

Concurrency Theory

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Lecture 12: Modelling Mutual-Exclusion Algorithms & Value-Passing CCS

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<https://proglang.github.io/teaching/25ws/ct.html>

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Peterson's Mutual Exclusion Algorithm

- **Goal:** ensuring **exclusive access to non-shared resources**
- Here: two competing processes P_1, P_2 and shared variables
 - b_1, b_2 (Boolean, initially **false**) – b_i indicates that P_i wants to enter critical section
 - k (in $\{1, 2\}$, arbitrary initial value) – index of prioritised process (“turn variable”)
- P_i uses local variable $j := 2 - i$ (index of other process)

Algorithm 12.1 (Peterson's algorithm for P_i)

```
while true do
    "non-critical section";
     $b_i := \text{true};$ 
     $k := j;$ 
    await  $\neg b_j \vee k = i;$ 
    "critical section";
     $b_i := \text{false};$ 
end
```

Representing Shared Variables in CCS

- Not directly expressible in CCS (communication by handshaking)
- Idea: consider **variables as processes** that communicate with environment by processing read/write requests

Example 12.2 (Shared variables in Peterson's algorithm)

- Encoding of b_1 with two (process) **states** B_{1t} (value tt) and B_{1f} (ff)
- **Read access** along ports $b1rt$ (in state B_{1t}) and $b1rf$ (in state B_{1f})
- **Write access** along ports $b1wt$ and $b1wf$ (in both states)
- Possible behaviours:

$$B_{1f} = \overline{b1rf}.B_{1f} + b1wf.B_{1f} + b1wt.B_{1t}$$

$$B_{1t} = \overline{b1rt}.B_{1t} + b1wf.B_{1f} + b1wt.B_{1t}$$

- Similarly for b_2 and k :

$$B_{2f} = \overline{b2rf}.B_{2f} + b2wf.B_{2f} + b2wt.B_{2t}$$

$$B_{2t} = \overline{b2rt}.B_{2t} + b2wf.B_{2f} + b2wt.B_{2t}$$

$$K_1 = \overline{kr1}.K_1 + kw1.K_1 + kw2.K_2$$

Modelling the Processes in CCS

Assumption: P_i cannot fail or terminate within critical section

Peterson's algorithm

```
while true do
    "non-critical section";
     $b_i := \text{true};$ 
     $k := j;$ 
    await  $\neg b_j \vee k = i;$ 
    "critical section";
     $b_i := \text{false};$ 
end
```

CCS representation

$$\begin{aligned}P_1 &= \overline{b1wt}.\overline{kw2}.P_{11} \\P_{11} &= b2rf.P_{12} + \\&\quad b2rt.(kr1.P_{12} + kr2.P_{11}) \\P_{12} &= \text{enter1.exit1.}\overline{b1wf}.P_1 \\P_2 &= \overline{b2wt}.\overline{kw1}.P_{21} \\P_{21} &= b1rf.P_{22} + \\&\quad b1rt.(kr1.P_{21} + kr2.P_{22}) \\P_{22} &= \text{enter2.exit2.}\overline{b2wf}.P_2\end{aligned}$$

$$\begin{aligned}\text{Peterson} &= (P_1 \parallel P_2 \parallel B_{1f} \parallel B_{2f} \parallel K_1) \setminus L \\ \text{for } L &= \{b1rf, b1rt, b1wf, b1wt, \\&\quad b2rf, b2rt, b2wf, b2wt, \\&\quad kr1, kr2, kw1, kw2\}\end{aligned}$$

