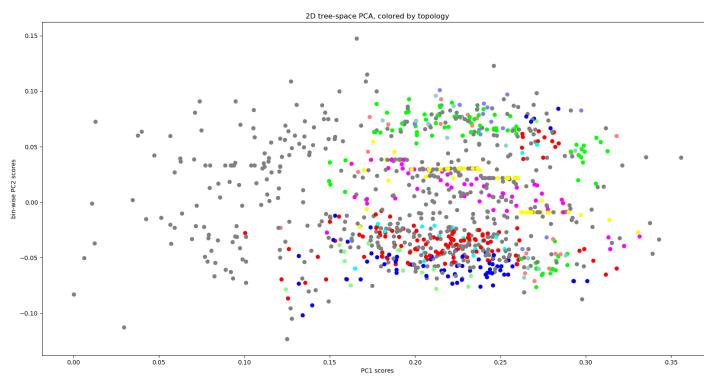
Specific splits: edge 18 present



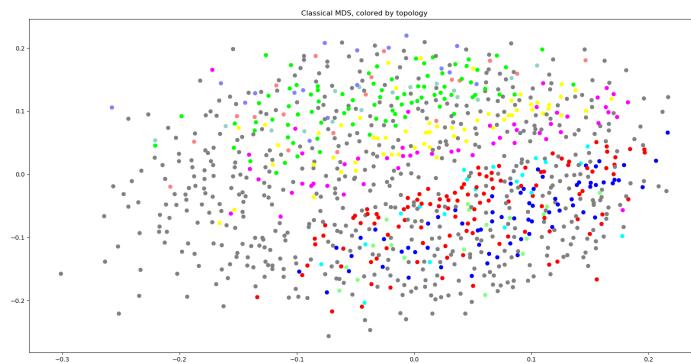
DS2 by bin



DS2 by topology



DS2 by topology



Observations:

Observations and concerns:

- ▶ Number of bins: preset or selected by KDE methods
- ▶ Danger of overfitting with many bins
- ▶ No guarantee second PCA is perpendicular to first PCA
- ▶ Third PCA generally sparse data to fit

Contributors



Aasa Feragen:



Megan Owen:

Treespace Working Group:



sites.google.com/site/treespaceworkinggroup/