

The axisymmetric magnetic field calculation program package magfield2

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Using this program package one can compute magnetic field and vector potential of an axially symmetric coil system, with coils having rectangular shape cross-section in the $z - r$ cylindrical symmetry (meridian) plane. The coils are obtained by rotation of the rectangles around the z -axis, the current in the coils has azimuthal direction, perpendicularly to the $z - r$ meridian plane.

The user has 2 completely different methods for the magnetic field calculation. One method uses elliptic integrals; then one can compute the field everywhere, but the computation time is large. For fast trajectory calculation it is usually better to use the method with Legendre polynomial expansion: in this case the calculation is much faster; nevertheless this method is not appropriate everywhere (see below the details).

Coil parameters (geometry and current)

Before starting the calculation, the user has to define the geometry and current parameters of the coils. For this purpose, the user has to make a coil parameter data (ASCII) file, with the following structure: the first line of the data file contains the integer number of the coils (in the program the variable name Ncoil is used for this number). Then there are Ncoil number of lines, each line contains the parameters of a coil (these are real numbers):

zmid **rin** **thick** **length** **current**

zmid: middle z value of the coil (m),

rin: inner radius of the coil (m),

thick: radial thickness of the coil (m),

length: length of the coil in the z direction (m),

current: total current of the coil (Amper); total current = number of windings \times current in the coil wire.

The z_{min} , z_{max} , r_{min} , r_{max} edge parameters of the coil rectangle are:
 $z_{min} = z_{mid} - \text{length}/2$, $z_{max} = z_{mid} + \text{length}/2$, $r_{min} = r_{in}$, $r_{max} = r_{in} + \text{thick}$.

When some of the field computation functions (`magfield2` or `magfield2_elliptic`) is for the first time called, the function `coilread` is called from inside these functions. Function `coilread` reads the coil parameters from the abovementioned data file (the name of the data file is defined by the user; see below at the sections `magfield2` and `magfield2_elliptic`). Then this function writes the number of the coils into the global integer `Ncoil`, and the coil parameters into the global double array `coil[Ncoilmax+1][5]`. The integer number `Ncoilmax` should be defined by the user with a `#define` command, in the beginning of the program which uses the package `magfield2` (for example: `#define Ncoilmax 100`). The number `Ncoilmax` should be not smaller than the number of the coils `Ncoil`: otherwise one gets an error message, and the program execution stops.

`magfield2_elliptic`: field calculation by elliptic integrals

In order to compute the magnetic field by elliptic integrals, the user has to call the function `magfield2_elliptic` in the following way:

```
magfield2_elliptic(z,r,inputcoil,m,&A,&Bz,&Br);
```

The input and output parameters here are the following:

`z,r`: cylindrical coordinates of the field point in meter (double real numbers);

`inputcoil`: this is a `char*` string constant, it contains the name of the coil parameter data file. One can define this name in the main calling program as: `strcpy(inputcoil,"inputcoil.dat");`. Of course, one can use arbitrary file name.

`m`: this integer is necessary for numerical integration. With $m=20$ one can get usually very good numerical accuracy, if the radial dimension (thickness) of the coils is not too large.

`A,Bz,Br`: these double real numbers are the results of the calculation. `A` denotes the vector potential in Teslameter (with axially symmetric coils and azimuthal current the vector potential has only azimuthal component); `Bz` and `Br` are the cylindrical coordinates of the magnetic field in Tesla.

The calculation method by the elliptic integrals has the advantage that it works everywhere, for arbitrary field point (even inside the windings of

the coils). Unfortunately, it has also a disadvantage: it is rather slow. Using the first and second complete elliptic integrals one needs for the field calculation a two-dimensional numerical integration for each coil (along the axial and the radial directions). In our method we use also the third complete elliptic integral, which has the advantage that the numerical integration is only in the radial direction necessary; this makes the computation much faster. Nevertheless, even with this improvement the computation is about 1000 times slower than with the Legendre polynomial expansion.

magsource, magfield2: field calculation by Legendre polynomial expansion

The magnetic field calculation by Legendre polynomial expansion is much faster than with the elliptic integrals. In order to understand this method, let us introduce some definitions. Let us fix a point $(z_0, 0)$ on the z axis. It is possible to compute in this axis point the higher derivatives of the magnetic field with high accuracy. From these higher derivatives one can build some numbers B_n ($n = 0, 1, \dots, n_{maxmag}$), where B_0 is the magnetic field in the $(z_0, 0)$ point, B_1 is proportional to the first z -derivative of the field here, B_2 is proportional to the second z -derivative, etc. So all these B_n numbers are defined in the axis point $(z_0, 0)$. It is a special property of the axially symmetric coil system that the magnetic field in an arbitrary off-axis point, which is not far from the axis point $(z_0, 0)$, can be computed by using these numbers B_n . We call the axis point $(z_0, 0)$ source point, and the numbers B_n we call source coefficients; namely, the B_n numbers depend on the parameters (geometry and current) of the coils, which represent the source of the magnetic field.