Specifying the Algorithm in CAAL

CAAL

Project ▾

Edit

Explore

Verify

Games ▾

About

Syntax



MutEx

Parse

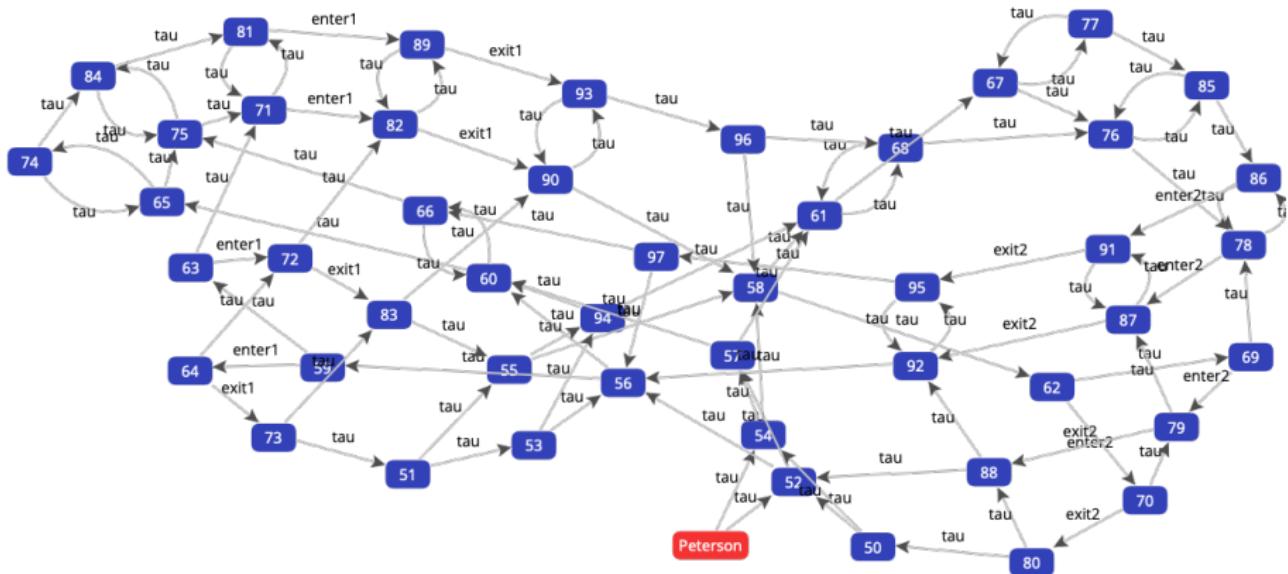
CCS

TCCS

14 ↴

```
1  *
2  * Peterson's algorithm for mutual exclusion (Lecture 12)
3  *
4
5  B1f = !b1rf.B1f + b1wf.B1f + b1wt.B1t;
6  * B1f = !b1rf.B1f + b1wf.B1f + b1wt.enabled1.B1t;
7  B1t = !b1rt.B1t + b1wf.B1f + b1wt.B1t;
8
9  B2f = !b2rf.B2f + b2wf.B2f + b2wt.B2t;
10 * B2f = !b2rf.B2f + b2wf.B2f + b2wt.enabled2.B2t;
11 B2t = !b2rt.B2t + b2wf.B2f + b2wt.B2t;
12
13 K1 = !kr1.K1 + kw1.K1 + kw2.K2;
14 K2 = !kr2.K2 + kw1.K1 + kw2.K2;
15
16 P1 = !b1wt.!kw2.P11;
17 P11 = b2rf.P12 + b2rt.(kr2.P11 + kr1.P12);
18 P12 = enter1.exit1.!b1wf.P1;
19
20 P2 = !b2wt.!kw1.P21;
21 P21 = b1rf.P22 + b1rt.(kr1.P21 + kr2.P22);
22 P22 = enter2.exit2.!b2wf.P2;
23
24 set L = {b1rf, b2rf, b1rt, b2rt, b1wf, b2wf, b1wt, b2wt, kr1, kr2, kw1, kw2};
25 Peterson = (P1 | P2 | B1f | B2f | K1) \ L;
26
27 MutExCCS = enter1.exit1.MutExCCS + enter2.exit2.MutExCCS;
```

Obtaining the LTS Using CAAL



The Mutual Exclusion Property

- **Done:** Formal description of Peterson's algorithm
- **To do:** Analysing its behaviour (manually or with tool support)
- **Question:** What does "ensuring mutual exclusion" formally mean?

Mutual exclusion

At **no point** in the execution of the algorithm, processes P_1 and P_2 will **both** be in their critical section.

