University of Technology, Graz

Master Thesis

Differential cryptanalysis with SAT solvers

Author: Lukas Prokop Supervisor: Maria Eichlseder Florian Mendel

A thesis submitted in fulfillment of the requirements for the master's degree in Computer Science

at the

Institute of Applied Information Processing and Communications

August 19, 2016





Lukas Prokop, BSc BSc

Differential cryptanalysis with SAT solvers

MASTER'S THESIS

to achieve the university degree of Master of Science

Master's degree programme: Computer Science

submitted to

Graz University of Technology

Supervisor

Dipl.-Ing. Dr.techn., Florian Mendel

Institute of Applied Information Processing and Communications

Second advisor: Maria Eichlseder

AFFIDAVIT

I declare that I have authored this thesis independently, that I have not used other
than the declared sources/resources, and that I have explicitly indicated all ma-
terial which has been quoted either literally or by content from the sources used.
The text document uploaded to TUGRAZonline is identical to the present master's
thesis dissertation.

Date	Signature

ABSTRACT

Hash functions are ubiquitous in the modern information age. They provide preimage, second preimage and collision resistance which are needed in a wide range of applications.

In August 2006, Wang et al. showed efficient attacks against several hash function designs including MD4, MD5, HAVAL-128 and RIPEMD. With these results differential cryptanalysis has been shown useful to break collision resistance in hash functions. Over the years advanced attacks based on those differential approaches have been developed.

To find collisions like Wang et al., a cryptanalyst needs to specify a differential characteristic. Looking at the differential behavior of the underlying operations of the hash algorithm shows how differential values propagate in the algorithm. The goal is to find a differential characteristic whose differences cancel out in the output. Once such a differential characteristic was discovered, in a second step the actual values for those differences are defined yielding an actual hash collision.

Finding a differential characteristic can be a cumbersome and tedious task. Whereas propagation can be automated using dedicated tools, finding an initial differential characteristic is a difficult task as it can be specified with arbitrary levels of granularity.

SAT solvers inherently implement both tasks. They consecutively propagate values which narrow the search space. The probability to find a satisfiable assignment increases if the narrowed search space has many satisfiable assignments. And finally the assignment reveals initial values. On the other hand, SAT solvers have no notion of differential values and therefore problem encoding becomes an important topic.

In this thesis we look at differential characteristics representing hash collisions and encode them as SAT problem. A SAT solver tells us whether this characteristic represents a valid hash state. We implemented a framework generating CNFs for these purposes and improved our CNF design to solve MD4 testcases as well as much more difficult SHA-256 testcases. Our greatest achievement was finding a SHA-256 hash collision over 24 rounds. Finally we also provide a small CNF analysis library to compare encoded problems with others.

Keywords: hash function, differential cryptanalysis, differential characteristic, MD4, SHA-256, collision resistance, satisfiability, SAT solver

ACKNOWLEDGEMENTS

First of all I would like to thank my academic advisor for his continuous support during this project. Many hours of debugging were involved in writing this master thesis project, but thanks to Florian Mendel, this project came to a release with nice results. Also thanks for continuously reviewing this document.

I would also like to thank Maria Eichlseder for her great support. Her unique way to ask questions brought me back on track several times. Mate Soos supported me during my bachelor thesis with SAT related issues and his support continued with this master thesis in private conversations.

Also thanks to Roderick Bloem and Armin Biere who organized a meeting one year before submitting this work defining the main approaches involved in this thesis. Armin Biere released custom lingeling versions for us, which allowed us to influence the guessing strategy in lingeling. He also shared his thoughts about our testcases with us.

And finally I am grateful for the support by Martina, who also supported me during good and bad days with this thesis, and my parents which provided a prosperous environment to me to be able to stand where I am today.

Thank you. どもありがとうございました。

All source codes are available at lukas-prokop.at/proj/megosat and published under terms and conditions of Free/Libre Open Source Software. This document was printed with LualFTEX in the Linux Libertine typeface.

Contents

1	Intr	roduction	1
	1.1	Overview	1
	1.2	Thesis Outline	2
2	Has	h algorithms	3
	2.1	Preliminaries Redux	3
		2.1.1 Merkle-Damgård designs	4
		2.1.2 Padding and length extension attacks	4
		2.1.3 Example usage	5
	2.2	MD ₄	5
	2.3	SHA-256	7
3	Diff	erential cryptanalysis	11
	3.1	Motivation	11
	3.2	Fundamentals	12
	3.2 3.3	T-100	12 14
	5	Differential notation	
	3.3	Differential notation	14
4	3·3 3·4 3·5	Differential notation	14 16
4	3·3 3·4 3·5	Differential notation	14 16 16
4	3.3 3.4 3.5 Sati	Differential notation	14 16 16

viii *CONTENTS*

	4.2	The DIMACS de-facto standard	22
	4.3	Terminology	23
	4.4	Basic SAT solving techniques	24
		4.4.1 Boolean constraint propagation (BCP)	24
		4.4.2 Watched literals	24
		4.4.3 Remark	25
	4.5	SAT solvers in use	25
5	SAT	features	29
	5.1	SAT features and CNF analysis	30
	5.2	Related work	30
	5.3	Statistical features	31
	5.4	Suggested SAT features	32
	5.5	Evaluation efficiency	34
	5.6	CNF dataset	34
	5.7	The average SAT problem	35
	5.8	Benford's law in CNF files	36
6	Prol	plem encoding	37
	6.1	STP approach	37
	6.2	Two instances and its difference	38
	6.3	Approach with a differential description	39
	6.4	Influencing evaluation order	39
7	Resi	ults	41
	7.1	Evaluating SAT features	41
	7.2	Finding hash collisions	42
		7.2.1 Attacking MD ₄	42
		7.2.2 Improvements with differential description	43
		7.2.3 Modifying the guessing strategy	43

CC	ONTEI	NTS	ix					
	7.3	Related work	43					
	7.4	Conclusion	43					
	7.5	Contributions	43					
8	Sum	amary and Future Work	45					
	8.1	Summary of results	45					
	8.2	Future work	45					
Αŗ	pend	lices	47					
A	Illus	strations	49					
В	B Hardware setup							
C	Test	cases	53					
D	Runtimes retrieved							



Chapter 1

Introduction

1.1 Overview

Hash functions are used as cryptographic primitives in many applications and protocols. They take an arbitrary input message and provide a hash value. Input message and hash value are considered as byte strings in a particular encoding. The hash value is of fixed length and satisfies several properties which make it useful in a variety of applications.

In this thesis we will consider the hash algorithms MD4 and SHA-256. They use basic arithmetic functions like addition and bit-level functions such as XOR to transform an input to a hash value. We use a bit vector as input to this implementation and all operations applied to this bit vector will be represented as clauses of a SAT problem. Additionally we represent differential characteristics of hash collisions as SAT problem. If and only if satisfiability is given, the particular differential state is achievable using two different inputs leading to the same output. As far as SAT solvers return an actual model satisfying that state, we get an actual hash collision which can be verified and visualized. If the internal state of the hash algorithm is too large, the attack can be computationally simplified by modelling only a subset of steps of the hash algorithm or changing the modelled differential path.

Based on experience with these kind of problems with previous non-SAT-based tools we aim to apply best practices to a satisfiability setting. We will discuss which SAT techniques lead to best performance characteristics for our MD4 and SHA-256 testcases.

1.2 Thesis Outline

This thesis is organized as follows:

- **In Chapter 1** we briefly introduce basic subjects of this thesis. We explain our high-level goal involving hash functions and SAT solvers.
- In Chapter 2 we introduce the MD4 and SHA-256 hash functions. Certain design decisions imply certain properties which can be used in differential cryptanalysis. We discuss those decisions in this chapter after a formal definition of the function itself. Beginning with this chapter we develop a theoretical notion of our tools.
- **In Chapter** 3 we discuss approaches of differential cryptanalysis. We start off with work done by Wang, et al. and followingly introduce differential notation to simplify representation of differential states. This way we can easily dump hash collisions.
- **In Chapter** 4 we discuss SAT solving. We give a brief overview over used SAT solvers and discuss how we can speed up SAT solvers for cryptographic problems.
- **In Chapter** 5 we define SAT features which help us to classify SAT problems. This is a small subproject we did to look at properties of resulting DIMACS CNF files.
- **In Chapter 6** we discuss how we represent a problem (i.e. the hash function and a differential characteristic) as SAT problem. This ultimatively allows us to solve the problem using a SAT solver.
- **In Chapter 7** we show data as result of our work. Runtimes are the main part of this chapter, but also results of the SAT features project are presented.
- **In Chapter 8** we suggest future work based on our results.



Chapter 2

Hash algorithms

In this chapter we will define hash functions and their desired security properties. Followingly we look at SHA256 and MD4 as established hash functions. MD4 unlike SHA256 is practically broken but has a comparably small internal state. It therefore allows a good starting point to devise our attacks. In a next step we scaled up to SHA-256 which has an internal state size at least twice as large. In chapter 6 we will represent them with Boolean algebra to make it possible to reason about states in those hash functions using SAT solvers.

2.1 Preliminaries Redux

Definition 2.1 (Hash function)

A *hash function* is a mapping $h: X \to Y$ with $X = \{0,1\}^*$ and $Y = \{0,1\}^n$ for some fixed $n \in \mathbb{N}_{\geq 1}$.

- Let $x \in X$, then h(x) is called hash value of x.
- Let $h(x) = y \in Y$, then x is called *preimage of y*.

Hash functions are considered as cryptographic primitives used as building blocks in cryptographic protocols. A hash function has to satisfy the following security requirements:

Definition 2.2 (Preimage resistance)

Given $y \in Y$, a hash function h is *preimage resistant* iff it is computationally infeasible to find $x \in X$ such that h(x) = y.

Definition 2.3 (Second-preimage resistance)

Given $x \in X$, a hash function h is second-preimage resistant iff it is computationally infeasible to find $x_2 \in X$ with $x \neq x_2$ such that $h(x) = h(x_2)$. x_2 is called second preimage.

Definition 2.4 (Collision resistance)

A hash function h is *collision resistant* iff it is computationally infeasible to find any two $x \in X$ and $x_2 \in X$ with $x \neq x_2$ such that $h(x) = h(x_2)$. Tuple (x, x_2) is called *collision*.

As far as hash functions accept input strings of arbitrary length, but return a fixed size output string, existence of collisions is unavoidable [22]. However, good hash functions make it very difficult to find collisions or preimages.

Any digital data can be hashed (i.e. used as input to a hash function) by considering it in binary representation. The format or encoding is not part of the hash function's specification.

2.1.1 Merkle-Damgård designs

The Merkle-Damgård design is a particular design of hash functions providing the following security guarantee:

Definition 2.5 (Collision resistance inheritance)

Let F_0 be a collision resistant compression function. A hash function in Merkle-Damgård design is collision resistant if F_0 is collision resistant.

This motivates thorough research of collisions in compression functions. The design was found independently by Ralph C. Merkle and Ivan B. Damgård. It was described by Merkle in his PhD thesis [14, p. 13-15] and followingly used in popular hash functions such as MD4, MD5 and the SHA2 hash function family. The single-pipe design works as follows:

- 1. Split the input into blocks of uniform block size. If necessary, apply padding to the last block to achieve full block size.
- 2. Compression function F_0 is applied iteratively using the output y_{i-1} of the previous iteration and the next input block x_i , denoted $y_i = F_0(y_{i-1}, x_i)$.
- 3. An optional postprocessing function is applied.

2.1.2 Padding and length extension attacks

Hash functions of single-piped Merkle-Damgård design inherently suffer from length extension attacks. MD4 and SHA256 apply padding to their input to nor-

2.2. MD4 5

malize their input size to a multiple of its block size. The compression function is applied afterwards. This design is vulnerable to length extensions.

Consider some collision (x_0, x_1) with $F_0(x_0) = y = F_0(x_1)$ where x_0 and x_1 have a size of one block. Let p be a suffix with size of one block. Then also $(x_0 || p, x_1 || p)$ (where || denotes concatenation) represents a collision in single-piped Merkle-Damgård designs, because it holds that:

$$F_0(F_0(x_0), p) = F_0(F_0(x_1), p) \iff F_0(y, p) = F_0(y, p)$$

Hence $(x_0 || p, x_1 || p)$ is a collision as well. As far as F_0 is applied recursively to every block, p can be of arbitrary size and (x_0, x_1) can be of arbitrary uniform size.

