Data 345

Applied Linear Algebra for Statistical Learning Class 7 (Sep. 18, 2025)

Vector (Sub)Spaces

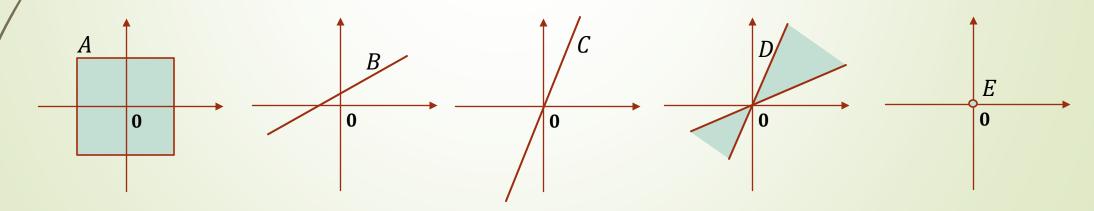
- Recall: we denoted by \mathbb{R}^n the set of all n-dimensional (real) vectors. We defined two operations for vectors: + (vector addition) and \cdot (scalar multiplication).
- This is a specific instance of a more general setting of "vector spaces."
- We will not worry extensively about the abstract definition. A real finite-dimensional vector space "is" some version of \mathbb{R}^n under appropriate relabeling.
- We will be primarily concerned with vector subspaces, which are smaller vector spaces embedded in a larger one.

Vector (Sub)Spaces

- Let $V = \mathbb{R}^n$ be a vector space and suppose that U is a subset of V. Then we say that U is a **subspace** of V if:
 - lacktriangle U is not empty, i.e., U has at least 1 vector in it;
 - U is "closed" under vector addition, meaning that if $x, y \in U$, then $x + y \in U$ as well;
 - U is "closed" under scalar multiplication, meaning that if $x \in U$ and $\lambda \in \mathbb{R}$, then $\lambda x \in U$ as well.
- Note that these conditions always imply that if U is a subspace then $\mathbf{0} \in U$: take any $\mathbf{x} \in U$. Then $(-1) \cdot \mathbf{x} \in U$ and $\mathbf{x} + (-1)\mathbf{x} \in U$, but $\mathbf{x} + (-1)\mathbf{x} = 0$.

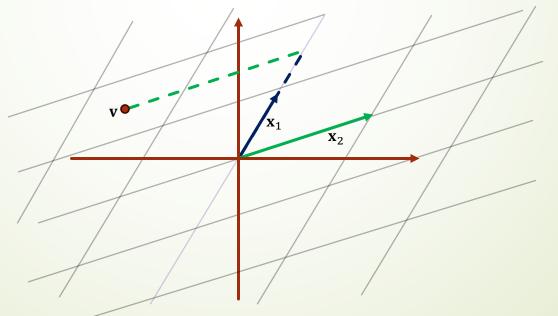
Vector (Sub)Spaces - Examples

- For any vector space V, the sets V and $\{0\}$ are both trivial subspaces of V.
- The solution set of a system of linear equations $A\mathbf{x} = \mathbf{0}$ with n unknowns is a subspace of \mathbb{R}^n .
- Any two subspaces of the same vector space overlap in a subspace. In other words, if U and W are subspaces of V, then the intersection U n W is also a subspace of V.



Linear Combinations

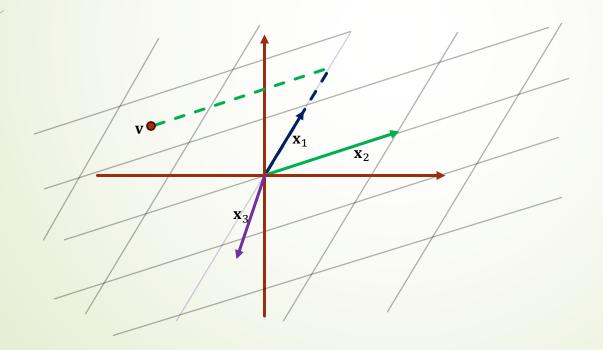
- Let V be a vector space, and suppose that $\mathbf{x}_1, \mathbf{x}_2, ..., \mathbf{x}_k$ are vectors in V. Then every vector $\mathbf{v} \in V$ of the form $\mathbf{v} = \lambda_1 \mathbf{x}_1 + \lambda_2 \mathbf{x}_2 + \cdots + \lambda_k \mathbf{x}_k$ (where λ_1 through λ_k are real numbers) is called a **linear combination** of \mathbf{x}_1 through \mathbf{x}_k .
- If you imagine the set of vectors \mathbf{x}_i as directions, then a linear combination of the vectors \mathbf{x}_i is simply any location on a "grid" in which the gridlines are lines parallel to the \mathbf{x}_i .



(Note: since λ_i may be any real number you can travel between gridlines)

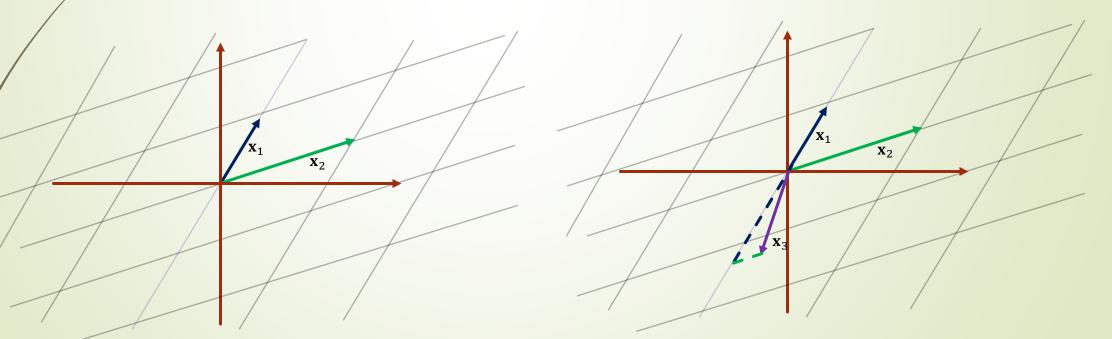
Linear Combinations

- We are particularly interested in linear combinations without redundancy of information.
- For instance, in our earlier picture, adding a new vector \mathbf{x}_3 introduces some redundancy, because we could already travel to any point in the Euclidean plane with just \mathbf{x}_1 and \mathbf{x}_2 .