Equivalently:

It is **always** the case that either P_1 or P_2 or both are **not** in their critical section.

Model Checking Mutual Exclusion in HML

Mutual exclusion

It is **always** the case that either P_1 or P_2 or both are **not** in their critical section.

Observations:

- Mutual exclusion is an **invariance** property (“always”).
- P_i is in its critical section iff action $\text{exit } i$ is enabled.

Mutual exclusion in HML

$Peterson \models \text{MutExHML}$

$\text{MutExHML} := \text{Inv}(\text{NotBoth})$

$\text{Inv}(F) \stackrel{\max}{=} F \wedge [\text{Act}] \text{Inv}(F)$ (cf. Theorem 11.1)

$\text{NotBoth} := [\text{exit1}]ff \vee [\text{exit2}]ff$

Absence of Deadlocks

Absence of deadlocks

It is **always** the case that the system can progress, i.e., perform any action.

Absence of deadlocks in HML

$$Peterson \models NoDeadlock$$

$$NoDeadlock := Inv(CanProgress)$$

$$Inv(F) \stackrel{\max}{\equiv} F \wedge [Act]Inv(F)$$

$$CanProgress := \langle Act \rangle tt$$

Possibility of Livelocks

Possibility of livelocks

It is **possible** for the system to reach a state which has a livelock (i.e., an infinite sequence of internal steps).

Possibility of livelocks in HML (cf. Example 11.11)

Peterson \models *HasLivelock*

HasLivelock := *Pos(Livelock)*

Pos(F) $\stackrel{\min}{=}$ $F \vee \langle Act \rangle Pos(F)$ (cf. Theorem 11.2)

Livelock $\stackrel{\max}{=}$ $\langle \tau \rangle Livelock$

Verification by Bisimulation Checking

- **Goal:** express **desired behaviour** of algorithm as an “abstract” CCS process
- Intuitively:
 - (1) Initially, either P_1 or P_2 can enter its critical section.
 - (2) Afterwards, the other process cannot enter the critical section before the first has left.

Mutual exclusion in CCS

$$\text{MutExCCS} = \text{enter1.exit1.MutExCCS} + \text{enter2.exit2.MutExCCS}$$

- Weak bisimilarity (Definition 5.10) does *not* hold as Peterson satisfies additional fairness constraints (prioritisation via variable k — distinguishing formula $\langle\langle\tau\rangle\rangle[[\text{enter2}]]\text{ff}$):
 $\text{Peterson} \not\approx \text{MutExCCS}.$
- However, Peterson and MutExCCS are **weakly simulation equivalent**:
 $\text{Peterson} \sqsubseteq \text{MutExCCS}$ and $\text{MutExCCS} \sqsubseteq \text{Peterson}$
where $P \sqsubseteq Q$ denotes that Q **weakly simulates** P , i.e., can respond to every $\xrightarrow{\alpha}$ -step of P by performing a $\xrightarrow{\alpha}$ -step (cf. Definition 5.3 of strong

Verification by Testing I

Approach:

- Make mutual exclusion algorithm interact with “monitor” process that observes its behaviour.
- Report error if and when undesired behaviour is detected.

The monitor process

$$\text{MutExTest} := \overline{\text{enter1}}.\text{MutExTest}_1 + \overline{\text{enter2}}.\text{MutExTest}_2$$
$$\text{MutExTest}_1 := \overline{\text{exit1}}.\text{MutExTest} + \overline{\text{enter2}}.\overline{\text{bad}}.\text{nil}$$
$$\text{MutExTest}_2 := \overline{\text{exit2}}.\text{MutExTest} + \overline{\text{enter1}}.\overline{\text{bad}}.\text{nil}$$
$$\text{Test} := (\text{Peterson} \parallel \text{MutExTest}) \setminus L'$$
$$L' := \{\text{enter1}, \text{enter2}, \text{exit1}, \text{exit2}\}$$

Verification by Testing II

Lemma 12.2

Let $P \in Prc$ be a process whose only visible actions are contained in L' . Then

$$Test \xrightarrow{\overline{bad}} \text{ iff } \text{ either } P \xrightarrow{\sigma} \xrightarrow{\text{enter1}} \xrightarrow{\text{enter2}} \text{ or } P \xrightarrow{\sigma} \xrightarrow{\text{enter2}} \xrightarrow{\text{enter1}}$$

for some sequence of actions $\sigma \in (\text{enter1 exit1} \mid \text{enter2 exit2})^*$.