Because of this vulnerability, cryptanalysts only need to find a collision in compression functions. In our tests will only consider input of one block and padding will be neglected due to this vulnerability.

2.1.3 Example usage

One example showing the use of hash functions as primitives are JSON Web Tokens (JWT) specified in RFC 7519 [12]. Its application allows web developers to represent claims to be transferred between two parties.

Section 8 defines implementation requirements and refers to RFC 7518 [8], which specifies cryptographic algorithms such as "HMAC SHA-256" to be implemented. It is (besides "none") the only required signature and MAC algorithm.

2.2 MD4

MD4 is a cryptographic hash function originally described in RFC 1186 [19], updated in RFC 1320 [20] and declared obsolete by RFC 6150 [24]. It was invented by Ronald Rivest in 1990 with properties given in Table 2.1. In 1995 [4] successful full-round attacks have been found to break collision resistance. Followingly preimage and second-preimage resistance in MD4 have been broken as well. Some of those attacks are described in [21] and [16]. We derived a Python 3 implementation based on a Python 2 implementation and made it available on github [18].

```
block size 512 bits namely variable block in RFC 1320 [20] digest size 128 bits as per Section 3.5 in RFC 1320 [20] internal state size 128 bits namely variables A, B, C and D word size 32 bits as per Section 2 in RFC 1320 [20]
```

Table 2.1: MD4 hash algorithm properties

MD₄ uses three auxiliary Boolean functions:

Definition 2.6

The Boolean IF function is defined as follows: If the first argument is true, the second argument is returned. Otherwise the third argument is returned.

The Boolean MAJ function returns true if the number of Boolean values true in arguments is at least 2. The Boolean XOR function returns true if the number of Boolean values true in arguments is odd.

Using the logical operators \land (AND), \lor (OR) and \neg (NEG) we can define them as (see section 4.1 for a thorough discussion of these operators):

$$\mathsf{IF}(X,Y,Z) \coloneqq (X \land Y) \lor (\neg X \land Z) \tag{2.1}$$

$$MAJ(X,Y,Z) := (X \land Y) \lor (X \land Z) \lor (Y \land Z)$$
 (2.2)

$$XOR(X, Y, Z) := (X \land \neg Y \land \neg Z) \lor (\neg X \land Y \land \neg Z)$$
$$\lor (\neg X \land \neg Y \land Z) \lor (X \land Y \land Z)$$

$$:= (X \oplus Y \oplus Z) \tag{2.3}$$

In the following a brief overview over MD4's design is given.

Padding and length extension. First of all, padding is applied. A single bit 1 is appended to the input. As long as the input does not reach a length congruent 448 modulo 512, bit 0 is appended. Followingly, length appending takes place. Represent the length of the input (without the previous modifications) in binary and take its first 64 less significant bits. Append those 64 bits to the input.

Initialization. The message is split into 512-bit blocks (i.e. 16 32-bit words). Four state variables A_i with $-4 \le i < 0$ are initialized with these hexadecimal values:

$$[A_{-4}]$$
 01234567 $[A_{-1}]$ 89abcdef $[A_{-2}]$ fedcba98 $[A_{-3}]$ 76543210

Round function with state variable updates. The round function is applied in three rounds with 16 iterations. In every iteration values A_{-1} , A_{-2} and A_{-3} are taken as arguments to function F. Function F is IF in round 1, followed by MAJ for round 2 and XOR for the final round 3. The resulting value is added to A_{-1} , current message block M and constant X. Finally the 32-bit sum will be left-rotated by p positions. Left rotation is formally defined in Definition 2.7. The values of X and p are defined as follows:

Let i be the iteration counter between 1 and 16 and r the round between 1 and 3. Then X takes the value of the i-th column and r-th row of matrix C. p takes the value of row r and column i mod 4 of matrix P.

2.3. SHA-256 7

$$P = \begin{pmatrix} 3 & 7 & 9 & 11 \\ 3 & 5 & 9 & 13 \\ 3 & 9 & 11 & 15 \end{pmatrix}$$

This round function design is visualized in Figure 2.1.

2.3 SHA-256

SHA-256 is a hash function from the SHA-2 family designed by the National Security Agency (NSA) and published in 2001 [7]. It uses a Merkle-Damgård construction with a Davies-Meyer compression function. The best known preimage attack was found in 2011 and breaks preimage resistance for 52 rounds [9]. The best known collision attack breaks collision resistance for 31 rounds of SHA-256 [13] and pseudo-collision resistance for 46 rounds [10].

```
block size 512 bits as per Section 1 of the standard [7] digest size 256 bits mentioned as Message Digest size [7] internal state size 256 bits as per Section 1 of the standard [7] word size 32 bits as per Section 1 of the standard [7]
```

TABLE 2.2: SHA-256 hash algorithm properties

Definition 2.7 (Shifts, rotations and a notational remark)

Consider a 32-bit word X with 32 binary values b_i with $0 \le i \le 31$. b_0 refers to the least significant bit. Shifting (\ll and \gg) and rotation (\ll and \gg) creates a new 32-bit word Y with 32 binary values a_i . We define the following notations:

$$Y := X \ll n \iff a_i := b_{i-n} \text{ if } 0 \leqslant i-n \leqslant 32 \text{ and } 0 \text{ otherwise}$$

 $Y := X \gg n \iff a_i := b_{i+n} \text{ if } 0 \leqslant i+n \leqslant 32 \text{ and } 0 \text{ otherwise}$
 $Y := X \ll n \iff a_i := b_{i-n \mod 32} \text{ as used in MD4}$
 $Y := X \gg n \iff a_i := b_{i+n \mod 32}$

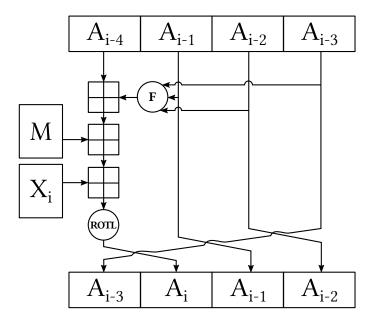


Figure 2.1: $\mathrm{MD4}$ round function updating state variables



Figure 2.2: SHA-256 round function as characterized in [5]

2.3. SHA-256

Besides MD₄'s MAJ and IF, another four auxiliary functions are defined. Recognize that \oplus denotes the XOR function whereas \boxplus denotes 32-bit addition.

Padding and length extension. The padding and length extension scheme of MD₄ is used also in SHA-256. Append bit 1 and followed by a sequence of bit 0 until the message reaches a length of 448 modulo 512 bits. Afterwards the first 64 bits of the binary representation of the original input are appended.

Initialization. In a similar manner to MD4, initialization of internal state variables (called "working variables" in [7, Section 6.2.2]) takes place before running the round function. The eight state variables are initialized with the following hexadecimal values:

$$A_{-1} =$$
 6a09e667 $A_{-2} =$ bb67ae85 $A_{-3} =$ 3c6ef372 $A_{-4} =$ a54ff53a $E_{-1} =$ 510e527f $E_{-2} =$ 9b05688c $E_{-3} =$ 1f83d9ab $E_{-4} =$ 5be0cd19

Furthermore SHA-256 uses 64 constant values in its round function. We initialize step constants K_i for $0 \le i < 64$ with the following hexadecimal values (which must be read left to right and top to bottom):

```
428a2f9871374491b5c0fbcfe9b5dba53956c25b59f111f1923f82a4ab1c5ed5d807aa9812835b01243185be550c7dc372be5d7480deb1fe9bdc06a7c19bf174e49b69c1efbe47860fc19dc6240ca1cc2de92c6f4a7484aa5cb0a9dc76f988da983e5152a831c66db00327c8bf597fc7c6e00bf3d5a7914706ca63511429296727b70a852e1b21384d2c6dfc53380d13650a7354766a0abb81c2c92e92722c85a2bfe8a1a81a664bc24b8b70c76c51a3d192e819d6990624f40e3585106aa07019a4c1161e376c082748774c34b0bcb5391c0cb34ed8aa4a5b9cca4f682e6ff3748f82ee78a5636f84c878148cc7020890befffaa4506cebbef9a3f7c67178f2
```

Precomputation of W. Let W_i for $0 \le i < 16$ be the sixteen 32-bit words of the padded input message. Then compute W_i for $16 \le i < 64$ the following way:

$$W_i := \sigma_1(W_{i-2}) + W_{i-7} + \sigma_0(W_{i-15}) + W_{i-16}$$

Round function. For every block of 512 bits, the round function is applied. The eight state variables are updated iteratively for i from 0 to 63.

$$E_i := A_{i-4} + E_{i-4} + \Sigma_1 (E_{i-1}) + \text{IF } (E_{i-1}, E_{i-2}, E_{i-3}) + K_i + W_i$$

 $A_i := E_i - A_{i-4} + \Sigma_0 (A_{i-1}) + \text{MAJ } (A_{i-1}, A_{i-2}, A_{i-3})$

 W_i and K_i refer to the previously initialized values.

Computation of intermediate hash values. Intermediate hash values for the Davies-Meyer construction are initialized with the following values:

$$H_0^{(0)} := A_{-1}$$
 $H_1^{(0)} := A_{-2}$ $H_2^{(0)} := A_{-3}$ $H_3^{(0)} := A_{-4}$ $H_4^{(i)} := E_{-1}$ $H_5^{(i)} := E_{-2}$ $H_6^{(i)} := E_{-3}$ $H_7^{(i)} := E_{-4}$

Every block creates its own E_i and A_i values for $60 \le i < 64$. These are used to compute the next intermediate values:

$$\begin{aligned} H_0^{(j)} &\coloneqq A_{63} + H_0^{(i-1)} & H_4^{(j)} &\coloneqq E_{63} + H_4^{(i-1)} \\ H_1^{(j)} &\coloneqq A_{62} + H_1^{(i-1)} & H_5^{(j)} &\coloneqq E_{62} + H_5^{(i-1)} \\ H_2^{(j)} &\coloneqq A_{61} + H_2^{(i-1)} & H_6^{(j)} &\coloneqq E_{61} + H_6^{(i-1)} \\ H_3^{(j)} &\coloneqq A_{60} + H_3^{(i-1)} & H_7^{(j)} &\coloneqq E_{60} + H_7^{(i-1)} \end{aligned}$$

Finalization. The final hash digest of size 256 bits is provided as

$$H_0^{(N)} \, \| \, H_1^{(N)} \, \| \, H_2^{(N)} \, \| \, H_3^{(N)} \, \| \, H_4^{(N)} \, \| \, H_5^{(N)} \, \| \, H_6^{(N)} \, \| \, H_7^{(N)}$$

where N denotes the index of the last block and operator \parallel denotes concatenation. Hence $H_0^{(N)}$ are the four least significant bytes of the digest.



"Just because it's automatic doesn't mean it works." —Daniel J. Bernstein

Chapter 3

Differential cryptanalysis

In chapter 2 we defined two hash functions. In this chapter we consider such functions from a differential perspective. Differential considerations will turn out to yield successful collision attacks on hash functions. We introduce a notation to easily represent differential characteristics.

3.1 Motivation

In August 2004, Wang et al. published results at Crypto'04 [25] which revealed that MD4, MD5, HAVAL-128 and RIPEMD can be broken practically using differential cryptanalysis. Their work is based on preliminary work by Hans Dobbertin [4]. On an IBM P690 machine, an MD5 collision can be computed in about one hour using this approach. Collisions for HAVAL-128, MD4 and RIPEMD were found as well. Patrick Stach's md4coll.c program [23] implements Wang's approach and can find MD4 collisions in few seconds on my Thinkpad x220 setup specified in Appendix B.

Let n denote the digest size, i.e. the size of the hash value h(x) in bits. Due to the birthday paradox, a collision attack has a generic complexity of $2^{n/2}$ whereas preimage and second preimage attacks have generic complexities of 2^n . In other words it is computationally easier to find any two colliding hash values than the preimage or second preimage for a given hash value.

