System Flow and Implementation Details

Project: SEE (Visual Assistant) — Flutter Mobile Application
Scope: Code-level execution paths, data flows, and implementation mechanics
Codebase analysed: `lib/` (35 Dart files), `android/.../MainActivity.kt`

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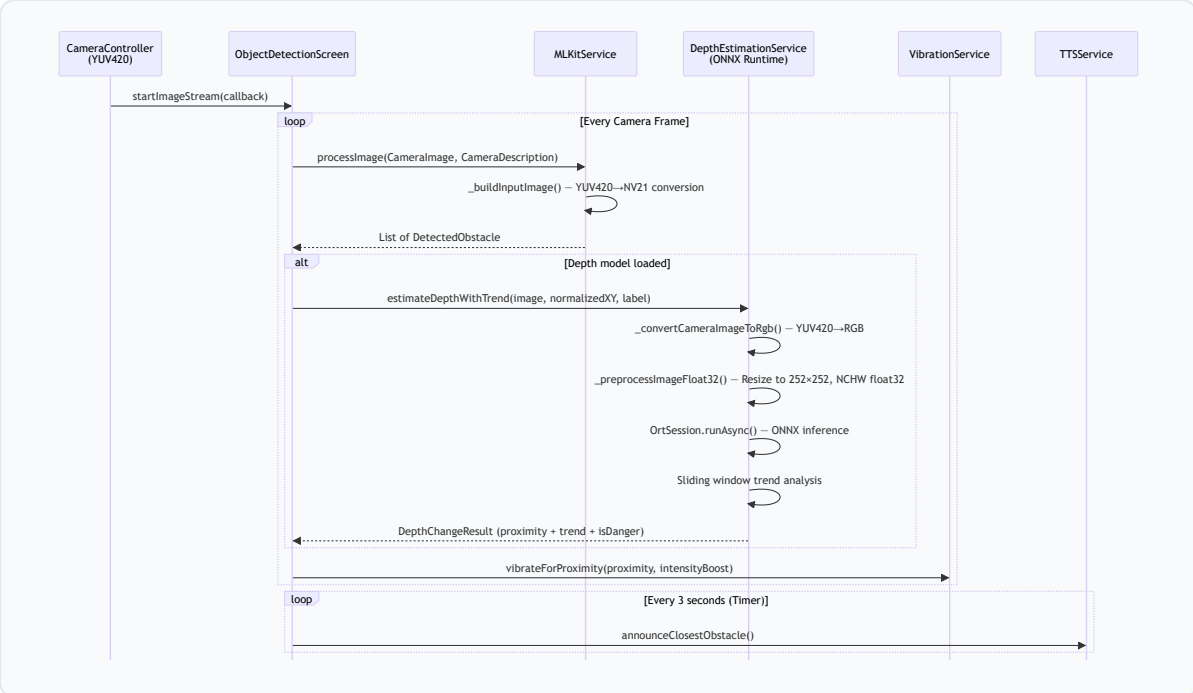
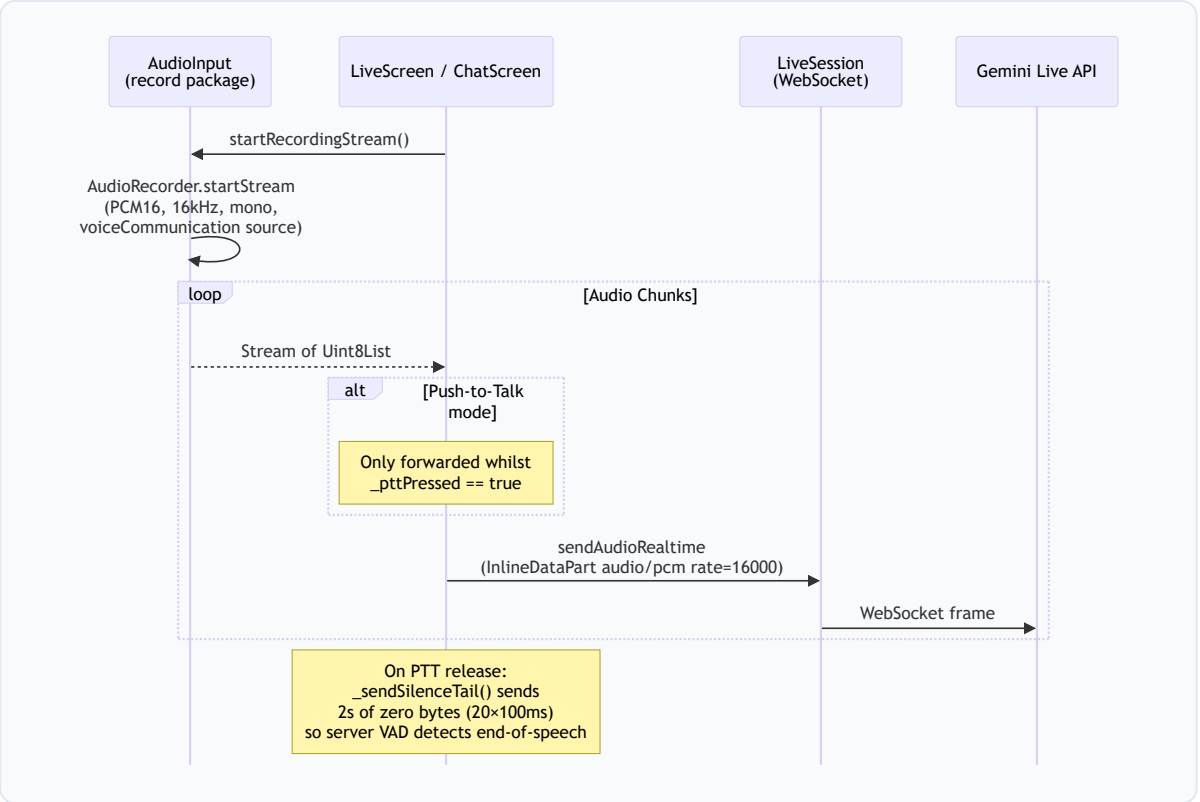
1. System Flowcharts

