# Tree distances under random walks on tree spaces

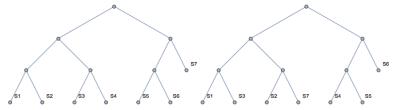
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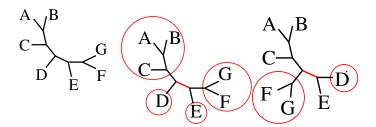
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## Distances between phylogenetic trees

Given two trees (rooted or unrooted) on the same set of leaves (taxa), to what extent to they differ?

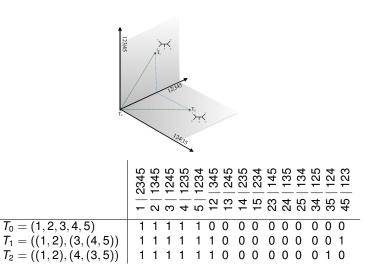


 Metrics on trees: Nearest Neighbor Interchange (NNI), Robinson-Foulds (RF) Δ, Subtree-Prune-Regraft (SPR), Tree Bisection and Reconnection (TBR), Billera-Holmes-Vogtmann (BHV), ... Nearest neighbor interchange move at edge between D and E:



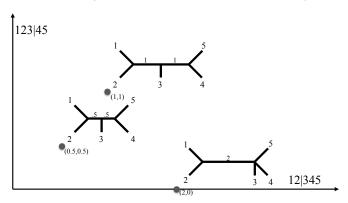
Subtree-prune-regraft move at edge between subtree containing AB and the rest of the tree:

### Trees as Vectors



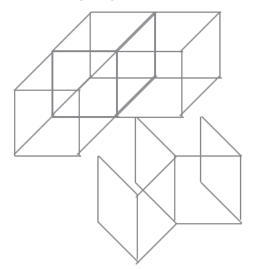
## Billeara-Holmes-Vogtmann space

- Trees on fixed n taxa, edge lengths positive reals
- Edges to leaves have fixed length 1
- Form a space with a metric which is locally Euclidean



## Billera-Holmes-Vogtmann treespace

- ▶ Adjacency of orthants: two orthants of dimension *k* share a face of dimension *l* if they have *l* edges in common.
- Gives gluing of orthants to obtain space



## Geodesics in treespace

- Piecewise Euclidean segments in a sequence of orthants
- Many cells to consider
- First algorithms exponential
- Polynomial-time algorithm of order O(n<sup>4</sup>) of Owen-Provan (2011) uses incompatibility graph of edges to compute which edges to drop and introduce successively.
- Owen-Provan algorithm foundational for computing means, interpolations, variances, principal components, ...

## Random walks in tree spaces

### Typical search algorithm:

- Generate a set of random trees
- Score them with respect to some optimality criterion
- Take the best or some of the best
- Perturb these trees with some local adjustments
- Take the best scoring and repeat.

## Random walks in tree spaces

## Effectiveness of this process depends upon

- How well random walks visit regions of tree space
- How well hill-climbing works
- Length of process

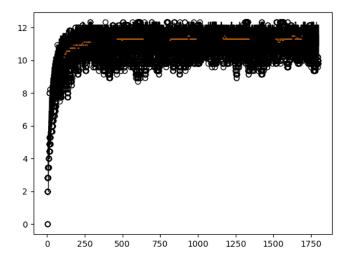
## Random walks in treespace

- Randomly generate an initial tree T<sub>0</sub>.
- Select a location to perform a move (NNI, SPR) at random
- ▶ Apply move to get T<sub>i+1</sub>
- ▶ Iterate to get sequence  $\{T_0, T_1, T_2, ...\}$

Look at BHV distances from  $T_0$ , gives sequence  $d_i = d(T_0, T_i)$ Sequence of trees of generally increasing distance- how long until essentially  $T_i$  is unrelated to  $T_0$ ?