Following results by Wang et al., differential cryptanalysis was shown as powerful tool for cryptanalysis of hash algorithms. This thesis applies those ideas to satisfiability approaches.

see						
l9f						
e8						
ge9						
45dc8e31 97e31fe5 2794bfo8 b9e8c3e9 Message 2						
see						
l9f						
e8						
ge9						
7a						

Table 3.1: One of two MD4 hash collisions provided in [25]. A message represents one block of 512 bits. Values are given in hexadecimal, message words are enumerated from left to right, top to bottom. Differences are highlighted in bold for illustration purposes. For comparison the first bits of Message 1 are 11000001... and the last bits are ...10011101.

3.2 Fundamentals

Definition 3.1 (Hash collision)

Given a hash function h, a hash collision is a pair (x_1, x_2) with $x_1 \neq x_2$ such that $h(x_1) = h(x_2)$.

Pseudo-collisions are also often considered when attacking hash functions. A *pseudo collision* is given if a hash collision can be found for a given hash function, but the initial vectors (IV) can be chosen arbitrarily.

Hash algorithms consume input values as blocks of bits. As far as the length of the input must not conform to the block size, padding is applied. Now consider such a block of input values and another copy of it. We use those two blocks as inputs for two hash algorithm instances, but provide slight modifications in few bits. Differential cryptanalysis is based on the idea to consider those execution states and tracing those difference to learn about the propagation of message differences. Compare this setup with Figure 3.1.

At the very beginning only the few defined differences are given. But as the hash algorithm progresses in computation, differences are propagated to more and more bits. Most likely the final value will differ in many bits, because of a desirable hash algorithm property called *avalanche effect*. A small difference in the input should lead to a significant difference in the output (i.e. visually recognizable).

Visualizing those differences helps the cryptanalyst to find modifications yielding a small number of differences in the evaluation state. The propagation of



Figure 3.1: Common attack setting for a collision attack: Hash function f is applied to two inputs M and M^* which differ by some predefined bits. ΔM describes the difference between these values. A hash collision is given if and only if output values C and C^* show the same value. In differential cryptanalysis we observe the differences between two instances applying function f to inputs M and M^* .

differences in a particular hash algorithm is called *differential path*. Empirical results in differential cryptanalysis indicate that spare paths are desirable, because it is easier to cancel out few differences in the output compared to many differences. The cryptanalyst consecutively modifies the input values to eventually receive a collision in the output value.

Definition 3.2

The propagation of differences in a particular function is called *differential* path. The complete differential state during a computation is called *differential* characteristic.

Theorem 3.1

Assuming the number of differences in a differential path is small, this path is expected to result in a hash collision with higher probability.

bit	binary	hexadecimal representation / differential notation
$=$ x_0	d6cb927a	11010110110010111001001001111010
x_1	29d5a578	001010011101010110100101011111000
x_2	45dc8e31	01000101110111001000111000110001
$-\frac{1}{x_0^*}$	56cb927a	01010110110010111001001001111010
x_1^*	b9d5a578	101110011101010110100101011111000
x_2^*	45dd8e31	01000101110111011000111000110001
Δx		u1010110110010111001001001111010
		n01n10011101010110100101011111000
		010001011101110n1000111000110001

Table 3.2: The three words different between Message 1 and Message 2 of the original MD4 hash collision by Wang et al. The last three lines show how differences can be written down using bit conditions. As far as 4 symbols are not from the set {0, 1} it holds that the messages differ by 4 bits.

3.3 Differential notation

Differential notation helps us to visualize differential characteristics by defining so-called *generalized bit conditions*. It was introduced by Christian Rechberger and Christophe de Cannière in 2006 [2, Section 3.2], inspired by *signed differences* by Wang et al. and is shown in Table 3.3.

Consider two hash algorithm instances. Let x_i be some bit from the first instance and let x_i^* be the corresponding bit from the second instance. Differences are computed using a XOR and commonly denoted as $\Delta x = x_i \oplus x_i^*$. Bit conditions allow us to encode possible relations between bits x_i and x_i^* .

For example, let us take a look at the original Wang et al. hash collision in MD4 provided in Table 3.1. We extract all values with differences and represent them using differential notation. This gives us Table 3.2.

The following properties hold for bit conditions:

- If $x_i = x_i^*$ holds and some value is known, $\{0, 1\}$ contains its bit condition.
- If $x_i \neq x_i^*$ holds and some value is known, $\{u, n\}$ contains its bit condition.
- If $x_i = x_i^*$ holds and the values are unknown, its bit condition is -.
- If $x_i \neq x_i^*$ holds and the values are unknown, its bit condition is x.

Applying this notation to hash collisions means that arbitrary bit conditions (expect for #) can be specified for the input values. In one of the intermediate iterations, we enforce a difference using one of the bit conditions $\{u, n, x\}$. This excludes trivial solutions with no differences from the set of possible solutions. And the final values need to lack differences thus are represented using a dash \neg .

(x_i, x_i^*)	(0,0)	(1,0)	(0,1)	(1, 1)	(x_i, x_i^*)	(0,0)	(1,0)	(0,1)	(1, 1)
?	✓	✓	✓	\checkmark	3	✓	\checkmark		
_	✓			✓	5	✓		\checkmark	
X		\checkmark	\checkmark		7	✓	\checkmark	\checkmark	
0	✓				Α		\checkmark		✓
u		\checkmark			В	✓	\checkmark		✓
n			\checkmark		С			\checkmark	✓
1				✓	D	✓		\checkmark	✓
#					E		\checkmark	\checkmark	✓

Table 3.3: Differential notation as introduced in [2]. The left-most column specifies a symbol called "bit condition" and right-side columns indicate which bit configurations are possible for two given bits x_i and x_i^* .

Δx	conjunctive normal form	Δx	conjunctive normal form
#	$(x) \wedge (\neg x)$	1	$(x) \wedge (x^*)$
0	$(\neg x) \wedge (\neg x^*)$	-	$\neg(x \oplus x^*)$
u	$(x) \wedge (\neg x^*)$	Α	(x)
3	$(\neg x^*)$	В	$(x \vee \neg x^*)$
n	$(\neg x) \wedge (x^*)$	С	(x^*)
5	$(\neg x)$	D	$(\neg x \lor x^*)$
Х	$(x \oplus x^*)$	Е	$(x \vee x^*)$
7	$(\neg x \vee \neg x^*)$?	

Table 3.4: All bit conditions represented as CNF using two Boolean variables x and x^* to represent two bits.

3.4 A simple addition example

Using this notation, we can now reason about the behavior of functions on differential values. We start with 1-bit addition as most basic exercise to the reader. Consider a matrix with two input rows and one output row. The values of the first two rows are added such that the bit difference at the third row is created.

Figure 3.5 illustrates this example. Remember that symbols such as – and 0 underlie semantics defined in Table 3.3. It is also interesting to see how propagation of values can work. In Figure 3.6 we see how an underspecified value? can be strengthened once we have checked which values can be taken. Recognize that the system is constrained by the function in use and the definition of the differential symbols.

Finally we can extend our testcases to 4 bits and retrieve testcases such as Table 3.7 and 3.8.

3.5 Differential characteristics in action

In the previous section we illustrated how propagation with differential values works and how differential characteristics are written down. It is always important to keep in mind which function the characteristic illustrates, because this is not documented with the characteristic.

Now consider MD4 as defined in Section 2.2. MD4 takes some input message (in our case limited to size of one block), the state variables are initialized and iteratively new A_i are computed.

Similarly, SHA-256 takes a message block M and initializes eight variables with an initial vector (IV). The remaining W_i are computed and iteratively, values A_i and E_i are computed.

Those values are structured in differential characteristics illustrated in Figure 3.2. Those layouts are used to specify our hash collisions we want to evaluate. Table 3.9 is also gives an application of the layout.

Table 3.5: A simple 1-bit addition example: On the left the differential characteristic is given. Two dashes, by definition, denote a missing difference in both arguments. The result of the addition most neither show a difference. This yields eight possible bit configurations where two values close to each other denote (M, M^*) of Figure 3.1. Due to the behavior of addition, we know that configurations 2, 3, 5 and 8 (from left to right) are invalid.

Table 3.6: Like Figure 3.5, but any difference value for the result bit is possible. As such we consider any possible bit configuration, but eventually recognize that only four bit configurations are consistent with the behavior of addition. Because all resulting configurations show no bit difference in the output bit, we can strengthen? by replacing it with -. This illustrates how knowledge about differential states can be propagated.

A:	0011	A:	x	A:	x	A:	x
B:	0101	B:	x	В:	x	В:	x
S:	1000	S:	????	S:	???-	S:	x???
	A:	0011	A:	x	A:		
	B:	0101	B:	x	В:	x	
	S:	0000	S:	???x	S:	x-??	

Table 3.7: Testcases for 4-bit addition: The upper line shows valid differential characteristics for 4-bit addition whereas the lower line show invalid ones for 4-bit addition. The rows are conventionally named using capital letters.

A:		A:	7C-3	A:	0uCD
S:	0000	S:	-3u?	S:	ADC7
	A:	x	A:	xxxx	
	S:	0000	S:	0000	

Table 3.8: Differential characteristics for the SHA-2 Sigma function. The upper line shows valid states. The lower line shows invalid ones.