1.1 Sensor & Hardware Integration — Camera Frame Pipeline

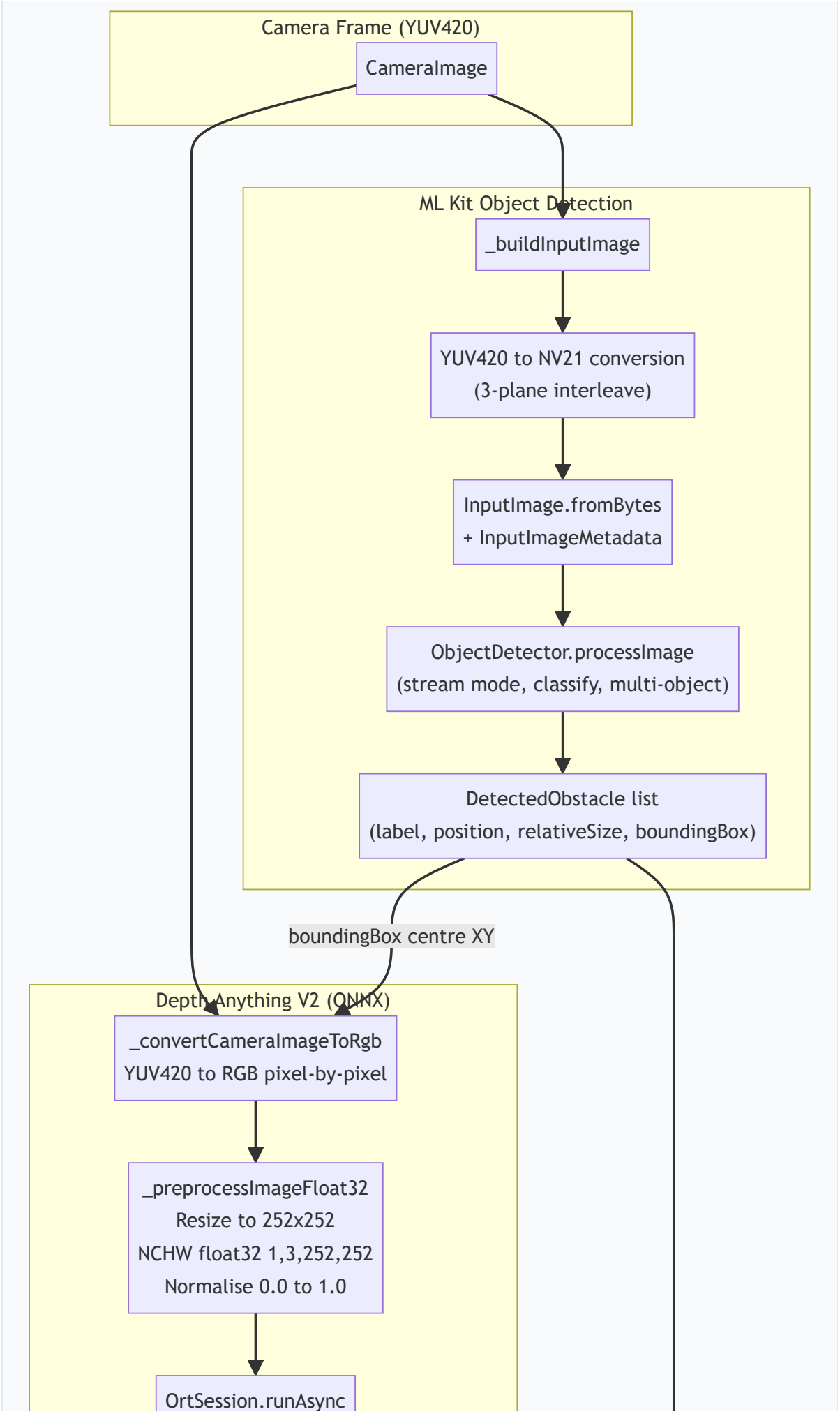
The camera pipeline has two distinct consumers: **ML Kit Object Detection** (processed on every frame) and the **Gemini Live API** (sampled at 1 fps and converted to JPEG via a native platform channel).

