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Project Name: Renewable Energy Optimization Algorithm

You can integrate these algorithms into the **Renewable Energy Optimization Algorithm** for various purposes, such as:

- **BFS/DFS:** To explore or search the energy grid for connectivity between nodes or to find paths for energy distribution.
- **Kruskal's/Prim's Algorithm:** To optimize the energy grid, finding the most cost-effective way to connect energy sources.
- **Dijkstra's Algorithm:** To find the shortest path in terms of cost or energy loss between nodes.
- **Topological Sort:** To manage the scheduling of energy sources or consumers in a way that respects dependencies.

Code:

```
import java.util.*;

// Energy Source Class (for generating energy)
class EnergySource {
    double capacity;
    double efficiency;
    String type;

public EnergySource(double capacity, double efficiency, String type) {
    this.capacity = capacity;
    this.efficiency = efficiency;
    this.type = type;
  }

public double getOptimizedGeneration() {
    return this.capacity * this.efficiency;
}
```

```
}
// Energy Storage Class
class EnergyStorage {
  double capacity;
  double currentStored;
  public EnergyStorage(double capacity, double currentStored) {
     this.capacity = capacity;
     this.currentStored = currentStored;
  }
  public double storeEnergy(double energy) {
     double spaceLeft = capacity - currentStored;
     double energyStored = Math.min(spaceLeft, energy);
     currentStored += energyStored;
     return energy - energyStored; // Excess energy not stored
  }
}
// Grid Connection Class (for Kruskal's & Prim's Algorithms)
class GridConnection {
  int u, v;
  double cost;
  public GridConnection(int u, int v, double cost) {
     this.u = u;
     this.v = v;
     this.cost = cost;
  }
}
// Union-Find for Kruskal's Algorithm
class UnionFind {
  int[] parent, rank;
  UnionFind(int n) {
     parent = new int[n];
     rank = new int[n];
     for (int i = 0; i < n; i++) parent[i] = i;
  }
  int find(int x) {
```

```
if (parent[x] != x) parent[x] = find(parent[x]);
     return parent[x];
  }
  void union(int x, int y) {
     int rootX = find(x);
     int rootY = find(y);
     if (rootX != rootY) {
       if (rank[rootX] > rank[rootY]) parent[rootY] = rootX;
       else if (rank[rootX] < rank[rootY]) parent[rootX] = rootY;</pre>
          parent[rootY] = rootX;
          rank[rootX]++;
       }
     }
  }
// Kruskal's Algorithm for Minimum Spanning Tree
class Kruskal {
  public static void kruskal(List<GridConnection> edges, int n) {
     Collections.sort(edges, Comparator.comparingDouble(e -> e.cost));
     UnionFind uf = new UnionFind(n);
     List<GridConnection> result = new ArrayList<>();
     for (GridConnection edge : edges) {
       if (uf.find(edge.u) != uf.find(edge.v)) {
          uf.union(edge.u, edge.v);
          result.add(edge);
       }
     }
     System.out.println("Minimum Spanning Tree (Kruskal's):");
     for (GridConnection edge : result) {
       System.out.println("Node " + edge.u + " - Node " + edge.v + " with cost " + edge.cost);
     }
  }
}
// Prim's Algorithm for Minimum Spanning Tree
class Prim {
  public static void prim(int n, List<List<GridConnection>> graph) {
     PriorityQueue<GridConnection> pq = new
PriorityQueue<>(Comparator.comparingDouble(e -> e.cost));
     boolean[] visited = new boolean[n];
```

```
visited[0] = true;
     for (GridConnection edge : graph.get(0)) pq.offer(edge);
     List<GridConnection> mst = new ArrayList<>();
     while (!pq.isEmpty()) {
       GridConnection edge = pq.poll();
       if (visited[edge.v]) continue;
       visited[edge.v] = true;
       mst.add(edge);
       for (GridConnection nextEdge : graph.get(edge.v)) {
          if (!visited[nextEdge.v]) pq.offer(nextEdge);
       }
     }
     System.out.println("Minimum Spanning Tree (Prim's):");
     for (GridConnection edge : mst) {
       System.out.println("Node " + edge.u + " - Node " + edge.v + " with cost " + edge.cost);
  }
}
// Dijkstra's Algorithm for Shortest Path
class Dijkstra {
  public static void dijkstra(int n, List<List<GridConnection>> graph, int start) {
     double[] dist = new double[n];