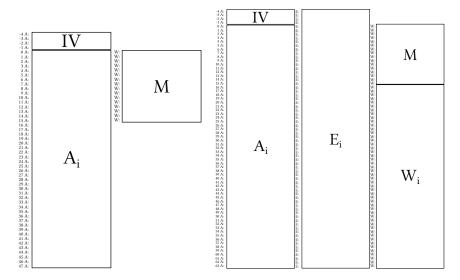


Figure 3.2: Layout of MD4 and SHA-256 differential characteristics

i		$\nabla S_{i,0}$	$\nabla S_{i,1}$	∇S_{i2}		i		$\nabla S_{i,0}$	$\nabla S_{i,1}$	$\nabla S_{i,2}$
-4	A:	01100111010001010010001100000001	.,,,	7,2		-4	A:	01100111010001010010001100000001	- 7.	
-3	A:	00010000001100100101010001110110				-3	A:	00010000001100100101010001110110	İ	
-2	A:	100110001011101011011100111111110				-2	A:	100110001011101011011100111111110	İ	
-1	A:	1110111111100110110101011110001001				-1	A:	1110111111100110110101011110001001		
0	A:	01101011110101001110010000010010	W:	010011010111101010011110010000011		0	A:	01101011110101001110010000010010	W:	01001101011110101001110010000011
1	A:	01110110010011111111011100u110001	W:	u10101101100101110010010011111010		1	A:	01110110010011111111011100u110001	W:	u10101101100101110010010011111010
2	A:	1010101101000000001110u01n1110010	W:	n01n10011101010110100101011111000		2	A:	101010110100000001110u01n1110010	W:	n01n10011101010110100101011111000
3	A:	101011u1001111010101001001010001	W:	01010111101001111010010111101110		3	A:	101011u1001111010101001001010001	W:	01010111101001111010010111101110
4	A:	001011000110001101010101111110010	W:	11011110011101001000101000111100		4	A:	001011000110001101010101111110010	W:	11011110011101001000101000111100
5	A:	000110100110001010u1101000000001	W:	11011100110000110110011010110011		5	A:	000110100110001010u1101000000001	W:	11011100110000110110011010110011
6	A:	0001101100unuu110001000001111010	W:	???????????????????????????????		6	A:	0001101100unuu110001000001111010	W:	10110110100000111010000000100000
7	A:	00101011100000010unn011001010000	W:	00111011001010100101110110011111		7	A:	00101011100000010unn011001010000	W:	00111011001010100101110110011111
8	A:	??????????????????????????????	W:	11000110100111010111000110110011		8	A:	011100110010001u111111111110110000	W:	11000110100111010111000110110011
9	A:	??????????????????????????????	W:	11111001111010011001000110011000		9	A:	101011n01unnu0001111100110011111	W:	11111001111010011001000110011000
10	A:	10n0010010000101????????????110	W:	11010111110011111110000000010111110		10	A:	10n00100100001010100000010101110	W:	11010111110011111110000000010111110
11	A:	u100011010110110?????????????111	W:	101001100011101110110010111101000		11	A:	u10001101011011001001010111111111	W:	10100110001110111011001011101000
12	A:	001011u00u101011?????????????011	W:	010001011101110n1000111000110001		12	A:	001011u00u101011111111100011111011	W:	010001011101110n1000111000110001
13	A:	10un1n0100110001????????????101	W:	10010111111100011000111111111100101		13	A:	10un1n01001100010100000111100101	W:	10010111111100011000111111111100101
14	A:	0000101001010001110	W:	001001111001010010111111100001000		14	A:	00001010010100011000100011010110	W:	001001111001010010111111100001000
15	A:	0001111010101u01100	W:	10111001111010001100001111101001		15	A:	0001111010101 <mark>u</mark> 010110011011010100	W:	10111001111010001100001111101001
16	A:	n00n0un011010010111				16	A:	n00n0un01101001010011011010111111		
17	A:	0001111100111010110				17	A:	00011111001110100001001000011110	İ	
18	A:	0101011100001101100				18	A:	01010111000011010000000010010100	İ	
19	A:	u1n1000000010111100				19	A:	uln100000001011110011010110100100		
20	A:	n1un10011111111011101000000110100				20	A:	n1un10011111111011101000000110100	İ	
21	A:	111100111011000001011111111010100			\Rightarrow	21	A:	111100111011000001011111111010100	İ	
22	A:	01011101110011010011001100111010				22	A:	01011101110011010011001100111010		
23	A:	01010000111011101100011110001111				23	A:	01010000111011101100011110001111		
24	A:	00000010000100100011011100011010				24	A:	00000010000100100011011100011010		
25	A:	10110000100101100001010011101010				25	A:	10110000100101100001010011101010		
26	A:	00001010100010010111011101000001				26	A:	00001010100010010111011101000001		
27	A:	00000110111011110101101010110011				27	A:	00000110111011110101101010110011		
28	A:	10110110010111010110110000100101				28	A:	10110110010111010110110000100101		
29	A:	10100010000011010100100001101001				29	A:	10100010000011010100100001101001		
30	A:	00101001110101111100011101100011				30	A:	00101001110101111100011101100011		
31	A:	111111001001001011010111110110110				31	A:	111111001001001011010111110110110		
32	A:	01001111110100100110100000101111				32	A:	01001111110100100110100000101111		
33	A:	00111000001111010110111011100100				33	A:	00111000001111010110111011100100		
34	A:	00100000011101011110100000010101				34	A:	001000000111010111110100000010101		
35	A:	n0100000001100110000010001110010				35	A:	n0100000001100110000010001110010		
36	A:	n000011111101011111011111001011001				36	A:	n00001111111010111110111110010111001		
37	A:	11001000000110100100001100001100				37	A:	11001000000110100100001100001100		
38	A:	10110000011001111110100110101100)	38	A:	10110000011001111110100110101100		
39	A:	00010010000010100001101100011100				39	A:	00010010000010100001101100011100		
40	A:	1100000010010000111000110000101				40	A:	11000000010010000111000110000101		
41	A:	00000110100001101111010100100110				41	A:	00000110100001101111010100100110		
42	A:	010011101101110111111111010000110				42 43	A:	010011101101110111111111010000110		
	A:	01010000011000111101000001101101					A:	01010000011000111101000001101101		
44	A:	11111000000101101111011100001100				44 45	A:	11111000000101101111011100001100		
45	A:	10001010110110110010110000000100					A: A:	10001010110110110010110000000100		
47	A: A:	100000011110010110111100011111100				46 47	A:	1000000101100110010111000110111100		
4/	A:	1000000011110010110110110100101111101				4/	A:	10000000111110010110110110100101111101		1

Table 3.9: One of the original MD4 collisions by Wang et al, with a few bits underspecified (left) and propagated values (right). The question marks indicate that any bit configuration for the two bits are possible. Dashes indicate that the bits have the same configuration in both instances, but the value itself is unknown. However, it turns out the description with missing values in iteration 6 (message) and iterations 8–19 is complete enough such that missing values can be deduced by other values the description of the algorithm.



"What idiot called them logic errors rather than bool shit?" —Unknown

Chapter 4

Satisfiability

Boolean algebra allows us to describe functions over two-valued variables. Satisfiability is the question for an assignment such that a function evaluates to true. Satisfiability problems are solved by SAT solvers. We discuss the basic theory behind satisfiability. We will learn that any computation can be represented as satisfiability problem. In Chapter 6 we will represent a differential cryptanalysis problem such that it is solvable iff the corresponding SAT problem is satisfiable.

4.1 Basic notation and definitions

Definition 4.1 (Boolean function)

A *Boolean function* is a mapping $h: X \to Y$ with $X = \{0,1\}^n$ for $n \in \mathbb{N}_{\geq 1}$ and $Y = \{0,1\}$.

Definition 4.2 (Assignment)

A *k*-assignment is an element of $\{0,1\}^k$.

Let f be some k-ary Boolean function. An assignment for function f is any k-assignment.

Definition 4.3 (Truth table)

Let f be some k-ary Boolean function. The *truth table of Boolean function* f assigns truth value 0 or 1 to any assignment of f.

Boolean functions are characterized by their corresponding truth table.

x_1	x_2	$f(x_1,x_2)$	x_1	x_2	$f(x_1,x_2)$	v	f(v)
1	1	1	1	1	1	1	0
1	0	0	1	0	1	0	1
0	1	0	0	1	1	(c) NOT	
0	0	0	0	0	0	,	•
) AND		(E				

TABLE 4.1: Truth tables for AND, OR and NOT

Table 4.1 shows example truth tables for the Boolean AND, OR and NOT functions. A different definition of the three functions is given the following way:

Definition 4.4

Let AND, OR and NOT be three Boolean functions.

- AND maps $X = \{0, 1\}^2$ to 1 if all values of X are 1. OR maps $X = \{0, 1\}^2$ to 1 if any value of X is 1.
- NOT maps $X = \{0, 1\}^1$ to 1 if the single value of X is 0.

All functions return 0 in the other case.

Those functions are denoted $a_0 \wedge a_1$, $a_0 \vee a_1$ and $\neg a_0$ respectively, for input parameters a_0 and a_1 .

It is interesting to observe, that any Boolean function can be represented using only these three operators. This can be proven by complete induction over the number of arguments *k* of the function.

Let k = 1. Then we consider any possible 2-assignment for one input variable x_1 and one value of $f(x_1)$. Then four truth tables are possible listed in Table 4.2. The description shows the corresponding definition of f using AND, OR and NOT only.

Now let *g* be some *k*-ary function. Let $(a_0, a_1, ..., a_k)$ be the *k* input arguments to g and $x_1 := g(a_0, a_1, \dots, a_k)$. Then we can again look at Table 4.2 to discover that 4 cases are possible: 2 cases where the return value of our new (k + 1)-ary function depends on value x_1 and 2 cases where the return value is constant.

This completes our proof.

Table 4.2: Unary f and its four possible cases

Boolean functions have an important property which is described in the following definition:

Definition 4.5

A Boolean function f is *satisfiable* iff there exists at least one input $x \in X$ such that f(x) = 1. Every input $x \in X$ satisfying this property is called *model*.

The corresponding tool to determine satisfiability is defined as follows:

Definition 4.6

A *SAT solver* is a tool to determine satisfiability (SAT or UNSAT) of a Boolean function. If satisfiability is given, it returns some model.

4.1.1 Computational considerations

The generic complexity of SAT determination is given by 2^n for n Boolean variables.

Let n be the number of variables of a Boolean function. No known algorithm exists to determine satisfiability in polynomial runtime. This means no algorithm solves the SAT problem with runtime behavior which depends polynomially on the growth of n.

This is known as the famous $\mathscr{P} \neq \mathscr{N}\mathscr{P}$ problem.

However, SAT solver can take advantage of the problem's description. For example consider function f in Display 4.1.

$$f(x_0, x_1, x_2) = x_0 \land (\neg x_1 \lor x_2) \tag{4.1}$$

Instead of trying all possible 8 cases for 3 Boolean variables, we can immediately see that x_0 is required to be 1. So we don't need to test $x_0 = 0$ and can skip 4 cases. This particular strategy is called *unit propagation*.

4.1.2 SAT competitions

SAT research is heavily concerned with finding good heuristics to find some model for a given SAT problem as fast as possible. Biyearly SAT competitions take place to challenge SAT solvers in a set of benchmarks. The committee evaluates the most successful SAT solvers solving the most problems within a given time frame.

SAT 2016 is currently ongoing, but in 2014 lingeling by Armin Biere has won first prize in the Application benchmarks track and second prize in the Hard Combinatorial benchmarks track for SAT and UNSAT instances respectively. Its parallelized sibling plingeling and Cube & Conquer sibling treengeling have won prizes in parallel settings.

In chapter 7 we will look at runtime results shown by (but not limited to) those SAT solvers.

4.2 The DIMACS de-facto standard

Definition 4.7

A *conjunction* is a sequence of Boolean functions combined using a logical OR. A *disjunction* is a sequence of Boolean functions combined using a logical AND. A *literal* is a Boolean variable (*positive*) or its negation (*negative*).

A SAT problem is given in *Conjunctive Normal Form* (CNF) if the problem is defined as conjunction of disjunctions of literals.

A simple example for a SAT problem in CNF is the exclusive OR (XOR). It takes two Boolean values a and b as arguments and returns true if and only if the two arguments differ.

$$(a \lor b) \land (\neg a \lor \neg b) \tag{4.2}$$

Display 4.2 shows one conjunction (denoted \land) of two disjunctions (denoted \lor) of literals (denoted a and b where prefix \neg represents negation). This structure constitutes a CNF.

Analogously we define a *Disjunctive Normal Form* (DNF) as disjunction of conjunctions of literals. The negation of a CNF is in DNF, because literals are negated and conjunctions become disjunctions, vice versa.

Theorem 4.1

Every Boolean function can be represented as CNF.

Theorem 4.1 is easy to prove. Consider the truth table of an arbitrary Boolean function f with k input arguments and j rows of output value false. We represent f as CNF.

Consider Boolean variables $b_{i,l}$ with $0 \le i \le j$ and $0 \le l \le k$. For every row i of the truth table with assignment (r_i) , add one disjunction to the CNF. This disjunction contains $b_{i,l}$ if $r_{i,l}$ is false. The disjunction contains $b_{i,l}$ if $r_{i,l}$ is true.

As far as f is an arbitrary k-ary Boolean function, we have proven that any function can be represented as CNF.

SAT problems are usually represented in the DIMACS de-facto standard. Consider a SAT problem in CNF with *nbclauses* clauses and enumerate all variables from 1 to *nbvars*. A DIMACS file is an ASCII text file. Lines starting with "c" are skipped (comment lines). The first remaining line has to begin with "p cnf" followed by *nbclauses* and *nbvars* separated by spaces (header line). All following non-comment lines are space-separated indices of Boolean variables optionally

prefixed by a minus symbol. Then one line represents one clause and must be terminated with a zero symbol after a space. All lines are conjuncted to form a CNF.

Variations of the DIMACS de-facto standard also allow multiline clauses (the zero symbol constitutes the end of a clause) or arbitrary whitespace instead of spaces. Another variant terminates DIMACS files once it encounters a single percent sign on a line. The syntactical details are individually published on a per competition basis.

LISTING 4.1: Display 4.2 represented in DIMACS format

```
p cnf 2 2
a b
-a -b
```

4.3 Terminology

Given a conjunctive structure of disjunctions, we can define terms related to this structure. Those terms will be used in the SAT features we suggest in Section 5.4.

Definition 4.8

A *clause* is a disjunction of literals. A k-clause is a clause consisting of exactly k literals. A *unit clause* is a 1-clause. A *Horn clause* is a clause with at most one positive literal. A *definite clause* is a clause with exactly one positive literal. A *goal clause* is a clause with no positive literal.

Definition 4.9

Given a literal, its *negated literal* is the literal with its sign negated. A literal is *positive*, if its sign is positive. A literal is *negative* if its sign is negative. An *existential literal* is a literal which occurs exactly once and its negation does not occur. A *used variable* is a variable which occurs at least once in the CNF.

The *literal frequency* is the number of occurences of a literal in the CNF divided by the number of clauses declared. Equivalently *variable frequency* defines the number of variable occurences divided by the number of clauses declared.