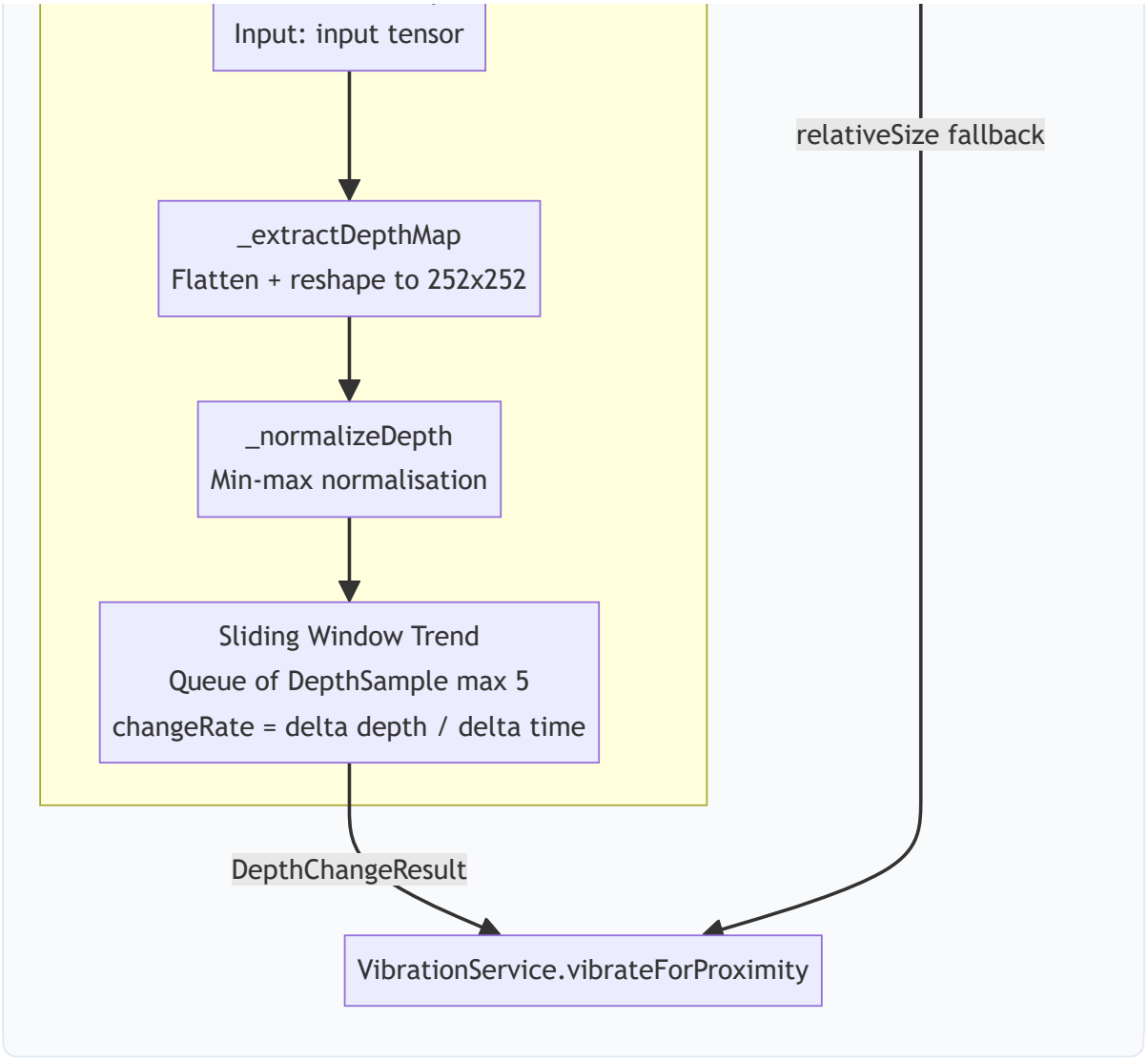


1.2 Microphone Audio Capture Pipeline (16 kHz PCM with Hardware AEC)

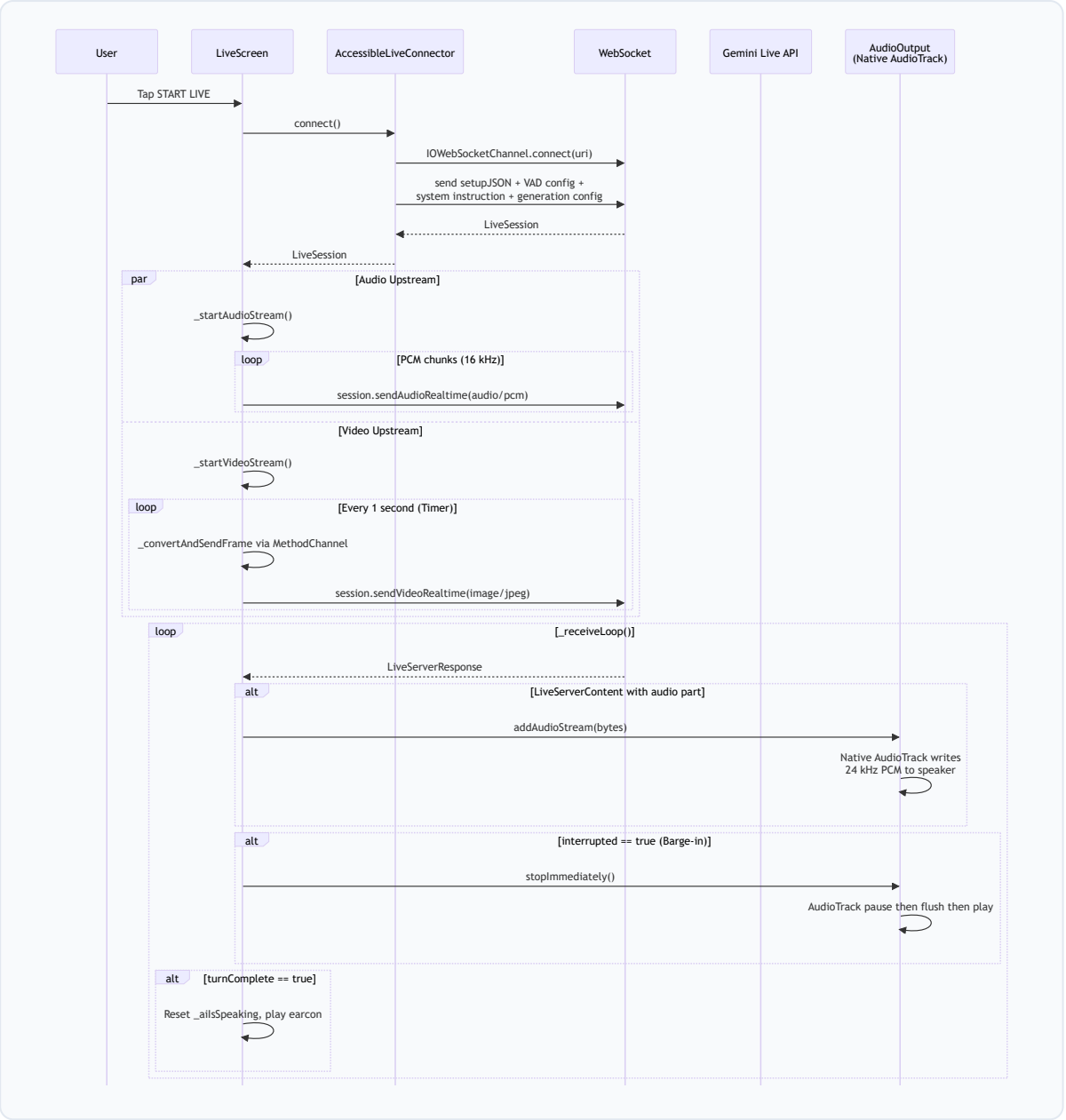


1.3 On-Device ML Inference — Depth Estimation & Object Detection


Camera Frame (YUV420)
CameraImage
ML Kit Object Detection
_buildInputImage
YUV420 to NV21 conversion
(3-plane interleave)
InputImage.fromBytes
+ InputImageMetadata
ObjectDetector.processImage
(stream mode, classify, multi-object)
DetectedObstacle list
(label, position, relativeSize, boundingBox)
boundingBox centre XY
Depth Anything V2 (ONNX)
_convertCameraImageToRgb
YUV420 to RGB pixel-by-pixel
_preprocessImageFloat32
Resize to 252x252
NCHW float32 1,3,252,252
Normalise 0.0 to 1.0
OrtSession.runAsync