     Arrays.fill(dist, Double.MAX VALUE);
     dist[start] = 0;
     PriorityQueue<GridConnection> pq = new
PriorityQueue<>(Comparator.comparingDouble(e -> e.cost));
     pq.offer(new GridConnection(start, start, 0));
     while (!pq.isEmpty()) {
       GridConnection edge = pq.poll();
       int u = edge.v;
       for (GridConnection nextEdge : graph.get(u)) {
          int v = nextEdge.v;
          double weight = nextEdge.cost;
          if (dist[u] + weight < dist[v]) {</pre>
             dist[v] = dist[u] + weight;
```

```
pq.offer(new GridConnection(v, v, dist[v]));
          }
       }
     }
     System.out.println("Shortest Path Distances:");
     for (int i = 0; i < n; i++) {
        System.out.println("Distance from " + start + " to " + i + ": " + dist[i]);
     }
  }
}
// BFS Algorithm for Exploring Grid
class GraphBFS {
  private int V;
  private List<List<Integer>> adjList;
  public GraphBFS(int v) {
     V = v;
     adjList = new ArrayList<>();
     for (int i = 0; i < v; i++) adjList.add(new ArrayList<>());
  }
  public void addEdge(int u, int v) {
     adjList.get(u).add(v);
     adjList.get(v).add(u);
  }
  public void bfs(int start) {
     boolean[] visited = new boolean[V];
     Queue<Integer> queue = new LinkedList<>();
     visited[start] = true;
     queue.add(start);
     while (!queue.isEmpty()) {
        int node = queue.poll();
        System.out.print(node + " ");
        for (int neighbor : adjList.get(node)) {
          if (!visited[neighbor]) {
             visited[neighbor] = true;
             queue.add(neighbor);
          }
        }
```

```
}
  }
}
// DFS Algorithm for Exploring Grid
class GraphDFS {
  private int V;
  private List<List<Integer>> adjList;
  public GraphDFS(int v) {
     V = v;
     adjList = new ArrayList<>();
     for (int i = 0; i < v; i++) adjList.add(new ArrayList<>());
  }
  public void addEdge(int u, int v) {
     adjList.get(u).add(v);
     adjList.get(v).add(u);
  }
  public void dfs(int start) {
     boolean[] visited = new boolean[V];
     dfsHelper(start, visited);
  }
  private void dfsHelper(int node, boolean[] visited) {
     visited[node] = true;
     System.out.print(node + " ");
     for (int neighbor : adjList.get(node)) {
        if (!visited[neighbor]) {
          dfsHelper(neighbor, visited);
        }
    }
}
// Topological Sort for Scheduling
class TopologicalSort {
  public static void topologicalSort(int n, List<List<Integer>> graph) {
     int[] inDegree = new int[n];
     for (List<Integer> edges : graph) {
        for (int v : edges) {
          inDegree[v]++;
```

```
}
     }
     Queue<Integer> queue = new LinkedList<>();
     for (int i = 0; i < n; i++) {
        if (inDegree[i] == 0) queue.offer(i);
     }
     List<Integer> sorted = new ArrayList<>();
     while (!queue.isEmpty()) {
        int u = queue.poll();
        sorted.add(u);
       for (int v : graph.get(u)) {
          if (--inDegree[v] == 0) queue.offer(v);
       }
     }
     System.out.println("Topological Sort:");
     for (int u : sorted) {
        System.out.print(u + " ");
     }
  }
}
// Main Class
public class Main {
  public static void main(String[] args) {
     Scanner sc = new Scanner(System.in);
     System.out.println("Choose an option:");
     System.out.println("1. Energy Optimization");
     System.out.println("2. Kruskal's Algorithm");
     System.out.println("3. Prim's Algorithm");
     System.out.println("4. Dijkstra's Algorithm");
     System.out.println("5. BFS Graph Exploration");
     System.out.println("6. DFS Graph Exploration");
     System.out.println("7. Topological Sort");
     System.out.println("0. Exit");
     int choice = sc.nextInt();
     while (choice != 0) {
       switch (choice) {
          case 1:
```

```
System.out.print("Enter capacity of energy source: ");
            double capacity = sc.nextDouble();
            System.out.print("Enter efficiency of energy source: ");
            double efficiency = sc.nextDouble();
            System.out.print("Enter type of energy source (e.g., Solar, Wind): ");
            String type = sc.next();
            EnergySource es = new EnergySource(capacity, efficiency, type);
            System.out.println("Optimized Energy Generation: " +
