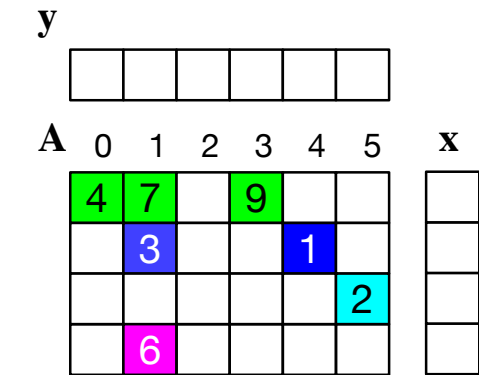


Loop Transformation Frameworks for Sparse Codes and Program Synthesis Opportunities

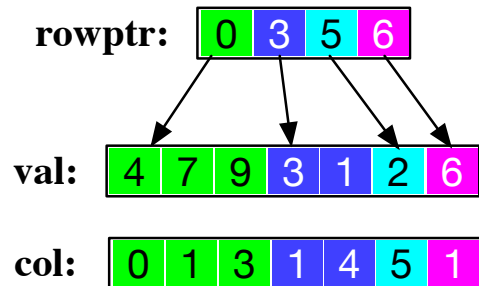
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Sparse Codes are Hard to Optimize and Transform



```
// Dense matrix vector mult.
for (i = 0; i < N; i++) {
    for (j = 0; j < N; j++)
        y[i] += A[i][j] * x[j];
}
```



```
// sparse matrix vector mult. (SpMV)
for (i=0; i<n; i++) {
    for(k=rowptr[i];k<rowptr[i+1];k++){
        y[i] += val[k]*x[col[k]];
    }
}
```

- Indirect accesses are slow
- Many different sparse formats
- Which sparse format is ideal depends on: algorithm, sparse structure, AND computation



Current Approaches

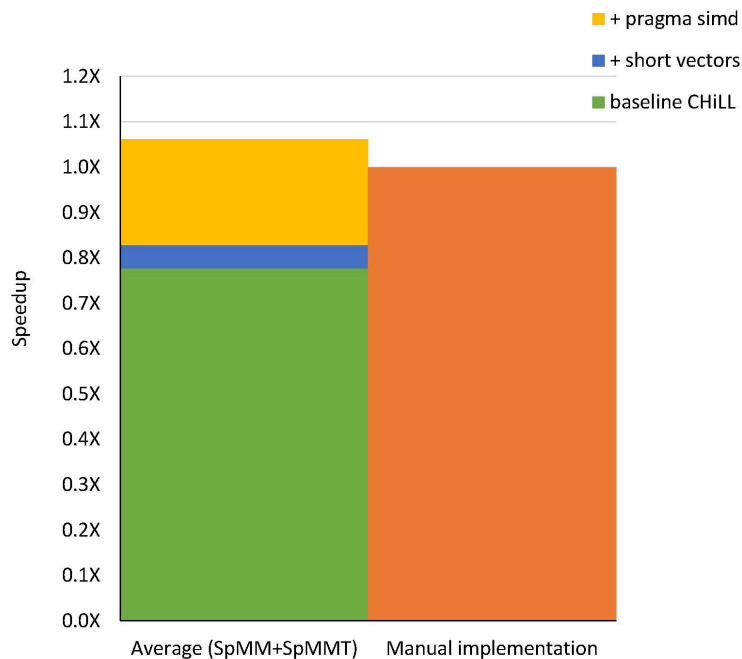
- Developing new sparse formats and optimizations: HiCOO, sparse tiling, wavefront parallelization, ...
- Code generation from a DSL
 - Bernoulli compiler work
 - TACO work generates efficient implementations given a sparse tensor formats and a tensor expression
- Transforming existing code
 - Sparse Polyhedral Framework
 - CHiLL-I/E, scripting compiler for specifying inspector-executor transformations



Transformation Example: SpMM from LOBPCG (NUCLEI)

```
/* SpMM from LOBCG on symmetric matrix */
for( i = 0; i < n ; i ++ ) {
  for( j = index [ i ]; j < index [ i + 1 ]; j ++ )
    for( k = 0; k < m ; k ++ );
    y [ i ][ k ] += A [ j ] * x [ col [ j ] ][ k ];
  /* transposed computation exploiting symmetry */
  for( j = index [ i ]; j < index [ i + 1 ]; j ++ )
    for( k = 0; k < m ; k ++ )
      y [ col [ j ] ][ k ] += A [ j ] * x [ i ][ k ];
}
```