1.4 Real-Time Bidirectional Streaming — Gemini Live API

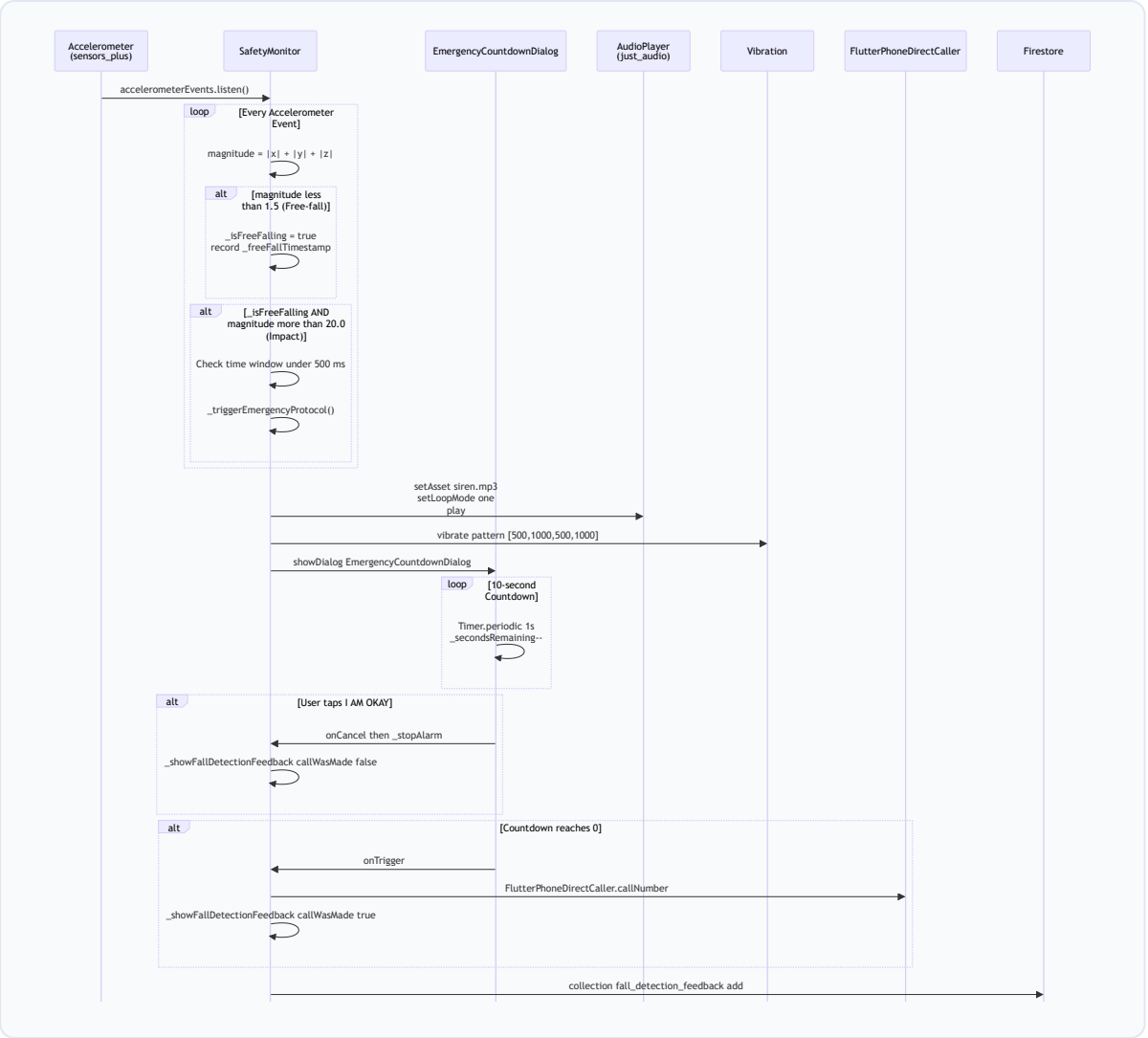


Barge-In Handling Detail

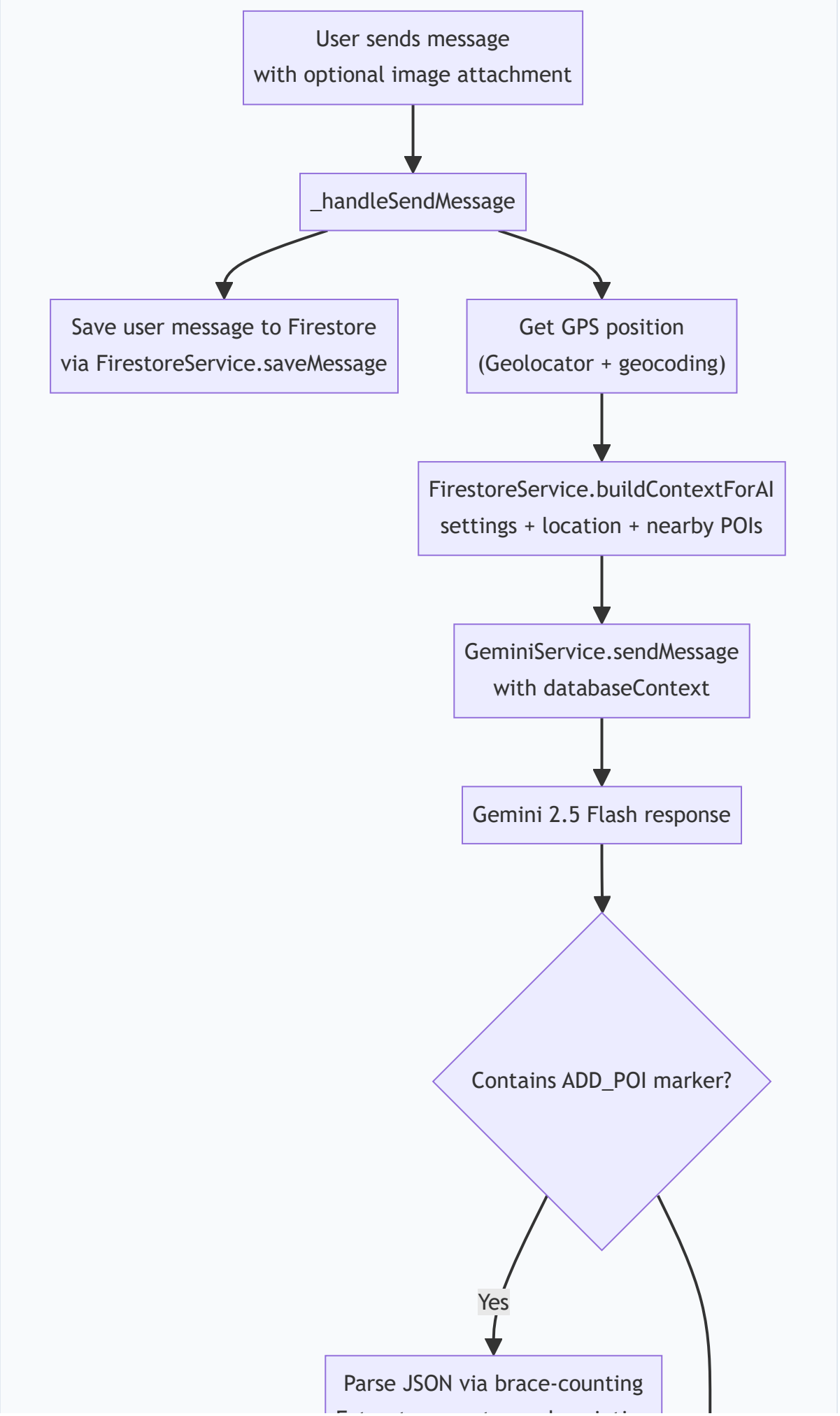
When the server signals `msg.interrupted == true`:

