1) The object function that must be solved for linear regression in one-dimension is the following:

$$L = \min_{w_{cap}, b_{Cap}} E\left[\left(w_{cap}. X + b_{cap} - Y \right)^{2} \right]$$

But, since, $Y = w \cdot x + b + \mathcal{E}$, we can rewrite the equation as:

$$L = \min_{w_{cap}, b_{Cap}} E\left[\left(w_{cap} - w \right) X + \left(b_{cap} - b \right) - \varepsilon \right]^{2}$$

The solutions to this equation can be solved in the usual way by differentiating the function w.r.t the parameter and equating them to 0.

$$\frac{\partial L}{\partial b_{cap}} = E[2((w_{cap} - w)X + (b_{cap} - b) - Y)] = 0$$

$$\frac{\partial L}{\partial w_{cap}} = E[2((w_{cap} - w)X + (b_{cap} - b) - Y).X)] = 0$$

Solving for the 2 equations, we get, $E[w_{cap}] = w$ and $E[b_{cap}] = b$

For calculating variance,

We know that:

$$w_{cap} = [X^T X]^{-1} X^T Y$$

where X is the augmented variable vector of length 2.

For truly linear model data we can write this as,

$$W_{cap} = [X^T X]^{-1} X^T (XW + \varepsilon)$$

=> $W_{cap} = W + [X^T X]^{-1} X^T \varepsilon$

where W is the augmented linear coefficient vector of length 2.

This can be interpreted in the following way: w_{cap} recovers the true value w with an error described by the right-hand term. We can express this relation as:

$$W_{cap} \sim W + N(0, ([X^T X]^{-1} X^T)([X^T X]^{-1} X^T)^T \sigma^2)$$

=> $W_{cap} \sim W + N(0, [X^T X]^{-1} \sigma^2)$

Since,

$$(X^{T}X)^{-1} = \frac{\sum x_{i}^{2}}{m \sum (x_{i} - E[x])^{2}} \frac{-\sum x_{i}}{m \sum (x_{i} - E[x])^{2}} \frac{\sum x_{i}}{m \sum (x_{i} - E[x])^{2}} \frac{1}{\sum (x_{i} - E[x])^{2}}$$

Also since, the var of the coefficient vector is equal to the var of the normal noise described in $W_{cap} \sim W + N(0, [X^T X]^{-1} \sigma^2)$

$$var\big(W_{Cap}\big) = \frac{var(b_{cap})}{cov(b_{cap}, w_{cap})} \frac{cov(b_{cap}, w_{cap})}{var(w_{cap})} = \sigma^2(X^TX)^{-1}$$

Using this relation, we get,

$$var(b_{cap}) = \frac{\sigma^2 \sum x_i^2}{m \sum (x_i - E[x])^2}$$
$$var(w_{cap}) = \frac{\sigma^2}{m \sum (x_i - E[x])^2}$$

2) If the variance and mean of X are known from an underlying distribution, we can rewrite the above equations as:

$$var(w_{cap}) = \frac{\sigma^2}{m \ var(x)}$$
$$var(b_{cap}) = \frac{\sigma^2 E[x^2]}{m \ var(x)}$$

3) If the data is re-centered using $x_i = x_i - \mu$,

The var(x')=var(x), therefore, $var(w_{cap})$ or the error in w_{cap} remains the same as before it was recentered.

However,

$$E[x'^{2}] = E[(x - \mu)^{2}]$$

$$= E[x^{2} + \mu^{2} - 2x\mu]$$

$$= E[x^{2}] - 2E[x]\mu + \mu^{2}$$

$$= [x^{2}] - \mu^{2}$$

$$< E[x^{2}]$$

Therefore, since the numerator of $var(b_{cap})$ reduces keeping everything else constant, the value of $var(b_{cap})$ or the error in b_{cap} reduces.

4) Please find the code in main.py.

Yes, the observed results agree with what was mentioned earlier. After re-centering, the error in w_{cap} remains the same, but the error in b_{cap} reduces from ~0.015 to ~0.00001.

- 5) There is no change in the slope, since the relative differences between the values of X or Y remain the same. Only the absolute value of X changes. Therefore, there is only a change in the intercept of our regression line.
- 6) We know that that,

$$\sum \rightarrow m E[X^T X]$$

On augmenting the feature set from 1 to 2 dimensions, X=[1 x].

We can then rewrite the above as:

$$\sum \to m E\begin{bmatrix} 1 \\ \chi \end{bmatrix} [1 \ x]]$$

$$\sum \to m E\begin{bmatrix} 1 & x \\ x & x^2 \end{bmatrix}$$

$$\sum \to m \begin{bmatrix} 1 & E[x] \\ E[x] & E[x^2] \end{bmatrix}$$

On re-centering the data, the above matrix changes to:

$$\Sigma \to m \begin{bmatrix} 1 & 0 \\ 0 & E[(x-\mu)^2] \end{bmatrix}$$

The eigenvalues of this matrix are E[(x- μ)²] and 1. The value of K(Σ) given by $K(\Sigma) = \frac{\text{Largest eigenvalue of } \Sigma}{\text{Smallest eigenvalue of } \Sigma}$

$$K(\Sigma) = \frac{\text{Largest eigenvalue of } \Sigma}{\text{Smallest eigenvalue of } \Sigma}$$

Is always lower than the value we get using the non-centered data.