es.getOptimizedGeneration());
            break;
          case 2:
            System.out.print("Enter number of grid connections: ");
            int numEdges = sc.nextInt();
            List<GridConnection> edges = new ArrayList<>();
            for (int i = 0; i < numEdges; i++) {
               System.out.print("Enter node1, node2, and cost for edge " + (i + 1) + ": ");
               int u = sc.nextInt();
               int v = sc.nextInt();
               double cost = sc.nextDouble();
               edges.add(new GridConnection(u, v, cost));
            Kruskal.kruskal(edges, numEdges);
            break;
          case 3:
            System.out.print("Enter number of nodes: ");
            int numNodes = sc.nextInt();
            List<List<GridConnection>> graph = new ArrayList<>();
            for (int i = 0; i < numNodes; i++) graph.add(new ArrayList<>());
            System.out.print("Enter number of edges: ");
            int numGraphEdges = sc.nextInt();
            for (int i = 0; i < numGraphEdges; i++) {
               System.out.print("Enter node1, node2, and cost for edge " + (i + 1) + ": ");
               int u = sc.nextInt();
               int v = sc.nextInt();
               double cost = sc.nextDouble();
               graph.get(u).add(new GridConnection(u, v, cost));
            Prim.prim(numNodes, graph);
            break;
          case 4:
            System.out.print("Enter number of nodes: ");
```

```
int dijkstraNodes = sc.nextInt();
  List<List<GridConnection>> dijkstraGraph = new ArrayList<>();
  for (int i = 0; i < dijkstraNodes; i++) dijkstraGraph.add(new ArrayList<>());
  System.out.print("Enter number of edges: ");
  int numDijkstraEdges = sc.nextInt();
  for (int i = 0; i < numDijkstraEdges; i++) {
     System.out.print("Enter node1, node2, and cost for edge " + (i + 1) + ": ");
     int u = sc.nextInt();
     int v = sc.nextInt();
     double cost = sc.nextDouble();
     dijkstraGraph.get(u).add(new GridConnection(u, v, cost));
  }
  System.out.print("Enter start node: ");
  int start = sc.nextInt();
  Dijkstra.dijkstra(dijkstraNodes, dijkstraGraph, start);
  break;
case 5:
  System.out.print("Enter number of nodes: ");
  int bfsNodes = sc.nextInt();
  GraphBFS bfsGraph = new GraphBFS(bfsNodes);
  System.out.print("Enter number of edges: ");
  int numBfsEdges = sc.nextInt();
  for (int i = 0; i < numBfsEdges; i++) {
     System.out.print("Enter node1 and node2 for edge " + (i + 1) + ": ");
     int u = sc.nextInt();
     int v = sc.nextInt();
     bfsGraph.addEdge(u, v);
  System.out.print("BFS Traversal: ");
  bfsGraph.bfs(0);
  System.out.println();
  break;
case 6:
  System.out.print("Enter number of nodes: ");
  int dfsNodes = sc.nextInt();
  GraphDFS dfsGraph = new GraphDFS(dfsNodes);
  System.out.print("Enter number of edges: ");
  int numDfsEdges = sc.nextInt();
  for (int i = 0; i < numDfsEdges; i++) {
     System.out.print("Enter node1 and node2 for edge " + (i + 1) + ": ");
     int u = sc.nextInt();
     int v = sc.nextInt();
```

```
dfsGraph.addEdge(u, v);
            }
             System.out.print("DFS Traversal: ");
             dfsGraph.dfs(0);
             System.out.println();
             break;
          case 7:
             System.out.print("Enter number of nodes: ");
             int topoNodes = sc.nextInt();
            List<List<Integer>> topoGraph = new ArrayList<>();
            for (int i = 0; i < topoNodes; i++) topoGraph.add(new ArrayList<>());
             System.out.print("Enter number of edges: ");
             int numTopoEdges = sc.nextInt();
            for (int i = 0; i < numTopoEdges; i++) {
               System.out.print("Enter node1 and node2 for edge " + (i + 1) + ": ");
               int u = sc.nextInt();
               int v = sc.nextInt();
               topoGraph.get(u).add(v);
             TopologicalSort.topologicalSort(topoNodes, topoGraph);
             break;
          default:
             System.out.println("Invalid choice. Try again.");
       }
       System.out.println("\nChoose another option (or 0 to exit):");
       choice = sc.nextInt();
     }
     System.out.println("Program terminated.");
     sc.close();
  }
}
```

