Tianyang ZHAO (Steven)

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EDUCATION

Department of Statistics, UCLA

Los Angeles, CA

Ph.D. Student, advised by *Prof. Ying Nian Wu*, collaborate with *Prof. Song-Chun Zhu*Sept 2019 -

VCLA research group, https://vcla.stat.ucla.edu/people.html

Yuanpei College, Peking University

Beijing, China

▶ Bachelor of Science in Data Science and Big Data Technology,

Aug 2015 - Jul 2019

➤ GPA (Junior Year): **3.70/4.0**; TOEFL: **111/120**;

Core Courses: Statistical Learning / Reinforcement Learning / Computer Vision & Deep Learning / Mathematical Statistics / Probability Theory / Algebraic Structure & Combinatorial Mathematics / Numerical Methods / Mathematical Analysis / Intro to Data Science / Intro to Computation / C&C++ / Data Structure & Algorithm / Algorithm Design & Analysis / Intro to Computer Systems / Compiler Design / Computer Networks / Database Systems (Honor Track)

The High School Affiliated to Renmin University of China (RDFZ)

Beijing, China

PUBLICATIONS

- ➤ **Tianyang Zhao**, Yifei Xu, Mathew Monfort, Wongun Choi, Chris Baker, Yibiao Zhao, Yizhou Wang, Ying Nian Wu. Multi-Agent Tensor Fusion for Contextual Trajectory Prediction. *IEEE Conference on CVPR 2019*;
- Yifei Xu, Jianwen Xie, **Tianyang Zhao**, Chris Baker, Yibiao Zhao, Ying Nian Wu. Energy-Based Continuous Inverse Optimal Control. *ArXiv:1904.05453*.

RESEARCH EXPERIENCE

Multi-Agent Trajectory Prediction for Autonomous Driving with Deep Learning and Inverse Optimal Control UCLA, Los Angeles, CA; ISEE Inc, Cambridge, MA

Research Assistant, Advisor: Ying Nian Wu, Professor at Department of Statistics, UCLA

Jun 2018 – Mar 2019
Co-advisors: Wongun Choi, Chris Baker, Yibiao Zhao, research scientists at ISEE, an MIT autonomous driving start-up

- Proposed, implemented, and trained a novel Multi-Agent Convolutional Tensor Fusion model to reason about social interactions among varying numbers of agents & between agents and scene contexts, which retains the spatial structure of agents and the scene;
- > Implemented a CGAN to learn a joint distribution of multi-agent trajectories based on the proposed Fusion model;
- Conducted ablative studies on Stanford Drone and NGSIM datasets, outperformed *Social GAN*;
- Paralleled the Multi-Agent code on GPU; presented the paper at CVPR 2019; published the source code on Github;
- Participated in proposing another Inverse Optimal Control (IOC) based prediction approach, which learns non-Markovian cost functions defined over entire trajectories; participated in extending weighted feature-based cost functions to neural network augmented ones; completed a manuscript submitted to *ArXiv*.

Music Generation with Hierarchical Deep Reinforcement Learning, EECS, Peking University Computer Vision and Digital Art (CVDA) research group Beijing, China Jun 2017 - Jun 2018

Research Assistant, Advisor: Yizhou Wang, Professor at School of Electronics Engineering and Computer Science, PKU

- Proposed novel hierarchical LSTM architectures and corresponding RL algorithms to learn long-range consistency for sequence modeling, and to generate music by combining learned patterns from dataset with structured domain knowledge;
- > Designed the architecture as follows: a higher level learns correlations across measures and patterns for chord progressions, and a lower level learns a distribution over the notes to generate within a measure; the two operate at different clock rates while communicating with each other;
- > Generated samples via supervised learning: https://github.com/HAPPIER-Music/; completed a manuscript.

OPEN SOURCE PROJECTS

- ➤ Proficient in C++, C, python, TensorFlow, PyTorch.
- For Chinese Chess Program Developing and AI Designing with Novel Heuristic α-β Tree Search: Developed a Chinese Chess game program from scratch; Proposed and implemented a novel approach of α-β tree search based on heuristic methods; Proved its superiority over conventional α-β tree search w.r.t. time complexity and winning rate; 3k+ lines in C++.
- Automatic Back-Propagation: Implemented automatic BP algorithm for any given DAG and Neural Nets from scratch, which calculated the backward path automatically, given any forward path.

AWARDS AND HONORS

- Merit Student (top 10%), Peking University, Nov 2017;
- ➤ 5 of 318, Botzone AI contest (Reversi), Peking University;
- Meritorious Winner (top 15%), Mathematical Contest in Modeling (MCM), Feb 2018;
- 3rd Prize, ACM Programming Contest in Peking University, May 2017