Proof.

see Luca Aceto, Anna Ingólfssdóttir, Kim Guldstrand Larsen and Jiří Srba:
Reactive Systems: Modelling, Specification and Verification, Cambridge University Press, 2007, Proposition 7.2

□

Absence of bad transitions

$$Test \models NoBadTransition$$

$$NoBadTransition := Inv([\overline{bad}]ff)$$

$$Inv(F) \stackrel{\max}{=} F \wedge [Act]Inv(F)$$

Value-Passing CCS

- **So far:** pure CCS
 - communication = mere synchronisation
 - no (explicit) exchange of data
- **But:** processes usually **do** pass around data

⇒ Value-passing CCS

- Introduced in Robin Milner: *Communication and Concurrency*, Prentice-Hall, 1989
- Assumption (for simplicity): only **integers** as data type

Example 12.3 (One-place buffer with data; cf. Example 2.5)

One-place buffer that outputs successor of stored value:

$$\begin{aligned}B &= \text{in}(x).B'(x) \\ B'(x) &= \overline{\text{out}}(x+1).B\end{aligned}$$

Syntax of Value-Passing CCS I

Definition 12.4 (Syntax of value-passing CCS)

- Let A, \bar{A}, Pid (ranked) as in Definition 2.1.
- Let e and b be integer and Boolean expressions, resp., built from integer variables x, y, \dots
- The set Prc^+ of **value-passing process expressions** is defined by:

$P ::= \text{nil}$	(inaction)
$ \quad a(x).P$	(input prefixing)
$ \quad \bar{a}(e).P$	(output prefixing)
$ \quad \tau.P$	(τ prefixing)
$ \quad P_1 + P_2$	(choice)
$ \quad P_1 \parallel P_2$	(parallel composition)
$ \quad P \setminus L$	(restriction)
$ \quad P[f]$	(relabelling)
$ \quad \text{if } b \text{ then } P$	(conditional)
$ \quad C(e_1, \dots, e_n)$	(process call)

Syntax of Value-Passing CCS II

Definition 12.4 (Syntax of value-passing CCS; continued)

A **value-passing process definition** is an equation system of the form

$$(C_i(x_1, \dots, x_{n_i}) = P_i \mid 1 \leq i \leq k)$$

where

- $k \geq 1$,
- $C_i \in Pid$ of rank n_i (pairwise distinct),
- $P_i \in Prc^+$ (with process identifiers from $\{C_1, \dots, C_k\}$), and
- all occurrences of an integer variable y in each P_i are **bound**, i.e.,
 $y \in \{x_1, \dots, x_{n_i}\}$ or y is in the scope of an input prefix of the form $a(y)$
(to ensure well-definedness of values).

Example 12.5

(1) $C(x) = \bar{a}(x + 1).b(y).C(y)$ is allowed

(2) $C(x) = \bar{a}(x + 1) \bar{a}(x + 2) \text{ nil}$ is disallowed as x is not bound

Semantics of Value-Passing CCS I

Definition 12.6 (Semantics of value-passing CCS)