Definition 4.10

The *clause length of a clause* is the number of literals contained. A clause is called *tautological* if a literal and its negated literal occurs in it.

A few basic properties hold in terms of satisfiability. For example existential literals are interesting, because they can be set to true and make one clause immediately satisfied without influencing other clauses.

4.4 Basic SAT solving techniques

Definition 4.11

Given two CNFs *A* and *B*, they are called *equisatisfiable* if and only if *A* is satisfiable if and only if *B*.

4.4.1 Boolean constraint propagation (BCP)

One of the most basic techniques to SAT solving is *Boolean Constraint Propagation*, also called *unit propagation*. It is so fundamental that SATzilla, introduced in Section 5.2, applies it immediately before looking at SAT features.

Let l be the literal of a unit clause in a CNF. Remove any clause containing l and replace any occurences of -l from the CNF. It is easy to see, that the resulting CNF is equisatisfiable, because due to the unit clause l must be true. So any clause containing l is satisfied and -l yields false, where $A \vee \bot$ is equivalent to A for any Boolean function A.

4.4.2 Watched literals

Watched Literals are another fundamental concept in SAT solving. It is very expensive to check satisfiability of all clauses for every assigned value of a literal. Watched Literals is a neat technique to reduce the number of checks.

In each clause two unassigned literals are declared to be "watched". Structurally it is implemented the other way around: A clauses watch list is maintained per literal. Now as long as at least two literals are unassigned, the clause cannot become false (recognize that a clause is false if all literals are false). Therefore the clause does not need to be visited as long as at least unassigned literals exist. This implies the following decision procedure:

- If all but one literal is false, propagate the remaining literal to be true.
- If all literals are false, report UNSAT.
- If any literal becomes true, watched literals do not change.
- Else replace the literal on the watch list with a remaining unassigned literal.

This empirical approach was established with the Chaff and zChaff SAT solvers [15] and has proven useful in various variants.

4.4.3 Remark

The previous two techniques shall illustrate basic approaches, but actual SAT solving research requires decades of development to tune individual SAT solvers. Memory models and concurrency strategies lead to fundamentally different runtime behaviors of SAT solvers.

As such an initial idea to initiate an individual SAT solver specifically designed for solving problems in differential cryptanalysis was dropped, because development time is expected too long for a master thesis to be fruitful. As such we focused on popular and established SAT solvers of the SAT community.

4.5 SAT solvers in use

In this thesis we consider the several SAT solvers. They have been selected either by their popularity or their good results at previous SAT competitions:

- · MiniSat 2.2.0
- treengeling, lingeling and plingeling, in versions:
 - lingeling ats1
 - lingeling ats101
 - lingeling ats102
 - lingeling ats104
 - lingeling baz
- CryptoMiniSat 4.5.3
- CryptoMiniSat 5
- glucose 4.0
- glucose syrup 4.0

Specifically this means the hash collision attacks we looked have run with these SAT solvers. The results are discussed in Section 7 and provided in Appendix D.

MiniSat is known as "Swiss army knife of SAT solving" meaning that it includes many well-established techniques that can be built upon. SAT competitions 2009, 2011, 2013 and 2014 included a special MiniSat hack track where participants are asked to modify MiniSat to prove the best performance with as little change to the MiniSat codebase as possible. Even though is not one of the fastest SAT solvers today, it provides a nice codebase to experiment with.

CryptoMiniSat is a derivative of MiniSat, which was originally modified for cryptographic problems. It famously features XOR clauses meaning that binary clauses of structure $a \oplus b$ could be added and will be resolved using Gaussian elimination. Temporarily development has been given up but most recently it was added again. Please recognize that our encoding introduced in Section 6.2 uses equivalence to model assignment and as such only clauses of structure $r = a \oplus b$ emerge rendering this feature impractical to use.

glucose was the gold winner 2011 in the SAT+UNSAT application track. Modifications of glucose also ranked high throughout the years of SAT competition. glucose is a sequential SAT solver whereas glucose syrup is its parallelized version.

lingeling is SAT solver developed by Armin Biere. Lingeling has been the winner of several tracks in the SAT competitions 2011 to 2016. For example it has won gold in the SAT+UNSAT application track in 2014. lingeling has two siblings: plingeling and treengeling. plingeling is a parallelized version of lingeling. As such it executes in multiple threads and shares units and equivalences between those instances. treengeling is a Cube & Conquer solver meaning it partitions the problem into many subproblems and solves them individually.

lingeling releases ats101, ats102 and ats104 are non-public releases of lingeling. They have been developed in private communication with Armin Biere. Our main goal was to achieve a separation between two sets of variables. First all variables of the first need to be assigned in the best possible way. Afterwards the second set of variables is considered. Specifically variables modelling the differences between the two hash algorithm instances should constitute the first set.

ats101 implements that difference variables are guessed with false first and usual heuristics apply for all other variables. Our intermediate results with incomplete CNF files showed a high number of restarts. Therefore ats102 disables backjumping and therefore skips decisions for important variables. Finally ats104 is not expected to distinguish from ats102. It only provides further debugging information.

The SAT solvers have generally been run without any special options, except for

- MiniSat was run with pre=once as it is generally recommended to run with the builtin preprocessor.
- Lingeling has been generally run with phase=-1 to prefer false as initial
 assignment to literals. However, lingeling ats101 implements this with a
 more forceful strategy.

Testcases with lingeling have all been run 5 times with various seeds (for reference, the default seed is o). Only the mean runtime value is displayed in the results in chapter 7.

Preprocessing is a difficult topic on its own. Sometimes preprocessing can provide a speedup, before actually solving the problem, but mostly SAT solvers implement preprocessing strategies themselves and run them repeatedly when solving the problem.



"What idiot called them logic errors rather than bool shit?" —Unknown

Chapter 5

SAT features

At the very beginning I was very intrigued by the question "What is an 'average' SAT problem?". Answers to this question can help to optimize SAT solver memory layouts. Specifically for this thesis I wanted to find out whether our problems distinguish from "average" problems in any way such that we can use this distinction for runtime optimization.

I came up with 8 questions related to basic properties of SAT problems we will discuss in depth in this section:

- 1. Given an arbitrary literal. What is the percentage it is positive?
- 2. What is the variables / clauses ratio?
- 3. How many literals occur only once either positive or negative?
- 4. What is the average and longest clause length among CNF benchmarks?
- 5. How many Horn clauses exist in a CNF?
- 6. Are there any tautological clauses?
- 7. Are there any CNF files with more than one connected variable component?
- 8. How many variables of a CNF are covered by unit clauses?

We will now define the terms used in those questions.

5.1 SAT features and CNF analysis

Definition 5.1 (SAT feature)

A *SAT feature* is a statistical value (named *feature value*) retrievable from some given SAT problem.

The most basic example of a SAT feature is the number of variables and clauses of a given SAT problem. This SAT feature is stored in the CNF header of a SAT problem encoded in the DIMACS format.

The general goal is to write a tool which evaluates several SAT features at the same time and retrieve them for comparison with other problems. Therefore it should be computationally easy to evaluate SAT features of a given SAT problem. A suggested computational limit is given with polynomial complexity in terms of number of variables and number of clauses for memory as well as runtime for evaluation algorithms. Sticking to this convention implies that evaluation of satisfiability must not be necessary to evaluate a SAT feature under the assumption that $\mathcal{P} \neq \mathcal{NP}$. Hence the number of valid models cannot be a SAT feature as far as satisfiability needs to be determined. But no actual hard computational limit is defined.

5.2 Related work

The most similar resource I found looking at SAT features was the SATzilla project [17, 26] in 2012. The authors systematically defined 138 SAT features categorized in 12 groups. Some features are only evaluated conditionally. The features themselves are not defined formally, but an implementation is provided bundled with example data. The following list provides an excerpt of the features:

nvarsOrig number of variables defined in the CNF header

nvars number of active variables

reducedVars nvarsOrig - nvars, divided by nvars

vars-clauses-ratio nvars divided by number of active clauses

POSNEG-RATIO-CLAUSE-mean mean of $2 \cdot ||0.5 - pos/length||$ where pos is the number of positive literals and length clause length of a specific clause

POSNEG-RATIO-CLAUSE-entropy like POSNEG-RATIO-CLAUSE-mean but entropy

TRINARY+ number of clauses with clause length 1, 2 or 3 divided by number of active clauses

31

HORNY-VAR-min minimum number of times a variable occurs in a Horn clause

cluster-coeff-mean let neighbors of a clause be all clauses containing any literal negated and let clauses c_1 and c_2 be conflicting if c_1 contains literal l and c_2 contains -l, then return the mean of 2 times the number of conflicting neighbors of a clause c divided by the number of unordered pairs of neighbors, returned iff computable within 20 seconds for all clauses

Please recognize that active clauses are the unsatisfied clauses after BCP has been applied. Equivalently active variables are remaining variables after application of BCP.

Many SAT solvers collect feature values to improve algorithm selection, restart strategies and estimate problem sizes. Recent trends to apply Machine Learning to SAT solving imply feature evaluation. SAT features and the resulting satisfiability runtime are used as training data for Machine Learning. One example using SAT features for algorithm selection is ASlib [1].

The SAT solvers of Section 4.5 we use also compute features they use when computing a solution. For example CryptoMiniSat 4.5.3 prints the following lines

c [features] numVars 56118, numClauses 358991, var_cl_ratio 0.156, binary 0.019, trinary 0.5

5.3 Statistical features

For our SAT features we need to define some basic statistical terminology. Let $x_1, x_2, ..., x_n$ be a finite sequence of numbers $(n \in \mathbb{N})$.

Arithmetic mean (or short: mean) is defined as

$$\overline{x} = \frac{1}{n} \sum_{i=1}^{n} x_i$$

Standard deviation (or short: sd) with mean \bar{x} is defined as

$$\sigma(x) = \sqrt{\frac{1}{n} \sum_{i=1}^{n} (x_i - \overline{x})}$$

Median with $x_1 \le x_2 \le ... \le x_n$ (i.e. sorted ascendingly) is defined as

$$m = \begin{cases} x_{\text{mid}} & \text{if } n \text{ odd} \\ \frac{x_{\text{mid}} + x_{\text{mid}+1}}{2} & \text{if } n \text{ even} \end{cases} \text{ with mid} = \frac{n}{2}$$

and often considered more "robust" than the arithmetic mean.

Entropy is defined according to Claude Shannon's information theory:

$$H(x) = -\sum_{i=1}^{n} x_i \cdot \log_2(x_i)$$

where $0 \cdot log_2(0) := 0$.

Furthermore *count* refers to the number of elements n, *largest* refers to the maximum element $\max_{1 \le i \le n} (x_i)$ and *smallest* refers to the minimum element $\min_{1 \le i \le n} (x_i)$.

5.4 Suggested SAT features

We wrote a tool called cnf-analysis. The evaluated features are partially inspired by SATzilla and lingeling. The latter prints basic statistics for every CNF it evaluates.