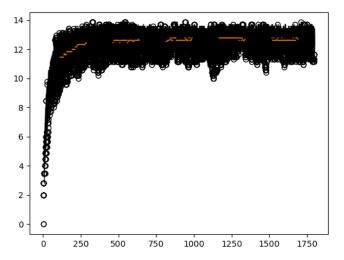
## Distances as walk lengthens

Example: compute distance from an initial tree of size 40 under random NNI walks:



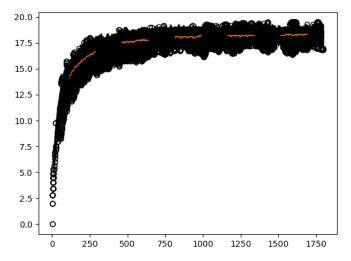
## Distances as walk lenghtens

Example: compute distance from an initial tree of size 50 under random NNI walks:



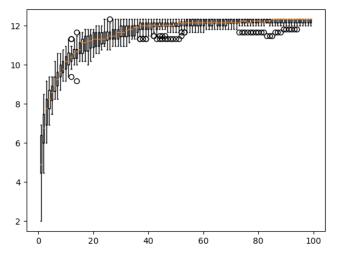
## Distances as walk lengthens

Example: compute distance from an initial tree of size 100 under random NNI walks:



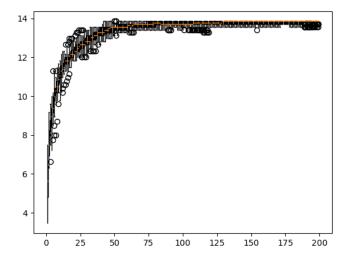
## Distances as walk lengthens

Example: compute distance from an initial tree of size 40 under random SPR walks:



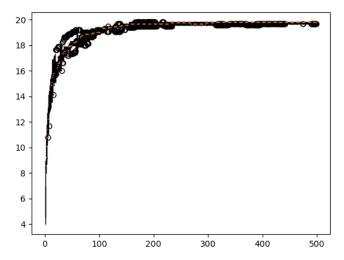
## Distances as walk lenghtens

Example: compute distance from an initial tree of size 50 under random SPR walks:



## Distances as walk lengthens

Example: compute distance from an initial tree of size 100 under random SPR walks:



# Walk for mixing

#### Observations:

- Diameter of treespace is n for both NNI and SPR.
- ▶ Neighborhoods larger for SPR than NNI (n² vs. n.)
- These are for undirected random walks
- Walks used for searching are generally directed by optimality criterion

## Walk duration to lose initial information

#### Observations:

- Seems to grow about n log n with size of tree.
- Faster for SPR than NNI
- NNI can reverse earlier progress away from T<sub>0</sub> more readily than SPR
- Coupon-collecting arguments give n log n bound for all edges to be affected
- Don't need complete coupon collecting as random trees will have some common edges already.

## Coupon collecting

Number of steps to collect all of a set of *N* coupons:

$$E(T) = \dots = \frac{n}{n} + \frac{n}{n-1} + \dots + \frac{n}{2} + \frac{n}{1}$$
$$\sim n \log n + \gamma n + \frac{1}{2} + O(\frac{1}{n})$$

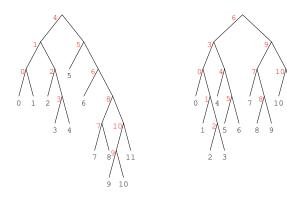
Much of time is spent waiting for the last few coupons. Randomly generated trees may have some common edges on average.

### Other results:

#### Observations:

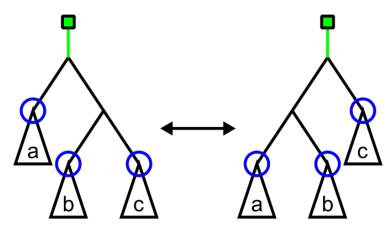
- For weighted trees (edge lengths Poisson distributed, for example) similar behavior
- Random walks with weighted edges- selecting an edge equally or proportional to weight, similar behavior
- NNI moves mixing rate not known even for ordered trees (rotation moves)
- ▶ In edge length one case, time to a maximally distant tree (distance  $2\sqrt{n-2}$ ) seems to grow as  $n \log n$ .

## Other settings: focus on tree shape, use ordered trees



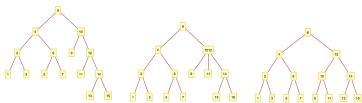
Two trees with left-to-right orders on the leaves (black) and nodes (red).

# Rotation operations



Rotation at a node.