A value-passing process definition $(C_i(x_1, \dots, x_{n_i}) = P_i \mid 1 \leq i \leq k)$ determines the LTS $(Prc^+, Act, \longrightarrow)$ with $Act := (A \cup \bar{A}) \times \mathbb{Z} \cup \{\tau\}$ whose transitions can be inferred from the following rules ($P, P', Q, Q' \in Prc^+$, $a \in A$, x_i integer variables, e_i/b integer/Boolean expressions, $z \in \mathbb{Z}$, $\alpha \in Act$, $\lambda \in (A \cup \bar{A}) \times \mathbb{Z}$):

$$(In) \frac{}{a(x).P \xrightarrow{a(z)} P[z/x]}$$

$$(Out) \frac{(z \text{ value of } e)}{\bar{a}(e).P \xrightarrow{\bar{a}(z)} P}$$

$$(\Tau) \frac{}{\tau.P \xrightarrow{\tau} P}$$

$$(Sum_1) \frac{P \xrightarrow{\alpha} P'}{P + Q \xrightarrow{\alpha} P'}$$

$$(Sum_2) \frac{Q \xrightarrow{\alpha} Q'}{P + Q \xrightarrow{\alpha} Q'}$$

$$(Par_1) \frac{P \xrightarrow{\alpha} P'}{P \parallel Q \xrightarrow{\alpha} P' \parallel Q}$$

$$(Par_2) \frac{Q \xrightarrow{\alpha} Q'}{P \parallel Q \xrightarrow{\alpha} P \parallel Q'}$$

$$(Com) \frac{P \xrightarrow{\lambda} P' \quad Q \xrightarrow{\bar{\lambda}} Q'}{P \parallel Q \xrightarrow{\tau} P' \parallel Q'}$$

Semantics of Value-Passing CCS II

Definition 12.6 (Semantics of value-passing CCS; continued)

$$\begin{array}{c} (\text{Rel}) \frac{P \xrightarrow{\alpha} P'}{P[f] \xrightarrow{f(\alpha)} P'[f]} \qquad (\text{Res}) \frac{P \xrightarrow{\alpha} P' \ (\alpha \notin (L \cup \bar{L}) \times \mathbb{Z})}{P \setminus L \xrightarrow{\alpha} P' \setminus L} \\ \\ (\text{If}) \frac{P \xrightarrow{\alpha} P' \ (b \text{ true})}{\text{if } b \text{ then } P \xrightarrow{\alpha} P'} \qquad (\text{Call}) \frac{P[z_1/x_1, \dots, z_n/x_n] \xrightarrow{\alpha} P'}{(C(x_1, \dots, x_n) = P, z_i \text{ value of } e_i) \xrightarrow{\alpha} C(e_1, \dots, e_n)} \end{array}$$

Remarks:

- $P[z_1/x_1, \dots, z_n/x_n]$ denotes the **substitution** of each free occurrence of x_i by z_i ($1 \leq i \leq n$).
- Operations on actions ignore values:
 $\overline{a(z)} := \overline{a}(z) \quad \overline{\overline{a}(z)} := a(z) \quad f(a(z)) := f(a)(z) \quad f(\overline{a}(z)) := \overline{f(a)}(z)$ (and so on)
- The binding restriction ensures that all expressions have a **defined value**.
- The **two-armed conditional if b then P else Q** is definable by

Semantics of Value-Passing CCS III

Example 12.7

- One-place buffer that outputs non-negative predecessor of stored value:

$$\begin{aligned}B &= \text{in}(x).B'(x) \\ B'(x) &= (\text{if } x = 0 \text{ then } \overline{\text{out}}(0).B) + (\text{if } x > 0 \text{ then } \overline{\text{out}}(x - 1).B)\end{aligned}$$

- Input of value “1”:

$$\frac{\begin{array}{c} (\text{In}) \\ \hline \text{in}(x).B'(x) \xrightarrow{\text{in}(1)} B'(1) \end{array}}{(\text{Call}) \frac{\begin{array}{c} \text{in}(1) \\ \hline B \xrightarrow{\text{in}(1)} B'(1) \end{array}}{}}$$