Code A: Multiple SpMV computations (SpMM), 7 lines of code



Data Transformation:
Convert Matrix Format
CSR → CSB
11 different block sizes/implementation

Parallelism:
Thread-level (OpenMP w/schedule)

Parallelism:
SIMD (AVX2)

Other:
Indexing simplification

```
subroutine csc2blkcoord
  use csc
  use blkcoord
  implicit none
  integer :: i, j, r, c, k, k1, k2, blkcr, blkcc, tm
  integer*4, dimension(:,:), allocatable :: top

  ! ... (omitted code) ...

  ! allocate matrix storage arrays
  allocate(gloc(nnz))
  allocate(gcloc(nnz))
  allocate(gval(nnz))

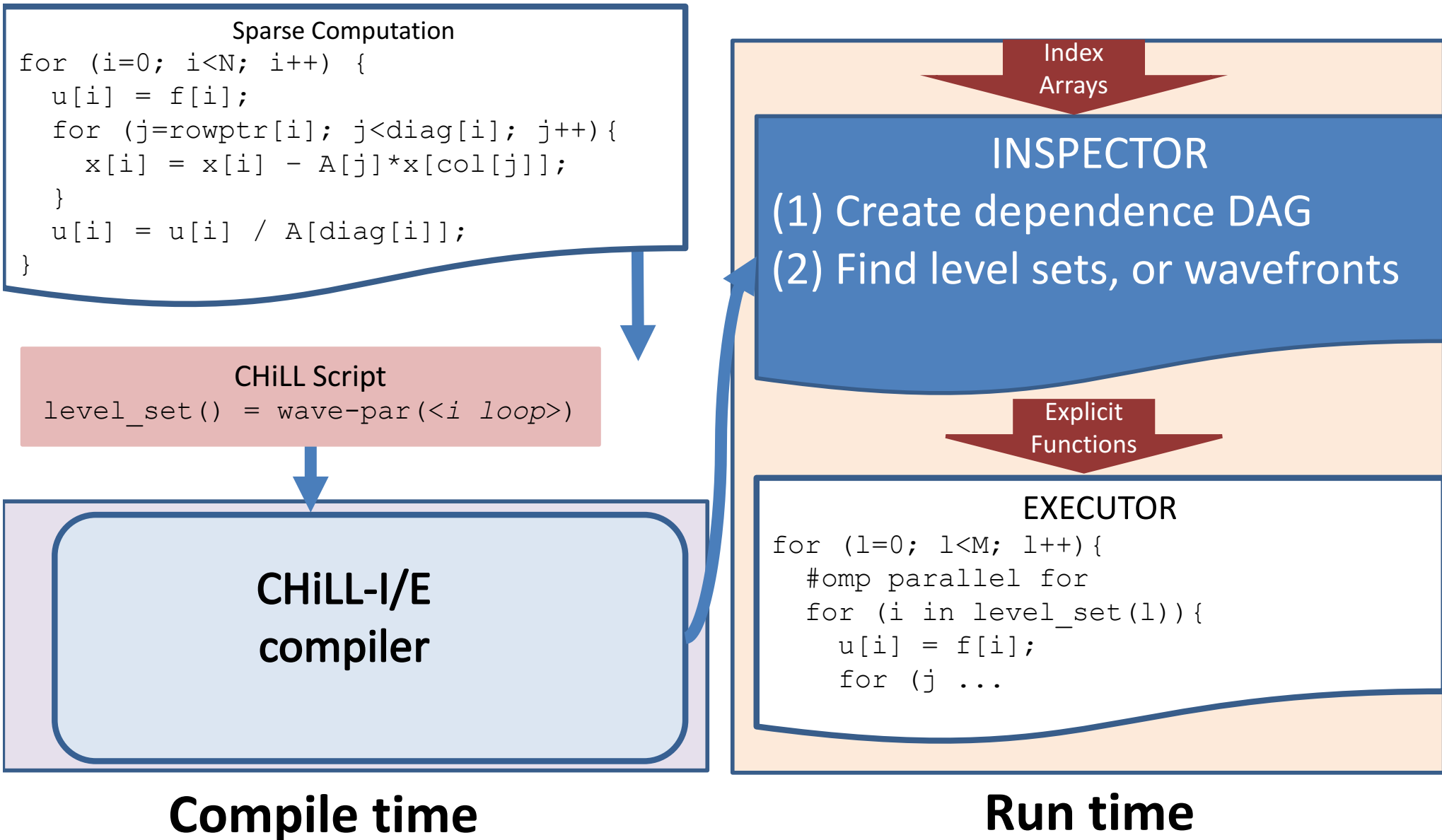
  ! set the pointers/offsets in each block
  tmp = 0
  do blkcr = 1, ncolblks
    do blkcc = 1, nrowblks
      H(blkcr,blkcc)%offset = (blkcr-1)*wblk
      H(blkcr,blkcc)%offset = (blkcc-1)*wblk
      H(blkcr,blkcc)%gptr = tmp
      tmp = tmp + H(blkcr,blkcc)%nnz
    enddo
  enddo

  ! write(0,*) ' row=',blkcr, ' col=',blkcc,
  !           ' nnz=',H(blkcr,blkcc)%nnz
  &
  ! place nonzeros into blocks
  top = 0
  do c = 1, numcols
    k1 = colater(c)
    k2 = colater(c)
    do
      ! ... (omitted code) ...
    enddo
  enddo
end subroutine csc2blkcoord
```