A summary of our suggested SAT features is given:

clause_variables_sd_mean

mean of sd of variables in a clause

clauses_length_(largest, smallest, mean, median, sd)

statistics related to the clause length

connected_(literal, variable)_components_count

two literals (variables) are connected if they occur in some clause together, count the number of connected components

definite_clauses_count

number of definite clauses in the CNF

existential literals count

number of existential literals in the CNF

existential_positive_literals_count

number of positive, existential literals in the CNF

(false, true) trivial

is the CNF satisfied if all variables are claimed to be false (true)?

goal_clauses_count

number of goal clauses in the CNF

literals_count

number of literals in the CNF (i.e. sum of clause lengths)

literals_frequency_k_to_k + 5

let n_l be the literal frequency of literal l, count the number of n_l satisfying $\frac{k}{100} \le n_l < \frac{k+5}{100}$ where k is a variable in $\{0, 5, 10, \dots, 90, 95\}$ and k = 95 counts $\frac{k}{100} \le n_l \le \frac{k+5}{100}$.

literals_frequency_(largest, smallest, mean, median, sd)_entropy

statistics related to literal frequencies

literals_occurence_one_count

number of literals with occurence 1

nbclauses, nbvars number of clauses (variables) as defined in the CNF header

negative_literals_in_clause_(smallest, largest, mean)

statistics related to number of negative literals in clauses

(positive, negative)_unit_clause_count

number of unit clauses with a positive (negative) literal

positive_literals_count

number of positive literals in CNF

positive_literals_in_clause_(largest, smallest, mean, median, sd)

statistics related to number of positive literals in clauses

positive_negative_literals_in_clause_ratio_(mean, entropy)

let r_c be the number of positive literals divided by clause length of clause c, mean and related of all r_c

positive_negative_literals_in_clause_ratio_mean

mean of all r_c

tautological_literals_count

number of clauses which contain a tautological literal

two_literals_clause_count

number of clauses with two literals

variables_frequency_k_to_k + 5

same as literals_frequency $_k$ _to $_k$ + 5 but for variables

variables frequency (largest, smallest, mean, median, sd, entropy)

same as literals_frequency but for variables

variables_used_count

number of variables with occurence greater o

5.5 Evaluation efficiency

The resource requirements of those features have been classified:

Type 1 read the files as bytes, a DIMACS parser is not necessary, constant memory is used

Type 2 features understand what a clause is, but still need constant memory

Type 3 subquadratic runtime and linear memory

Type 4 unrestricted

Memory and runtime is always considered in comparison with the filesize.

This classification should support future considerations regarding feature evaluation tools. The suggested SAT features above have been explicitly selected to avoid Type 4 implementations to limit the time to compute features. The Python implementation triggered MemoryErrors on a computer with 4 GB RAM for a 770 MB CNF file. Followingly a much more efficient Go implementation was implemented which requires much less memory and is much faster. bench_573.smt2.cnf took 1 second in Go instead of 2 minutes in Python. However, the data evaluated is less accurate compared to Python, because Python unlike Go provide nice implementation of statistical tools in the standard library.

In the following section we want to evaluate SAT features and compare test cases.

TODO: illustrate memory and runtime comparison with numbers

5.6 CNF dataset

To evaluate CNF features of a representative set of CNF files, it was necessary to identify equivalent CNF files in the best possible way. Therefore I defined a hashing algorithm standardizing the CNF input provided to a SHA1 instance. Every CNF file is identifiable by its "cnfhash 2.0.0" hash value.

In the next step a complete set of CNF files of previous SAT competitions was collected. The following CNF file collections have been considered:

- SAT Race 2008
- SAToo Competition
- SAT-Race 2010

- SAT11 Competition
- SAT Challenge 2012
- SAT Competition 2013
- SAT Competition 2014
- SAT-Race 2015
- SAT Competition 2016
- SATlib

The benchmarks are mostly contributed by the participants of the associated conferences. Others are reused from previous years. Individual projects allow to generate CNF files for specific problems in a selectable problem size; such as CNFgen ?? by Massimo Lauria.

Some files turned out to be problematic. In SATlib, 3 gzipped files couldn't be decompressed and several files contain empty clauses. Empty clauses are assumed to immediately falsify the CNF and are therefore pointless. I removed trailing zeros in CNFs. Variants of the DIMACS standard also expect lines with a percent symbol to terminate the CNF. Besides those minor issues documented as part of the cnf-analysis project, 175 gigabytes of CNF files have been evaluated with a total of 68069 CNF files (62251 unique CNF files).

5.7 The average SAT problem

Proposition 5.1

The set of public benchmarks in SAT competitions between 2008 and 2015 represent average SAT problems

It is important to point out that public benchmark files are specifically chosen to be evaluated before a conference is held. Hence they are expected to terminate within a given time frame and are therefore not oversized. On the one hand this ensures that the problems are actually solvable, however they might not be a representative selection. At this point no better data set is available and therefore we proceeded with this dataset.

According to my results, an average SAT problem consists of:

- 83,650 clauses in average ranging from 21 to 53,616,734
- The longest clause we found had 61,473 literals, but the longest clause of CNFs typically covers 17 literals.

- At least 114 up to 150,609,758 literals were found in a CNF.
- The clause-variables ratio lies between 1.5 and 27720 with mean 8.35 and $\sigma = 189$.
- The average length of a clause is expected to be 3.
- In average a CNF file has 67 connected variable components.
- In average 31,315 clauses are definite clauses and 29,995 clauses are goal clauses.
- In average a literal occurs in 1.3 % of the clauses of the CNF.
- 48 % of literals in a clause are positive.
- The arithmetic mean tells 137 unit clauses per CNF file can be expected, but the median tells it is mostly o.
- The largest variable found was 13,842,706 and 13,829,558 variables were used at most.

5.8 Benford's law in CNF files

Given this huge set of CNF files and therefore integers, we evaluated whether Benford's law holds.

Theorem 5.1

Consider arbitrary data from tables, listings or other sources in publications, newspaper and so on and so forth, the digit 1 occurs in about 30 % of the time. The first digit is 1 about 30 percent of the time and 9 only about 4.6 percent of the time.

A paper by Theodore P. Hill [hill1998first] characterizes Benford's Law as the following conjecture:



"There is concensus that encoding techniques usually have a dramatic impact on the efficiency of the SAT solver"

—Magnus Björk

Chapter 6

Problem encoding

We already discussed how SAT solvers work and which input they take. We also sketched how hash algorithm properties got broken using differential cryptanalysis. In this section we combine those subjects and describe how we designed an attack setting.

6.1 STP approach

Our first approach started with STP [6] initially written by Vijay Ganesh and David L. Dill. It is currently maintained by Mate Soos.

First we wrote an implementation using the CVC language to model the MD4 hash algorithm. Reimplementing hash algorithms in CVC language (i.e. generating the corresponding code) seemed cumbersome and we switched to the Python binding. With little modifications to a working pure-Python implementation, the prototype was working.

However, STP was not fruitful for us, because we needed good control over the SAT encoding which we expected to have a major influence on the performance. We use minisat as SAT solver in the backend, but STP allows to exchange it for CryptoMiniSat which is a more modern and versatile SAT solver.

6.2 Two instances and its difference

Our second approach was our own library which generated a CNF for a given hash algorithm implementation which is fed with a symbolic variable. Only integer operations have been implemented.

Our tool *algotocnf* implements the following strategy:

- 1. Take a differential characteristic as input and specify the hash algorithm in use.
- 2. Initialize symbolic variables for two instances (bitvectors). Every bit is therefore represented as a boolean variable. If you apply addition, operator overloading in python will ensure that clauses are generated to describe the addition consisting of XORs and MAJs. Equivalently other operations related to integers are implemented as well.
- Constants used in the implementation are automatically converted to unit clauses.
- 4. After running the hash algorithm with symbolic variables per instance, all constraints related to the hash algorithm are added.
- 5. Followingly the differential characteristic is read. Values such as A_i represent intermediate states of bitvectors. Therefore the corresponding bitvectors are looked up and constraints resulting from the differential characteristic are added.
- 6. Finally the SAT solver is called. The CNF was mostly solved on a cluster specified in Appendix B. Afterwards the program is run again to create the exactly same problem instance and the solver's solution replaces symbolic values with boolean values. The resulting differential characteristic is parsed backed and printed out.

We think *algotocnf* mainly differs from other SAT tools because of its differential implementation. When adding clauses resulting from the differential characteristic as constraints, the question arises how those bit conditions are encoded. Essentially, we have only boolean values available, but bit conditions tell constraints such as "a difference is given, but the actual value is unknown".

It seemed trivial to add a *difference variable* for every pair of boolean values representing a bit in the two instances. Furthermore the difference variable Δx is connected by a XOR with the variables of the pair (x', x).

$$\Delta x = x' \oplus x$$

Therefore it should be trivial for a preprocessor to simplify the formula appropriately or actually we don't expect runtime differences for the larger amount of variables.

This implementation is central to the runtime discussion of chapter 7.

TODO: all clauses use a a = b op c design, hence e.g. XOR clauses are not possible for diff vars

TODO: we expect hash algorithm give a pretty dense CNF description

6.3 Approach with a differential description

Using the approach in the previous section, we were able to find actual MD4 collisions using a SAT solver. A SHA256 implementation followed which obviously lead to worse runtime results, because the internal state of SHA-256 is much larger (by a factor of at least 2). Can we further improve the runtime of the SAT solver?

Because we work with bitvectors and apply high-level operations like MAJ or addition, we can additionally implement how differences in those operations propagate. Magnus Daum's thesis on "Cryptanalysis of Hash Functions of the MD4-Family" [daum] discusses how differences propagate in MAJ and ITE functions. Trivially, XORs propagate differences the way they are.

This approach explicitly models differentiable behavior, which should be deducible by the SAT solver itself. However, this lead to a major speedup which can be observed in the runtime results of chapter 7.

6.4 Influencing evaluation order

Proposition 6.1

Deriving difference values first, followed by actual bit values for the two instances, leads to a speedup.

This proposed principle is fundamental to differential cryptanalysis. A previous tool at our institute implements propagation of hash algorithm values without SAT solver and this strategy is essential to good performance. So basically in terms of SAT solvers we want to guess values for differential variables first and furthermore false should be assigned first, before guessing for true. This is justified by the desire to find as little differences as possible in a hash collision.

The development of lingeling ats101 was guided by the desire to influence the evaluation order. We explicitly enforced it with the following approach:

Let Δx be the difference variable of pair (x, x'). We introduce a new boolean variable x^* . We add clause

$$x^* = (\Delta x \wedge x)$$

and explicitly tell the SAT solver to guess on x^* before guessing on Δx , x or x'.

The SAT solver will assign x'=0 first, because of the evaluation order. So either Δx or x must be false. Δx is assigned false, because as difference variable it has a higher priority over x. Equivalently for x'=1 we have Δx needs to be true. So we actually achieve an early guess on the difference variable.

This another approach evaluates in the results chapter.



Chapter 7

Results

In Section 5 we looked at SAT features which to some extent characterize a SAT problem. In Section 6 we discussed problem encoding for our hash collision attacks. In this section, we want to look at the feature value results and runtime results we retrieved.

7.1 Evaluating SAT features

In the introduction of chapter 5 we posed 8 questions. In the following we want to answer them with the data provided by the cnf-analysis project.

Given an arbitrary literal. What is the percentage it is positive? We look at every clause and determine the ratio of positive to the total number of literals. We determine the mean per CNF file and the mean among all CNF files and retrieve a value of 0.48 meaning that 48 % of the literals are positive.

What is the variables / clauses ratio? In average a CNF file has 12,219 variables and 89,541 clauses. Its variables-clauses ratio is 0.1365.

How many literals occur only once either positive or negative? In average there are 36 existential literals per CNF file, but its standard deviation of 967 is very high.

What is the average and longest clause length among CNF benchmarks? The average clause length is 3.04 with a standard deviation of 0.99 and the

longest clause length found was 61,473. Long clauses are typically outliers excluding specific assignments.

- **How many Horn clauses exist in a CNF?** In average 29,994 goal clauses and 31,315 definite clauses exist with an average number of 83649 clauses in a CNF file.
- Are there any tautological clauses? In a file, 1679 tautological literals have been found. However, its mean is 0.07 with a standard deviation of 9.63 meaning that tautological clauses are very rare.
- Are there any CNF files with more than one connected variable component? Indeed, an average CNF file contains 67.07 connected variable components. However, its median is 1 anyway implying that at least half of the CNF files have only 1 connected variable component.
- How many variables of a CNF are covered by unit clauses? In average 124 variables are covered by unit clauses. This is an insignificant number compared to 12,219 variables in an average CNF.

Do our generated problems distinguish from these average problems?

• In average our (MD4 and SHA-256 hash collision) problems contain 84,821 variables and 515,646 clauses meaning that our problems are comparably large.

7.2 Finding hash collisions

TODO: is simplification worth it?

TODO: discuss runtime and development, tuning by doing difference variables first, diff desc makes a difference

Appendix D provide a more exhaustive list of runtimes retrieved.

7.2.1 Attacking MD4

In Section 6.2 we introduced a basic encoding involving two hash algorithm instances and difference variables. Constraints resulting from the hash algorithm description and given differential characteristic are added.