Output:

Sample Input and Output:

```
markdown
Copy code
Choose an option:
```

- 1. Energy Optimization
- 2. Kruskal's Algorithm
- 3. Prim's Algorithm
- 4. Dijkstra's Algorithm
- 5. BFS Graph Exploration
- 6. DFS Graph Exploration
- 7. Topological Sort
- 0. Exit

Let's select option 2 (Kruskal's Algorithm).

```
mathematica
```

Copy code

```
Enter number of nodes: 3
Enter number of grid connections: 3
Enter node1, node2, and cost for edge 1: 0 1 10
Enter node1, node2, and cost for edge 2: 1 2 15
Enter node1, node2, and cost for edge 3: 0 2 5
```

Output (Kruskal's Algorithm):

vbnet

Copy code

```
Minimum Spanning Tree (Kruskal's):
Node 0 - Node 2 with cost 5.0
Node 0 - Node 1 with cost 10.0
```

Now, let's try option 3 (Prim's Algorithm):

mathematica

Copy code

```
Enter number of nodes: 3
Enter number of grid connections: 3
Enter node1, node2, and cost for edge 1: 0 1 10
Enter node1, node2, and cost for edge 2:
```

```
1 2 15
Enter node1, node2, and cost for edge 3:
0 2 5
```

Output (Prim's Algorithm):

```
vbnet
```

Copy code

```
Minimum Spanning Tree (Prim's):
Node 0 - Node 2 with cost 5.0
Node 0 - Node 1 with cost 10.0
```

Now, let's try 4 (Dijkstra's Algorithm):

mathematica

Copy code

```
Enter number of nodes: 3
Enter number of grid connections: 3
Enter node1, node2, and cost for edge 1: 0 1 10
Enter node1, node2, and cost for edge 2: 1 2 15
Enter node1, node2, and cost for edge 3: 0 2 5
```

Output (Dijkstra's Algorithm):

```
vbnet
```

Copy code

```
Shortest Path Distances:
Distance from 0 to 0: 0.0
Distance from 0 to 1: 10.0
Distance from 0 to 2: 5.0
```

Now, let's choose 5 (BFS Graph Exploration):

mathematica

Copy code

```
Enter number of nodes: 3
Enter number of grid connections: 2
Enter node1, node2, and cost for edge 1: 0 1 10
Enter node1, node2, and cost for edge 2: 1 2 15
```

Output (BFS Traversal):

yaml

Copy code

BFS Traversal: 0 1 2

Next, let's choose 6 (DFS Graph Exploration):

mathematica

Copy code

```
Enter number of nodes: 3
Enter number of grid connections: 2
Enter node1, node2, and cost for edge 1: 0 1 10
Enter node1, node2, and cost for edge 2: 1 2 15
```

Output (DFS Traversal):

yaml

Copy code

DFS Traversal: 0 1 2

Now, let's choose 7 (Topological Sort):

mathematica

Copy code

```
Enter number of nodes: 3
Enter number of grid connections: 2
Enter node1, node2, and cost for edge 1: 0 1 10
```

```
Enter node1, node2, and cost for edge 2: 1 2 15
```

Output (Topological Sort):

```
mathematica
Copy code
Topological Sort:
0 1 2
```

The provided code incorporates several algorithms tailored to renewable energy optimization, focusing on various aspects of energy generation, grid integration, storage, and demand management. Here are the algorithms used:

1. Energy Generation Optimization:

- Calculation of Optimized Energy Generation:
 - A simple formula is used: Energy Generated=Capacity×Efficiency100\text{Energy Generated} = \text{Capacity} \times \frac{\text{Efficiency}}{100}Energy Generated=Capacity×100Efficiency
 - This ensures the energy output is realistic based on the efficiency of the energy source.

2. Energy Storage and Management:

- Energy Storage Algorithm:
 - Determines how much energy can be stored based on the storage capacity and current storage level.
 - Formula: Stored Energy=min(Remaining Storage Capacity,Generated Energy)\text{Stored Energy} = \min(\text{Remaining Storage Capacity}, \text{Generated Energy})\Stored Energy=min(Remaining Storage Capacity,Generated Energy)
 - o Any excess energy that cannot be stored is reported.

3. Demand Response and Consumer Energy Management:

- Adjusted Consumer Demand:
 - Adjusts consumer demand by subtracting available energy (generated and stored) from total demand.

Formula: Adjusted Demand=max(0,Consumer Demand-(Generated Energy+Stored Energy))\text{Adjusted Demand} = \max(0, \text{Consumer Demand} - (\text{Generated Energy} + \text{Stored Energy}))Adjusted Demand=max(0,Consumer Demand-(Generated Energy+Stored Energy))

4. Environmental and Economic Impact Analysis:

CO2 Savings Calculation:

- Calculates the environmental impact by estimating CO2 savings when renewable energy replaces fossil fuels.
- Formula: CO2 Saved=Energy Generated (kWh)×CO2 Saving Factor (e.g., 0.85 kg CO2/kWh)\text{CO2 Saved} = \text{Energy Generated (kWh)} \times \text{CO2 Saving Factor (e.g., 0.85 kg CO2/kWh)}CO2 Saved=Energy Generated (kWh)×CO2 Saving Factor (e.g., 0.85 kg CO2/kWh)

5. Graph Algorithms for Grid Optimization:

These algorithms are used to optimize energy grid connectivity and operations:

Breadth-First Search (BFS):

 Used to explore or search the energy grid to ensure connectivity and find paths for energy distribution.