Code B: Manually-optimized SpMM from LOBCG, 2109 lines of code

Take-away message: Compiler-optimized Code A faster than manual Code B!

CHiLL-I/E: Inspector-Executor Transformations



Opportunities to Leverage Synthesis Tools?

- Constraint-solving-based synthesis techniques
 - Polyhedral model uses Farkas lemma to derive scheduling constraints from data dependences
 - Sparse Polyhedral Framework can produce constraints for the uninterpreted functions the inspector must produce at runtime
- Run-time realization of uninterpreted functions
 - Could be synthesized to specialize for usage
 - Data structure synthesis tools like Cozy



Deriving constraints for uninterpreted functions

- Constraint-based data dependence analysis
- Transformations introduce new uninterpreted functions and modify data dependences
- Convert data dependence relations into constraints on uninterpreted functions



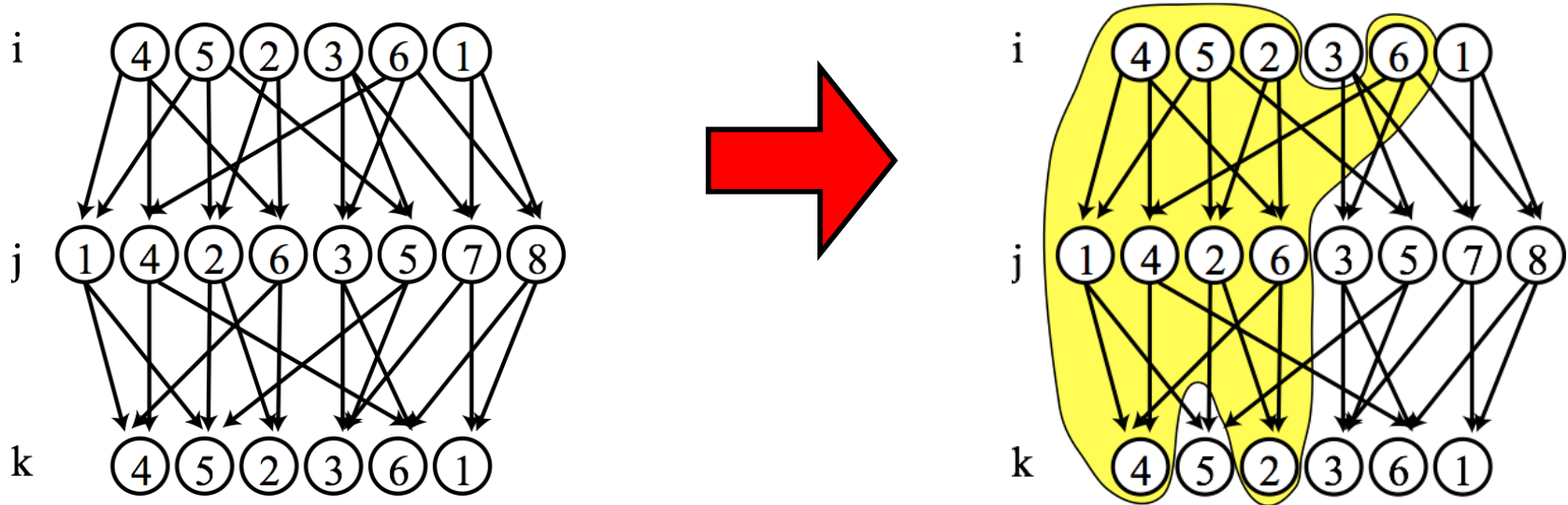
Constraint-Based Data Dependence Analysis of Sparse Computation

```
for (int j=0; j<n; j++){
    x[j] = x[j] / Lx[colPtr[j]];
    for(int p=colPtr[j]+1; p<colPtr[j+1]; p++){
        x[row[p]] = x[row[p]] - Lx[p] * x[j];
    }
}
```