# Rotation as a slide through a vertex, intermediate temporarily ternary tree



# Rooted binary trees and their dual polygonal triangulations

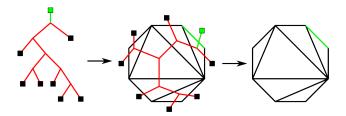
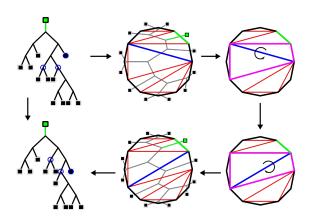


Figure: Converting a rooted binary tree with 7 leaves into its corresponding triangulation of an octagon with a marked edge.

# An edge flip in 12-gon and corresponding rooted binary tree and rotation,



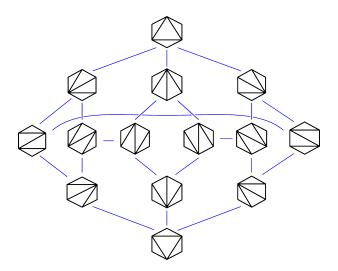
### Rotation distance

<u>Def</u> The rotation distance  $d_R(S, T)$  between two trees S and T with the same number of nodes is the minimum number rotations needed to transform S to T.

Well-defined? yes, via all-right tree.

Bounds? No more than 2n - 2 ever, via all-right tree. Culik-Wood (1982) No more than 2n - 6 for n > 11, realized! Sleator-Tarjan-Thurston (1988)

# The associahedron for triangulations of the hexagon.



### Walks on the associahedron

- Randomly generate an initial tree  $T_0$ .
- Select a location to perform a left/right rotation at random
- Apply move to get T<sub>i+1</sub>
- ▶ Iterate to get sequence  $\{T_0, T_1, T_2, \dots\}$

Look at rotation distances from  $T_0$ , gives sequence  $d_i = d(T_0, T_i)$ 

Sequence of trees of generally increasing distance- how long until essentially  $T_i$  is unrelated to  $T_0$ ?

Cannot compute rotation distance effectively beyond about size 15

Walks in associahedra: appear to mixing with times growing, appears linearly, only for small *n* possible.

## Contributors



Alejandro Morejon:



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Treespace Working Group:



sites.google.com/site/treespaceworkinggroup/



### Rotation distance bounds

Sleator-Tarjan-Thurston (1983):  $d_R(S, T) \le 2n - 6$  for trees of size 11 or greater.

Sleator-Tarjan-Thurston (1983): There is an N such that for all n > N, there are trees of size n such that  $d_R(S, T) = 2n - 6$  for trees of size 11 or greater.

Proof uses hyperbolic volume estimates of three manifolds, not very constructive.

### Known results from exhaustion

n nodes	1	2	3	4	5	6	7	8	9	10	11	12	13
n + 1 leaves	2	3	4	5	6	7	8	9	10	11	12	13	14
n+2 gons	3	4	5	6	7	8	9	10	11	12	13	14	15
max dist	0	1	2	4	5	7	9	11	12	15	16	18	20
gap from 2n	-2	-3	-4	-4	-5	-5	-5	-5	-6	-5	-6	-6	-6
# trees	1	2	5	14	42	132	429	1430	4862	16796	58786	208k	743ŀ

n is the number of internal nodes in  $T_i$ . Culik-Wood:  $d(T_1, T_2) \le 2n - 2$  for all n S-T-T:  $d(T_1, T_2) \le 2n - 6$  for all  $n \ge 11$  Number of tree pairs: 1, 4, 25, 196, 1764, 17424, 184041, 2044900, 23639044, 282105616 3455793796, 43268992144, 551900410000, 7152629313600, 93990019574025, 1250164827828900

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Proof uses hyperbolic volume estimates of three manifolds, not very constructive.

Exhaustive results up to about 20 gave antipodal tree pairs of all sizes tested greater than 11.

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Dehornoy (2009) There are explicit tree pairs at distances  $2n - O(\sqrt{n})$  for large n.

Pournin (2012) Explict examples for all sizes at least 11.



## Rotation distance algorithms

No known polynomial time algorithms for exact rotation distance.