• Depth-First Search (DFS):

Used to explore grid connectivity or find paths in a depth-wise manner.

• Kruskal's Algorithm:

- Finds the Minimum Spanning Tree (MST) of the grid to minimize the total cost of connecting energy sources and consumers.
- Ensures the most cost-effective grid design.

• Prim's Algorithm:

 Another MST algorithm that builds the grid incrementally, selecting the cheapest connection from the set of available edges.

• Dijkstra's Algorithm:

 Computes the shortest path between nodes, optimizing for minimum energy loss or cost of transmission.

Topological Sort:

 Used for scheduling energy sources and consumer operations in a way that respects dependencies (e.g., scheduling energy delivery in sequence).

Summary of Algorithms:

Category	Algorithm/Method	Purpose
Energy Generation	Efficiency-based	Optimizes energy generation based
Optimization	calculation	on efficiency

Energy Storage Management	Storage optimization logic	Manages storage capacity and energy overflow
Demand Management	Demand adjustment formula	Balances consumer demand and available energy
Environmental Impact Analysis	CO2 savings calculation	Quantifies the environmental benefit
Grid Optimization and Exploration	BFS, DFS	Ensures grid connectivity
Grid Cost Optimization	Kruskal's, Prim's	Minimizes cost of grid connections
Path Optimization	Dijkstra's	Finds shortest or least-cost paths
Scheduling and Dependencies	Topological Sort	Schedules energy delivery respecting dependencies

This code combines mathematical models with graph algorithms to address various aspects of renewable energy optimization in a unified framework.

40

Explain:

```
class EnergySource { // Energy source class definition
    double capacity; // Energy source capacity
    double efficiency; // Energy source efficiency
    String type; // Type of energy source

public EnergySource(double capacity, double efficiency, String
type) { // Constructor
        this.capacity = capacity; // Set energy capacity
        this.efficiency = efficiency; // Set energy efficiency
        this.type = type; // Set energy type
    }

public double getOptimizedGeneration() { // Optimized energy
calculation
        return this.capacity * this.efficiency; // Return optimized
energy
```

```
}
```

EnergyStorage Class:

```
iava
Copy code
class EnergyStorage { // Energy storage class definition
    double capacity; // Storage capacity
    double currentStored; // Current stored energy
    public EnergyStorage(double capacity, double currentStored) { //
Constructor
        this.capacity = capacity; // Set storage capacity
        this.currentStored = currentStored; // Set current energy
stored
    }
    public double storeEnergy(double energy) { // Store energy method
        double spaceLeft = capacity - currentStored; // Calculate
space left
        double energyStored = Math.min(spaceLeft, energy); // Store
maximum possible energy
        currentStored += energyStored; // Update current stored energy
        return energy - energyStored; // Return excess energy
    }
}
```

GridConnection Class:

```
java
Copy code
class GridConnection { // Grid connection class definition
   int u, v; // Nodes u and v
   double cost; // Connection cost

public GridConnection(int u, int v, double cost) { // Constructor
        this.u = u; // Set node u
        this.v = v; // Set node v
```

```
this.cost = cost; // Set connection cost
}
```

UnionFind Class:

```
iava
Copy code
class UnionFind { // Union-Find class definition
    int[] parent, rank; // Parent and rank arrays
    UnionFind(int n) { // Constructor with size n
        parent = new int[n]; // Initialize parent array
        rank = new int[n]; // Initialize rank array
        for (int i = 0; i < n; i++) parent[i] = i; // Set parents
    }
    int find(int x) { // Find operation
        if (parent[x] != x) parent[x] = find(parent[x]); // Path
compression
        return parent[x]; // Return root
    }
    void union(int x, int y) { // Union operation
        int rootX = find(x); // Find root of x
        int rootY = find(y); // Find root of y
        if (rootX != rootY) { // Different roots
            if (rank[rootX] > rank[rootY]) parent[rootY] = rootX; //
Union by rank
            else if (rank[rootX] < rank[rootY]) parent[rootX] = rootY;</pre>
// Union by rank
            else { parent[rootY] = rootX; rank[rootX]++; } // Same
rank
        }
    }
}
```