We considered MD4 testcases A, B and C (compare with Appendices ??, ?? and ??) and generated the corresponding CNF files. The SAT solvers mentioned in Section 4.5 were used to evaluate whether the problem is solvable in reasonably

time. For every testcase we defined a time limit of at most 1 day (i.e. 86,400 seconds). Some testcases listed have been evaluated for a larger time limit.

SAT solver	testcase	runtime (in seconds)
minisat 2.2.0	MD ₄ , A	65
cryptominisat 4.5.3	MD_4 , A	24
cryptominisat 5.0.0	MD_4 , A	29
glucose 4.0	MD_4 , A	10
glucose-syrup 4.0	MD_4 , A	31
lingeling-ats1	MD_4 , A	TODO
lingeling-ats101	MD_4 , A	18
lingeling-ats102	MD_4 , A	TODO
lingeling-ats104	MD ₄ , A	125745
plingeling-ats101	MD ₄ , A	88
treeneling-ats101	MD ₄ , A	64

7.2.2 Improvements with differential description

7.2.3 Modifying the guessing strategy

7.3 Related work

7.4 Conclusion

TODO: we attacked MD4 and SHA2, but can see the problems with

7.5 Contributions

To strengthen Reproducible Research, the source code and data resulting from this thesis is available online. It allows the reader to run the experiments again and verify our claims. We did our best to describe our hardware setup as accurately as possible. At the following website, any results part of this project are collected:

http://lukas-prokop.at/proj/megosat/

Several subprojects are part of this master thesis:

algotocnf

A python library implementing the encoding described in chapter 6.

Python3 library and program: https://github.com/prokls/algotocnf

cnf-hash

A standardized way to produce a unique hash for CNF files

Go implementation: https://github.com/prokls/cnf-hash-go **Python3 implementation:** https://github.com/prokls/cnf-hash-py

Testsuite: https://github.com/prokls/cnf-hash-tests2

cnf-analysis

Evaluate SAT features for a given CNF file.

Go implementation: https://github.com/prokls/cnf-analysis-go **Python3 implementation:** https://github.com/prokls/cnf-analysis-py

Testsuite: https://github.com/prokls/cnf-analysis-tests

Chapter 8

Summary and Future Work

- 8.1 Summary of results
- 8.2 Future work

Appendices

Appendix A

Illustrations

i		$\nabla S_{i,0}$	$\nabla S_{i,1}$	$\nabla S_{i,2}$
-4	A:	01100111010001010010001100000001		
-3	A:	00010000001100100101010001110110		
-2	A:	1001100010111010110111100111111110		
-1	A:	1110111111100110110101011110001001		
0	A:	01101011110101001110010000010010	W:	01001101011110101001110010000011
1	A:	01110110010011111111011100 <mark>u</mark> 110001	W:	u1010110110010111001001001111010
2	A:	101010110100000001110u01n1110010	W:	n01n10011101010110100101011111000
3	A:	101011u1001111010101001001010001	W:	01010111101001111010010111101110
4	A:	001011000110001101010101111110010	W:	11011110011101001000101000111100
5	A:	000110100110001010u1101000000001	W:	11011100110000110110011010110011
6	A:	0001101100unuu110001000001111010	W:	10110110100000111010000000100000
7	A:	00101011100000010unn011001010000	W:	00111011001010100101110110011111
8	A:	011100110010001u11111111110110000	W:	11000110100111010111000110110011
9	A:	101011n01unnu0001111100110011111	W:	11111001111010011001000110011000
10	A:	10n00100100001010100000010101110	W:	11010111110011111110000000001011110
11	A:	u10001101011011001001010111111111	W:	101001100011101110110010111101000
12	A:	001011u00u10101111111110001111011	W:	010001011101110n1000111000110001
13	A:	10un1n01001100010100000111100101	W:	100101111110001100011111111100101
14	A:	00001010010100011000100011010110	W:	001001111001010010111111100001000
15	A:	0001111010101 <mark>u</mark> 010110011011010100	W:	10111001111010001100001111101001
16	A:	n00n0un01101001010011011010111111		
17	A:	00011111001110100001001000011110		
18	A:	01010111000011010000000010010100		
19	A:	uln10000000101111001101011000100		
20	A:	n1un10011111111011101000000110100		
21	A:	111100111011000001011111111010100		
22	A:	01011101110011010011001100111010		
23	A:	01010000111011101100011110001111		
24	A:	00000010000100100011011100011010		
25	A:	10110000100101100001010011101010		
26	A:	00001010100010010111011101000001		
27	A:	00000110111011110101101010110011		
28	A:	10110110010111010110110000100101		
29	A:	10100010000011010100100001101001		
30	A:	001010011101011111100011101100011		
31	A:	111111001001001011010111110110110		
32	A:	01001111110100100110100000101111		
33	A:	00111000001111010110111011100100		
34	A:	00100000011101011110100000010101		
35	A:	n0100000001100110000010001110010		
36	A:	n0000111111010111101111001011001		
37	A:	11001000000110100100001100001100		
38	A:	101100000110011111110100110101100		
39	A:	00010010000010100001101100011100		
40	A:	11000000010010000111000110000101		
41	A:	00000110100001101111010100100110		
42	A:	0100111011011101111111111010000110		
43	A:	01010000011000111101000001101101		
44	A:	11111000000101101111011100001100		
45	A:	10001010110110110010110000000100		
46	A:	1000001010011001011100011011100		
47	A:	10000001111001011011010010111101		
				l

Table A.1: One of the original MD4 collision given by Wang, et al.

Appendix B

Hardware setup

In the following we introduce two hardware setups which were used to run our testcases. The first setup is referred to as "Thinkpad x220" throughout the document whereas the second setup is referred to as "Cluster".

Type model	Thinkpad Lenovo x220 tablet, 4299-2P6
Processor	Intel i5-2520M, 2.50 GHz, dual-core, Hyperthreaded
RAM	16 GB (extension to common retail setup)
Memory	160 GB SSD
L3 cache size	3072 KB

Table B.1: Thinkpad x220 Tablet specification [11]

Processor	Intel Xeon X5690, 3.47 GHz, 6 cores, Hyperthreaded
RAM	192 GB
L3 cache size	12288 KB

TABLE B.2: Cluster node nehalem192go specification [3]

Appendix C

Testcases

Figures $C._3$, $C._2$, $C._1$ and $C._4$ show testcases used to test performance measures.

TODO: SAT features

TODO: SAT features

TODO: SAT features

TODO: SAT features

i		$ abla S_{i,0}$	$\nabla S_{i,1}$	$\nabla S_{i,2}$
-4	A:	01100111010001010010001100000001		1.51,2
-3	A:	0001000000110010010010001100000001		
-2	A:	1001100010111010110111100111111110		
-1	A:	1110111111100110110110111110001001		
0		1110111111100110110101011110001001	W:	
	A:	x	W:	x
1 2	A:		W:	
	A:	X		x
3	A:	xxx	W:	
4	A:	xx	W:	X
5	A:	xxxxxxxxxxxxxxxxx	W:	
6	A:	xxx-x-xxxxx	W:	
7	A:	xx	W:	
8	A:	x-x-x-x-x-x-x-x-x-x-x-x-x-x-x-x-x	W:	x
9	A:	xx	W:	
10	A:	xxxxx-xxx	W:	
11	A:	xxxx-x	W:	
12	A:	xx	W:	x
13	A:		W:	
14	A:	-x	W:	
15	A:	x-xxx	W:	
16	A:	-xxx		
17	A:			
18	A:			
19	A:	x		
20	A:	Y		
21	A:			
22	A:			
23	A:			
24	A:			
25	A:			
26	A:			
27	A:			
28	A:			
!				
29	A:			
30	A:			
31	A:			
32	A:	x		
33	A:			
34	A:			
35	A:			
36	A:			
37	A:			
38	A:			
39	A:			
40	A:			
41	A:			
42	A:			
43	A:			
44	A:			
45	A:			
46	A:			
47	A:			
				I.

Table C.1: MD4 testcase C

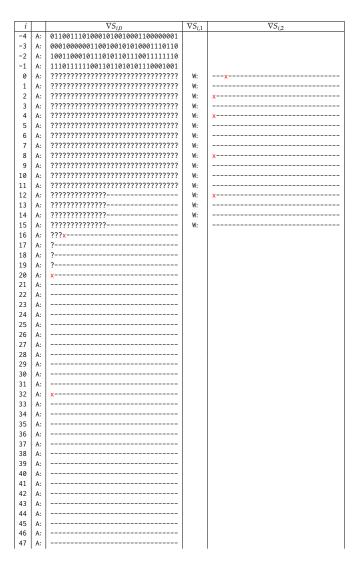


TABLE C.2: MD4 2 TODO description

		$\nabla S_{i,0}$	$\nabla S_{i,1}$	$\nabla S_{i,2}$
-4	A:	01100111010001010010001100000001	, 01,1	1 51,2
-3	A:	00010000001100100101010001110110		
-2	A:	1001100010111010110111100111111110		
-1	A:	1110111111100110110101011110001001		
0	A:	??????????????????????????????	W:	
1	A:	7777777777777777777777777777777	w:	
2	A:	7777777777777777777777777777777	w:	¥
3	A:	77777777777777777777777777777777	w:	
4	A:	77777777777777777777777777777777	w:	¥
5	A:	77777777777777777777777777777777	w:	
6	A:	???????????????????????????????	W:	
7	A:	77777777777777777777777777777777	w:	
8	A:	77777777777777777777777777777777	w:	v
9	A:	77777777777777777777777777777777	W:	
10	A:	7777777777777777777777777777777	w:	
11	A:	7777777777777777777777777777777	w:	
12	A:	7777777777777777777777777777777	W:	×
13	A:	77777777777777777777777777777777	W:	
14	A:	77777777777777777777777777777777	w:	
15	A:	77777777777777777777777777777777	w:	
16	A:	77777777777777777777777777777777	""	
17	A:	77777777777777777777777777777777		
18	A:	7777777777777777777777777777777		
19	A:	77777777777777777777777777777777		
20	A:	77777777777777777777777777777777		
21	A:			
22	A:			
23	A:			
24	A:			
25	A:			
26	A:			
27	A:			
28	A:			
29	A:			
30	A:			
31	A:			
32	A:	x		
33	A:			
34	A:			
35	A:			
36	A:			
37	A:			
38	A:			
39	A:			
40	A:			
41	A:			
42	A:			
43	A:			
44	A:			
45	A:			
46	A:			
47	A:			

Table C.3: MD4 testcase A

i		$\nabla S_{i,0}$	$\nabla S_{i,1}$	$\nabla S_{i,2}$
-4	A:	01100111010001010010001100000001	.,,-	
-3	A:	00010000001100100101010001110110		
-2	A:	100110001011101011011100111111110		
-1	A:	111011111100110110101011110001001		
0	A:	7777777777777777777777777777777	W:	???????????????????????????????
1	A:	7777777777777777777777777777777	W:	7777777777777777777777777777777
2	A:	77777777777777777777777777777777	W:	77777777777777777777777777777777
3	A:	7777777777777777777777777777777	W:	77777777777777777777777777777777
4	A:	7777777777777777777777777777777	W:	7777777777777777777777777777777
5	A:	7777777777777777777777777777777	W:	7777777777777777777777777777777
6	A:	7777777777777777777777777777777	W:	7777777777777777777777777777777
7	A:	7777777777777777777777777777777	W:	7777777777777777777777777777777
8	A:	7777777777777777777777777777777	W:	777777777777777777777777777777
9	A:	77777777777777777777777777777777	W:	7777777777777777777777777777777
10	A:	77777777777777777777777777777777	W:	7777777777777777777777777777777
11	A:	77777777777777777777777777777777	W:	7777777777777777777777777777777
12	A:	77777777777777777777777777777777	W:	7777777777777777777777777777777
13	A:	77777777777777777777777777777777	W:	7777777777777777777777777777777
14	A:	77777777777777777777777777777777	W:	7777777777777777777777777777777
15	A:	77777777777777777777777777777777	W:	7777777777777777777777777777777
16	A:	7777777777777777777777777777777	, "·	
17	A:	77777777777777777777777777777777		
18	A:	77777777777777777777777777777777		
19	A:	77777777777777777777777777777777		
20	A:	77777777777777777777777777777777		
21	A:			
22	A:			
23	A:			
24	A:			
25	A:			
26	A:			
27	A:			
28	A:			
29	A:			
30	A:		1	
31	A:			
32	A:	*777777777777777777777777777777		
33	A:			
34	A:			
35	A:			
36	A:			
37	A:			
38	A:			
39	A:			
40	A:			
41	A:			
42	A:			
43	A:			
44	A:			
45	A:			
46	A:			
47	A:		1	
	Λ.			

