

# PROMISE OSAINE EKPO

Website: [www.cs.cornell.edu/~promiseekpo](http://www.cs.cornell.edu/~promiseekpo) | LinkedIn: [linkedin.com/in/promise-ekpo-osaine](https://linkedin.com/in/promise-ekpo-osaine)

## RESEARCH INTERESTS

**Post-Training & Alignment:** RLHF, DPO, Reward Modeling, Multi-Objective Optimization for LLM Alignment, Constitutional AI

**Optimization & Training:** Lagrangian Methods, Constrained Optimization, Nash Equilibrium, Distributed Training, Model Scaling

**Generative AI & LLMs:** Large Language Models, Multimodal Learning, RAG, Prompt Engineering, Fine-tuning

**Reinforcement Learning:** Multi-Agent RL, Policy Optimization (PPO, MAPPO), Fairness-Aware RL, Human-in-the-Loop Learning

## EDUCATION

**Cornell University**, Ph.D. in Computer Science (GPA: 3.94/4.0) August 2023 - May 2028

*Advisor:* Prof. Angelique Taylor, AirLAB | *Focus:* Multi-Agent RL, Fairness, Optimization, Healthcare AI

**Princeton University**, M.Sc. in Computer Science (GPA: 3.67/4.0) August 2021 - May 2023

*Thesis:* Investigating Persuasiveness in Large Language Models | *Advisor:* Prof. Jaime Fernández Fisac

## HIGHLIGHTED RESEARCH PROJECTS

**Fair Generalized Nash Equilibrium (Fair-GNE) for Multi-Objective Optimization** 2024 - Present

*Cornell University AirLAB* | *Submitted to L4DC 2026 & IFAC 2026*

- Developed novel constrained optimization framework using Lagrangian dual ascent for automatic penalty parameter learning, **eliminating manual hyperparameter tuning—directly applicable to KL penalty adaptation in RLHF/DPO**
- Designed game-theoretic multi-objective optimization with KKT conditions for convergence guarantees, addressing fairness-efficiency trade-offs in multi-agent systems (**parallels alignment challenges balancing helpfulness, harmlessness, honesty in LLMs**)
- Implemented distributed training experiments across 200+ concurrent GPU jobs on HPC clusters using SLURM, **demonstrating scalability to large-scale model training scenarios**
- Established rigorous experimental methodology with statistical significance testing (bootstrap resampling, effect size analysis) across 20-30 random seeds, ensuring reproducibility critical for production ML systems

- **Technical Stack:** PyTorch, EPyMARL, Weights & Biases, SLURM, CUDA, NumPy, JAX

## AI Safety: Investigating Persuasiveness & Alignment in Large Language Models

2022 -

2023

*Princeton University Safe Robotics Lab / Advisor: Prof. Jaime Fernández Fisac*

- Investigated emergent manipulative behaviors in LLMs (GPT-2/3/4, ChatGPT) **when combined with sequential decision-making, addressing alignment failures and reward hacking**
- Designed novel reward functions for evaluating persuasiveness as extension of Google BIG-BENCH benchmark, **contributing to AI safety frameworks for responsible deployment**
- Conducted systematic experiments revealing social biases and persuasive capabilities embedded in pre-trained language models, informing safety considerations for post-training alignment methods
- **Technical Stack:** Hugging Face Transformers, PyTorch, OpenAI API (GPT-3/4), Python

## FairSkillMARL: Fairness-Aware Multi-Agent Reinforcement Learning

2023 -

Present

*Cornell University AirLAB / [Submitted to AAMAS 2026](#)*

- Established principled fairness and reward modeling framework for MARL addressing gaps between algorithmic definitions and real-world equity in AI systems
- Designed novel disparity metrics capturing workload balance and skill-task alignment, demonstrating that single-objective fairness can lead to inequitable outcomes—**analogous to multi-objective alignment in LLMs**
- Built MARLHospital simulation environment with heterogeneous agents, enabling reproducible evaluation of fairness-efficiency trade-offs with transparent metrics
- Benchmarked against QMIX, MAPPO, and fairness baselines with hyperparameter tuning using Weights & Biases, providing comprehensive ablation studies