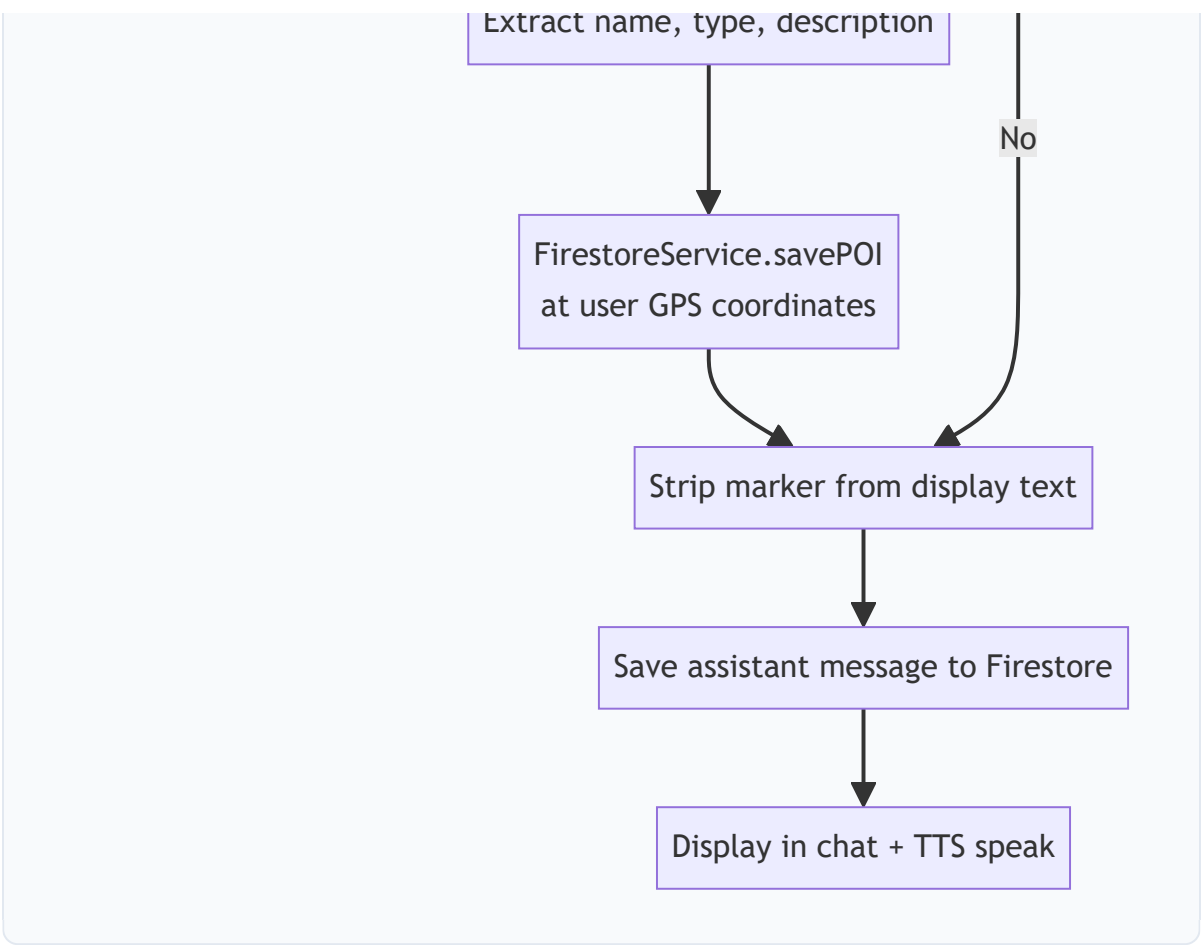
1. `AudioOutput.stopImmediately()` is called, which invokes the native `flush` method.
2. The native Kotlin code executes `audioTrack.pause()` → `audioTrack.flush()` → `audioTrack.play()`, instantly clearing the playback buffer.
3. The `_aiIsSpeaking` flag is reset and `_isFirstAudioChunk` is set to `true` so the next response triggers a fresh earcon.

