

Let us use the proposed procedure by Peter

$$g_T^a(x, k_T^2) = g_T^a(x) \frac{1}{\pi \langle k_\perp^2 \rangle_{g_1}} e^{-k_T^2 / \langle k_\perp^2 \rangle_{g_1}}$$

$$\text{where } g_T^a(x) \stackrel{ww}{=} \int_x^1 \frac{dy}{y} g_1^a(y)$$

now we have:

$$F_{LT}^{\cos \phi_u} = - \frac{2M}{Q} x^2 \sum_q e_q^2 g_T^q(x) D_1^q(z) G(P_{uT})$$

$$\int d^2 p_{uT} F_{LT}^{\cos \phi_u} = - \frac{2M}{Q} x^2 \sum_q e_q^2 g_T^q(x) D_1^q(z)$$

consistent with 7.2 a and 7.2 b

Now we revisit

$$x g_T^q(x, k_T^2) = g_{1T}^{\perp q}(x, k_T^2) \quad 3.3 e$$

$$x g_T^q(x, k_T^2) = \frac{k_T^2}{2M^2} g_{1T}^{\perp q}(x, k_T^2)$$

$$\Rightarrow \underline{g_{1T}^{\perp q}(x, k_T^2) = \frac{2M^2 x}{k_T^2} g_T^q(x) \frac{1}{\pi \langle k_\perp^2 \rangle_{g_1}} e^{-k_T^2 / \langle k_\perp^2 \rangle_{g_1}} = \frac{2M^2}{k_T^2} g_{1T}^{\perp q}(x) \frac{1}{\pi \langle k_\perp^2 \rangle_{g_1}} e^{-k_\perp^2 / \langle k_\perp^2 \rangle_{g_1}}}$$

this has to be if we choose the above parametrization of  $g_T^q(x, k_T^2)$

this will be our formula 6.1

$$\text{So that we have } F_{LT}^{\cos(\phi_u - \phi_s)} = C \left[ \int_0^1 g_{1T}^{\perp} D_1 \right]$$

$$F_{LT}^{\cos(\phi_u - \phi_s)} = x \sum_q e_q^2 g_{1T}^{\perp q}(x) D_1(z) \frac{2M e^{-P_{uT}^2 / \langle P^2 \rangle}}{\pi \langle k_\perp^2 \rangle_{g_1}^2} \left( \frac{P_{uT}^2 z^2 \langle k_\perp^2 \rangle_{g_1}}{e^{\langle P_\perp^2 \rangle^2 + \langle k_\perp^2 \rangle_{g_1} \langle P_\perp^2 \rangle z^2} - 1} \right) \frac{1}{P_{uT}}$$

this will be the formula