Table C.4: MD4 4 TODO

i		$\nabla S_{i,0}$	$\nabla S_{i,1}$	$\nabla S_{i,2}$	$\nabla S_{i,3}$
-4	A:		W:		
-3	A:		W:		
-2	A:		W:		
-1	A:		W:		
0	A:		W:		
1	A:		W:		
2	A:		W:		
3	A:	x	W:	???????????????????????????????	??????????????????????????????
4	A:		W:	???????????????????????????????	??????????????????????????????
5	A:		W:	???????????????????????????????	??????????????????????????????
6	A:		W:	???????????????????????????????	??????????????????????????????
7	A:		W:	???????????????????????????????	??????????????????????????????
8	A:		W:		??????????????????????????????
9	A:		W:		
10	A:		W:		
11	A:		W:		??????????????????????????????
12	A:		W:		
13	A:		W:		
14	A:		W:		
15	A:		W:		
16	A:		W:		
17	A:		W:		

Table C.5: SHA256 18-t9 TODO

i		$\nabla S_{i,0}$	$\nabla S_{i,1}$	$\nabla S_{i,2}$	$\nabla S_{i,3}$
-4	A:		W:		,-
-3	A:		W:		
-2	A:		W:		
-1	A:		W:		
0	A:		W:		
1	A:		W:		
2	A:		W:		
3	A:		W:		
4	A:		W:		
5	A:	x??????????????????????????????	W:	???????????????????????????????	??????????????????????????????
6	A:		W:	???????????????????????????????	??????????????????????????????
7	A:		W:	???????????????????????????????	??????????????????????????????
8	A:		W:	???????????????????????????????	??????????????????????????????
9	A:		W:	???????????????????????????????	
10	A:		W:		
11	A:		W:		
12	A:		W:		
13	A:		W:		??????????????????????????????
14	A:		W:		
15	A:		W:		
16	A:		W:		
17	A:		W:		
18	A:		W:		
19	A:		W:		
20	A:		W:		

Table C.6: SHA256 21-t9 TODO

i		$\nabla S_{i,0}$	$\nabla S_{i,1}$	$\nabla S_{i,2}$	$\nabla S_{i,3}$
-4	A:		W:		·
-3	A:		W:		
-2	A:		W:		
-1	A:		W:		
0	A:		W:		
1	A:		W:		
2	A:		W:		
3	A:		W:		
4	A:		W:		
5	A:		W:		
6	A:		W:		
7	A:	x???????????????????????????????	W:	???????????????????????????????	??????????????????????????????
8	A:		W:	???????????????????????????????	??????????????????????????????
9	A:		W:	???????????????????????????????	
10	A:		W:	???????????????????????????????	??????????????????????????????
11	A:		W:	???????????????????????????????	
12	A:		W:		
13	A:		W:		
14	A:		W:		
15	A:		W:		?????????????????????????????
16	A:		W:		
17	A:		W:		
18	A:		W:		
19	A:		W:		
20	A:		W:		
21	A:		W:		
22	A:		W:		

Table C.7: SHA256 23-t9 TODO

i		$\nabla S_{i,0}$	$\nabla S_{i,1}$	$\nabla S_{i,2}$	$\nabla S_{i,3}$
-4	A:	, S _{1,0}	W:	, 3 _{1,2}	, J _{1,3}
-3	A:		W:		
-2	A:		W:		
-1	A:		W:		
0	A:		W:		
1	A:		W:		
2	A:		W:		
3	A:		W:		
4	A:		W:		
5	A:		W:		
6	A:		W:		
7	A:	x????????????????????????????	W:	7777777777777777777777777777777	777777777777777777777777777777
8	A:		W:	777777777777777777777777777777777	7777777777777777777777777777777
9	A:		W:	77777777777777777777777777777777	
10	A:		W:	77777777777777777777777777777777	222222222222222222222222222222222222222
11	A:		W:	777777777777777777777777777777777	
12	A:		W:		
13	A:		W:		
14	A:		W:		
15	A:		W:		??????????????????????????????
16	A:		W:		
17	A:		W:		
18	A:		W:		
19	A:		W:		
20	A:		W:		
21	A:		W:		
22	A:		W:		
23	A:		W:		

Table C.8: SHA256 24-t9 TODO

Appendix D

Runtimes retrieved

List of Figures

2.1	MD ₄ round function updating state variables	8
2.2	SHA-256 round function as characterized in [5]	8
3.1	Common attack setting for a collision attack	13
3.2	Layout of MD4 and SHA-256 differential characteristics	18

List of Tables

2.1	MD ₄ hash algorithm properties	5
2.2	SHA-256 hash algorithm properties	7
3.1	Hexadecimal values of one MD4 collisions given in paper $[25]$	12
3.2	Bit differences in the original Wang et al. hash collision	14
3.3	Differential notation as introduced in $[2]$	15
3.4	Representation of bit conditions as CNF	15
3.5	A simple 1-bit addition example	17
3.6	Propagation of bit conditions in a differential characteristic	17
3.7	Testcases for 4-bit addition	17
3.8	Differential characteristics for the SHA-2 Sigma function	17
3.9	One of the original MD4 collisions by Wang et al, with a few bits underspecified and followingly propagated	18
4.1	Truth tables for AND, OR and NOT	20
4.2	Unary f and its four possible cases $\dots \dots \dots \dots$	20
A.1	One of the original MD4 collision given by Wang, et al	50
B.1	Thinkpad x220 Tablet specification [11]	51
B.2	Cluster node nehalem192go specification [3]	51
C.1	MD ₄ testcase C	54
C.2	MD ₄ 2 TODO description	55

66 LIST OF TABLES

C.3	MD ₄ testcase A	56
C.4	MD ₄ 4 TODO	57
C.5	SHA256 18-t9 TODO	58
C.6	SHA256 21-t9 TODO	58
C.7	SHA256 23-t9 TODO	59
C.8	SHA256 24-to TODO	50

Bibliography

- [1] Bernd Bischl et al. "ASlib: A benchmark library for algorithm selection". In: Artificial Intelligence 237 (2016), pp. 41 -58. ISSN: 0004-3702. DOI: http://dx.doi.org/10.1016/j.artint.2016.04.003. URL: http://www.sciencedirect.com/science/article/pii/S0004370216300388.
- [2] Christophe De Cannière and Christian Rechberger. "Finding SHA-1 Characteristics: General Results and Applications". In: *ASIACRYPT*. Ed. by Xuejia Lai and Kefei Chen. Vol. 4284. LNCS. Springer, 2006, pp. 1–20. ISBN: 3-540-49475-8. URL: http://dx.doi.org/10.1007/11935230_1.
- [3] Intel Corporation. Intel Xeon Processor X5690 (12M Cache, 3.46 GHz, 6.40 GT/s Intel QPI) Specifications. URL: http://ark.intel.com/products/52576/Intel-Xeon-Processor-X5690-12M-Cache-3_46-GHz-6_40-GTs-Intel-QPI (visited on 04/05/2016).
- [4] Hans Dobbertin. "Cryptanalysis of MD4". In: Journal of Cryptology 11.4 (1998), pp. 253–271. ISSN: 1432-1378. DOI: 10.1007/s001459900047. URL: http://dx.doi.org/10.1007/s001459900047.
- [5] Christoph Dobraunig, Maria Eichlseder, and Florian Mendel. "Analysis of SHA-512/224 and SHA-512/256". In: *Advances in Cryptology–ASIACRYPT* 2015. Springer, 2014, pp. 612–630.
- [6] Vijay Ganesh and David L Dill. "A decision procedure for bit-vectors and arrays". In: *International Conference on Computer Aided Verification*. Springer. 2007, pp. 519–531.
- [7] National Institute of Standards Information Technology Laboratory and Technology. "Federal Information Processing Standards Publication 180-4". In: *National Bureau of Standards, US Department of Commerce* (2015). URL: http://dx.doi.org/10.6028/NIST.FIPS.180-4 (visited on 05/10/2016).
- [8] M. Jones. JSON Web Algorithms (JWA). RFC 7518. The Internet Engineering Task Force, 2015, pp. 1–69. URL: https://tools.ietf.org/html/rfc7518 (visited on 05/09/2016).

68 BIBLIOGRAPHY

[9] Dmitry Khovratovich, Christian Rechberger, and Alexandra Savelieva. "Bicliques for preimages: attacks on Skein-512 and the SHA-2 family". In: *Fast Software Encryption*. Springer. 2012, pp. 244–263.

- [10] Mario Lamberger and Florian Mendel. "Higher-Order Differential Attack on Reduced SHA-256." In: *IACR Cryptology ePrint Archive* 2011 (2011), p. 37.
- [11] Lenovo Group Ltd. ThinkPad X220 Tablet (4299) Onsite (2011). URL: http://www.lenovo.com/shop/americas/content/pdf/system_data/x220t_tech_specs.pdf (visited on 04/05/2016).
- [12] N. Sakimura M. Jones J. Bradley. JSON Web Token (JWT). RFC 7519. The Internet Engineering Task Force, 2015, pp. 16–16. URL: https://tools.ietf.org/html/rfc7519#section-8 (visited on 05/09/2016).
- [13] Florian Mendel, Tomislav Nad, and Martin Schläffer. "Improving local collisions: new attacks on reduced SHA-256". In: *Advances in Cryptology–EUROCRYPT 2013*. Springer, 2013, pp. 262–278.
- [14] RC Merkle. "Secrecy, Authentification, and Public Key Systems". PhD thesis. PhD thesis, Stanford University, Dpt of Electrical Engineering, 1979.
- [15] Matthew W Moskewicz et al. "Chaff: Engineering an efficient SAT solver". In: *Proceedings of the 38th annual Design Automation Conference*. ACM. 2001, pp. 530–535.
- [16] Yusuke Naito et al. "Improved Collision Attack on MD4". In: (2005), pp. 1–5. URL: http://eprint.iacr.org/.
- [17] Eugene Nudelman et al. "Satzilla: An algorithm portfolio for SAT". In: *Solver description*, *SAT competition* 2004 (2004).
- [18] prokls. MD4 in pure Python 3.4. URL: https://gist.github.com/prokls/86b3c037df19a8c957fe.
- [19] Ronald Rivest. *The MD4 Message Digest Algorithm*. RFC 1186. The Internet Engineering Task Force, 1990, pp. 1–18. URL: https://tools.ietf.org/html/rfc1186.
- [20] Ronald Rivest. *The MD4 Message-Digest Algorithm*. RFC 1320. The Internet Engineering Task Force, 1992, pp. 1–20. URL: https://tools.ietf.org/html/rfc1320.
- [21] Yu Sasaki et al. "New Message Difference for MD4". In: (2007), pp. 1–20. URL: http://www.iacr.org/archive/fse2007/45930331/45930331.pdf.
- [22] Martin Schläffer and Elisabeth Oswald. "Searching for differential paths in MD4". In: *Fast Software Encryption*. Springer. 2006, pp. 242–261.
- [23] Patrick Stach. MD4 collision generator. URL: http://crppit.epfl.ch/documentation/Hash_Function/Fastcoll_MD4/md4coll.c (visited on o4/05/2016).

BIBLIOGRAPHY 69

[24] S. Turner and L. Chen. *The MD4 Message Digest Algorithm*. RFC 6150. The Internet Engineering Task Force, 2011, pp. 1–10. URL: https://tools.ietf.org/html/rfc6150 (visited on 03/15/2016).

- [25] Xiaoyun Wang et al. "Collisions for Hash Functions MD4, MD5, HAVAL-128 and RIPEMD." In: *IACR Cryptology ePrint Archive* 2004 (2004), p. 199.
- [26] Lin Xu et al. "SATzilla: portfolio-based algorithm selection for SAT". In: *Journal of Artificial Intelligence Research* (2008), pp. 565–606.