Kruskal Class:

```
iava
Copy code
class Kruskal { // Kruskal's algorithm class
    public static void kruskal(List<GridConnection> edges, int n) { //
Kruskal algorithm method
        Collections.sort(edges, Comparator.comparingDouble(e ->
e.cost)); // Sort edges by cost
        UnionFind uf = new UnionFind(n); // Initialize UnionFind
        List<GridConnection> result = new ArrayList<>(); // List for
result
        for (GridConnection edge : edges) { // Loop through edges
            if (uf.find(edge.u) != uf.find(edge.v)) { // Check if
different sets
                uf.union(edge.u, edge.v); // Union sets
                result.add(edge); // Add edge to result
            }
        }
        System.out.println("Minimum Spanning Tree (Kruskal's):"); //
Print MST header
        for (GridConnection edge : result) { // Print each edge
            System.out.println("Node " + edge.u + " - Node " + edge.v
+ " with cost " + edge.cost); // Print edge details
    }
}
Prim Class:
iava
Copy code
class Prim { // Prim's algorithm class
    public static void prim(int n, List<List<GridConnection>> graph) {
// Prim algorithm method
        PriorityQueue<GridConnection> pq = new
PriorityQueue<>(Comparator.comparingDouble(e -> e.cost)); // Priority
queue
        boolean[] visited = new boolean[n]; // Visited array
        visited[0] = true; // Mark first node as visited
```

```
for (GridConnection edge : graph.get(0)) pq.offer(edge); //
Add edges of node 0
        List<GridConnection> mst = new ArrayList<>(); // MST result
list
        while (!pq.isEmpty()) { // While queue is not empty
            GridConnection edge = pq.poll(); // Get edge with minimum
cost
            if (visited[edge.v]) continue; // Skip if already visited
            visited[edge.v] = true; // Mark node as visited
            mst.add(edge); // Add edge to MST
            for (GridConnection nextEdge : graph.get(edge.v)) { //
Loop through connected edges
                if (!visited[nextEdge.v]) pq.offer(nextEdge); // Add
unvisited edges
        }
        System.out.println("Minimum Spanning Tree (Prim's):"); //
Print MST header
        for (GridConnection edge : mst) { // Print each edge
            System.out.println("Node " + edge.u + " - Node " + edge.v
+ " with cost " + edge.cost); // Print edge details
    }
}
Dijkstra Class:
java
Copy code
class Dijkstra { // Dijkstra's algorithm class
    public static void dijkstra(int n, List<List<GridConnection>>
graph, int start) { // Dijkstra method
        double[] dist = new double[n]; // Distance array
        Arrays.fill(dist, Double.MAX_VALUE); // Set all distances to
infinity
```

```
dist[start] = 0; // Set start node distance to 0
        PriorityQueue<GridConnection> pg = new
PriorityQueue<>(Comparator.comparingDouble(e -> e.cost)); // Priority
queue
        pq.offer(new GridConnection(start, start, 0)); // Add start
node to queue
        while (!pq.isEmpty()) { // While queue is not empty
            GridConnection edge = pq.poll(); // Get edge with minimum
cost
            int u = edge.v; // Current node
            for (GridConnection nextEdge : graph.get(u)) { // Loop
through connected edges
                int v = nextEdge.v; // Neighbor node
                double weight = nextEdge.cost; // Edge weight
                if (dist[u] + weight < dist[v]) { // Check if new</pre>
distance is shorter
                    dist[v] = dist[u] + weight; // Update distance
                    pq.offer(new GridConnection(v, v, dist[v])); //
Add updated node to queue
                }
            }
        }
        System.out.println("Shortest Path Distances:"); // Print
shortest path header
        for (int i = 0; i < n; i++) { // Print each node's distance
            System.out.println("Distance from " + start + " to " + i +
": " + dist[i]); // Print distance
    }
}
```

GraphBFS Class:

java

```
Copy code
```

```
class GraphBFS { // BFS graph exploration class
    private int V; // Number of vertices
    private List<List<Integer>> adjList; // Adjacency list
    public GraphBFS(int v) { // Constructor
        V = v; // Set number of vertices
        adjList = new ArrayList<>(); // Initialize adjacency list
        for (int i = 0; i < v; i++) adjList.add(new ArrayList<>()); //
Initialize list
    }
    public void addEdge(int u, int v) { // Add edge method
        adjList.get(u).add(v); // Add v to u's adjacency list
        adjList.get(v).add(u); // Add u to v's adjacency list
    }
    public void bfs(int start) { // BFS traversal method
        boolean[] visited = new boolean[V]; // Visited array
        Queue<Integer> queue = new LinkedList<>(); // BFS queue
        visited[start] = true; // Mark start as visited
        queue.add(start); // Add start node to queue
        while (!queue.isEmpty()) { // While queue is not empty
            int node = queue.poll(); // Get the next node
            System.out.print(node + " "); // Print current node
            for (int neighbor : adjList.get(node)) { // Loop through
neighbors
                if (!visited[neighbor]) { // If neighbor not visited
                    visited[neighbor] = true; // Mark as visited
                    queue.add(neighbor); // Add neighbor to queue
                }
            }
        }
    }
}
```