## PUBLICATIONS

*Selected publications in reinforcement learning, generative AI, fairness-aware systems, and AI safety.*

[1] **Promise Ekpo**, Angelique Taylor, Lekan Molu. "A Generalized Nash Equilibrium-Seeking Scheme for Trauma Resuscitation." Submitted to IFAC Conference 2026. [\[PDF\]](#)

[2] **Promise Ekpo**, Lekan Molu, Angelique Taylor. "Generalized Nash Equilibrium-Seeking Fairness in Multiagent Healthcare Automation." Submitted to L4DC 2026. [\[PDF\]](#)

[3] **Promise Ekpo**, Gonzalo Gonzalez Pumariega, Lekan Molu, Angelique Taylor. "Skill-Aligned Fairness in Multi-Agent Learning for Collaboration in Healthcare." Submitted to AAMAS 2026. [\[PDF\]](#)

[4] **Promise Ekpo**. "Investigating Persuasiveness in Large Language Models." M.S.E. Thesis, Princeton University, 2023. [\[PDF\]](#)

[5] Tauhid Tanjim, **Promise Ekpo**, Hee Rin Lee, Angelique Taylor et al. "Human-Robot Teaming Field Deployments: A Comparison Between Verbal and Non-verbal Communication." IEEE RO-MAN Workshop 2025. [\[PDF\]](#)

[6] Oluwatosin Ogundare, Tolu Owadokun, Temitope Ogundare, **Promise Ekpo**, Ha Linh Nguyen, Stephen Bello. "Integrated Artificial Intelligence in Healthcare and the Patient's Experience of Care." Scientific Reports (Nature), 2024. [\[PDF\]](#)

## INDUSTRIAL EXPERIENCE

**AI Safety & Verification Research Intern, Siemens (Robust Intelligence Team)**  
August 2023

June 2023 -

- Developed explainable AI (XAI) framework for graph neural network medical diagnosis systems using GNNExplainer, **improving model interpretability for safety-critical healthcare applications**
- Built multimodal safety monitoring system combining computer vision (deep learning) with real-time localization for warehouse robotics, engineering data fusion algorithms for seamless sensor integration
- Designed and executed proof-of-concept experiments on real-world medical datasets, informing production deployment decisions for AI safety systems

## TECHNICAL SKILLS

**Languages:** Python (expert), Java, C++, SQL, JavaScript

**ML Frameworks:** PyTorch (primary), TensorFlow, JAX, Hugging Face Transformers, Stable Baselines3

**LLM & Gen AI:** OpenAI API (GPT-3/4), Anthropic Claude, Hugging Face (BERT, GPT-2/3, LLaMA), Prompt Engineering, Fine-tuning

**RL Libraries:** EPyMARL, RLLib, Stable Baselines3, OpenAI Gym, PettingZoo, PDDL/PDDLGym

**Distributed Computing:** SLURM (HPC clusters), CUDA, Multi-GPU training, Distributed PyTorch, Ray

**MLOps & Tools:** Weights & Biases, TensorBoard, Docker, Git, Conda/pip, Jupyter, VS Code

**Scientific Computing:** NumPy, SciPy, Pandas, Matplotlib, Scikit-learn, Statistical Testing (bootstrap, t-tests)

## SELECTED AWARDS & HONORS

- CMD-IT/ACM Richard Tapia Conference, Best Poster Award - Graduate Category (1st Place, \$1,500) 2025
- NeurIPS Women in Machine Learning Grant (\$990) + Netflix & RTC Grant (\$3,000) 2025
- Cadence Technology Award - Women in Tech Category (8% acceptance, \$5,000) 2023
- Gordon Wu Fellowship, Princeton University (0.03% acceptance rate) 2021
- Dean's Honor Award, Best Graduating Student, Dept. of Computer Engineering, University of Benin 2020

## TEACHING EXPERIENCE

**Teaching Assistant**, Cornell University  
May 2024

September 2023 -

- CS 4780/5780 "Introduction to Machine Learning" and CS 4789/5789 "Introduction to Reinforcement Learning"

**Teaching Assistant/Preceptor**, Princeton University  
2022 - May 2023

September

- COS 126 "Computer Science: An Interdisciplinary Approach" (Java Programming)