- Let V be a vector space and $\mathbf{x}_1, \mathbf{x}_2, ..., \mathbf{x}_k$ a set of vectors in V. These vectors are said to be **linearly independent** if $\mathbf{0} = \lambda_1 \mathbf{x}_1 + \lambda_2 \mathbf{x}_2 + \cdots + \lambda_k \mathbf{x}_k$ implies that $\lambda_1 = \lambda_2 = \cdots = \lambda_k = 0$. In other words, the only way to reach the vector $\mathbf{0}$ by the directions \mathbf{x}_i is by traveling a net distance of 0 in each direction.
- If the set $\mathbf{x}_1, \mathbf{x}_2, ..., \mathbf{x}_k$ is not linearly independent then it is said to be **linearly dependent**. This means the equation $\mathbf{0} = \lambda_1 \mathbf{x}_1 + \lambda_2 \mathbf{x}_2 + \cdots \lambda_k \mathbf{x}_k$ has some non-trivial solution (at least one λ_i is not 0).



Linear Independence

- A set of k vectors can only be linearly independent or linearly dependent.
 There is no third option.
- If any of the vectors $\mathbf{x}_1, \mathbf{x}_2, ..., \mathbf{x}_k$ is the zero vector then the set is automatically linearly dependent. The same is true if any two vectors are equal.
- A set of vectors $\mathbf{x}_1, \mathbf{x}_2, ..., \mathbf{x}_k$ is linearly dependent if and only if at least one of them is a linear combination of the others.
- We already have a way to check if a set of vectors is independent!

Checking Linear Independence

Let $\mathbf{x}_1, \mathbf{x}_2, ..., \mathbf{x}_k$ be a set of vectors in \mathbb{R}^n . The set is linearly dependent if and only if there is a nontrivial solution to the equation $0 = \lambda_1 \mathbf{x}_1 + \lambda_2 \mathbf{x}_2 + \cdots + \lambda_k \mathbf{x}_k$. If we let A be the $n \times k$ matrix $[\mathbf{x}_1 | \mathbf{x}_2 | \cdots | \mathbf{x}_k]$, then this is literally equivalent to getting a non-trivial solution to the system of equations:

$$A \cdot \begin{bmatrix} \lambda_1 \\ \lambda_2 \\ \vdots \\ \lambda_k \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

- Since $[0, 0, ..., 0]^T$ is <u>always</u> a solution to this equation, this implies the solution set is infinite. In particular, not every column of A contains a pivot when A is row-reduced via Gaussian elimination.
- Therefore, a set $\{x_1, x_2, ..., x_k\}$ of vectors is linearly independent if and only if we arrange the set into a matrix A (where the columns of A are the vectors x_i) and every column contains a pivot after performing Gaussian elimination.

Checking Linear Independence

Example: Determine whether $\{x_1, x_2, x_3\} \subset \mathbb{R}^4$ is linearly independent.

$$\mathbf{x}_1 = \begin{bmatrix} 1\\2\\-3\\4 \end{bmatrix} \qquad \mathbf{x}_2 = \begin{bmatrix} 1\\1\\0\\2 \end{bmatrix} \qquad \mathbf{x}_3 = \begin{bmatrix} -1\\-2\\1\\1 \end{bmatrix}$$

$$\{\mathbf{x}_1,\mathbf{x}_2,\mathbf{x}_3\}$$

$$\begin{bmatrix} 1 & 1 & -1 \\ 2 & 1 & -2 \\ -3 & 0 & 1 \\ 4 & 2 & 1 \end{bmatrix}$$

(Gaussian elimination)
$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

> [0.0 0.0 1] [0.0 0.0 0.0])

3 columns, 3 pivots. Therefore, the set is linearly independent.

Checking Linear Independence

▶ Determine whether the set $\{x_1, x_2, x_3, x_4\} \subset \mathbb{R}^4$ is linearly independent:

$$\mathbf{x}_1 = \begin{bmatrix} 1 \\ -2 \\ 1 \\ -1 \end{bmatrix}$$
 $\mathbf{x}_2 = \begin{bmatrix} -4 \\ -2 \\ 0 \\ 4 \end{bmatrix}$ $\mathbf{x}_3 = \begin{bmatrix} 2 \\ 3 \\ -1 \\ -3 \end{bmatrix}$ $\mathbf{x}_4 = \begin{bmatrix} 17 \\ -10 \\ 11 \\ 1 \end{bmatrix}$

$$\begin{bmatrix} 1 & -4 & 2 & 17 \\ -2 & -2 & 3 & -10 \\ 1 & 0 & -1 & 11 \\ -1 & 4 & -3 & 1 \end{bmatrix} (Gaussian elimination) \begin{bmatrix} 1 & 0 & 0 & -7 \\ 0 & 1 & 0 & -15 \\ 0 & 0 & 1 & -18 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

A = matrix([[1, -4, 2, 17], [-2, -2, 3, -10], [1, 0, -1, 11], [-1, 4, -3, 1]])

A.rref()

0.0s

Pythol

1 0 0 -7

0 1 0 -15

0 0 1 -18