1.5 Background Fall Detection and SOS Sequence



1.6 Chat Message Flow with POI Extraction


User sends message
with optional image attachment
_handleSendMessage
Save user message to Firestore
via FirestoreService.saveMessage
Get GPS position
(Geolocator + geocoding)
FirestoreService.buildContextForAI
settings + location + nearby POIs
GeminiService.sendMessage
with databaseContext
Gemini 2.5 Flash response
Contains ADD_POI marker?
Yes
Parse JSON via brace-counting


Extract name, type, description
No
FirestoreService.savePOI
at user GPS coordinates
Strip marker from display text
Save assistant message to Firestore
Display in chat + TTS speak

2. Implementation Details

2.1 State Management

The application uses **Flutter's built-in `StatefulWidget` / `setState` pattern** exclusively. There is no provider, bloc, or riverpod dependency. State is managed as follows:

Domain	State Container	Key Variables
Theme	`ThemeNotifier` (singleton `ChangeNotifier`)	`_themeMode` (light/dark)
Fall Detection	`_SafetyMonitorState`	`_isFreeFalling`, `_freeFallTimestamp`, `_isAlertActive`, `_emergencyPhone`
Object Detection	`_ObjectDetectionScreenState`	`_obstacles`, `_isDetecting`, `_depthModelLoaded`, `_streamErrorCount`
Live Session	`_LiveScreenState`	`_isConnected`, `_isStreamingAudio/Video`, `_aiIsSpeaking`, `_pushToTalkMode`, `_pttPressed`
Chat	`_ChatScreenState`	`_messages` (list), `_isLiveMode`, `_isRecording`, `_isAiSpeaking`, `_pendingImageBytes`
Depth Estimation	`DepthEstimationService`	`_depthHistory` (Map of Queue), `_cachedResult`, `_isProcessing`
ML Kit	`MLKitService`	`_isProcessing` (frame-level mutex), `_frameCount`
TTS	`TTSService` (singleton)	`_isReady`, `_isSpeaking`, `_lastSpoken`, `_lastSpokenTime`

High-frequency sensor streams (camera, accelerometer) are throttled explicitly:

- **Depth estimation:** Minimum 333 ms between inferences (max ~3 FPS) via `_minInterval`.
- **Vibration:** 300 ms throttle via `_lastVibration` timestamp comparison.

- **TTS obstacle announcements:** 3-second `Timer.periodic` in `ObjectDetectionScreen`.
- **Video frames to Gemini:** 1-second `Timer.periodic` in `LiveScreen`.
- **Location awareness POI announcements:** 5-second cooldown in `LocationAwarenessService`.

2.2 Data Structures & Transformation

YUV420 → NV21 Conversion (Dart, for ML Kit)

Located in `ml_kit_service.dart`:

```
Uint8List _convertYUV420ToNV21(CameraImage image) {
  final int ySize = width * height;
  final int uvSize = (width * height) ~/ 2;
  final Uint8List nv21 = Uint8List(ySize + uvSize);

  // Copy Y plane row-by-row (respecting bytesPerRow stride)
  for (int y = 0; y < height; y++) {
    for (int x = 0; x < width; x++) {
      nv21[y * width + x] = yPlane.bytes[y * yPlane.bytesPerRow + x];
    }
  }

  // Interleave V and U planes (NV21 = VUVU ordering)
  int uvIndex = ySize;
  for (int y = 0; y < uvHeight; y++) {
    for (int x = 0; x < uvWidth; x++) {
      nv21[uvIndex++] = vPlane.bytes[vIdx]; // V first
      nv21[uvIndex++] = uPlane.bytes[uIdx]; // then U
    }
  }
  return nv21;
}
```

YUV420 → JPEG Conversion (Native Kotlin, for Gemini video stream)

Located in `MainActivity.kt`. Uses Android's `YuvImage.compressToJpeg()` after constructing an NV21 byte array from the three YUV planes received via `MethodChannel`. Quality is set to 40 for bandwidth efficiency.

YUV420 → RGB → Float32 NCHW (Dart, for ONNX Depth)

Located in `depth_estimation_service.dart`:

```
Float32List _preprocessImageFloat32(Uint8List rgbBytes, int w, int h) {
  final inputData = Float32List(1 * 3 * 252 * 252);

  for (int c = 0; c < 3; c++) {       // Channel: R, G, B
    for (int y = 0; y < 252; y++) {
      for (int x = 0; x < 252; x++) {
        // Nearest-neighbour resize
        final srcX = (x * w / 252).round().clamp(0, w - 1);
        final srcY = (y * h / 252).round().clamp(0, h - 1);
        // NCHW layout: all channel-c values contiguous
        inputData[(c*252*252) + (y*252) + x] =
            rgbBytes[(srcY*w + srcX)*3 + c] / 255.0;
      }
    }
  }
  return inputData;
}
```

Temporal Depth Trend — Sliding Window

Located in `depth_estimation_service.dart`:

- Per-object label `Queue<DepthSample>` with a maximum of **5 samples**.
- Trend is calculated as `changeRate = (currentDepth - oldestSample.normalizedDepth) / timeDelta`.
- Thresholds: `>0.15/s` → `approaching_fast`; `>0.05/s` → `approaching`; `←0.15/s` → `moving_away_fast`.
- `isDanger` flag: `isApproaching && currentDepth > 0.5`.
- Stale entries (>3 seconds since last sample) are cleaned up via `_cleanupOldHistory()`.

Firestore Data Models

```
conversations/{userId}/topics/{topicId}
    ├── createdAt: Timestamp
    ├── lastUpdated: Timestamp
    ├── firstMessage: String (truncated to 100 chars)
    ├── lastMessage: String
    └── messages/{messageId}
            ├── role: 'user' | 'assistant' | 'system'
            ├── content: String
            ├── timestamp: Timestamp
            ├── imageUrl: String?
            └── hasImage: bool

users/{fullName}
    ├── profile: { fullName, email, phone, emergencyContactName,
    │              emergencyContactPhone, uid, createdAt, lastActive }
    └── settings: { visualImpairment, hearingImpairment,
                    mobilityImpairment, preferredVoice,
                    speechRate, highContrastMode }

pois/{poiName}
    ├── name, type, description, safetyNotes
    ├── location: { latitude, longitude, address }
    ├── addedBy: String
    └── createdAt: Timestamp

fall_detection_feedback/{docId}
    ├── userPhone, triggerCorrect, callCorrect
    ├── emergencyNumberDialed, timestamp, deviceTime, userId

traffic_feedback/{docId}
    ├── wasSuccessful: bool
    ├── timestamp, deviceTime
```

POI Extraction from Gemini Response

The chat screen parses Gemini responses for `ADD_POI` markers using **brace-counting** (not regex) to reliably extract nested JSON:

```
int depth = 0;
for (int i = jsonStart; i < displayResponse.length; i++) {
  if (displayResponse[i] == '{') depth++;
  if (displayResponse[i] == '}') depth--;
  if (depth == 0) { jsonEnd = i + 1; break; }
}
```

2.3 Error Handling & Edge Cases

Camera & Sensor Permissions

Scenario	Handling
Camera permission denied	Full-screen card with "Open Settings" button via `permission_handler.openAppSettings()`.
Location permission denied	`Geolocator.requestPermission()`; if permanently denied, TTS speaks a message and UI shows retry/settings dialog.
Location permission permanently denied	`AlertDialog` with "Open Settings" option.
Microphone permission denied	`AudioInput` throws `Exception('Microphone permission not granted')`.