$$\underbrace{\{ [j, p] \rightarrow [j', p'] : \overbrace{j = j' \wedge p < p'}^{\text{lexicographical Ordering}} \wedge \overbrace{\text{row}(p) = j'}^{\text{Array Access Equality}} \wedge \underbrace{0 \leq j, j' < n \wedge \text{colPtr}(j) < p < \text{colPtr}(j+1) \wedge \text{colPtr}(j') < p' < \text{colPtr}(j'+1)}_{\text{Loop Bounds}} \}}_{\text{Loop Bounds}}$$



Example Transformation Introducing an Uninterpreted Function



$$T_{F_1 \rightarrow F_2} = \{[s, 0, i] \rightarrow [s, 0, t, 0, i] \mid t = \Theta(0, i)\} \\ \cup \{[s, 1, j] \rightarrow [s, 0, t, 1, j] \mid t = \Theta(1, j)\} \dots$$

$$F_1 = \{[s, 0, i]\} \cup \{[s, 1, j]\} \cup \{[s, 2, k]\}$$



$$F_2 = \{[s, 0, t, 0, i] \mid t = \Theta(0, i)\} \cup \{[s, 0, t, 1, j] \mid t = \Theta(1, j)\} \dots$$



Transformed Dependences Need to be Lexicographically Non-Negative

$$D_{I_0 \rightarrow J_0} = \{[s, 0, i] \rightarrow [s, 1, j] \mid i = l(j) \vee i = r(j)\}$$



$$\begin{aligned} T_{F_1 \rightarrow F_2} &= \{[s, 0, i] \rightarrow [s, 0, t, 0, i] \mid t = \Theta(0, i)\} \\ &\cup \{[s, 1, i] \rightarrow [s, 0, t, 1, j] \mid t = \Theta(1, j)\} \cdots \end{aligned}$$



$$\begin{aligned} D_{I_0 \rightarrow J_0} &= \{[s, 0, t_1, 0, i] \rightarrow [s, 0, t_2, 1, j] \mid (t_1 = \Theta(0, i) \wedge t_2 = \Theta(1, j) \wedge i = l(j)) \\ &\quad \vee (t_1 = \Theta(0, i) \wedge t_2 = \Theta(1, j) \wedge i = r(j))\} \end{aligned}$$



Constraints Derived from Dependence

$$D_{I_0 \rightarrow J_0} = \{[s, 0, t_1, 0, i] \rightarrow [s, 0, t_2, 1, j] \mid (t_1 = \Theta(0, i) \wedge t_2 = \Theta(1, j) \wedge i = l(j)) \vee (t_1 = \Theta(0, i) \wedge t_2 = \Theta(1, j) \wedge i = r(j))\}$$



$$\forall s, t_1, t_2, i, j : (i = l(j) \vee i = r(j)) \Rightarrow \Theta(0, i) \leq \Theta(1, j)$$

If iteration i must be executed before iteration j , then iteration i must be in the same or earlier tile than j .



Summary: Synthesis and Transformed Sparse Codes

- Use dependence analysis of original code and inspector-executor transformations to create constraints
- Remains to be seen how these constraints can be used to synthesize inspector code
- Use data structure synthesis to generate specialized implementations of run-time realizations of uninterpreted functions (not discussed)