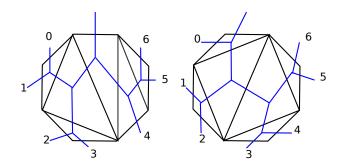
Baril-Pallo (2006) heuristic approximation algorithms

Cleary- St. John (2008) linear time approximation algorithm

Cleary- St. John (2009) rotation distance is fixed-parameter tractable

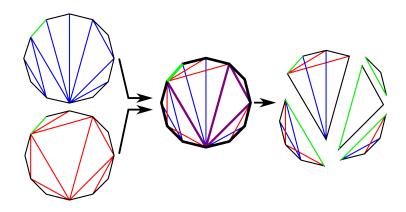
## Incidence of common edges

Easier to see from the polygonal perspective, taking trees as duals of triangulations of regular n-gons: Never undo a matched edge (S-T-T).



# Breaking apart along common edges

Root edges are marked in green- the purple edges are common to both the blue and the red.

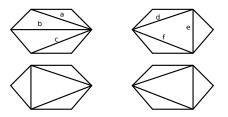


Tree pair is separated into several pieces, and total distance is sum of distances between pairs.



## One-off edges are easy but not symmetric

Two one-off edges *a* and *c* in the left triangulation with respect to the right one, but there is just one one-off edge *e* in the right one with respect to the left one:



Two triangulations of the hexagon, with no one-off edges present in either triangulation.

# Breaking apart along common edges

#### Questions:

- How often does a triangulation have a common edge?
- How many common edges on average? Distribution?
- How many sizable pieces result?
- On average, how large is the largest piece?
- How many immediate edge flips are there on average?

In general, interested what happens as the size grows.

(joint with Andrew Rechnitzer and Thomas Wong)

### Definition

The generating function for the combinatorial class  $\mathcal{P}$  will be denoted P(z), where z is conjugate to the number of non-rooted edges in the polygon between a pair of triangulations. Thus,

$$P(z) = \sum_{n=1}^{\infty} c_n^2 z^{n+1}$$

Define the auxiliary variables m and q on the generating function P(z) with m conjugate to the number of matched edges and q conjugate to the size of the  $\mathcal{R}$ -piece containing the root edge.

### **Theorem**

The two functions P(z; m, q) and R(z) are related by:

$$P(z; m, q) = R(q(z + mP(z; m, 1))).$$



### Theorem

The two functions P(z; m, q) and R(z) are related by:

$$P(z; m, q) = R(q(z + mP(z; m, 1))).$$

Proof: Recursive construction of  $\mathscr{P}$ . Each pair of triangulations can be constructed by first picking the corresponding root component in  $\mathscr{R}$  ( size q) and substituting:

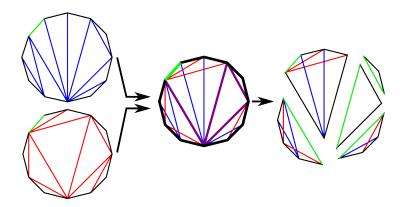
- 1. If that edge is an edge in the superimposed triangulation, do nothing;
- If that edge is a common chord, replace it with the corresponding P-piece. This substitution step does not contribute to the root component size q, but it does increase the number of matched edges by 1 since the replaced edge is now a common chord.

Thus  $\mathscr{P} = \mathscr{R} \circ (\mathscr{P} + \mathscr{Z})$  where  $\mathscr{Z}$  is the atomic class denoting an edge in the root component.

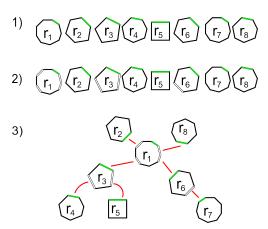


# Breaking apart along common edges

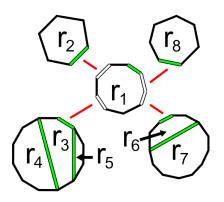
Root edges are marked in green- the purple edges are common to both the blue and the red.



# Assembling a sequence of 8 $\mathscr{R}$ -pieces



# Amalgamating the primitive pieces:



## Expected reduction properties

Questions: given a large tree pair diagram:

- ▶ How much does it reduce?
- How many common edges are there?
- What are the sizes of the primitive pieces?