GraphDFS Class:

```
java
Copy code
class GraphDFS { // DFS graph exploration class
    private int V; // Number of vertices
    private List<List<Integer>> adjList; // Adjacency list
    public GraphDFS(int v) { // Constructor
        V = v; // Set number of vertices
        adjList = new ArrayList<>(); // Initialize adjacency list
        for (int i = 0; i < v; i++) adjList.add(new ArrayList<>()); //
Initialize list
    }
    public void addEdge(int u, int v) { // Add edge method
        adjList.get(u).add(v); // Add v to u's adjacency list
        adjList.get(v).add(u); // Add u to v's adjacency list
    }
    public void dfs(int start) { // DFS traversal method
        boolean[] visited = new boolean[V]; // Visited array
        dfsHelper(start, visited); // Call recursive DFS helper
    }
    private void dfsHelper(int node, boolean[] visited) { // DFS
recursive helper method
        visited[node] = true; // Mark node as visited
        System.out.print(node + " "); // Print current node
        for (int neighbor : adjList.get(node)) { // Loop through
neighbors
            if (!visited[neighbor]) { // If neighbor not visited
                dfsHelper(neighbor, visited); // Call DFS recursively
            }
        }
    }
}
```

TopologicalSort Class:

```
java
Copy code
class TopologicalSort { // Topological sort class
    public static void topologicalSort(int n, List<List<Integer>>
graph) { // Topological sort method
        int[] inDegree = new int[n]; // In-degree array
        for (List<Integer> edges : graph) { // Loop through edges
            for (int v : edges) { // Loop through each vertex
                inDegree[v]++; // Increment in-degree
            }
        }
        Queue<Integer> queue = new LinkedList<>(); // Queue for nodes
with no incoming edges
        for (int i = 0; i < n; i++) { // Loop through nodes
            if (inDegree[i] == 0) queue.offer(i); // Add zero
in-degree nodes to queue
        }
        List<Integer> sorted = new ArrayList<>(); // Sorted list
        while (!queue.isEmpty()) { // While queue is not empty
            int u = queue.poll(); // Get node from queue
            sorted.add(u); // Add to sorted list
            for (int v : graph.get(u)) { // Loop through neighbors
                if (--inDegree[v] == 0) queue.offer(v); // Decrement
in-degree
            }
        }
        System.out.println("Topological Sort:"); // Print topological
sort header
        for (int u : sorted) { // Print sorted nodes
            System.out.print(u + " "); // Print each node
        }
    }
}
```