Let us define the convergence radius ρ_c as the minimal distance of the source point from the coils. The z component of the magnetic field in the field point (z, r) can be computed by the following series:

$$B_z = \sum_{n=0}^{\infty} B_n * \left(\frac{\rho}{\rho_c}\right)^n P_n(u),$$

where ρ is the distance of the field point (z, r) from the source point $(z_0, 0)$, $u = (z - z_0)/\rho$, $P_n(u)$ is Legendre polynomial. The vector potential A and the radial field component B_r can be computed by similar expansions. This series has an important property: it is convergent only for $\rho < \rho_c$, i.e. only

for those field points, which are inside of the convergence circle, defined by the source point as centre and ρ_c as radius.

Let us assume that the user wants to make magnetic field calculation for z values between $z0min$ and $z0max$, using the above Legendre polynomial expansion method. Then the source points should be defined within this interval. The program uses the simplest configuration: it defines source points in equidistant distribution between $z0min$ and $z0max$, with $delz0$ distance between two neighbouring points. The user should define the number $delz0$, so that it is 2-3 times smaller than the minimal inner coil radius. Then the user defines the name of the coil parameter data file: `strcpy(inputcoil,"inputcoil.dat");` (where `inputcoil` is a `*char` string constant). In addition, the user has to define 2 integer numbers, `nmaxmag` and `Nspmagma`, by `#define` command. Here `nmaxmag` denotes the maximal index value n for the source coefficients B_n (`nmaxmag=300` is usually a good choice); `Nspmagma` should be defined so that it is not smaller than the number of source points `Nsp`, where $Nsp=(z0max-z0min)/delz0+1$.

Then the user calls the function `magsource`:

```
magsource(z0min,z0max,delz0,inputcoil);
```

This function reads first the coil parameter data file by calling function `coilread`, then it calculates the source points, it computes the source coefficients B_n ($n=0, \dots, nmaxmag$) in all source points, and finally it writes the source points and source coefficients into the data file `magsource.dat`. At this point the user can stop the program running, and continue the field calculation at a later time (since all information necessary for the Legendre polynomial method is saved in the data file `magsource.dat`).

In order to compute the magnetic field by using the Legendre polynomial expansion, the user has to call the function `magfield2` in the following way:

```
magfield2(z,r,inputcoil,n,&A,&Bz,&Br);
```

The input and output parameters here are the same as in the case of `magfield2_elliptic`. In order to make the Legendre polynomial expansion calculation, the program searches the best source point; this means: it calculates for all source points the ρ distance between field point (z, r) and source point, and it looks for the minimal ρ/ρ_c ratio. The program can use the Legendre series expansion, if this ratio is smaller than 1. If it is larger than 1, the series is not convergent. In this case the Legendre series method

is not possible to employ, and the program computes the magnetic field by the elliptic integrals, calling the function `magfield2_elliptic`. This is the reason why the user has to give the coil parameter file name `inputcoil` and the integration number `n` to the function `magfield2`: if the Legendre series method is available for the computation, the program does not use `inputcoil` and `n`, since in this case only the source points and source coefficients from the data file `magsource.dat` are employed.

An example for the main calling program is the following:

```
#include <stdio.h>
#include <stdlib.h>
#include <math.h>

#define Ncoilmax 100
#define nmaxmag 300
#define Nspmagmax 3000

void test(char *inputcoil);

#include "magfield2.c"

main()
{
    double z0min,z0max,delz0;
    char inputcoil[100];

    z0min=-0.5;
    z0max=2.5;
    delz0=0.02;
    strcpy(inputcoil,"inputcoil.dat");
    magsource(z0min,z0max,delz0,inputcoil);
    //
```

```

    test(inputcoil);
return 0;
}

```

```

////////////////////////////////////

```

```

void test(char *inputcoil)
{
    double z,r,A,Bz,Br,Aell,Bzell,Brell,errA,errBz,errBr;
    int i,m;
    m=20;

    z=0.;
    r=0.02;
    magfield2(z,r,inputcoil,m,&A,&Bz,&Br);
    printf("A,Bz,Br= %19.11e %19.11e %19.11e \n \n",A,Bz,Br);
    magfield2_elliptic(z,r,inputcoil,m,&A,&Bz,&Br);
    printf("A,Bz,Br= %19.11e %19.11e %19.11e \n",A,Bz,Br);
    r=0.;
    for(i=0;i<=20;i++)
    {
        z=i*0.1;
        magfield2(z,r,inputcoil,m,&A,&Bz,&Br);
        printf("z,r,A,Bz,Br= %12.5f %12.5f %17.9e %17.9e %17.9e
            \t \n",z,r,A,Bz,Br);
        magfield2_elliptic(z,r,inputcoil,m,&A,&Bz,&Br);
        printf("A,Bz,Br(elliptic)= %17.9e %17.9e %17.9e \t
            \n",A,Bz,Br);
    }
    //
    return;
}

```