Network & API Failures

Scenario	Handling
Gemini API error (chat mode)	Returns `"Error communicating with AI service"` — displayed as model message.
Live API WebSocket closed	`_receiveLoop()` detects 'Closed' and calls `_stopAll()` to tear down streams.
Custom VAD connect fails	Falls back to `_sdkFallbackConnect()` using standard Firebase AI SDK.
Places API (New) HTTP error	Falls back to `_searchPlacesOldApi()` using legacy Nearby Search endpoint.
Location timeout	15-second timeout; falls back to `Geolocator.getLastKnownPosition()`.

ML Inference Failures

Scenario	Handling
Stream mode repeated failures	After **100** consecutive empty results, switches to file-based detection with 2-second Timer.
ONNX model load failure	Returns `false`; object detection continues without depth data.
Depth estimation busy	Returns `_cachedResult` when within 333 ms throttle window.

TTS Engine Binding (Xiaomi/MIUI)

`TTSService.initialize()` retries configuration up to **5 times** with increasing delays (1s, 2s, 3s, 4s, 5s). If all attempts fail, `_isReady` is still set to `true` so that `speak()` can retry at call time.

App Lifecycle

Both `LiveScreen` and `ObjectDetectionScreen` implement `WidgetsBindingObserver`:

- **`inactive`**: Calls `_stopAll()` / cancels timers and disposes camera.
- **`resumed`**: Re-initialises the camera.

2.4 Package Implementation

`record` (Audio Capture)

Configured in `audio_input.dart`:

```
final stream = await _recorder.startStream(
  const RecordConfig(
    encoder: AudioEncoder.pcm16bits,
    numChannels: 1,
    sampleRate: 16000,
    androidConfig: AndroidRecordConfig(
      audioSource: AndroidAudioSource.voiceCommunication,
      audioManagerMode: AudioManagerMode.modeInCommunication,
      muteAudio: false,
    ),
  ),
);
```

- `voiceCommunication` enables Android's built-in `AcousticEchoCanceler`, `NoiseSuppressor`, and `AutomaticGainControl`.
- `modeInCommunication` optimises the audio pipeline for two-way communication.
- `muteAudio: false` ensures AI speech continues to play through the speaker.

`just_audio` (Siren Playback)

Used in `SafetyMonitor` for the emergency alarm:

```
await _audioPlayer.setAsset('assets/audio/siren.mp3');
await _audioPlayer.setLoopMode(LoopMode.one);
_audioPlayer.play();
```

The siren loops until `_stopAlarm()` calls `_audioPlayer.stop()`, and `Vibration.cancel()` stops the vibration pattern.

Native `AudioTrack` (AI Speech Playback)

The `AudioOutput` class communicates with native Kotlin via `MethodChannel('audio_output_channel')`. The native implementation in

`MainActivity.kt`:

1. Sets `AudioManager.MODE_IN_COMMUNICATION` globally.
2. Creates an `AudioTrack` with `USAGE_VOICE_COMMUNICATION` and `CONTENT_TYPE_SPEECH` at **24 kHz** (Gemini's output sample rate).
3. Attaches `AcousticEchoCanceler` and `NoiseSuppressor` to the audio session.
4. Forces routing to the **built-in loudspeaker** (not earpiece) using `setCommunicationDevice()` on Android 12+ or `isSpeakerphoneOn` on older devices.
5. Maximises `STREAM_VOICE_CALL` volume for blind users.

The `flush` method (for barge-in) executes `audioTrack.pause()` → `audioTrack.flush()` → `audioTrack.play()`.

Firebase AI SDK (`firebase_ai`)

- **Chat mode:** `FirebaseAI.vertexAI().generativeModel(model: 'gemini-2.5-flash')` — standard `generateContent()` with `Content.multi([TextPart, InlineDataPart])`.
- **Live mode:** `FirebaseAI.vertexAI(location: 'us-central1').liveGenerativeModel(model: 'gemini-live-2.5-flash-native-audio')` with `ResponseModalities.audio` and `SpeechConfig(voiceName: 'Kore')`.
- **Custom VAD:** `AccessibleLiveConnector` bypasses the SDK's `connect()` by constructing the WebSocket URI manually and sending a custom setup JSON with `realtime_input_config.automatic_activity_detection`.

`flutter_tts` (Text-to-Speech)

Implemented as a **singleton** (`TTSService._instance`) with:

- Language: `en-US`, speech rate: `0.5`, volume: `1.0`, pitch: `1.0`.
- Duplicate suppression: same message within 2 seconds is skipped (unless `force: true`).
- `awaitSpeakCompletion(true)` enables synchronous speech in `speak()`.

`onnxruntime` (Depth Estimation)

- Model: `assets/models/depth_anything_v2.onnx` (Depth Anything V2, ViT-S variant).
- Input: `Float32List` tensor shaped `[1, 3, 252, 252]` (NCHW). 252 is a multiple of the ViT patch size (14).
- Inference: `OrtSession.fromBuffer(bytes, options)` → `session.runAsync(runOptions, {'input': tensor})`.
- Output: Flattened depth map reshaped to `252×252`, normalised via min-max to `[0.0, 1.0]`.

`google_mlkit_object_detection`

- Configured in **stream mode** with `classifyObjects: true` and `multipleObjects: true`.
- Object position is categorised into `left` / `center` / `right` based on `centerX` relative to image width thirds.
- Relative size = `objectArea / imageArea`, used for proximity estimation when depth is unavailable.
- `isClose` threshold: `relativeSize > 0.10`; `isVeryClose`: `> 0.25`.