- Output of predecessor:

$$\frac{\begin{array}{c} (\text{Out}) \\ \hline \overline{\text{out}}(1 - 1).B \xrightarrow{\overline{\text{out}}(0)} B \end{array}}{(\text{If}) \frac{\begin{array}{c} \overline{\text{out}}(1 - 1).B \xrightarrow{\overline{\text{out}}(0)} B \\ \text{if } 1 > 0 \text{ then } \overline{\text{out}}(1 - 1).B \xrightarrow{\overline{\text{out}}(0)} B \end{array}}{}} \\ \frac{(\text{Sum}_2) \quad \dots}{(\text{Call}) \frac{\begin{array}{c} (\text{if } 1 = 0 \text{ then } \overline{\text{out}}(0).B) + (\text{if } 1 > 0 \text{ then } \overline{\text{out}}(1 - 1).B) \xrightarrow{\overline{\text{out}}(0)} B \end{array}}{}}$$

Translation of Value-Passing into Pure CCS I

- **To show:** Value-passing process definitions can be represented in pure CCS.
- **Idea:** Each parametrised construct ($a(x)$, $\bar{a}(e)$, $C(e_1, \dots, e_n)$) corresponds to an **indexed family** of constructs in pure CCS, one for each possible (combination of) integer value(s).
- Requires extension of pure CCS by **infinite** choices (“ $\sum \dots$ ”), restrictions, and process definitions.

Translation of Value-Passing into Pure CCS II

Definition 12.8 (Translation of value-passing into pure CCS)

For each $P \in Prc^+$ without free variables, its **translated form** $\widehat{P} \in Prc$ is given by

$$\begin{array}{ll} \widehat{\text{nil}} := \text{nil} & \widehat{\tau.P} := \tau.\widehat{P} \\ \widehat{a(x).P} := \sum_{z \in \mathbb{Z}} a_z. \widehat{P[z/x]} & \widehat{\bar{a}(e).P} := \bar{a}_z. \widehat{P} \quad (\text{z value of } e) \\ \widehat{P_1 + P_2} := \widehat{P_1} + \widehat{P_2} & \widehat{P_1 \parallel P_2} := \widehat{P_1} \parallel \widehat{P_2} \\ \widehat{P \setminus L} := \widehat{P} \setminus \{a_z \mid a \in L, z \in \mathbb{Z}\} & \widehat{P[f]} := \widehat{P}[f] \quad (\widehat{f}(a_z) := f(a)_z) \\ \text{if } b \text{ then } P := \begin{cases} \widehat{P} & \text{if } b \text{ true} \\ \text{nil} & \text{otherwise} \end{cases} & C(\widehat{e_1, \dots, e_n}) := C_{z_1, \dots, z_n} \quad (\text{z}_i \text{ value of } e_i) \end{array}$$

Moreover, each defining equation $C(x_1, \dots, x_n) = P$ of a process identifier is translated into the indexed collection of process definitions

$$\left(C_{z_1, \dots, z_n} = P[z_1/\widehat{x_1}, \dots, z_n/\widehat{x_n}] \mid z_1, \dots, z_n \in \mathbb{Z} \right)$$

Translation of Value-Passing into Pure CCS III

Example 12.9 (cf. Example 12.7)

$$B = \text{in}(x).B'(x)$$

$$B'(x) = (\text{if } x = 0 \text{ then } \overline{\text{out}}(0).B) + (\text{if } x > 0 \text{ then } \overline{\text{out}}(x - 1).B)$$

translates to

$$\begin{aligned} B &= \sum_{z \in \mathbb{Z}} \text{in}_z.B'_z \\ B'_z &= P_z + Q_z \text{ where } P_z := \begin{cases} \overline{\text{out}}_0.B & \text{if } z = 0 \\ \text{nil} & \text{otherwise} \end{cases} \text{ and } Q_z := \begin{cases} \overline{\text{out}}_{z-1}.B & \text{if } z > 0 \\ \text{nil} & \text{otherwise} \end{cases} \end{aligned}$$

Theorem 12.10 (Correctness of translation)

For all $P, P' \in \text{Prc}^+$ and $\alpha \in \text{Act}$,

$$P \xrightarrow{\alpha} P' \iff \widehat{P} \xrightarrow{\widehat{\alpha}} \widehat{P}'$$

where $\widehat{a(z)} := a_z$, $\widehat{\bar{a}(z)} := \bar{a}_z$, and $\widehat{\tau} := \tau$.

Proof.

by induction on the structure of P (omitted)