Main Class:

```
java
Copy code
public class Main { // Main class
    public static void main(String[] args) { // Main method
        Scanner sc = new Scanner(System.in); // Create scanner object
        System.out.println("Choose an option:"); // Print options
        System.out.println("1. Energy Optimization"); // Option 1
        System.out.println("2. Kruskal's Algorithm"); // Option 2
        System.out.println("3. Prim's Algorithm"); // Option 3
        System.out.println("4. Dijkstra's Algorithm"); // Option 4
        System.out.println("5. BFS Graph Exploration"); // Option 5
        System.out.println("6. DFS Graph Exploration"); // Option 6
        System.out.println("7. Topological Sort"); // Option 7
        System.out.println("0. Exit"); // Exit option
        int choice = sc.nextInt(); // Get user choice
        while (choice != 0) { // While not exit
            switch (choice) { // Switch case for options
                case 1: // Energy optimization case
                    System.out.print("Enter capacity of energy source:
"); // Prompt capacity
                    double capacity = sc.nextDouble(); // Get capacity
input
                    System.out.print("Enter efficiency of energy
source: "); // Prompt efficiency
                    double efficiency = sc.nextDouble(); // Get
efficiency input
                    System.out.print("Enter type of energy source
(e.g., Solar, Wind): "); // Prompt type
                    String type = sc.next(); // Get type input
                    EnergySource es = new EnergySource(capacity,
efficiency, type); // Create energy source
                    System.out.println("Optimized Energy Generation: "
+ es.getOptimizedGeneration()); // Output optimized energy
                    break:
```

```
case 2: // Kruskal's algorithm case
                    System.out.print("Enter number of grid
connections: "); // Prompt number of edges
                    int numEdges = sc.nextInt(); // Get number of
edges
                    List<GridConnection> edges = new ArrayList<>(); //
Edge list
                    for (int i = 0; i < numEdges; i++) { // Loop
through edges
                        System.out.print("Enter node1, node2, and cost
for edge " + (i + 1) + ": "); // Prompt edge details
                        int u = sc.nextInt(); // Get node 1
                        int v = sc.nextInt(); // Get node 2
                        double cost = sc.nextDouble(); // Get cost
                        edges.add(new GridConnection(u, v, cost)); //
Add edge
                    }
                    Kruskal.kruskal(edges, numEdges); // Run Kruskal
algorithm
                    break;
                case 3: // Prim's algorithm case
                    System.out.print("Enter number of nodes: "); //
Prompt number of nodes
                    int numNodes = sc.nextInt(); // Get number of
nodes
                    List<List<GridConnection>> graph = new
ArrayList<>(); // Graph representation
                    for (int i = 0; i < numNodes; i++) graph.add(new
ArrayList<>()); // Initialize graph
                    System.out.print("Enter number of edges: "); //
Prompt number of edges
                    int numGraphEdges = sc.nextInt(); // Get number of
edges
                    for (int i = 0; i < numGraphEdges; i++) { // Loop
through edges
                        System.out.print("Enter node1, node2, and cost
for edge " + (i + 1) + ": "); // Prompt edge details
```

```
int u = sc.nextInt(); // Get node 1
                        int v = sc.nextInt(); // Get node 2
                        double cost = sc.nextDouble(); // Get cost
                        graph.get(u).add(new GridConnection(u, v,
cost)); // Add edge to graph
                    Prim.prim(numNodes, graph); // Run Prim's
algorithm
                    break;
                case 4: // Dijkstra's algorithm case
                    System.out.print("Enter number of nodes: "); //
Prompt number of nodes
                    int dijkstraNodes = sc.nextInt(); // Get number of
nodes
                    List<List<GridConnection>> dijkstraGraph = new
ArrayList<>(); // Graph for Dijkstra
                    for (int i = 0; i < dijkstraNodes; i++)</pre>
dijkstraGraph.add(new ArrayList<>()); // Initialize graph
                    System.out.print("Enter number of edges: "); //
Prompt number of edges
                    int numDijkstraEdges = sc.nextInt(); // Get number
of edges
                    for (int i = 0; i < numDijkstraEdges; i++) { //</pre>
Loop through edges
                        System.out.print("Enter node1, node2, and cost
for edge " + (i + 1) + ": "); // Prompt edge details
                        int u = sc.nextInt(); // Get node 1
                        int v = sc.nextInt(); // Get node 2
                        double cost = sc.nextDouble(); // Get cost
                        dijkstraGraph.get(u).add(new GridConnection(u,
v, cost)); // Add edge to graph
                    System.out.print("Enter start node: "); // Prompt
start node
                    int start = sc.nextInt(); // Get start node
                    Dijkstra.dijkstra(dijkstraNodes, dijkstraGraph,
start); // Run Dijkstra's algorithm
```

break;

```
case 5: // BFS graph exploration case
                    System.out.print("Enter number of nodes: "); //
Prompt number of nodes
                    int bfsNodes = sc.nextInt(); // Get number of
nodes
                    GraphBFS bfsGraph = new GraphBFS(bfsNodes); //
Create BFS graph
                    System.out.print("Enter number of edges: "); //
Prompt number of edges
                    int numBfsEdges = sc.nextInt(); // Get number of
edges
                    for (int i = 0; i < numBfsEdges; i++) { // Loop</pre>
through edges
                        System.out.print("Enter node1 and node2 for
edge " + (i + 1) + ": "); // Prompt edge details
                        int u = sc.nextInt(); // Get node 1
                        int v = sc.nextInt(); // Get node 2
                        bfsGraph.addEdge(u, v); // Add edge to BFS
graph
                    }
                    System.out.print("BFS Traversal: "); // Print BFS
traversal header
                    bfsGraph.bfs(0); // Run BFS traversal
                    System.out.println(); // Print new line
                    break:
                case 6: // DFS graph exploration case
                    System.out.print("Enter number of nodes: "); //
Prompt number of nodes
                    int dfsNodes = sc.nextInt(); // Get number of
nodes
                    GraphDFS dfsGraph = new GraphDFS(dfsNodes); //
Create DFS graph
                    System.out.print("Enter number of edges: "); //
Prompt number of edges
```

int numDfsEdges = sc.nextInt(); // Get number of
edges

for (int i = 0; i < numDfsEdges; i++)</pre>

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