`vibration` + `HapticFeedback` (Haptic Feedback)

`VibrationService` attempts the `vibration` plugin first; if it fails, it sets `_useFlutterHaptics = true` and falls back to Flutter's `HapticFeedback` API. Three intensity levels:

Effective Proximity	Method	Pattern
> 0.10 (very close)	`_vibrateHeavy()`	`heavyImpact` × 2 (100 ms gap)
> 0.05 (close)	`_vibrateMedium()`	`mediumImpact` × 1
> 0.01 (detected)	`_vibrateLight()`	`lightImpact` × 1

Approaching objects receive an `intensityBoost` of `0.2` added to the raw proximity value, clamped to `[0.0, 1.0]`.

2.5 Earcon System (Accessibility Cues)

The `LiveScreen` implements non-verbal audio cues for blind users:

Event	Earcon	Implementation
AI starts listening	`_playListeningEarcon()`	`HapticFeedback.lightImpact()` + `SystemSound.play(SystemSoundType.click)`
User releases PTT	`_playProcessingEarcon()`	`HapticFeedback.mediumImpact()` × 2 (100 ms apart)
AI starts responding	`_playResponseEarcon()`	`HapticFeedback.heavyImpact()` + `SystemSound.play(SystemSoundType.click)`

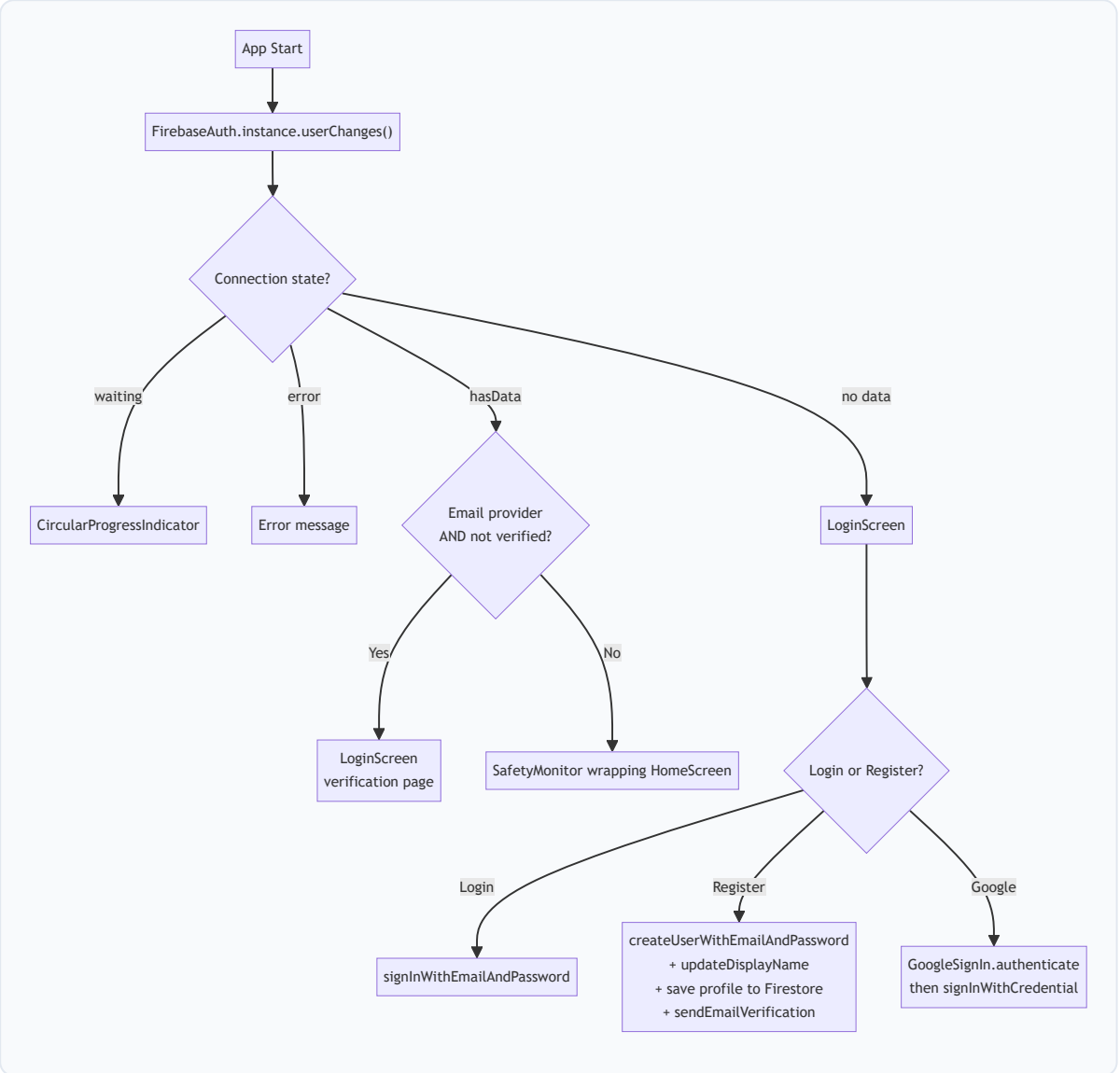
2.6 Traffic Light Monitoring

The `LiveScreen` includes a traffic light monitoring mode that:

1. Sends an initial text prompt asking Gemini to identify the pedestrian crossing signal colour.

2. Re-prompts every **5 seconds** via `Timer.periodic`, instructing Gemini to only speak if the colour has changed.
3. On stop, collects user feedback (was it successful?) and uploads to `Firestore.collection('traffic_feedback')`.

2.7 Authentication Flow



2.8 Navigation & Location Awareness

- **Route calculation:** `NavigationService.getRoute()` calls the Google Directions API (walking mode) and parses steps into `NavigationStep` objects.
- **Live tracking:** `Geolocator.getPositionStream(distanceFilter: 5)` updates every 5 metres. `_checkArrivalAtStep()` advances to the next step when within **10 metres** of the current step's end point.
- **Explore mode:** `LocationAwarenessService.startExploring()` tracks position with a 10-metre distance filter. On each update (throttled to 5-second intervals), it calls the Places API (New) `searchNearby` endpoint within a 100-metre radius. New POIs are

announced via TTS, and previously announced names are stored in a `Set<String>` (capped at 50 entries).

Report generated from codebase analysis on 26 February 2026.